Tutorial 2: Render 3D objects with OpenGL

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Agenda

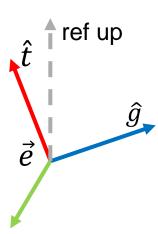
- Transformation in OpenGL
 - Homogenous coordinates
 - View transformation
 - Projection transformation
 - Solution of quiz1
- How to finish homework1: draw 3D object with OpenGL
 - Vertex shader
 - Fragment shader

Homogenous Coordinates

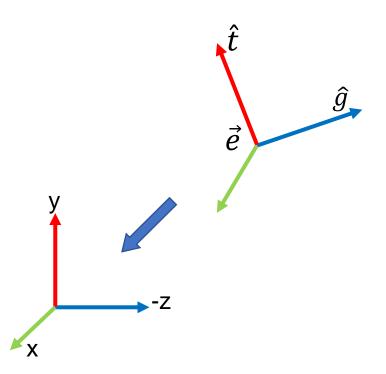
- 3D point = $(x, y, z, 1)^T$
- 3D vector = $(x, y, z, 0)^T$
- In general, a 3D point can be expressed by $(kx, ky, kz, k)^T, k \neq 0$
- Then we can use a 4x4 matrix for affine transformations

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} a & b & c & t_x \\ d & e & f & t_y \\ g & h & i & t_z \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

- How to define a camera in 3D space? (right handed)
- Position
- Look at / gaze direction
- Ref up direction
- Compute a orthonormal basis with cross product

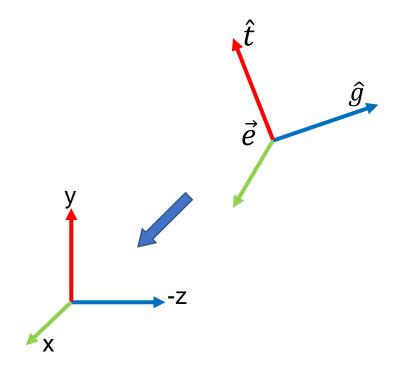


- Transform camera to:
 - position: origin point
 - up at y axis
 - look along –z axis
- And transform all objects along with the camera.
- Translate camera to origin point first, then rotate it such that \hat{t} aligns to y and \hat{g} aligns to -z.



Translate camera to origin point

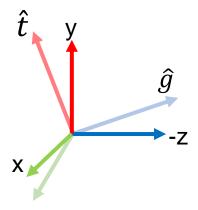
$$\bullet \ T_{view} = \begin{bmatrix} 1 & 0 & 0 & -x_e \\ 0 & 1 & 0 & -y_e \\ 0 & 0 & 1 & -z_e \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



- Rotate \hat{t} to y, rotate \hat{g} to -z, rotate $\hat{g} \times \hat{t}$ to x
- This is difficult... So we consider inverse rotation.

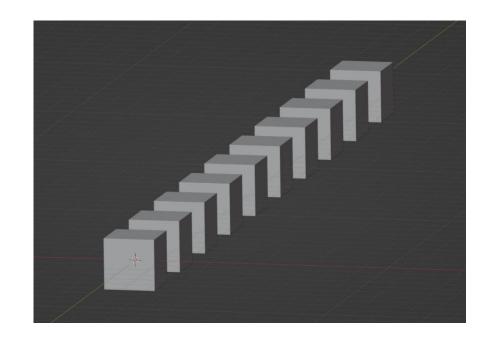
•
$$R_{view}^{-1} = \begin{bmatrix} x_{\hat{g} \times \hat{t}} & x_{\hat{t}} & x_{-\hat{g}} & 0 \\ y_{\hat{g} \times \hat{t}} & y_{\hat{t}} & y_{-\hat{g}} & 0 \\ z_{\hat{g} \times \hat{t}} & z_{\hat{t}} & z_{-\hat{g}} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

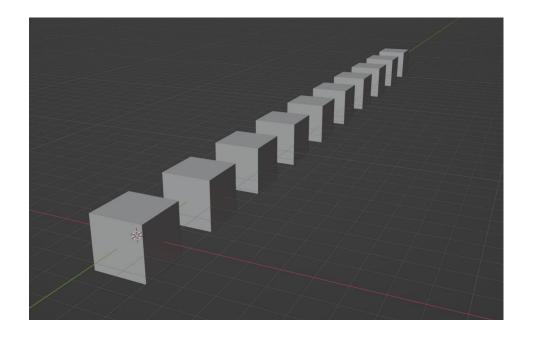
• $R_{view} = (R_{view}^{-1})^T$ Why? Orthogonal matrix



