

# MATH2621 — Higher Complex Analysis. VIII

## Properties of differentiable functions

# This lecture?

In this lecture, we look at more consequences of the Cauchy–Riemann equations.

## An example

The Cauchy Riemann equations enable us to define new complex functions and show that they are complex differentiable. For instance, recall the definition of the hyperbolic functions:

$$\cosh(x) = \frac{e^x + e^{-x}}{2} \quad \text{and} \quad \sinh(x) = \frac{e^x - e^{-x}}{2} \quad \forall x \in \mathbb{R}.$$

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Recall also that  $\cosh' = \sinh$  and  $\sinh' = \cosh$ , and that

$$\begin{aligned}\cosh(x + y) &= \cosh(x) \cosh(y) + \sinh(x) \sinh(y) \\ \sinh(x + y) &= \sinh(x) \cosh(y) + \cosh(x) \sinh(y).\end{aligned}$$

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We define two new functions of a complex variable as follows:

$$\begin{aligned}\operatorname{ch}(x + iy) &= \cosh(x) \cos(y) + i \sinh(x) \sin(y) \\ \operatorname{sh}(x + iy) &= \sinh(x) \cos(y) + i \cosh(x) \sin(y).\end{aligned}$$

## Exercise 1

Is  $\chi$  differentiable? What is its derivative? What about  $\psi$ ?

Answer.

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Is  $\operatorname{ch}$  differentiable? What is its derivative? What about  $\operatorname{sh}$ ?

Answer. Write  $\operatorname{ch}(x + iy) = u(x, y) + iv(x, y)$ . Then

$$u(x, y) = \cosh(x) \cos(y)$$

$$v(x, y) = \sinh(x) \sin(y)$$

$$u_x(x, y) = \sinh(x) \cos(y)$$

$$v_x(x, y) = \cosh(x) \sin(y)$$

$$u_y(x, y) = -\cosh(x) \sin(y)$$

$$v_y(x, y) = \sinh(x) \cos(y).$$

The partial derivatives are continuous and the Cauchy–Riemann equations hold in the open set  $\mathbb{C}$ , so  $\operatorname{ch}$  is differentiable in  $\mathbb{C}$ . Moreover,

$$\begin{aligned}\operatorname{ch}'(x + iy) &= \frac{\partial u}{\partial x}(x, y) + i \frac{\partial v}{\partial x}(x, y) \\ &= \sinh(x) \cos(y) + i \cosh(x) \sin(y),\end{aligned}$$

that is,  $\operatorname{ch}' = \operatorname{sh}$ .



## Exercise 2

Is  $\sinh$  differentiable? What is its derivative?

Answer.



## Exercise 2

Is  $\sin$  differentiable? What is its derivative?

Answer. You do this!



## Exercise 2

Is sh differentiable? What is its derivative?

Answer. You do this!



Recall that we defined  $\text{Log}(z) = \ln |z| + i \text{Arg}(z)$  for all  $z \in \mathbb{C} \setminus \{0\}$ .

## Exercise 3

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Answer. As usual, we may write

$$\text{Log}(x + iy) = u(x, y) + iv(x, y),$$

where  $u(x, y) = \ln(x^2 + y^2)^{1/2}$  and  $v(x, y) = \text{Arg}(x + iy)$ .

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Note that Log cannot be differentiable at 0 since it is not defined there, nor on the negative real axis  $(-\infty, 0)$ , as it is not continuous there.

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In  $\mathbb{C} \setminus (-\infty, 0]$ , which is open, we may apply the Cauchy–Riemann equations.

## Answer to Exercise 3

Observe that

$$\begin{aligned}\frac{\partial u(x, y)}{\partial x} &= \frac{1}{(x^2 + y^2)^{1/2}} \frac{1}{2(x^2 + y^2)^{1/2}} 2x = \frac{x}{x^2 + y^2}, \\ \frac{\partial u(x, y)}{\partial y} &= \frac{1}{(x^2 + y^2)^{1/2}} \frac{1}{2(x^2 + y^2)^{1/2}} 2y = \frac{y}{x^2 + y^2}.\end{aligned}$$

## Answer to Exercise 3 (continued)

In the right half-plane where  $x > 0$ , we may write

$\text{Arg}(x + iy) = \tan^{-1}(y/x)$ , and so

$$\begin{aligned}\frac{\partial v(x, y)}{\partial x} &= \frac{1}{1 + (y/x)^2} \frac{-y}{x^2} = \frac{-y}{x^2 + y^2}, \\ \frac{\partial v(x, y)}{\partial y} &= \frac{1}{1 + (y/x)^2} \frac{1}{x} = \frac{x}{x^2 + y^2}.\end{aligned}$$

In the upper half-plane where  $y > 0$ , we may write

$\text{Arg}(x + iy) = -\tan^{-1}(x/y) + \pi/2$ ; in the lower half plane where  $y < 0$ , we may write  $\text{Arg}(x + iy) = -\tan(x/y) - \pi/2$ . Two very similar calculations show that the same formulae hold for the partial derivatives in these cases too.



