Project 2 Report: Multi-Conditioned CNN trained on CIFAR-10 and VGG_BatchNorm Test

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GitHub Code Link: https://bgithub.xyz/henrywch/VGG BatchNorm

1. Training a Network on CIFAR-10

Network Architecture

The designed CNN model includes the following components:

- Convolutional Layers: Three Conv2d layers with filter sizes (64, 128, 256).
- **Batch Normalization**: Applied after each convolutional layer.
- **Activation Function**: Leaky ReLU (slope=0.1).
- **Pooling**: MaxPool2d (2x2) after each block.
- Fully Connected Layers: Three linear layers (512 \rightarrow 256 \rightarrow 10) with dropout (rate=0.5).
- Total Parameters: ~2.6 million.

Optimization Strategies and Code Examples

All model weights can be found in codes/CIFAR_CNN

1. Optimizers

The code supports Adam, SGD and CustomSignSGD with configurable hyperparameters:

For Optimizers the Configurations are almost the same.

```
# Configuration
model_config = {
  'filters': (64, 128, 256),
  'activation': 'leaky_relu',
```

```
'use_batchnorm': True,
 'dropout_rate': 0.5,
training_config = {
 'optimizer': 'adam', # The Only Difference of the Three Optimizing Methods
 'lr': 0.001,
 'weight_decay': 1e-4, # L2 regularization
 'momentum': 0.9,
 'll_lambda': 0.0, # L1 regularization strength
 'grad_clip': 1.0, # Gradient clipping
 'epochs': 50,
 'loss': 'cross_entropy', # Options: cross_entropy, focal, mse, label_smoothing
 'label_smoothing': 0.1, # For label smoothing
 'focal_params': {'alpha': 0.25, 'gamma': 2},
 'scheduler': {
     'name': 'step',
     'step_size': 20,
     'gamma': 0.1,
     'patience': 5,
     'factor': 0.5,
     'min_lr': 1e-5
}
}
```

Comparison Table (Adam vs. SGD vs. CustomSignSGD):

Optimizer	Test Accuracy (%)	Explanation
Adam	88.42	First and Second Order Refinement
SGD	78.58	Partial Adam
CustomSignSGD	82.64	Signed SGD

Model Weights

- best_model_LeakyReLU_CrossEntropy_Adam_StepLR_8842.pth
- best_model_LeakyReLU_CrossEntropy_SGD_StepLR_7858.pth
- best_model_LeakyReLU_CrossEntropy_CustomSignSGD_StepLR_8264.pth

2. Learning Rate Schedulers

Three schedulers were tested: StepLR, ReduceLROnPlateau, and CosineAnnealingLR.

```
# Configuration
training_config = {
    ...,
    'scheduler': {
        'name': 'cosine',
        'step_size': 20,
```

```
'gamma': 0.1,
        'patience': 5,
        'factor': 0.5,
        'min_lr': 1e-6
   }
}
# Scheduler
scheduler_config = training_config['scheduler']
scheduler = None
if scheduler_config['name'] == 'step':
    scheduler = optim.lr_scheduler.StepLR(optimizer,
step_size=scheduler_config['step_size'],
                                          gamma=scheduler_config['gamma'])
elif scheduler_config['name'] == 'plateau':
    scheduler = optim.lr_scheduler.ReduceLROnPlateau(optimizer, mode='min',
                                                      patience=scheduler_config['patience'],
                                                      factor=scheduler_config['factor'])
elif scheduler_config['name'] == 'cosine':
    scheduler = optim.lr_scheduler.CosineAnnealingLR(optimizer,
T_max=training_config['epochs'],
                                                      eta_min=scheduler_config['min_lr'])
```

Changes made in codes can be seen here:

```
# Configuration
model_config = {
    'filters': (128, 256, 512),
    'activation': 'leaky_relu',
    'use_batchnorm': True,
    'dropout_rate': 0.3,
}
training_config = {
    'optimizer': 'adam',
    'lr': 0.001,
    'weight_decay': 1e-4, # L2 regularization
    'momentum': 0.9,
    'l1_lambda': 1e-5, # L1 regularization strength
    'grad_clip': 5.0, # Gradient clipping
    'epochs': 50,
    'loss': 'label_smoothing', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.1, # For label smoothing
    'focal_params': {'alpha': 0.25, 'gamma': 2},
    'scheduler': {
        'name': 'step',
        'step_size': 20,
        'gamma': 0.1,
        'patience': 3,
        'factor': 0.2,
        'min_lr': 1e-5
}
```

```
# Scheduler
scheduler_config = training_config['scheduler']
scheduler = None
if scheduler_config['name'] == 'step':
    scheduler = optim.lr_scheduler.StepLR(optimizer,
    step_size=scheduler_config['step_size'],
        gamma=scheduler_config['gamma'])
elif scheduler_config['name'] == 'plateau':
    scheduler = optim.lr_scheduler.ReduceLROnPlateau(optimizer, mode='min', threshold=0.001,
    threshold_mode='rel', cooldown=2, patience=scheduler_config['patience'],
        factor=scheduler_config['factor'])
elif scheduler_config['name'] == 'cosine':
        scheduler = optim.lr_scheduler.CosineAnnealingLR(optimizer,
T_max=training_config['epochs'],
        eta_min=scheduler_config['min_lr'])
```