Projection Transformation

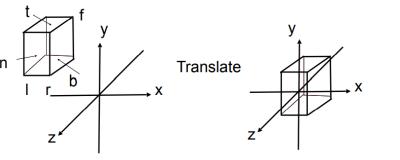
Orthogonal v.s. Perspective

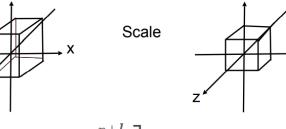




Orthographic Projection

- Goal: map a cuboid $[l,r] \times [b,t] \times [-n,-f]$ to canonical cube $[-1,1]^3$
- Translate center to origin first, then scale.





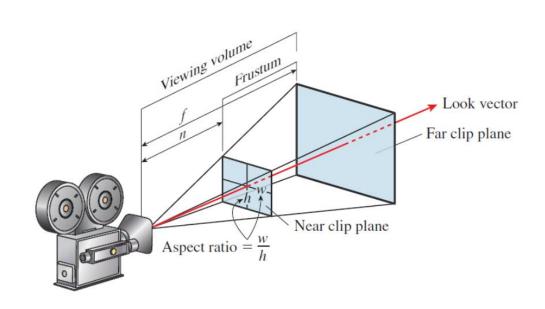
$$M_{ortho} \; = \left[egin{array}{ccccc} rac{2}{r-l} & 0 & 0 & -rac{r+l}{r-l} \ 0 & rac{2}{t-b} & 0 & -rac{t+b}{t-b} \ 0 & 0 & -rac{2}{f-n} & -rac{f+n}{f-n} \ 0 & 0 & 0 & 1 \end{array}
ight]$$

Note!

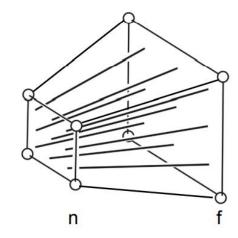
OpenGL uses right-handed cartesian coordinates.

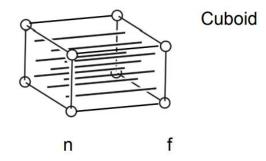
But NDC is left-handed cartesian coordinates.

So we need to flip z







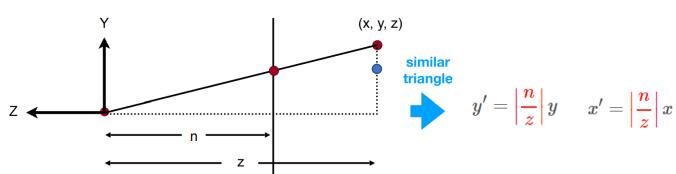


$$\bullet \begin{bmatrix} x_{clip} \\ y_{clip} \\ z_{clip} \\ 1 \end{bmatrix} = M_{persp} \begin{bmatrix} x_{view} \\ y_{view} \\ z_{view} \\ 1 \end{bmatrix}$$

•
$$M_{persp} = M_{ortho} M_{persp \to ortho}$$

$$M_{persp \to ortho} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} nx \\ ny \\ ? \\ -z \end{bmatrix}$$

$$M_{persp \to ortho} = \begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ ? & ? & ? & ? \\ 0 & 0 & -1 & 0 \end{bmatrix}$$



- Figure out the third line of $M_{persp \rightarrow ortho}$.
- Any point on the near plane will not change.
- Any point's z coord on far plane will not change.

For any point on near plane:

$$\begin{bmatrix} x \\ y \\ -n \\ 1 \end{bmatrix} = \begin{bmatrix} nx \\ ny \\ -n^2 \\ n \end{bmatrix}$$

So:

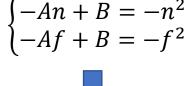
$$\begin{bmatrix} 0 & 0 & A & B \end{bmatrix} \begin{bmatrix} x \\ y \\ -n \\ 1 \end{bmatrix} = -n^2 \qquad \begin{bmatrix} 0 & 0 & A & B \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -f \end{bmatrix} = -f^2$$

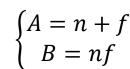
For any point on near plane:

$$\begin{bmatrix} 0 \\ 0 \\ -f \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -n^2 \\ f \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & A & B \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -f \\ 1 \end{bmatrix} = -f^2$$