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Hence the partial derivatives are continuous and the Cauchy–Riemann equations hold in the open set  $\mathbb{C} \setminus (-\infty, 0]$ , and so  $\text{Log}$  is differentiable in this set.

## Answer to Exercise 3 (continued)

The derivative of Log is given by

$$\text{Log}'(x + iy) = \frac{\partial u(x, y)}{\partial x} + i \frac{\partial v(x, y)}{\partial x} = \frac{x - iy}{x^2 + y^2} = \frac{\bar{z}}{z\bar{z}} = \frac{1}{z}$$

in  $\mathbb{C} \setminus (-\infty, 0]$ .



## A topological question

If  $f$  is defined in an open set  $\Omega$ , and  $f$  is constant along all horizontal and vertical line segments contained in  $\Omega$ , must  $f$  be constant? It is easy to see that if  $\Omega$  is not polygonally path-connected, then  $f$  need not be constant. But what if  $\Omega$  is polygonally path-connected? Recall that a polygonally path-connected open subset of  $\mathbb{C}$  is called a domain.

# An answer

## Proposition

*Suppose that  $f$  is a function defined on a domain  $\Omega$  in  $\mathbb{C}$ , and  $f$  is constant along all horizontal and vertical line segments contained in  $\Omega$ . Then  $f$  is constant in  $\Omega$ .*

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Proof. Two distinct points of  $\Omega$  may always be connected by a polygonal path, involving finitely many line segments, so it will suffice to know that  $f$  is constant along line segments.

Take a line segment  $\ell$ , with endpoints  $z_0$  and  $z_1$ , and write  $z_t = (1 - t)z_0 + tz_1$ , where  $t \in [0, 1]$ . Then  $z_t$  moves along the line segment  $\ell$  from  $z_0$  to  $z_1$  as  $t$  varies between 0 and 1.

# Proof

Suppose that  $z \in \Omega$  and  $z$  lies on  $\ell$ . Since  $\Omega$  is open, there is a ball  $B(z, \varepsilon)$  contained in  $\Omega$ . We claim that  $f$  is constant on  $B(z, \varepsilon) \cap \ell$ .

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Indeed, by elementary geometry, if  $z' \in B(z, \varepsilon) \cap \ell$ , then the line segments joining  $x + iy$  and  $x' + iy$  and joining  $x' + iy$  and  $x' + iy'$  both lie inside  $B(z, \varepsilon)$  and hence in  $\Omega$ . By hypothesis,  $f$  is constant along both these segments, and so  $f(z) = f(z')$ , and our claim is proved.



## Proof (continued)

To show that  $f$  is constant along the whole line segment  $\ell$ , we argue by contradiction.

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Since  $f$  is not constant, the set is not empty, and  $0 \leq t^* \leq 1$ .

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Since  $f$  is not constant, the set is not empty, and  $0 \leq t^* \leq 1$ . But  $f$  is constant on  $B(z_{t^*}, \varepsilon_{t^*}) \cap \ell$  for some positive  $\varepsilon_{t^*}$ , so  $f$  is constant near  $t^*$ , contradicting the definition of  $t^*$ , and showing that  $f$  is constant on  $\ell$ . □

# Consequences of the Cauchy–Riemann equations

## Theorem

*Suppose that  $f$  is differentiable in a domain  $\Omega$  in  $\mathbb{C}$ . Then*

- (a) if  $f' = 0$  in  $\Omega$ , then  $f$  is constant on  $\Omega$ ;*
- (b) if  $|f|$  is constant, then  $f$  is constant on  $\Omega$ ;*
- (c) if  $\operatorname{Re}(f)$  or  $\operatorname{Im}(f)$  is constant, then  $f$  is constant on  $\Omega$ .*

**Proof.** As usual, write  $f(x + iy) = u(x, y) + iv(x, y)$ .

First, suppose that  $f' = 0$ . Then  $\partial u/\partial x$ ,  $\partial u/\partial y$ ,  $\partial v/\partial x$ , and  $\partial v/\partial y$  are all 0. By the proposition,  $f$  is constant.

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Next, suppose that  $|f|$  is a constant,  $C$  say, in  $\Omega$ . If  $C = 0$ , then  $f = 0$ , a constant, so without loss of generality we may suppose that  $C \neq 0$ .

## Proof of theorem

Then

$$u^2 + v^2 = C^2 > 0. \quad (1)$$

Differentiating (1) with respect to  $x$  and with respect to  $y$  gives

$$2u \frac{\partial u}{\partial x} + 2v \frac{\partial v}{\partial x} = 0 \quad (2)$$

$$2u \frac{\partial u}{\partial y} + 2v \frac{\partial v}{\partial y} = 0. \quad (3)$$

Using the Cauchy–Riemann equations with (3), we get

$$2v \frac{\partial u}{\partial x} - 2u \frac{\partial v}{\partial x} = 0. \quad (4)$$

Eliminating  $\frac{\partial v}{\partial x}$  from (2) and (4) shows that  $2(u^2 + v^2) \frac{\partial u}{\partial x} = 0$ .