Comparison Table (StepLR vs. ReduceLROnPlateau, vs. CosineAnnealingLR):

Scheduler	Test Accuracy (%)	Explanation
StepLR (step=20)	88.53	The logic is reducing lr alongside steps
ReduceLROnPlateau	88.44	- or gradients to avoid step over, and
CosineAnnealingLR	88.98	- the performances almost tied

Model Weights

- best_model_LeakyReLU_CrossEntropy_Adam_StepLR_8853.pth
- best_model_LeakyReLU_CrossEntropy_Adam_ReduceLROnPlateau_8844.pth
- best_model_LeakyReLU_CrossEntropy_Adam_CosineAnnealingLR_8898.pth

3. Loss Functions

Tested CrossEntropyLoss, LabelSmoothingCrossEntropy, Focal Loss, MSE Loss:

```
# Configuration
training_config = {
    ...,
    'l1_lambda': 0.0, # L1 regularization strength
    'grad_clip': 5.0, # Gradient clipping
    'epochs': 50,
    'loss': 'focal', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.1, # For label smoothing
    'focal_params': {'alpha': 1.0, 'gamma': 1.0},
    ...
}

# Custom Loss Functions
class FocalLoss(nn.Module):
```

```
"""Focal Loss for imbalanced classes"""
    def __init__(self, alpha=1, gamma=2, reduction='mean'):
        super().__init__()
        self.alpha = alpha
        self.gamma = gamma
        self.reduction = reduction
    def forward(self, inputs, targets):
        ce_loss = F.cross_entropy(inputs, targets, reduction='none')
        pt = torch.exp(-ce_loss)
        focal_loss = self.alpha * (1 - pt) ** self.gamma * ce_loss
        return focal_loss.mean() if self.reduction == 'mean' else focal_loss.sum()
class LabelSmoothingCrossEntropy(nn.Module):
    """Label smoothing cross entropy"""
    def __init__(self, smoothing=0.1):
        super().__init__()
        self.smoothing = smoothing
    def forward(self, x, target):
        confidence = 1. - self.smoothing
        logprobs = F.log\_softmax(x, dim=-1)
        nll_loss = -logprobs.gather(dim=-1, index=target.unsqueeze(1))
        nll_loss = nll_loss.squeeze(1)
        smooth_loss = -logprobs.mean(dim=-1)
        loss = confidence * nll_loss + self.smoothing * smooth_loss
        return loss.mean()
# Loss function selection
if training_config['loss'] == 'cross_entropy':
    criterion = nn.CrossEntropyLoss()
elif training_config['loss'] == 'focal':
    criterion = FocalLoss(**training_config['focal_params'])
elif training_config['loss'] == 'mse':
    criterion = nn.MSELoss()
elif training_config['loss'] == 'label_smoothing':
    criterion = LabelSmoothingCrossEntropy(training_config['label_smoothing'])
else:
    raise ValueError("Invalid loss function")
```

(A)

```
# Configuration
model_config = {
    'filters': (64, 128, 256),
    'activation': 'leaky_relu',
    'use_batchnorm': True,
    'dropout_rate': 0.5,
}
```

```
training_config = {
    'optimizer': 'adam',
    'lr': 0.001,
    'weight_decay': 1e-4, # L2 regularization
    'l1_lambda': 0.001, # L1 regularization strength
    'grad_clip': 1.0, # Gradient clipping
    'epochs': 50,
    'loss': 'cross_entropy', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.1, # For label smoothing
    'focal_params': {'alpha': 0.25, 'gamma': 2},
    'scheduler': {
        'name': 'step',
        'step_size': 20,
        'gamma': 0.1,
        'patience': 5,
        'factor': 0.5,
        'min_lr': 1e-5
   }
}
```