 $\begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ ? & ? & ? & ? \\ 0 & 0 & 1 & 0 \end{bmatrix}$





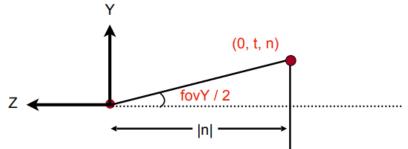
$$\bullet \ M_{persp \to ortho} = \begin{vmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+f & nf \\ 0 & 0 & -1 & 0 \end{vmatrix}$$

So we can write final perspective matrix.

$$M_{persp} = M_{ortho} M_{persp
ightarrow ortho} = egin{bmatrix} rac{2n}{r-l} & 0 & rac{r+l}{r-l} & 0 \ 0 & rac{2n}{t-b} & rac{t+b}{t-b} & 0 \ 0 & 0 & -rac{f+n}{f-n} & -rac{2nf}{f-n} \ 0 & 0 & -1 & 0 \end{bmatrix}$$

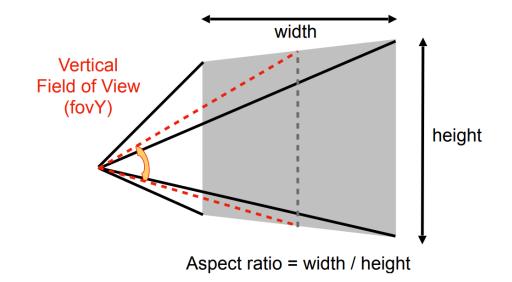
- How are I, r, t, b defined?
- Usually we assume symmetry. (i.e. I = -r, t = -b)

$$\begin{cases}
t = n \tan \frac{\text{fovY}}{2} \\
r = \text{asp} \times n \tan \frac{\text{fovY}}{2}
\end{cases}$$



$$\tan \frac{fovY}{2} = \frac{t}{|n|}$$

$$aspect = \frac{r}{t}$$

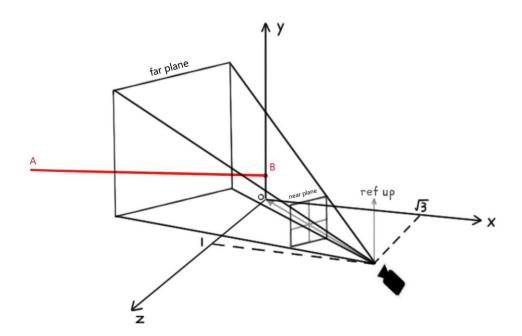


Viewport Tranformation

- Map all points in NDC space to screen, drop Z
- $[-1, 1]^2 \rightarrow [0, width] \times [0, height]$

$$M_{viewport} = egin{pmatrix} rac{width}{2} & 0 & 0 & rac{width}{2} \ 0 & rac{height}{2} & 0 & rac{height}{2} \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$

Solution of Quiz.1



1. Consider a line segment AB in world space. $A(-2\sqrt{3}, \frac{\sqrt{3}}{2}, 4)$, $B(0, \frac{\sqrt{3}}{3}, 0)$. A pin-hole camera is positioned at $(\sqrt{3}, 0, 1)$, looking at the origin point. The reference up vector of the camera is (0, 1, 0). The vertical field of view (fovY) is 60 degrees and aspect ratio is 1. The distance from camera to near plane is $\sqrt{3}$, and distance from camera to far plane is $3\sqrt{3}$. Screen resolution is 800×800 . The origin point of the screen is at its left-bottom corner.

Please calculate the coordinate of two end points of the line segment that screen can display in screen space.

Hint: You need to account for clipping.

Solution:

$$M_{view} = \begin{bmatrix} \frac{1}{2} & 0 & -\frac{\sqrt{3}}{2} & 0\\ 0 & 1 & 0 & 0\\ \frac{\sqrt{3}}{2} & 0 & \frac{1}{2} & -2\\ 0 & 0 & 0 & 1 \end{bmatrix}, M_{persp} = \begin{bmatrix} \sqrt{3} & 0 & 0 & 0\\ 0 & \sqrt{3} & 0 & 0\\ 0 & 0 & -2 & -3\sqrt{3}\\ 0 & 0 & -1 & 0 \end{bmatrix}$$

In NDC space:

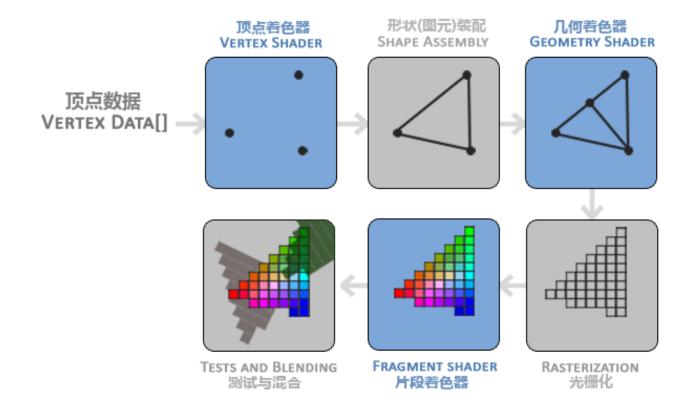
$$A' = M_{persp} M_{view} A = (-3, \frac{1}{2}, 2 - \sqrt{3}, 1)$$

$$B' = M_{persp} M_{view} B = (0, \frac{1}{2}, 2 - \frac{3\sqrt{3}}{2}, 1)$$

A' is not in $[-1,1]^3$, so the end point on screen should be $(-1,\frac{1}{2},z)$ (no need to compute z's value). Convert (-1,0.5) and (0,0.5) to screen space. Two end points are (0,600) and (400,600) respectively.

Shader

A standard OpenGL rendering pipeline



Shader

- How shader work?
- Here is the typical structure of a shader
- Written in GLSL (similar gramma as C)
- Usually put in file my_shader.glsl

```
#version version number
in type in_variable_name;
in type in_variable_name;
out type out_variable_name;
uniform type uniform_name;
void main()
  // process input
  // output result to out variable
  out variable name = weird stuff we processed;
```

Vertex Shader

- Call back: in last tutorial...
 - we draw a right triangle.
 - Vertex coordinates are given in NDC space.
 - But now we only have coordinate in world space.

```
const float vertices[] = { 0, 0, 0, 1, 0, 0, 0, 1, 0};
```

```
// in vertex shader
#version 330 core
layout (location = 0) in vec3 pos;

void main() {
    gl_Position = vec4(pos, 1.0);
}
```

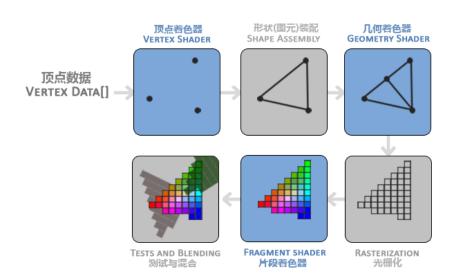
```
(-1, -1) (0, 1) (1, 1) (1, 1) (1, 1) (1, -1)
```

```
// in fragment shader
#version 330 core
out vec4 color;

void main() {
    color = vec4(1.0, 0.5, 0.2, 1.0);
}
```

Vertex Shader

- Transform 3D world coordinate to NDC coordinate
- Vertex Coordinate = $M_{proj} M_{modelview} P$
- Take vertex coordinate (and other info) from VBO with layout.
- Projection, model and view matrix are the same for all vertices, so use uniform.



Vertex Shader - Layout

```
// in vertex shader
layout (location = 0) in vec3 pos;
layout (location = 1) in vec3 normal;
```

```
// in headers and .cpp files
struct Vertex {
 vec3 position;
 vec3 normal;
// vertex attribute: position
glVertexAttribPointer(0, 3, GL_FLOAT, GL_FALSE, sizeof(Vertex), (void *)0);
glEnableVertexAttribArray(∅);
// vertex attribute: normal
glVertexAttribPointer(1, 3, GL_FLOAT, GL_FALSE, sizeof(Vertex),
                                     (void *)(sizeof(glm::vec3)));
glEnableVertexAttribArray(1);
```

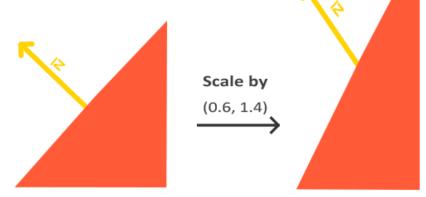
Vertex Shader - Uniform

```
// in vertex shader
uniform mat4 model;
uniform mat4 view;
uniform mat4 proj;
```

```
// in .cpp files
// generate perspective projection matrix.
glm::mat4 proj = glm::perspective(glm::radians(fov), aspect_ratio, near, far);
// define a identify model matrix for Stanford bunny.
glm::mat4 model_bunny;
int modelLoc = glGetUniformLocation(ourShader.ID, "model");
glUniformMatrix4fv(modelLoc, 1, GL_FALSE, glm::value_ptr(model_bunny));
... // same for View Matrix and Projection Matrix
// We have provide a class Shader, and you only need to call Shader::setMat4().
shader.setMat4("model", model_bunny);
```

