# **Artificial Life Summer 2025**

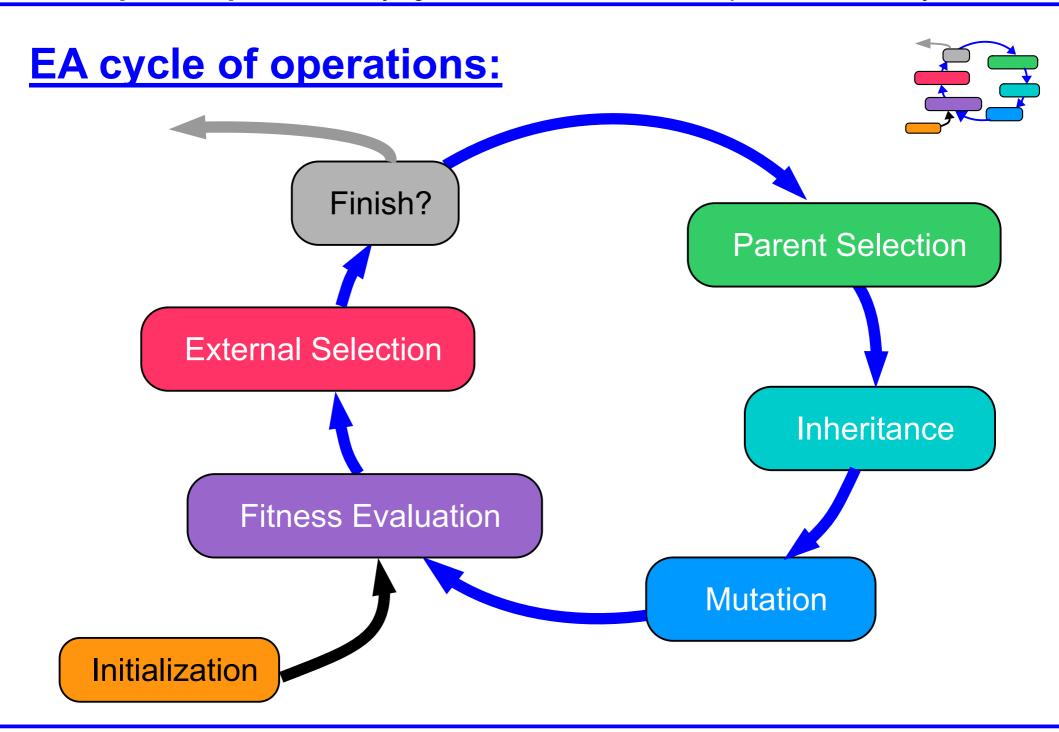
# **Evolutionary Algorithms 3**

Master Computer Science [MA-INF 4201] Mon 14:15 – 15:45, HSZ, HS-2

Dr. Nils Goerke, Autonomous Intelligent Systems, Department of Computer Science, University of Bonn

# **Overview:**

- Genome structure
- Example: 8 queens
- Super-individuals
- External-selection and parent-selection combined
- Probabilistic parent-selection
  - Wheel of fortune
  - Softmax selection
  - Tournament selection
- Genetic programming
- Co-evolution



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Naive structuring of the genome:

"Normal" structuring of the genome:

**Sophisticated structuring** of the genome:



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Pro: easy to implement, only few knowledge necessary.

Con: large search space, a lot of local maxima possible, may be hard or impossible to find a good solution.

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**Sophisticated structuring** of the genome:



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#### "Normal" structuring of the genome:

Pro: still easy to implement, some knowledge necessary, wide variety to implement inheritance and mutation.

Con: still a lot of bad or illegal genomes possible.

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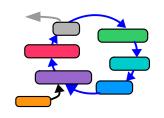
Pro: still easy to implement, some knowledge necessary, wide variety to implement inheritance and mutation.

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# Sophisticated structuring of the genome:

Pro: only legal, or good genomes are to be investigated.

Con: profound knowledge about the process and of the kind of possible solutions is required, can become computational expensive to implement inheritance and mutation.



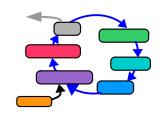
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find the shortest route visiting each point from a set of given points (cities) exactly once (Traveling Salesman Problem).

#### **Genome:**

#### **Fitness Function:**





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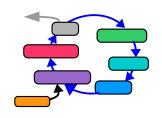
#### **Genome:**

an ordered set of points (cities, C<sub>i</sub>), sequence of cities to be visited, containing each city exactly once.

$$\mathbf{g} = \{ C_3, C_{17}, C_i, C_{42}, ... \}$$

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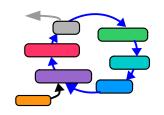
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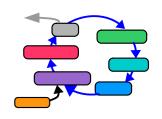
f(g) is the sum of all distances  $d(C_i, C_{i+1})$  between subsequent cities in the list (genome). Of course all distances  $d(C_i, C_j)$  between the cities i and j is required; either by a distance matrix or by a calculation from the coordinates.



# **Easy Inheritance:**

#### **Mutation:**



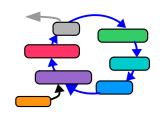


#### **Easy Inheritance:**

Since a classical cross over will generate illegal genomes the k=1, copy operator, omitting recombination is O.K.

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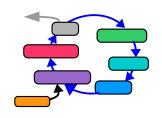
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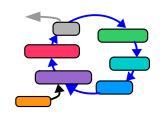
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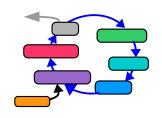
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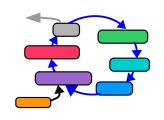
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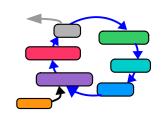
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# **Sophisticated Inheritance:**

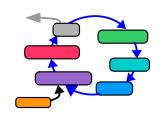
A more sophisticated inheritance operator would have to guarantee that the offspring still represent legal genomes,

- routes that visit each city exactly once - .

This may cause high computational effort, which might be larger than the potential benefit.

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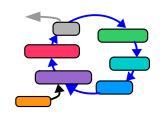
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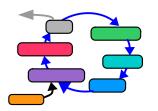
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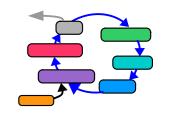
How do you know?

Either by theory (if available), or by a heuristics.





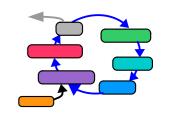




The 8 queens puzzle with an evolutionary algorithm:

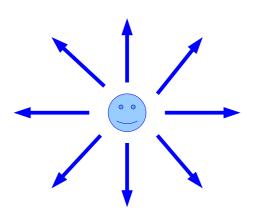
The task of the 8 queens puzzle is to place 8 queens on a chess board (8x8) so that they can not reach each other.



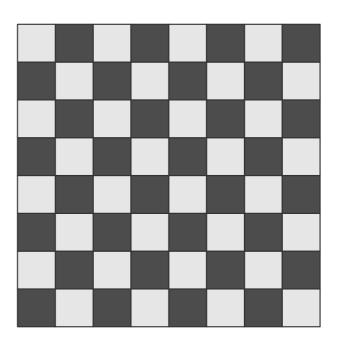


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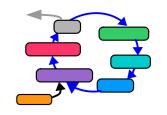


allowed moves for a queen



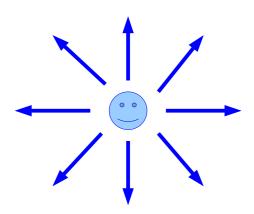
chess board with 8x8 = 64 positions



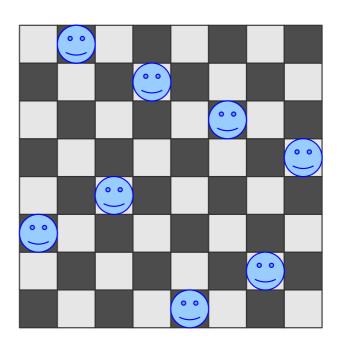


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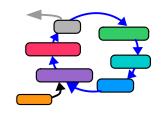
allowed moves for a queen



One of the **92** solutions

chess board with 8x8 = 64 positions





# Very naive implementation of the genome:

a 64 bit binary vector; queen is 1, no queen is 0; more than 8 queens are possible.

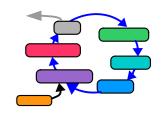
This very naive implementation is generating an extremely large search space with 2^64 possible genomes. This is beyond any computing power to be investigated in total.

# Semi naive implementation of the genome:

a 64 bit binary vector; queen is 1, no queen is 0; exactly 8 queens == 8 bits set are possible.

Still the resulting search space is very large.





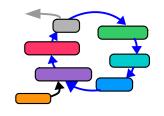
Normal/Sophisticated implementation of the genome:

8 rows of 8 bit binary vectors; queen is 1, no queen is 0; each row contains exactly one queen.

This is reducing the search space to  $8^8 = 16777216$  possibilities, (which can be managed by brute-force).





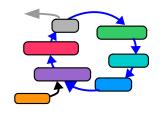


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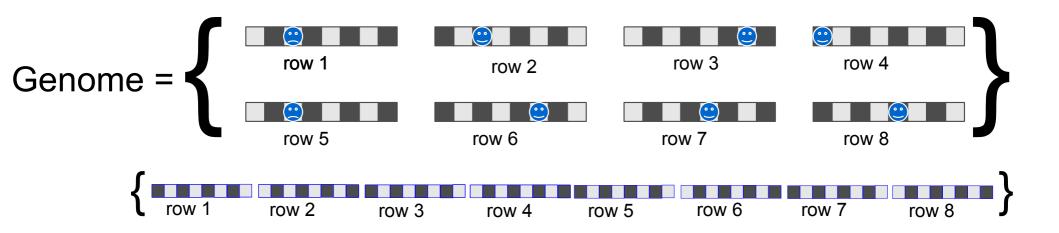




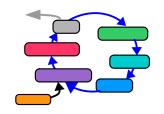
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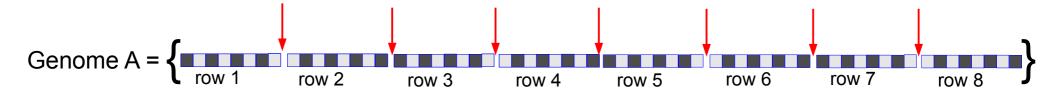
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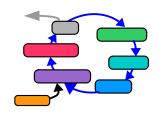




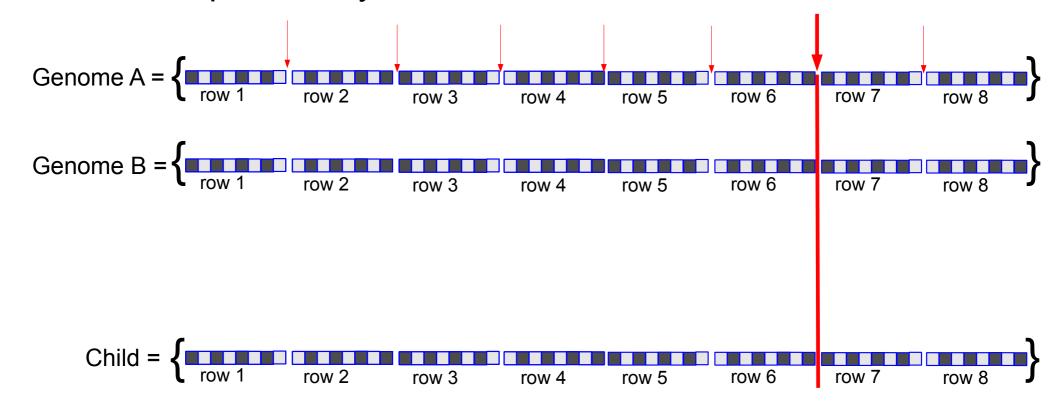
Inheritance, recombination, 1 point cross over cross-over points only between the rows



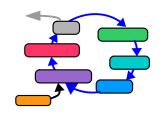




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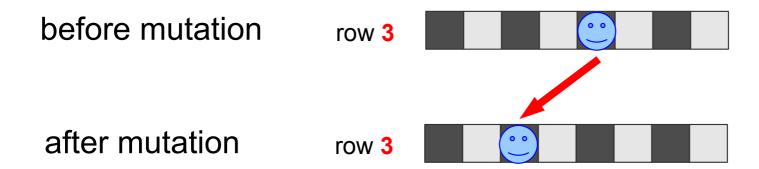




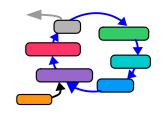


Mutation only the position of the queen within the row is altered

Chose a random row  $\mathbf{r}$  (1, ..., 8): and pick a new random position (1, ..., 8) for the queen







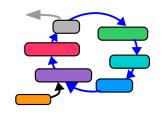
A more sophisticated implementation of the genome:

If you have an even more sophisticated idea for structuring the genome, don't forget to shape the inheritance and mutation operators and the fitness function accordingly.