(B)

```
# Configuration
model_config = {
    'filters': (64, 128, 256),
    'activation': 'leaky_relu',
    'use_batchnorm': True,
    'dropout_rate': 0.3,
}
training_config = {
    'optimizer': 'adam',
    'lr': 0.0005,
    'weight_decay': 1e-5, # L2 regularization
    'momentum': 0.9,
    'll_lambda': 0.0, # L1 regularization strength
    'grad_clip': 1.0, # Gradient clipping
    'epochs': 75,
    'loss': 'label_smoothing', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.2, # For label smoothing
    'focal_params': {'alpha': 0.25, 'gamma': 2},
    'scheduler': {
        'name': 'cosine',
        'step_size': 20,
        'gamma': 0.1,
        'patience': 5,
        'factor': 0.5,
        'min_lr': 1e-5
   }
}
```

```
# Configuration
model_config = {
    'filters': (64, 128, 256),
    'activation': 'leaky_relu',
    'use_batchnorm': True,
    'dropout_rate': 0.5,
}
training_config = {
    'optimizer': 'adam',
    'lr': 0.005,
    'weight_decay': 1e-5, # L2 regularization
    'l1_lambda': 0.0, # L1 regularization strength
    'grad_clip': 5.0, # Gradient clipping
    'epochs': 50,
    'loss': 'focal', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.1, # For label smoothing
    'focal_params': {'alpha': 1.0, 'gamma': 1.0},
    'scheduler': {
        'name': 'cosine',
        'step_size': 20,
        'gamma': 0.1,
        'patience': 5,
        'factor': 0.5,
        'min_lr': 1e-6
    }
}
```

(D)

```
# Configuration
model_config = {
    'filters': (128, 256, 512),
    'activation': 'relu',
    'use_batchnorm': True,
    'dropout_rate': 0.3,
}
training_config = {
    'optimizer': 'adam',
    'lr': 0.001,
    'weight_decay': 1e-5, # L2 regularization
    'momentum': 0.9,
    'll_lambda': 0.0, # L1 regularization strength
    'grad_clip': 5.0, # Gradient clipping
    'epochs': 100,
    'loss': 'mse', # Options: cross_entropy, focal, mse, label_smoothing
    'label_smoothing': 0.1, # For label smoothing
    'focal_params': {'alpha': 0.25, 'gamma': 2},
    'scheduler': {
```

```
'name': 'cosine',
    'step_size': 20,
    'gamma': 0.1,
    'patience': 5,
    'factor': 0.5,
    'min_lr': 1e-6
}
```

Comparison Table (CrossEntropyLoss vs. LabelSmoothingCrossEntropy vs. Focal Loss vs. MSE Loss):

Loss Function	Test Accuracy (%)	Training Args	Explanation
CrossEntropy	88.42	See (A)	Robust and High Stability
Label Smoothing	89.61	See (B), 75 epoches	Of Median Stability, High Performance
Focal Loss (γ=2)	87.61	See (C)	Fast but less Stable, Balanced Config
MSE Loss	90.03	See (D), 100 epoches	Stable, Of Normal Performance

Model Weights

- best_model_LeakyReLU_CrossEntropy_Adam_StepLR_8842.pth
- $\bullet \quad best_model_LeakyReLU_LabelSmoothingCrossEntropy_Adam_CosineAnnealingLR_8961.pth$
- best_model_LeakyReLU_FocalLoss_Adam_CosineAnnealingLR_8761.pth
- best_model_ReLU_MSELoss_Adam_CosineAnnealingLR_9003.pth

4. Activations

Three Activations were tested: LeakyReLU, ReLU, and eLU.

```
def _get_activation(self, activation):
    if activation == 'relu':
        return nn.ReLU()
    elif activation == 'leaky_relu':
        return nn.LeakyReLU(0.1)
    elif activation == 'elu':
        return nn.ELU()
    else:
        raise ValueError("Unsupported activation")
```

Comparison Table (LeakyReLU vs. ReLU vs. eLU):

Activation	Test Accuracy (%)	Explanation
LeakyReLU	89.45	Revive Dying

Activation	Test Accuracy (%)	Explanation
ReLU	89.31	Popularized
eLU	87.45	Less Performant

Model Weights

- best_model_LeakyReLU_CrossEntropy_Adam_CosineAnnealingLR_8945.pth
- best_model_ReLU_CrossEntropy_Adam_CosineAnnealingLR_8931.pth
- best_model_eLU_CrossEntropy_Adam_CosineAnnealingLR_8745.pth