Vertex Shader – Normal Transformation

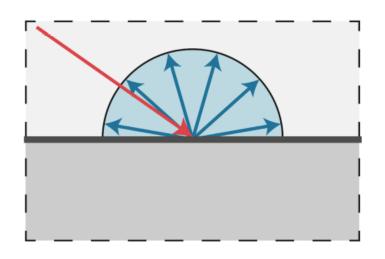
- Let normal vector be N and tangent vector be T.
- Suppose we calculate lighting in view space...
- After model view transformation M, T became T'.
- After transformation, correct normal should be N'. Let correct normal transformation matrix be G.
- $N' \cdot T' = (GN) \cdot (MT) = (GN)^T (MT) = N^T G^T MT$
- $N' \cdot T'$ and $N \cdot T$ should both be 0.
- So $G^T M = I, G = (M^{-1})^T$

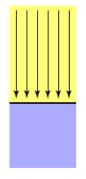


Vertex Shader

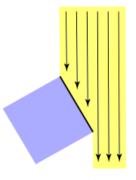
```
#version 330 core
layout (location = 0) in vec3 pos;
layout (location = 1) in vec3 normal;
uniform mat4 model;
uniform mat4 view;
uniform mat4 proj;
out vec3 frag normal;
void main() {
    gl_Position = proj * view * model * vec4(pos, 1.0);
    frag normal
       = vec3((transpose(inverse(view * model))) * vec4(normal, 0.0));
```

- Diffuse
 - color is the same for all viewing directions.
 - decided by angle between surface normal and light direction

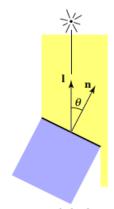




Top face of cube receives a certain amount of light

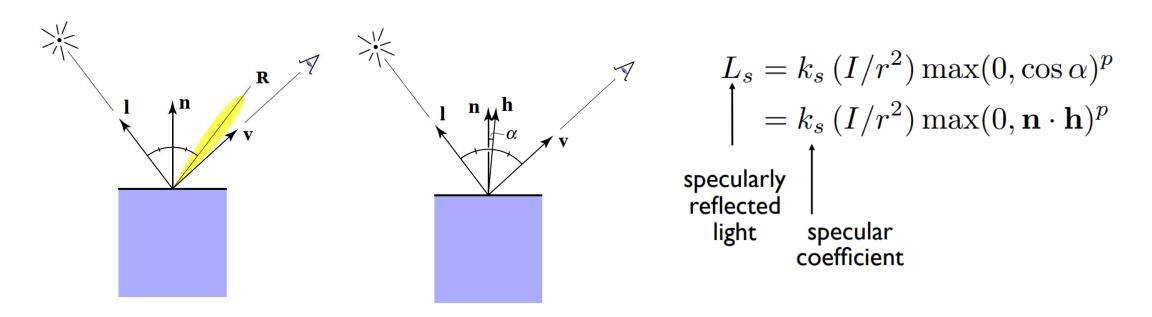


Top face of 60° rotated cube intercepts half the light

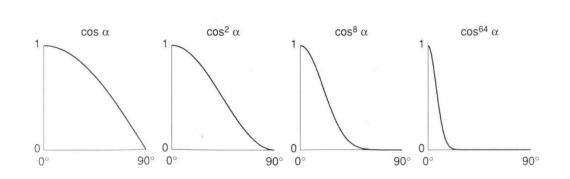


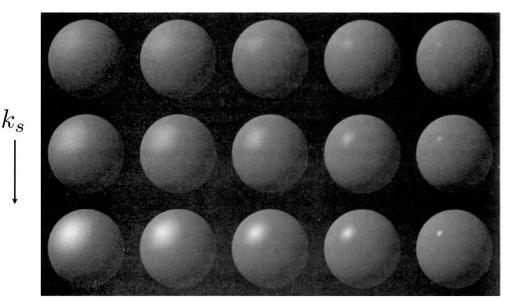
In general, light per unit area is proportional to $\cos \theta = 1 \cdot n$