Go ahead,

feel free to do experiments





The objective, is to find a placement of the 8 queens so that they can't reach each other.

The fitness function for the EA should reflect this:

a large value of f if the placement is o.k.

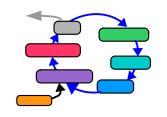
a small value of f if the placement is not o.k.

A fitness function that yields a binary value (O,I) is not a good idea for an evolutionary algorithm.

The resulting fitness surface is flat (O), with only a few isolated peeks (I).

The value of this kind of fitness function is not reflecting, that a genome can be close to a possible solution.





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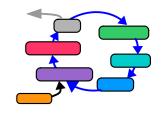
An appropriate fitness function for an EA must be shaped accordingly;

In addition, the fitness function **f** value should implement, that genomes **g**, close to an optimal solution should yield a larger fitness value **f**(**g**) than those far away.

The optimal would be, to have a fitness function f(g) that is proportional to the distance between the genome g to an optimal genome g\*.

Unfortunately this is not possible in general.





The objective, is to find a placement of the 8 queens so that they can't reach each other.

A proposal for a fitness function for the 8 queens problem:

Each possibilty that one queen can attack another queen is counted as -1

The fitness value f(g) is the sum of all attack possibilities.

This yields a graded response as required, with a maximal value  $f(g^*) = 0.0$  when no attack is possible.

#### **Caution:**

This fitness function is only appropriate if the number of queens is fixed to 8 (0 queens => 0 attack possibilities)



### **Example:**

Implementing a task using an Evolutionary Algorithm, a series of structuring decision will be necessary.

The sequence below is not common theory, but just my personal choice of doing it.

Objective: specify the objective

Genome: structure the genome

Fitness Function: define an appropriate fitness function

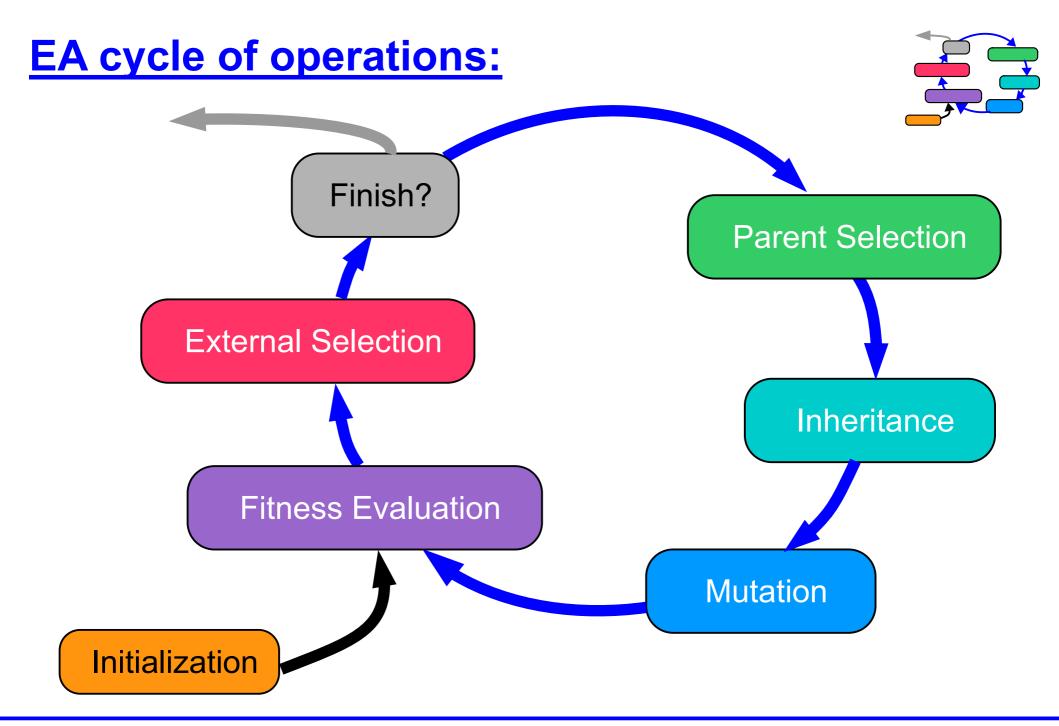
Inheritance: layout the inheritance process

Mutation: layout the mutation process

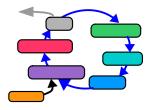
Selection Strategy: specify the selection strategy

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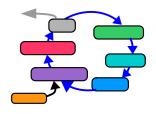
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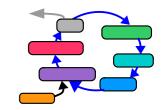
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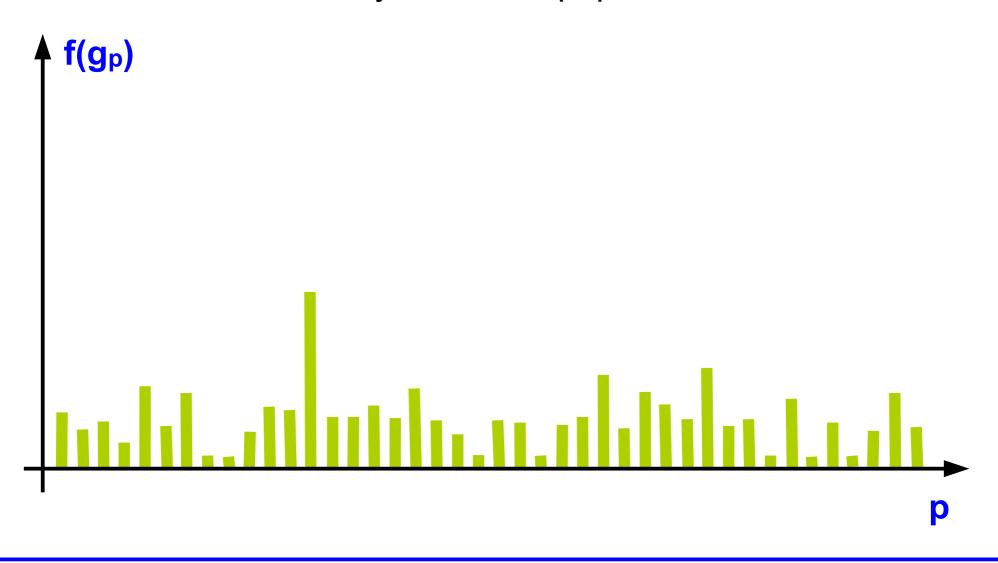
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The fitness values throughout the population will typically vary.



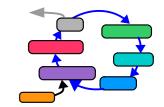


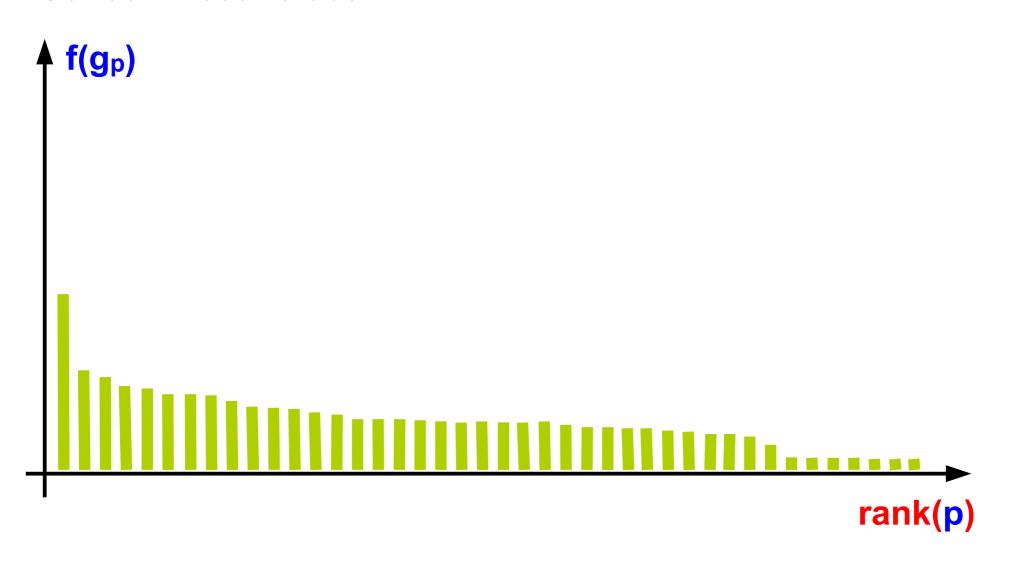
Fitness values will vary within the population.



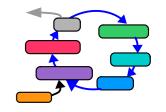
# EA:

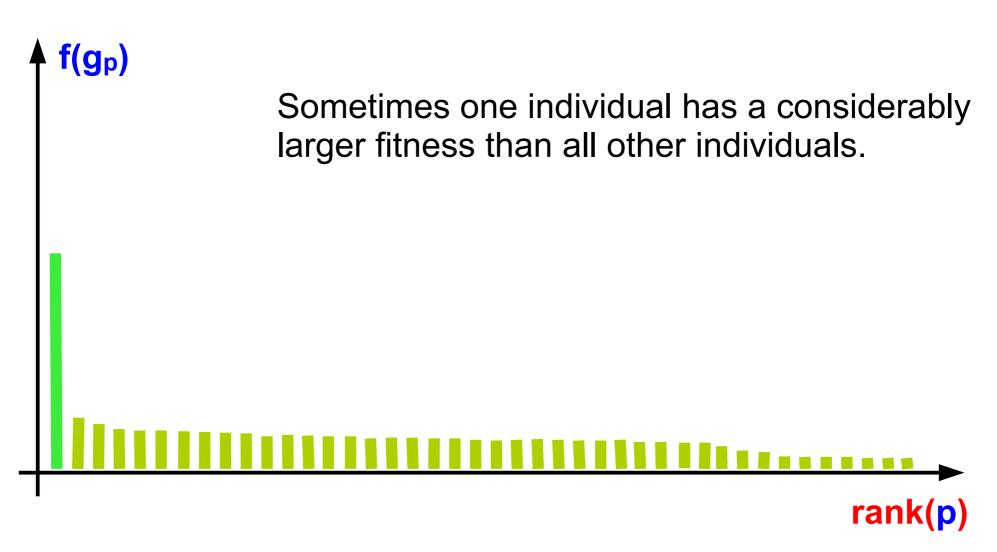
# **Super-Individual**



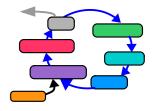












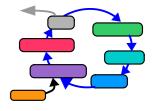
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In the case, that one individual has a considerably larger fitness than all other individuals, it can happen that this individual is selected more often