From (1),  $\frac{\partial u}{\partial x} = 0$ . Similarly,  $\frac{\partial v}{\partial x} = 0$ , so  $f' = 0$ , and  $f$  is constant.

## Proof of theorem (continued)

Suppose now that  $\operatorname{Re}(f)$  is constant. Then  $\partial u/\partial x = \partial u/\partial y = 0$ , so from the Cauchy–Riemann equations,  $\partial v/\partial x = \partial v/\partial y = 0$ , whence  $f' = 0$  and  $f$  is constant.

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The argument if  $\operatorname{Im}(f)$  is constant is similar. □



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The argument if  $\operatorname{Im}(f)$  is constant is similar. □

In fact, it is possible to show that if  $f$  is complex differentiable in a polygonally path-connected open set  $\Omega$ , then either  $f$  is constant or  $\operatorname{Range}(f)$  is open, which means that  $f$  cannot satisfy any equations that restrict its range to lie in a one-dimensional set, such as a curve.

# The Cauchy–Riemann equations in polar coordinates

## Theorem

*Suppose that the complex function  $f$  is differentiable at the point  $z_0 \in \mathbb{C} \setminus \{0\}$ , and that  $z_0 = r_0 e^{i\theta_0}$ . Then*

$$\frac{\partial u}{\partial \theta}(r_0, \theta_0) = -r_0 \frac{\partial v}{\partial r}(r_0, \theta_0) \quad \text{and} \quad \frac{\partial v}{\partial \theta}(r_0, \theta_0) = r_0 \frac{\partial u}{\partial r}(r_0, \theta_0).$$

*Further,*

$$\begin{aligned} f'(z_0) &= e^{-i\theta_0} \left( \frac{\partial u}{\partial r}(r_0, \theta_0) + i \frac{\partial v}{\partial r}(r_0, \theta_0) \right) \\ &= \frac{-ie^{-i\theta_0}}{r} \left( \frac{\partial u}{\partial \theta}(r_0, \theta_0) + i \frac{\partial v}{\partial \theta}(r_0, \theta_0) \right). \end{aligned}$$

*Conversely, if  $f$  is defined on a ball  $B = B(z_0, \epsilon)$  with  $z_0 \in \mathbb{C} \setminus \{0\}$  such that the the four partial derivatives of above exist on  $B$ , are continuous at  $z_0$  and satisfy the two equation of above at  $z_0$ , then  $f$  is differentiable at  $z_0$ .*

# A corollary

## Corollary

*The function  $\text{Log}$  is differentiable in  $\mathbb{C} \setminus (-\infty, 0]$ .*

**Proof.** Write  $\text{Log}(re^{i\theta})$  in the form  $u(r, \theta) + iv(r, \theta)$ . Then  $u(r, \theta) = \ln(r)$  and  $v(r, \theta) = \theta$ . Hence

$$\begin{aligned}\frac{\partial u}{\partial r}(r_0, \theta_0) &= \frac{1}{r_0} & \frac{\partial u}{\partial \theta}(r_0, \theta_0) &= 0 \\ \frac{\partial v}{\partial r}(r_0, \theta_0) &= 0 & \frac{\partial v}{\partial \theta}(r_0, \theta_0) &= 1.\end{aligned}$$

Clearly, the polar form of the Cauchy–Riemann equations is satisfied. Further, the partial derivatives are continuous in the open set  $\mathbb{C} \setminus (-\infty, 0]$ , so  $\text{Log}$  is differentiable in this set.  $\square$

## Inverse functions

Suppose that  $\Omega$  and  $\Upsilon$  are open subsets of  $\mathbb{C}$ , and that  $f$  is one-to-one from  $\Omega$  onto  $\Upsilon$ . Then  $f$  has an inverse function, usually written  $f^{-1}$ , from  $\Upsilon$  to  $\Omega$ : we define  $f^{-1}(w) = z$  if  $f(z) = w$ .

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*Suppose that  $\Omega$  and  $\Upsilon$  are open subsets of  $\mathbb{C}$ , that  $f : \Omega \rightarrow \Upsilon$  is one-to-one, and that  $f(z_0) = w_0$ . If  $f$  is differentiable at  $z_0$  and  $f^{-1}$  is differentiable at  $w_0$ , then  $(f^{-1})'(w_0) = 1/f'(z_0)$ .*

Proof.

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and the desired result follows. □

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Later, we will investigate whether the inverse function is differentiable.

# Definition

The examples and theorems above show that functions that are complex differentiable in an open set have special properties; we are going to study them in much greater detail. This justifies giving them a name.

## Definition

Suppose that  $\Omega$  is an open subset of  $\mathbb{C}$  and  $f : \Omega \rightarrow \mathbb{C}$  is a function. If  $f$  is differentiable in  $\Omega$ , that is, if it is differentiable at every point of  $\Omega$ , then we say that  $f$  is *holomorphic* or *(complex) analytic* or *regular* in  $\Omega$ , and we write  $f \in H(\Omega)$ .

If  $\Omega = \mathbb{C}$  and  $f$  is differentiable in  $\Omega$ , then we say that  $f$  is *entire*.