- Specular
 - brighter near mirror reflection direction



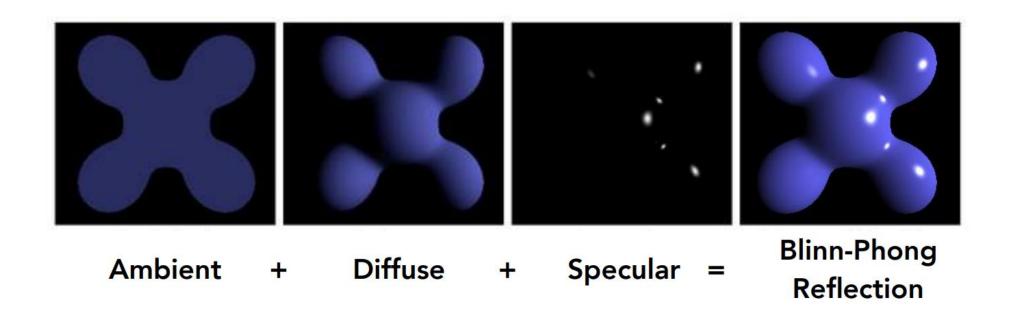
- Specular
 - brighter near mirror reflection direction





Note: showing Ld + Ls together

 $p \longrightarrow$

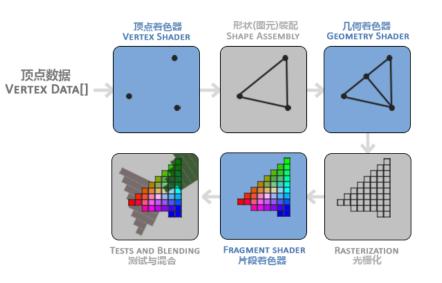


$$L = L_a + L_d + L_s$$

= $k_a I_a + k_d (I/r^2) \max(0, \mathbf{n} \cdot \mathbf{l}) + k_s (I/r^2) \max(0, \mathbf{n} \cdot \mathbf{h})^p$

Fragment Shader

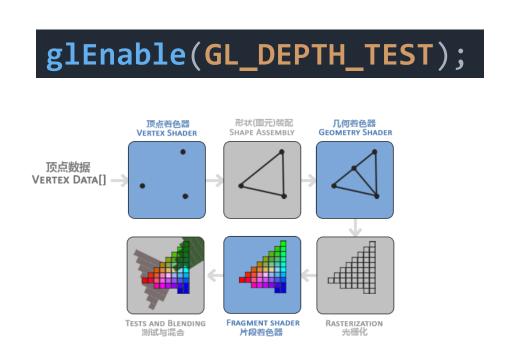
```
void main() {
    // ambient
   float ambientStrength = 0.1;
   vec3 ambient = ambientStrength * lightColor;
    // diffuse
   vec3 norm = normalize(Normal);
   vec3 lightDir = normalize(LightPos - FragPos);
   vec3 diffuse = max(dot(norm, lightDir), 0.0) * lightColor;
    // specular
   float specularStrength = 0.5;
   vec3 viewDir = normalize(-FragPos);
   vec3 reflectDir = reflect(-lightDir, norm);
   float spec = pow(max(dot(viewDir, reflectDir), 0.0), 32);
   vec3 specular = specularStrength * spec * lightColor;
   vec3 result = (ambient + diffuse + specular) * objectColor;
   FragColor = vec4(result, 1.0);
```



```
#version 330 core
out vec4 FragColor;
in vec3 FragPos;
in vec3 Normal;
in vec3 LightPos;
uniform vec3 lightColor;
uniform vec3 objectColor;
```

Last step – depth test and alpha blend

 Enable depth test to decide whether or not to draw current triangle.



Z-Buffer Visibility Tests



Reference & Supplementary material

- LearnOpenGL CN
 - https://learnopengl-cn.github.io/
- GAMES101-现代计算机图形学入门-闫令琪 Lec.4
 - https://www.bilibili.com/video/BV1X7411F744?p=4&share_source=copy _web&vd_source=26e548adcc52816031d5eccbe815724b
- Transformation in OpenGL
 - https://blog.xehoth.cc/CG/OpenGL/Transformation-OpenGL/
- Shader Toy
 - https://www.shadertoy.com/browse

Thank You

Have fun with homework1. Have a nice holiday...