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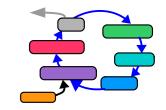
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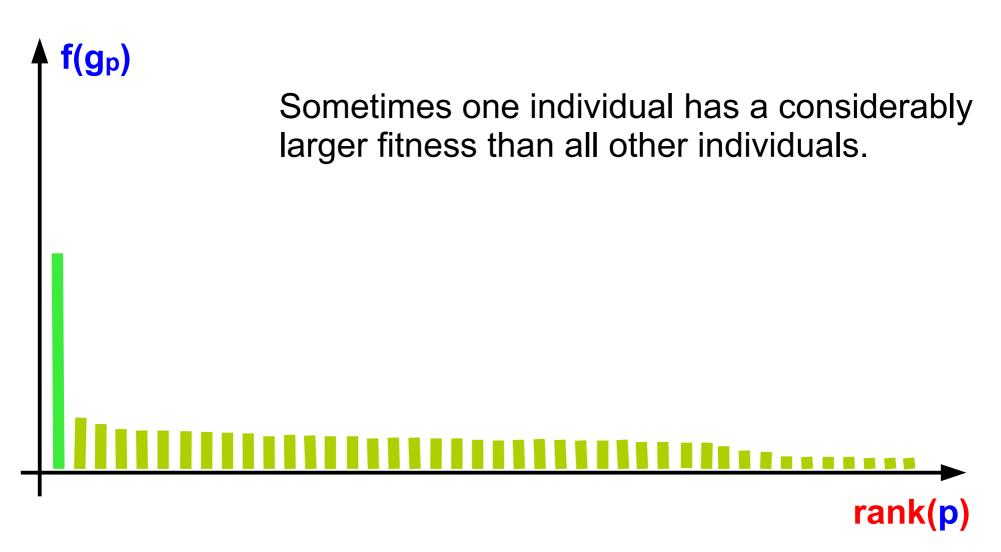
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(e.g. fitness proportional selection,  $\mu \ll \lambda$ , ...).

Thus, it will produce more offspring than other individuals, increasing the number of individuals with a high fitness; which is explicitly intended by the principle of inheritance.



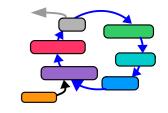


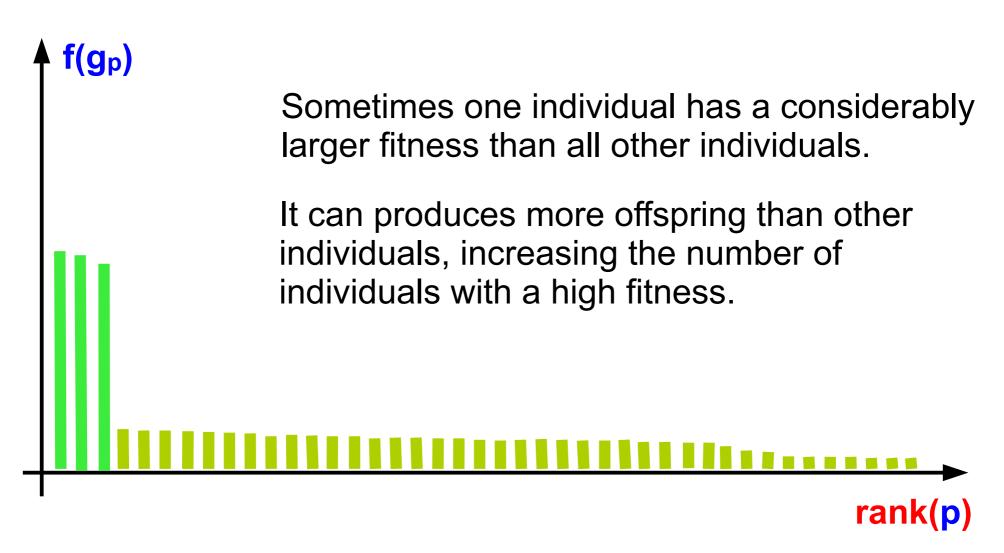


Mon 2.6.25,



### **Super-Individual**

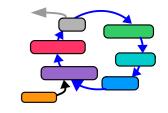


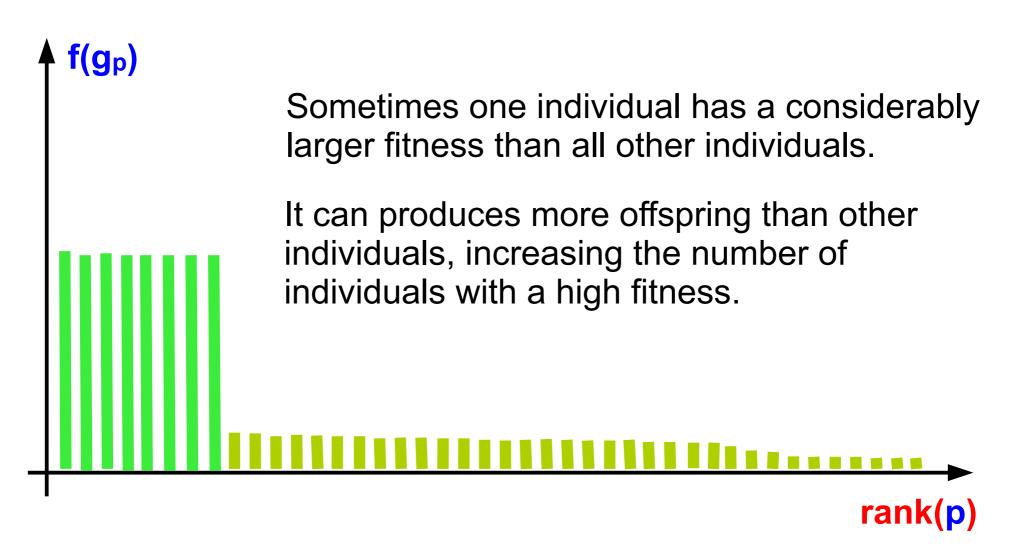


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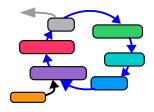


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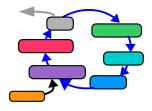


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It can happen, that an individual with a rather high fitness is generating so much offspring, that they dominate the entire population.

Which means, that a large percentage of the population has identical (or almost identical) genomes.





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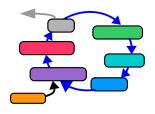
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Which means, that a large percentage of the population has identical (or almost identical) genomes.

On one hand, a Super-Individual with a large fitness is good for the overall performance of the population,

on the other hand, if a large percentage of the population has identical genomes the **diversity** throughout the population is lost.



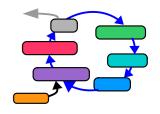


Generally speaking, the occurrence of a super-individual should be avoided to maintain the necessary diversity within the population (EAs are multi hypothesis approaches).

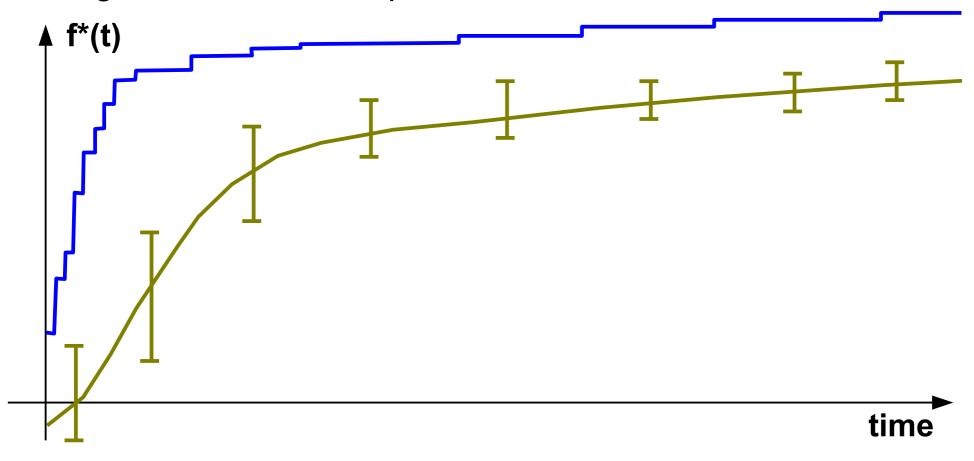
The detection of a super-individual can be really hard. A hint for the occurrence is a shrinking variance of fitness values in the parent population.

A close investigation of the performance graph is helpful.

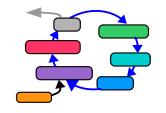




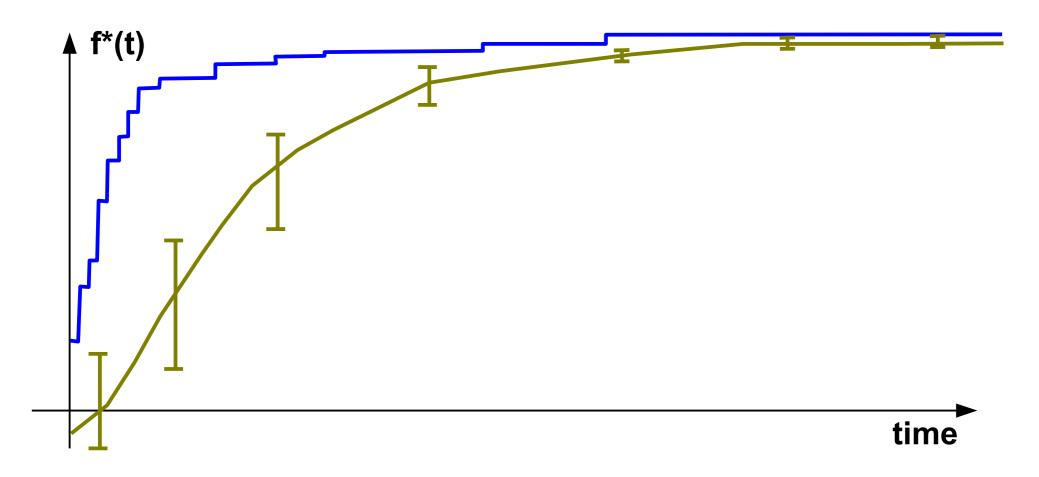
The performance graph is showing the development of the fitness f\*(t) of the best individual and the average fitness in each generation with respect to time.