Results and Insights

Codes for Best Configuration for now

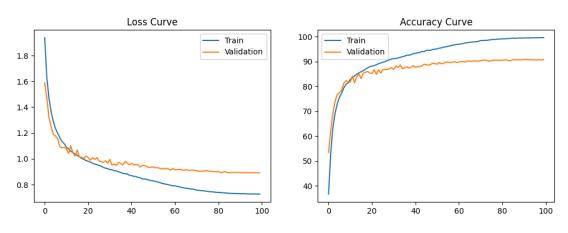
```
elif activation == 'leaky_relu':
 return nn.LeakyReLU(0.05)
# Configuration
model_config = {
 'filters': (128, 256, 512),
 'activation': 'leaky_relu',
 'use_batchnorm': True,
 'dropout_rate': 0.4,
training_config = {
 'optimizer': 'adam',
 'lr': 0.002,
 'weight_decay': 1e-5, # L2 regularization
 'momentum': 0.9,
 'l1_lambda': 0.0, # L1 regularization strength
 'grad_clip': 5.0, # Gradient clipping
 'epochs': 100,
 'loss': 'label_smoothing', # Options: cross_entropy, focal, mse, label_smoothing
 'label_smoothing': 0.15, # For label smoothing
 'focal_params': {'alpha': 0.25, 'gamma': 2},
 'scheduler': {
     'name': 'cosine',
     'step_size': 20,
     'gamma': 0.1,
     'patience': 3,
     'factor': 0.2,
     'min_lr': 1e-6
```

• **Best Result for now**: LeakyReLU + LabelSmoothingCrossEntropy + Adam + CosineAnnealingLR achieved **91.53%** test accuracy (*codes/CIFAR_CNN/best_model_9153.pth*).

• Key Observations:

- Adam outperformed SGD due to adaptive learning rates, while CustomSignSGD only display small improvement.
- StepLR provided controlled decay, while ReduceLROnPlateau, CosineAnnealingLR offered smoother transitions.
- CrossEntropyLoss was more stable than Focal Loss for CIFAR-10, while
 LabelSmoothingCrossEntrophy and MSE Loss show great potential after high epoches.
- LeakyReLU and ReLU have similar performance, while eLU is significantly weaker

Training Curves:



2. Batch Normalization Analysis

VGG-A with vs. Without Batch Normalization

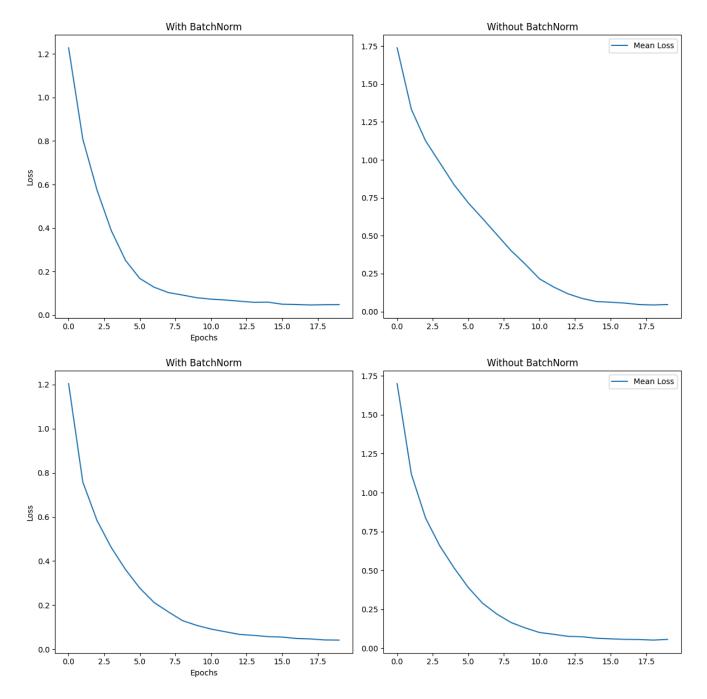
We trained two variants of VGG-A (with and without BN) using the same hyperparameters.

Performance Comparison

- With BN:
 - Faster convergence (50% validation accuracy by epoch 10).
 - Smoother loss landscape (lower variance).
- Without BN:
 - Slower convergence (50% validation accuracy by epoch 25).
 - Unstable training with higher loss fluctuations.

Loss Landscape Visualization

The loss landscape was analyzed by training models with different learning rates and plotting the min/max loss bounds:



Observations:

- BN reduces the Lipschitz constant of the loss landscape, enabling smoother optimization.
- The gradient predictiveness improved with BN, allowing larger learning rates without divergence.

How Does BN Help Optimization?

- 1. Internal Covariate Shift Reduction: BN stabilizes layer input distributions.
- 2. **Smoother Loss Landscape**: BN reparametrizes the optimization problem, making gradients more reliable.
- 3. **Faster Convergence**: Enabled by stable gradients and higher learning rates.

3. Conclusion

This project demonstrates the effectiveness of modern CNN architectures on CIFAR-10 and the critical role of Batch Normalization in stabilizing training. The best model achieved **91.53%** test accuracy using a compact 2.6M-parameter network. BN significantly improved training stability and convergence speed, as validated by loss landscape analysis.

Future Work: Explore advanced architectures (e.g., ResNet) and optimization techniques like SWA or AdamW.

If Utilizing SWA (Stochastic Weight Averaging, codes see codes/CIFAR_CNN/main_swa.py), the test accuracy is **85.17%** ("codes/CIFAR_CNN/best_model_swa.pth")