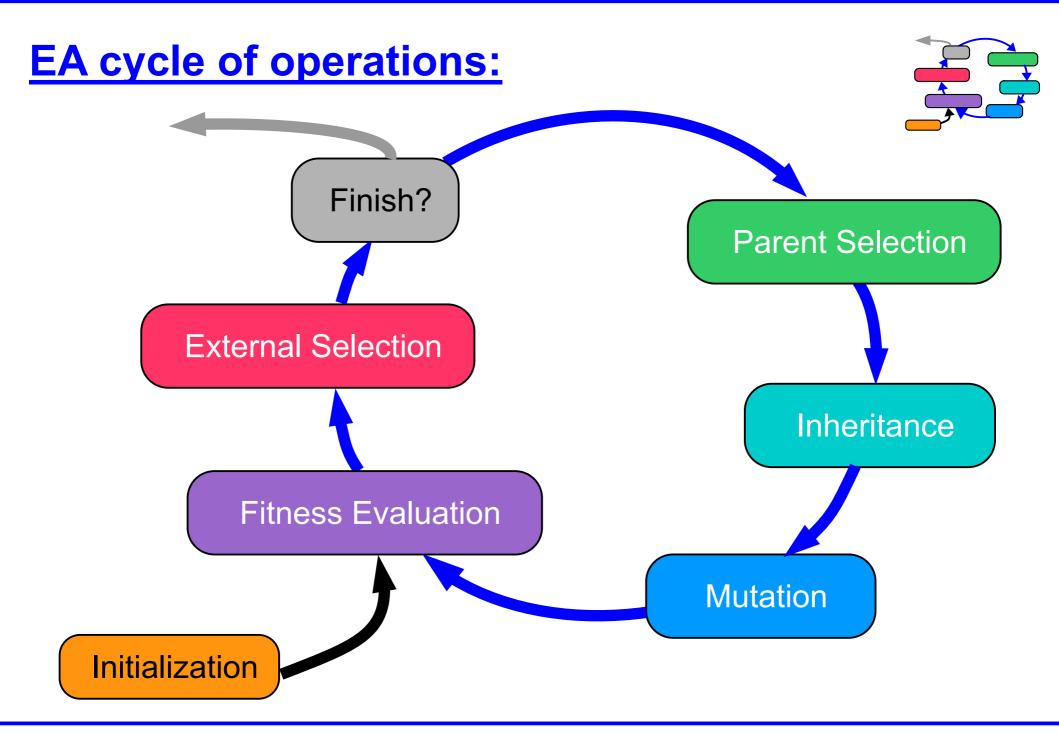


The performance graph might me an indicator for the occurrence of a super-individual dominating the population.



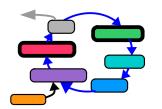
# **Overview**

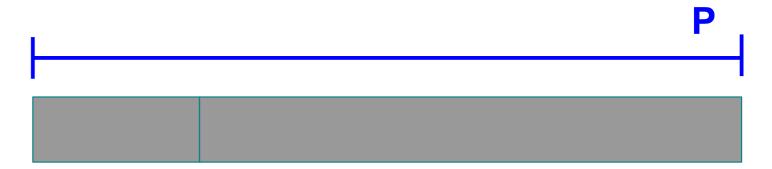
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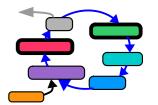


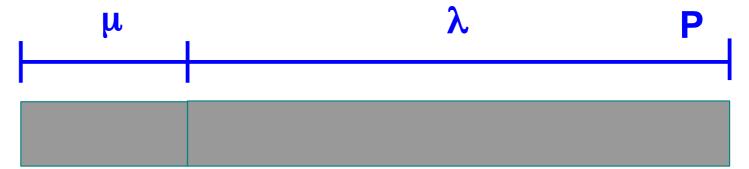
**Parent Selection** 





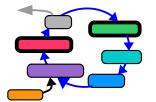
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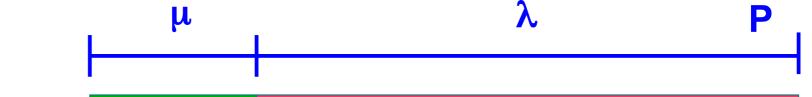




**Parent Selection** 

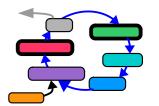


Have P, keep  $\mu$ , generate  $\lambda$  offspring



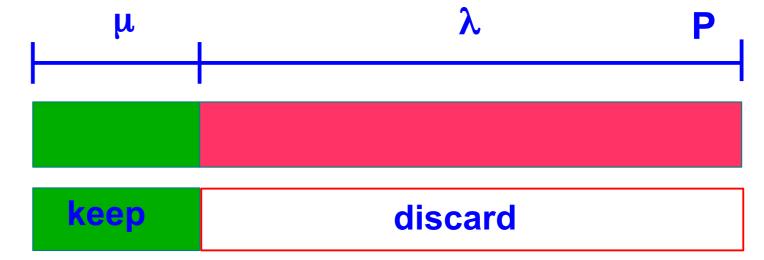
external selection

**Parent Selection** 



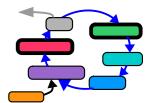
Have P, keep  $\mu$ , generate  $\lambda$  offspring

external selection





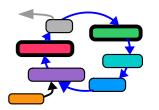
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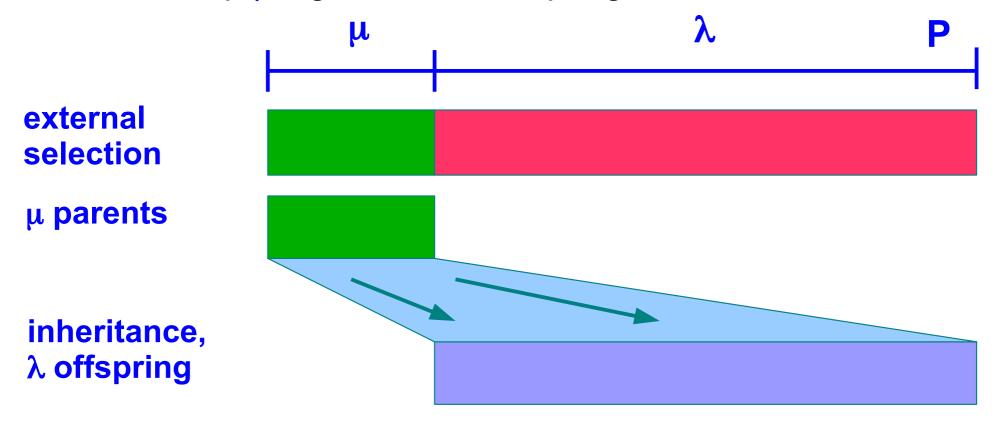






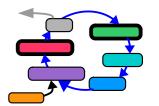
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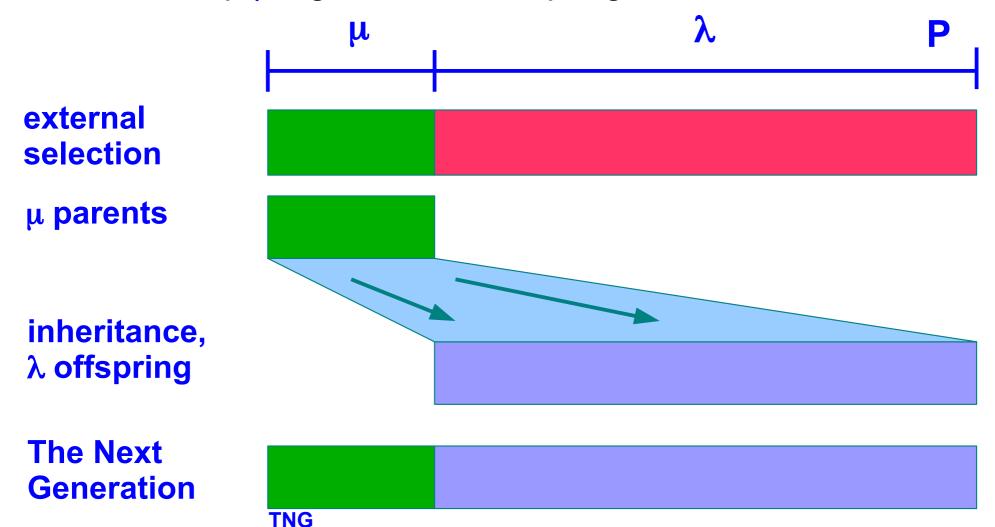






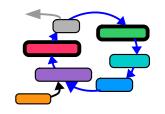
#### **Parent Selection**





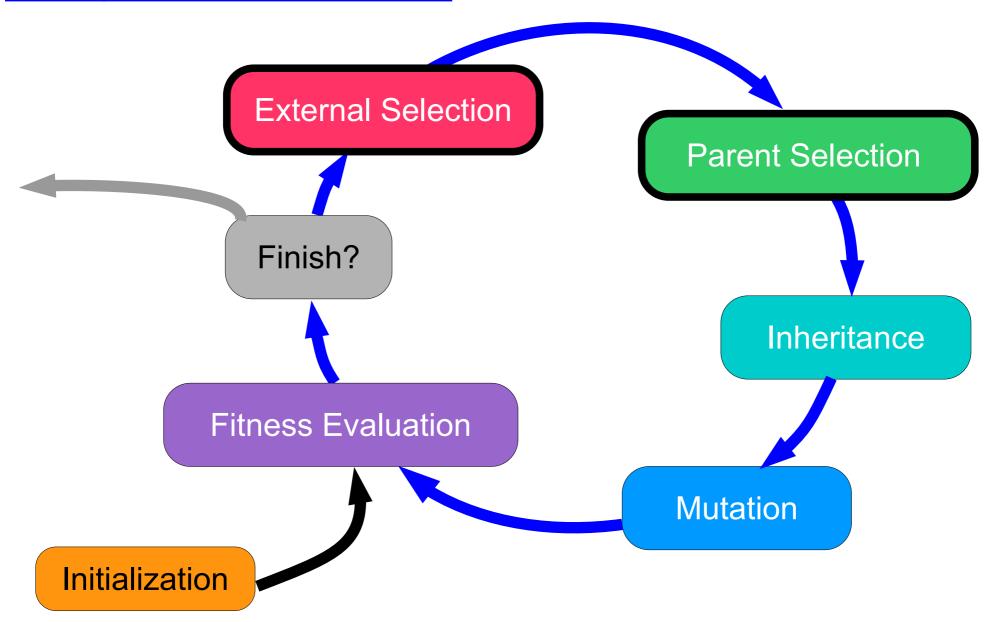


#### **Parent Selection**



- (1+1):  $\mu=1$  one parent,  $\lambda=1$  one child, inheritance by copying, only mutation rank based, deterministic external selection
- $(1 + \lambda)$ :  $\mu = 1$  one parent,  $\lambda$  children, offspring, inheritance by copying, only mutation rank based, deterministic external selection
- $(\mu + \lambda)$ :  $\mu$  parents,  $\lambda$  offspring, parents survive recombination, mutation, external selection.
- $(\mu, \lambda)$ :  $\mu$  parents,  $\lambda$  offspring, recombination, mutation, external selection, parents are discarded.

# **EA** cycle of operation



66 © Nils Goerke, University Bonn, 6/2025



#### **Parent Selection**

#### **External Selection**

An alternative scheme to operate the evolutionary algorithm is to **separate** parent selection from external selection.

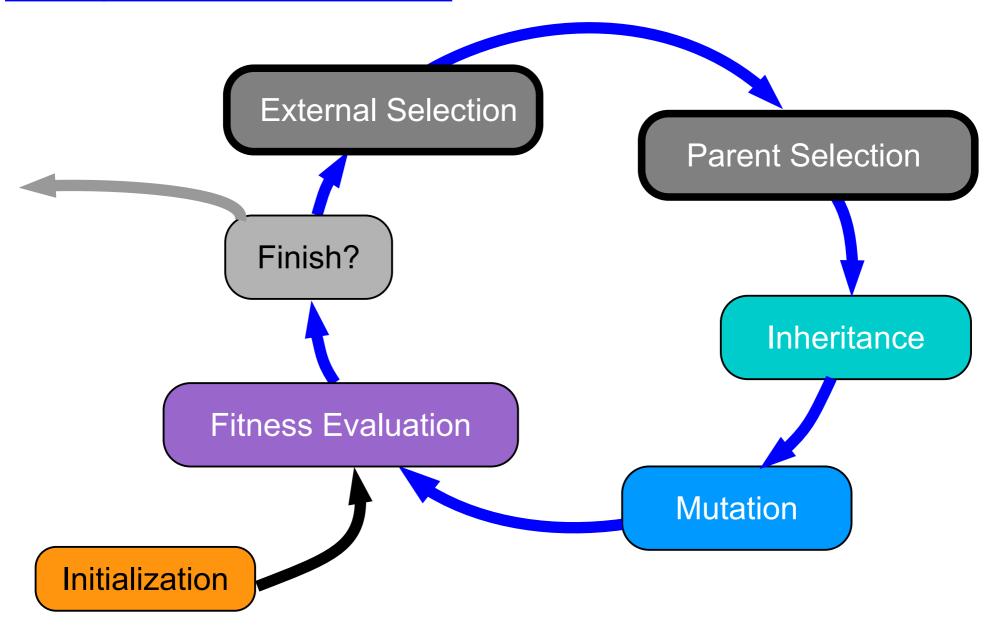
Then, within external selection, the  $\mu$  individuals to survive, are selected from the complete population of P individuals, and  $\lambda$  individuals are discarded.

And, within parent selection the parents are selected from the complete population as well, building the pool of parents for subsequent inheritance.

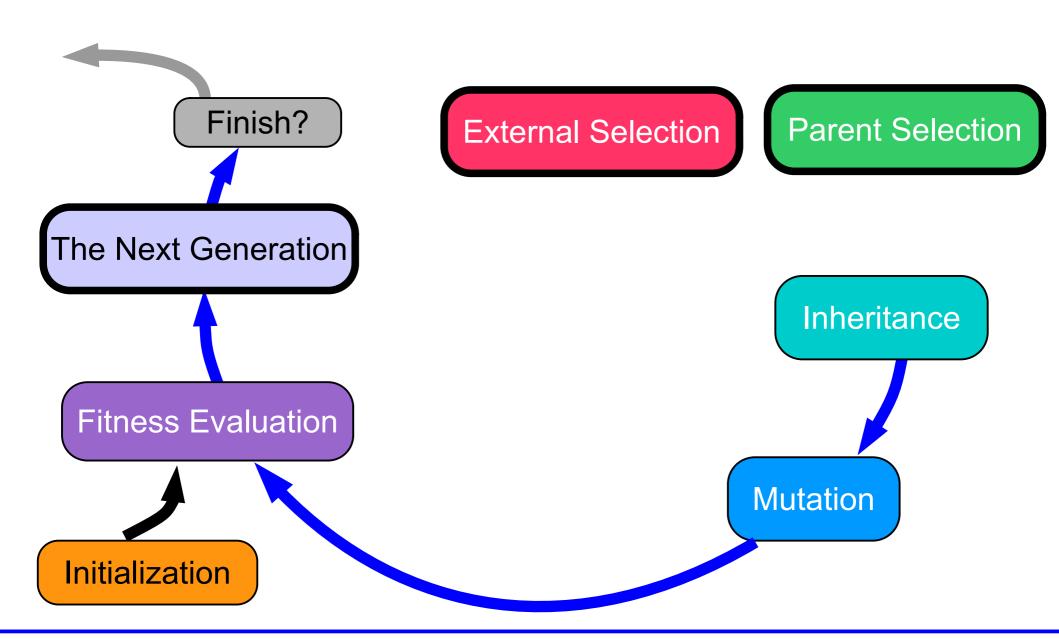
The inheritance step generates  $\lambda$  new individuals, from the pool of parents; the pool of parents is erased afterwards.

The Next Generation is build by combining the  $\mu$  survivors with the  $\lambda$  offspring ( $\mu + \lambda = P$ ).

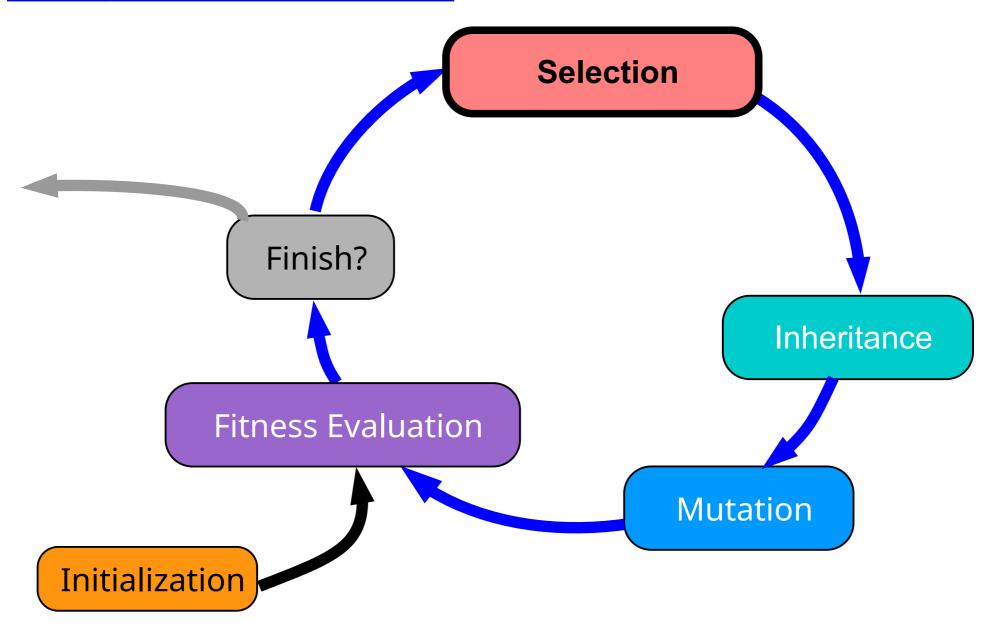
# **EA** cycle of operation



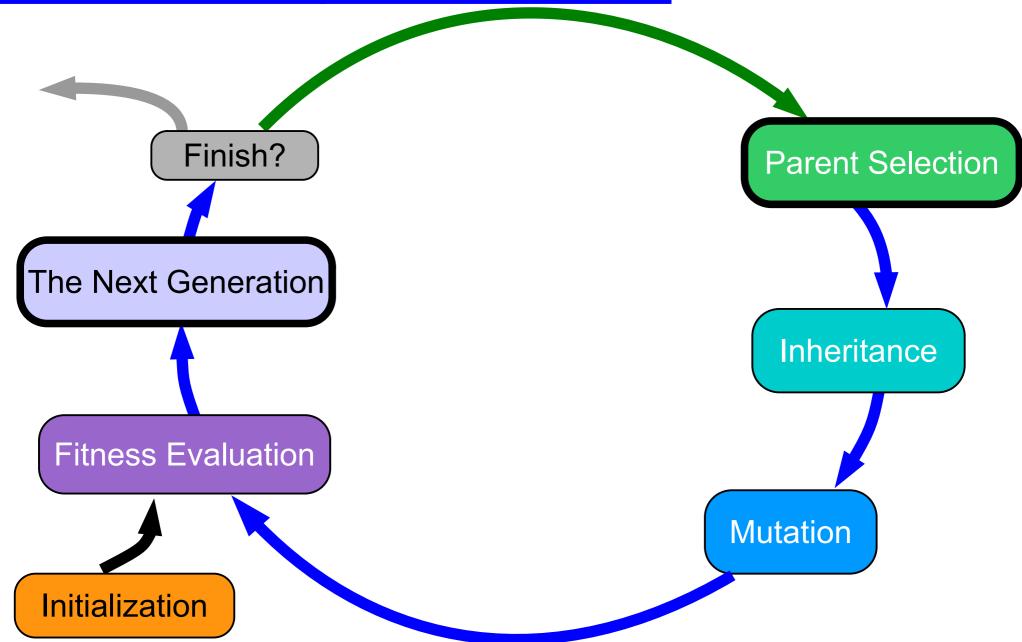
# **EA** alternative cycle of operation



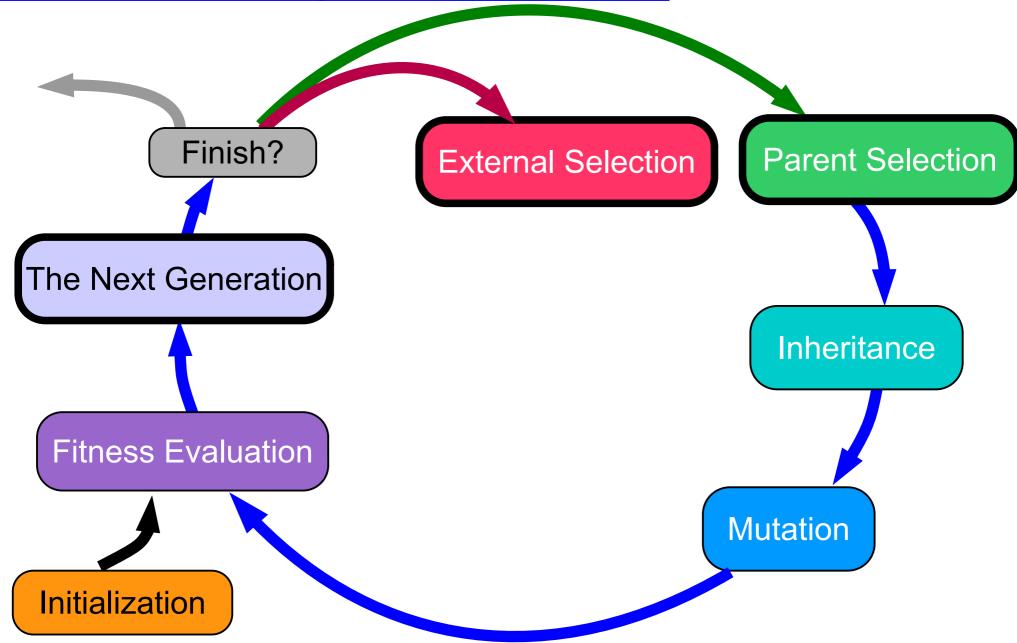
# **EA cycle of operation**



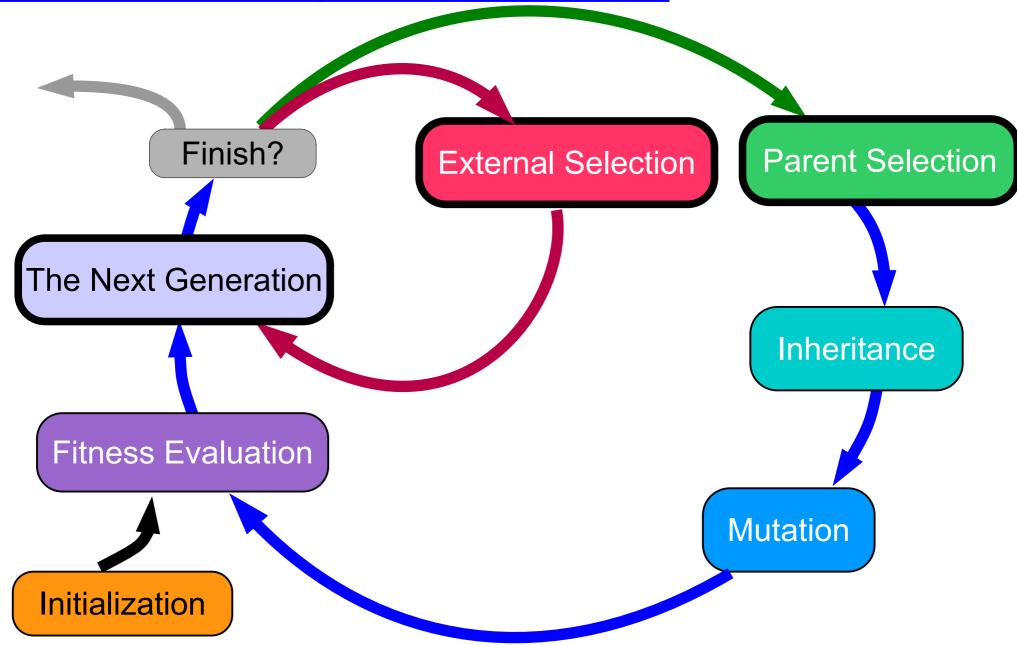
# **EA alternative cycle of operation**



# **EA alternative cycle of operation**



# **EA** alternative cycle of operation





**External Selection** 

Have P, keep  $\mu$ , generate  $\lambda$  offspring

P



**External Selection** 

Have P, keep  $\mu$ , generate  $\lambda$  offspring

F

parent selection





**External Selection** 

Have P, keep  $\mu$ , generate  $\lambda$  offspring

parent selection



pool of parents





**External Selection** 

Have P, keep  $\mu$ , generate  $\lambda$  offspring

parent selection





pool of parents



external selection



**External Selection** 

Have P, keep  $\mu$ , generate  $\lambda$  offspring

parent selection



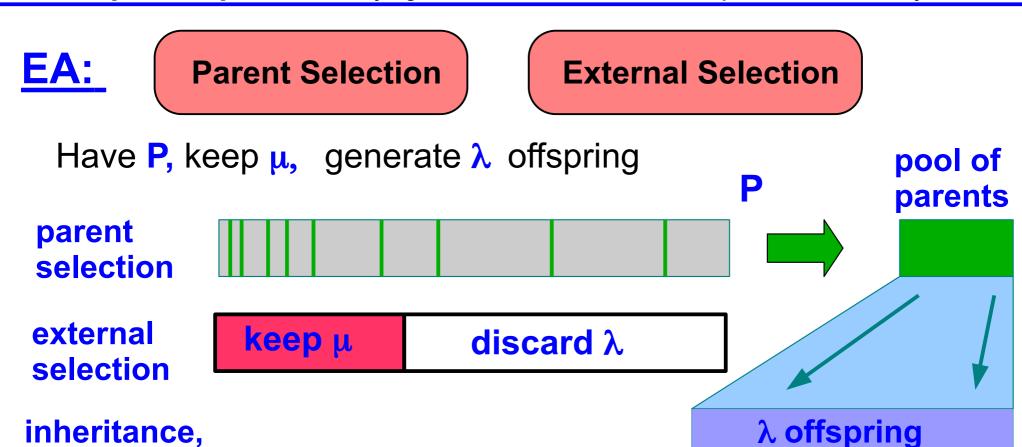
pool of parents



external selection

 $\mathbf{discard} \lambda$ 

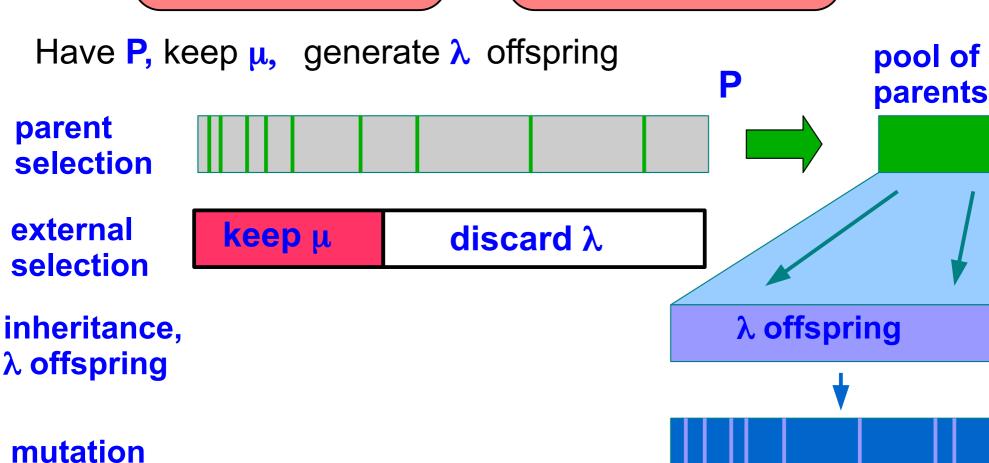


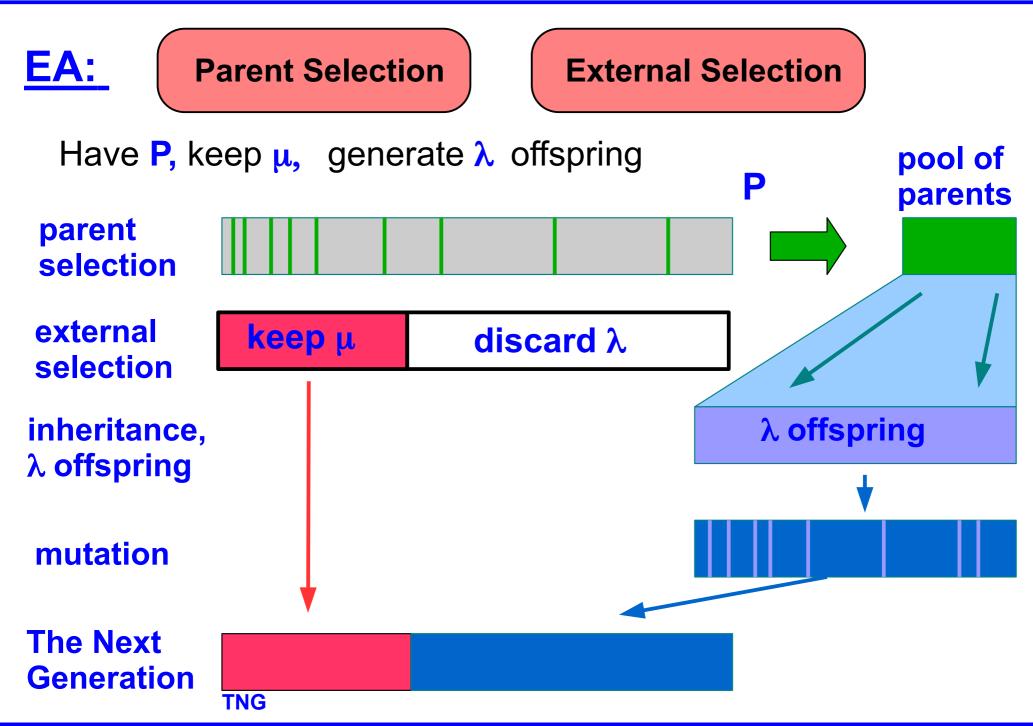


**λ offspring** 

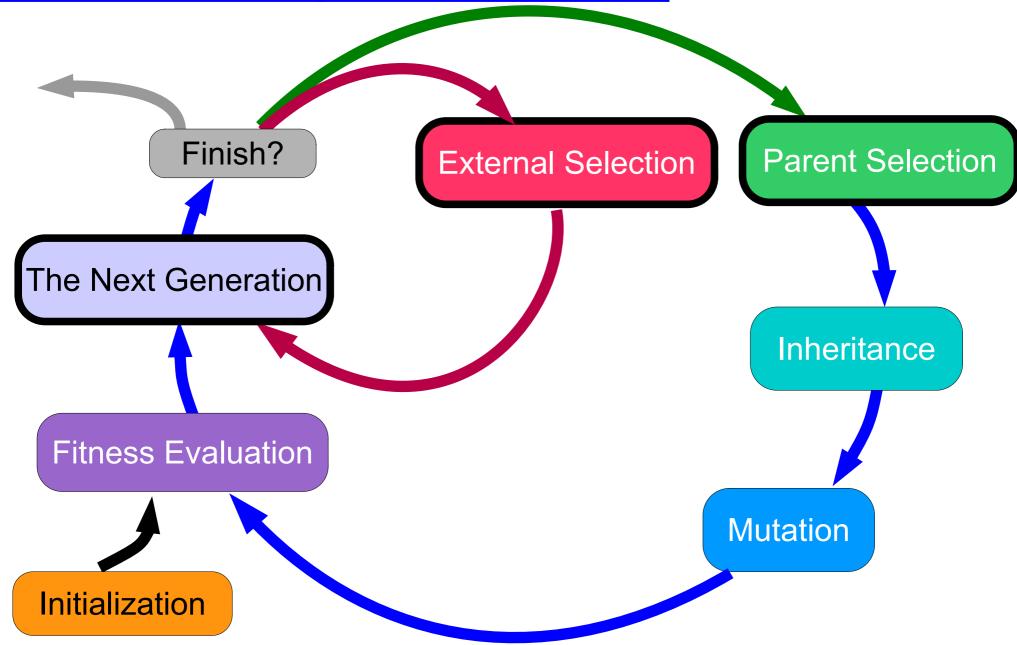


**External Selection** 



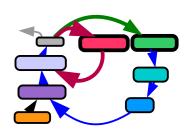


# **EA** alternative cycle of operation





#### Selection

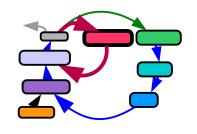


## Common strategies for the **selection** are:

- random choice
- schedule based, e.g. round robin
- fitness based elitism:
   fitness proportional choice
   rank proportional choice
- fitness based stochastic:
   fitness proportionate, probabilistic choice
   rank proportionate, probabilistic choice
- combinations of the above



## **External Selection**



Elitism is a way to design the selection, and inheritance steps to shape the next generation following the principle of Exploitation.

Using elitism a subset of the population is surviving (excluding mutation), and will be part of the next generation.

Typically the  $\mu$  best individuals are chosen to survive.

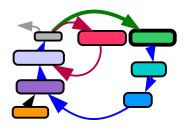
The ( $\mu + \lambda$ ) deterministic, rank dependent strategy, with taking the  $\mu$  best individuals as parents is a common implementation of elitism.

But the pool of parents, and the elite of  $\mu$  surviving individuals can be different.

# **Overview**

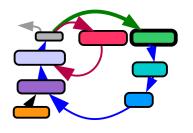
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Within parent selection one has to try to obey the two principles of Exploration and Exploitation at the same time.

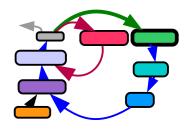




Within parent selection one has to try to obey the two principles of **Exploration** and **Exploitation** at the same time.

Of course, one is trying to use the acquired knowledge as good as possible, while maintaining the diversity within the population.



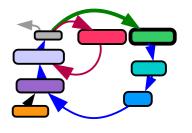


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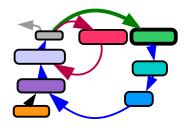
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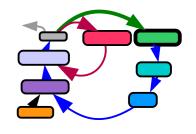
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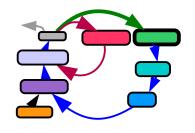
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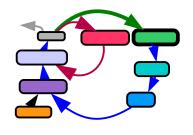
fitness proportional or rank proportional





It showed to be feasible to make up the set of parents with those individuals, that have shown a good fitness f(g), and explicitly include additional individuals that have not performed as good.

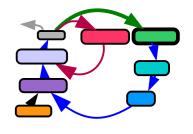




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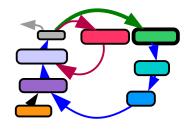
Common probabilistic, fitness based parent selection:

- Wheel of Fortune, (Roulette-Wheel Selection)
- Boltzmann Selection, Softmax-Selection
- Tournament selection

# **Overview**

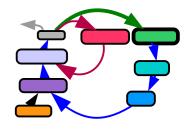
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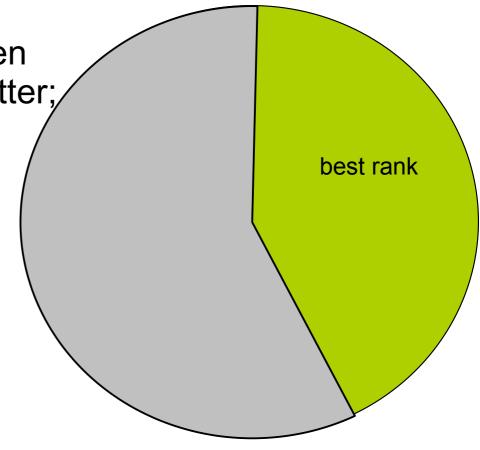


A widely used way to implement a probabilistic, rank proportionate parent selection is the wheel of fortune,

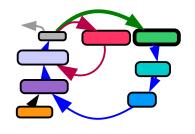




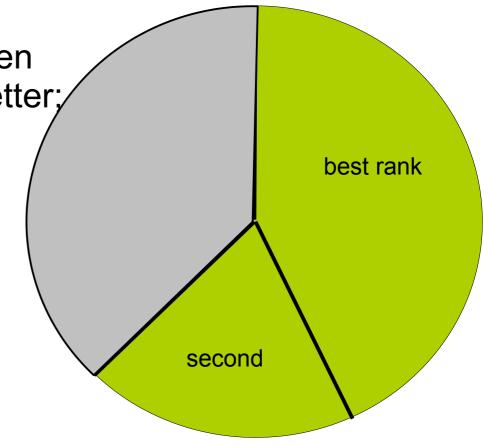
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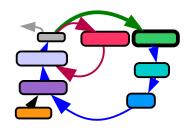




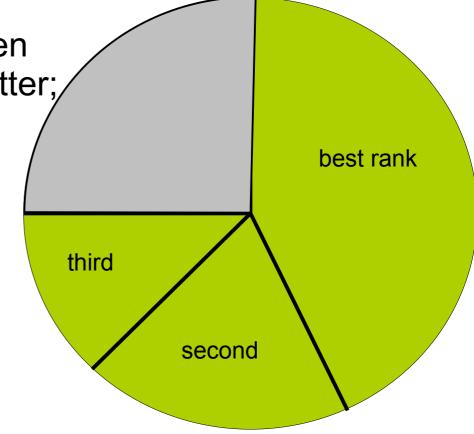
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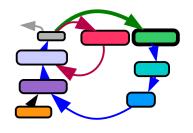




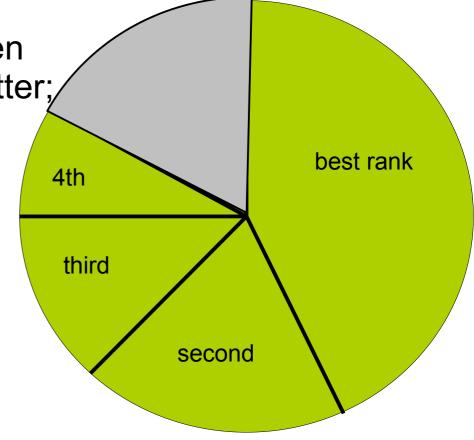
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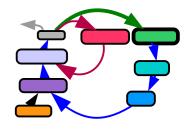




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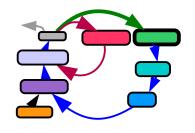
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Where the probability  $\omega$  to be chosen is larger, when the fitness f(g) is better; is larger, when the rank r(f(g))

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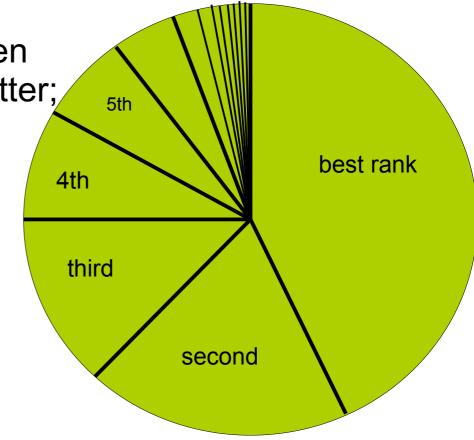




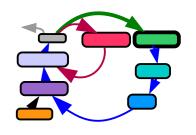
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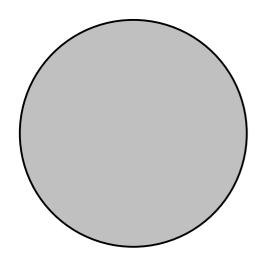






#### "Wheel of Fortune",..

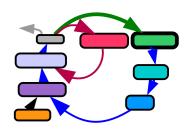
The chance, or the probability  $\omega$  to be chosen is larger with smaller fitness dependent rank r(f(g)) of the individual.



**P=2**:

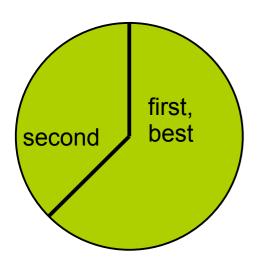






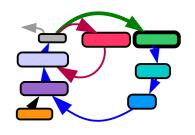
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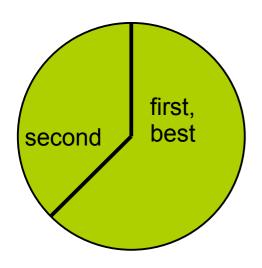
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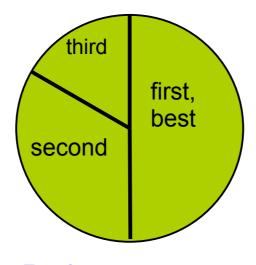


## "Wheel of Fortune",...

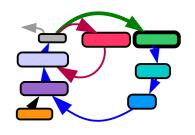
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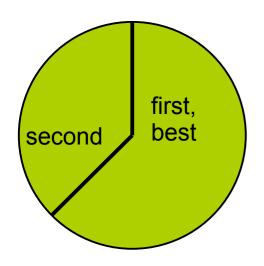




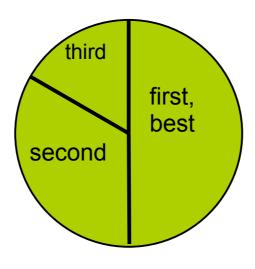


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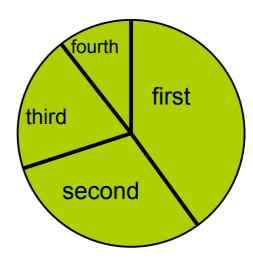
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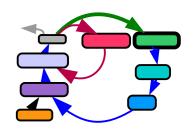
**P=3**:



P=4:

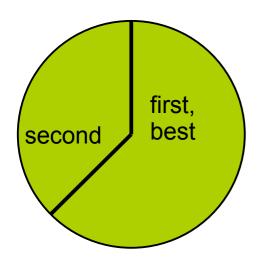
 $^{\circ}$  Nils Goerke, University Bonn, 6/2025 106



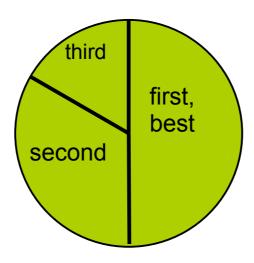


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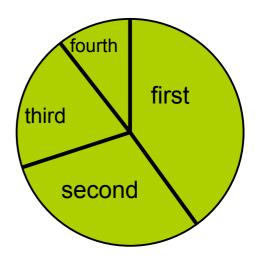
The chance, or the probability  $\omega$  to be chosen is larger with smaller fitness dependent rank r(f(g)) of the individual.



**P=2:** 2/3 + 1/3 = 1.0



**P=3:** 3/6 + 2/6 + 1/6 = 1.0

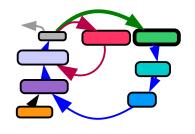


P=4: 4/10 + 3/10 + 2/10 + 1/10 = 1.0

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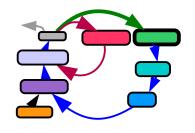
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A probabilistic parent selection, depending on the reached fitness values f(g) is a common way to implement this.

Common probabilistic, fitness based parent selection:

- Wheel of Fortune, (Roulette-Wheel Selection)
- Boltzmann Selection, Softmax-Selection
- Tournament selection





Another common way to implement the parent selection, is using the **softmax function** for probabilistic selection.

The parents are taken randomly from the population. The probability  $\omega_p$  to be taken is determined by the fitness f(p) of the individual p.

$$\omega_p = \frac{e^{f(p)/\tau}}{\sum_{q=1}^{P} e^{f(q)/\tau}}$$

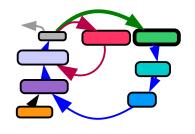
The positive parameter  $\tau$  is called a temperature. Large value of  $\tau$  generates a (nearly) equiprobable distribution.

Easy to implement, easy to control the selection pressure.

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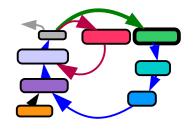
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Another common way to shape the parent selection, is called tournament selection.

Some individuals are taken randomly from the population, and compared pairwise (randomly chosen) in a form of tournament, the winner of each tournament is now eligible for the pool of parents.

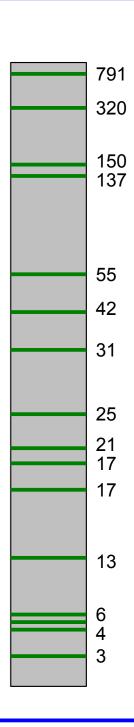
To further increase the fitness of the pool of parents, the winning individuals can now undergo further stages of tournaments among each other.

Easy to implement, easy to control the selection pressure.





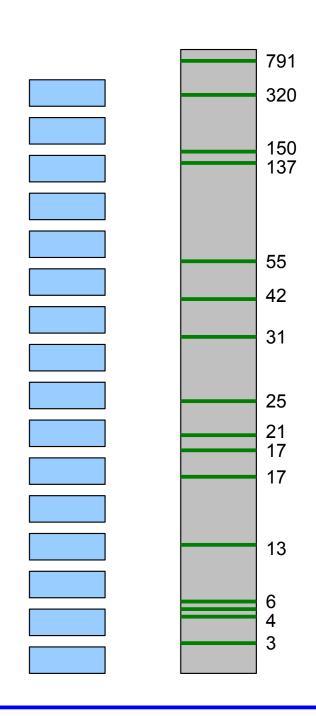
## **Tournament selection**



115

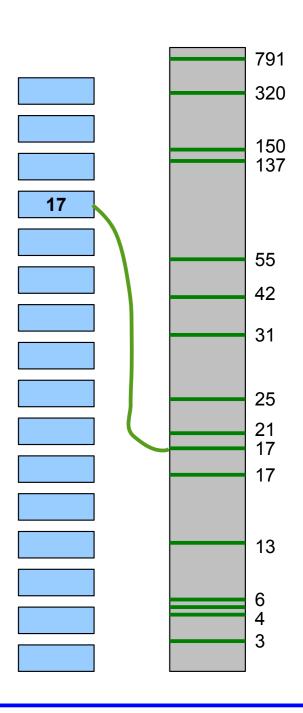


## **Tournament selection**

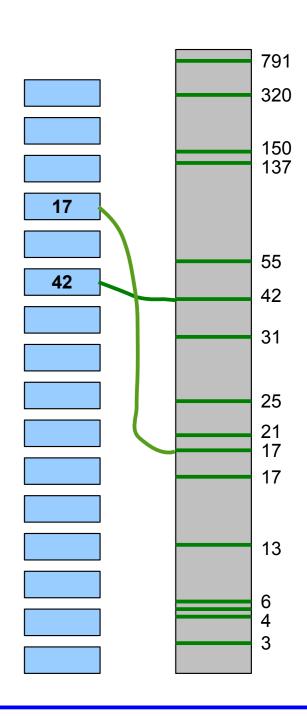


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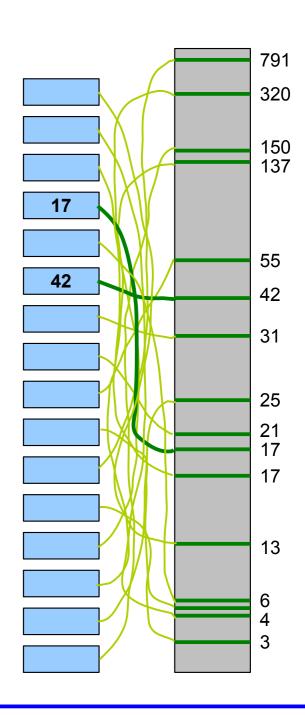




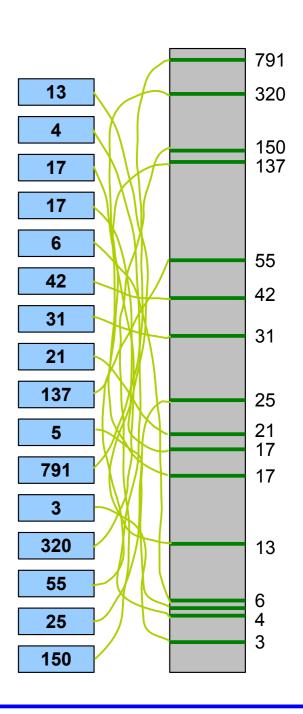




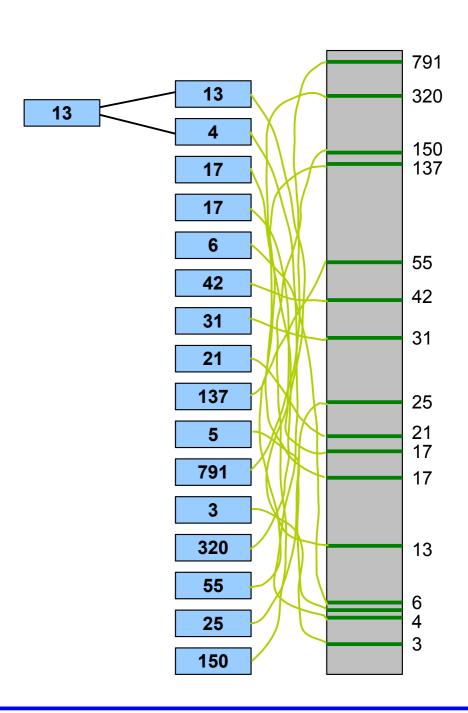




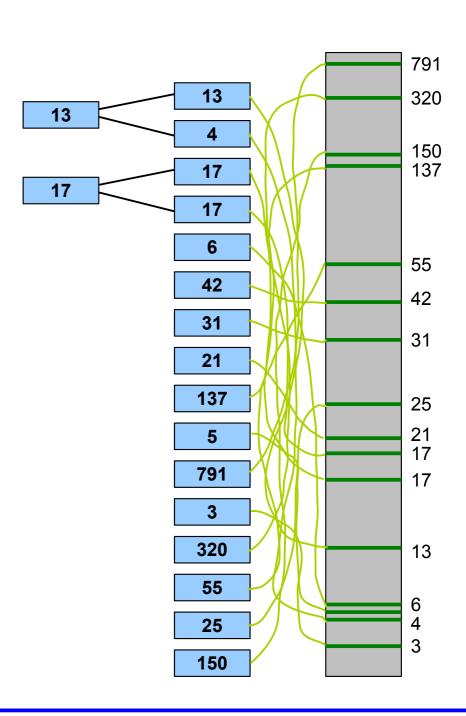




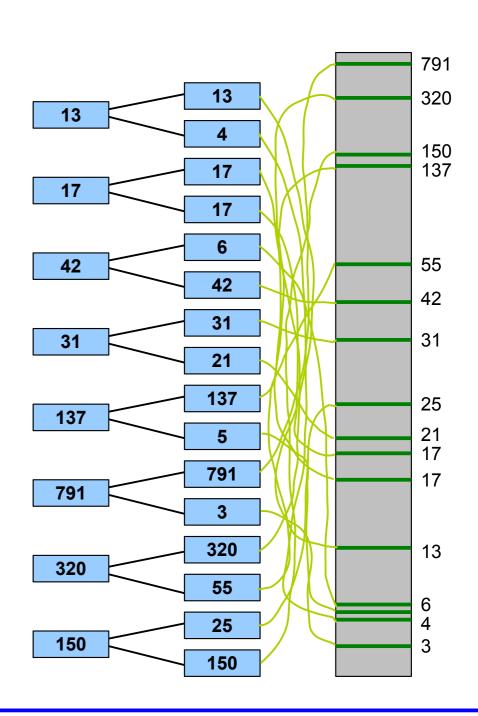


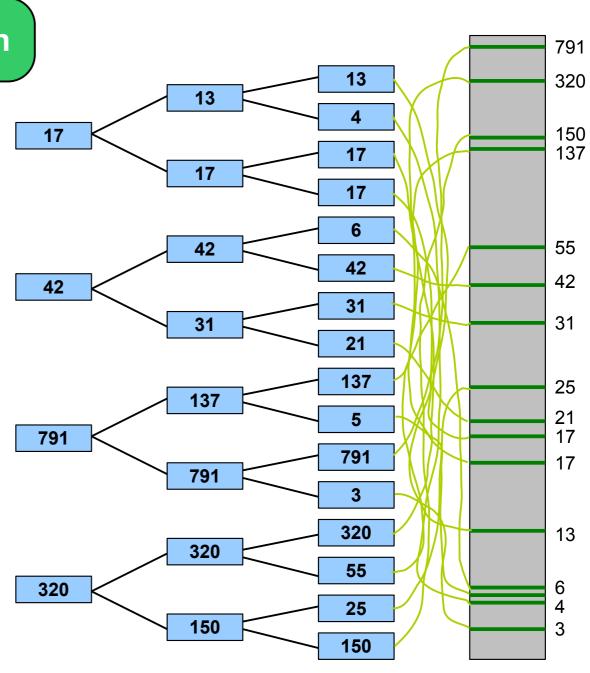


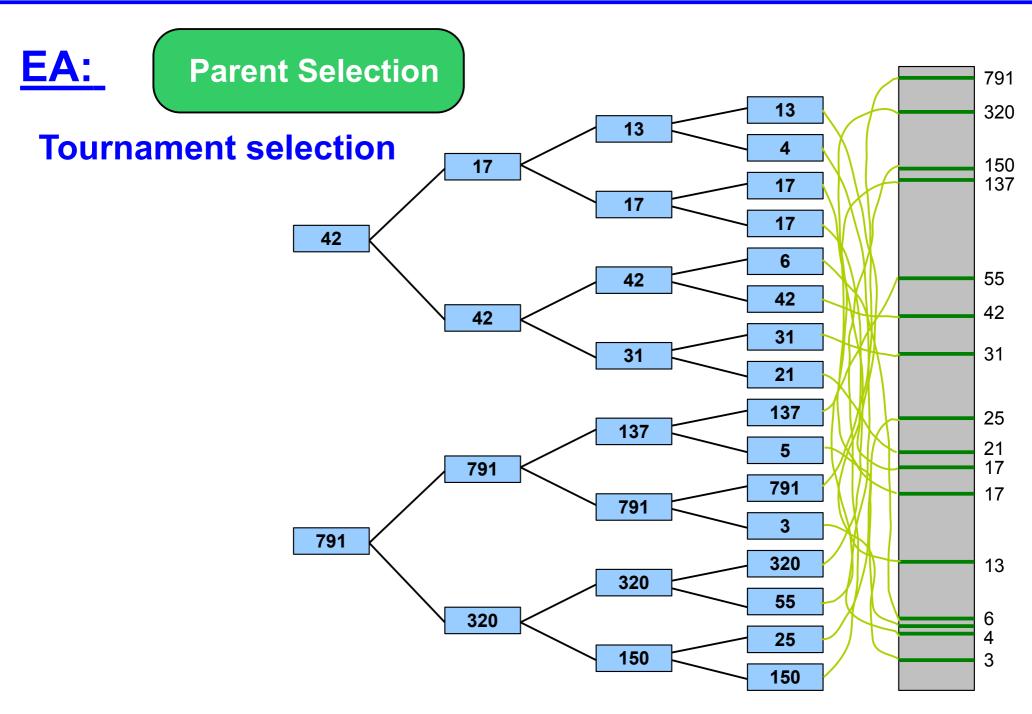


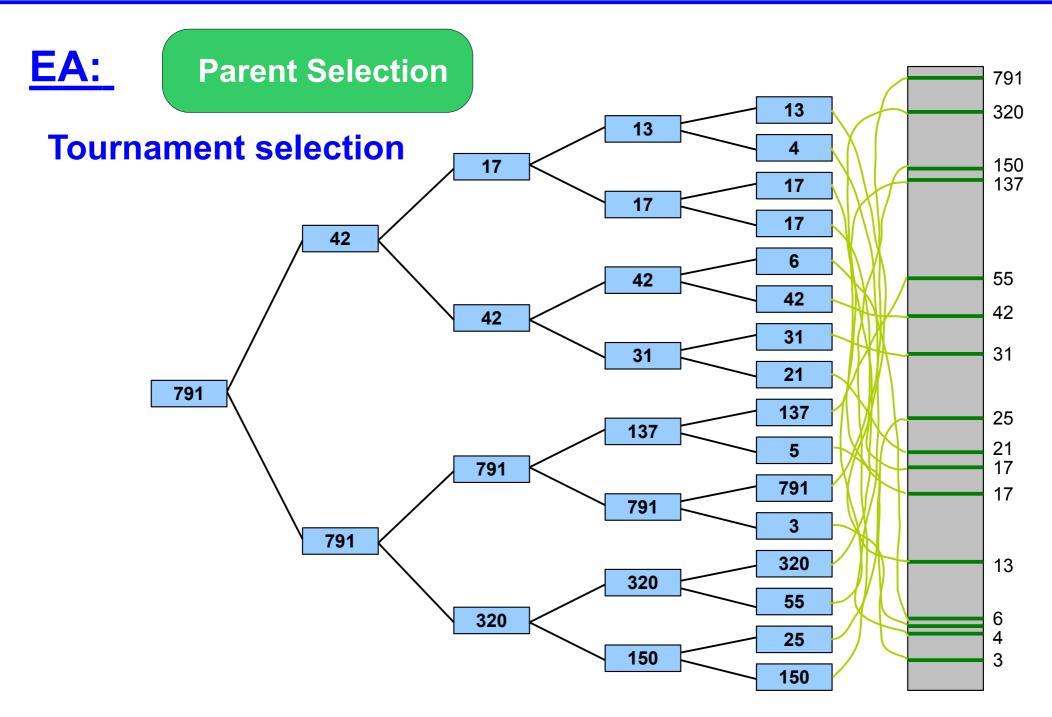


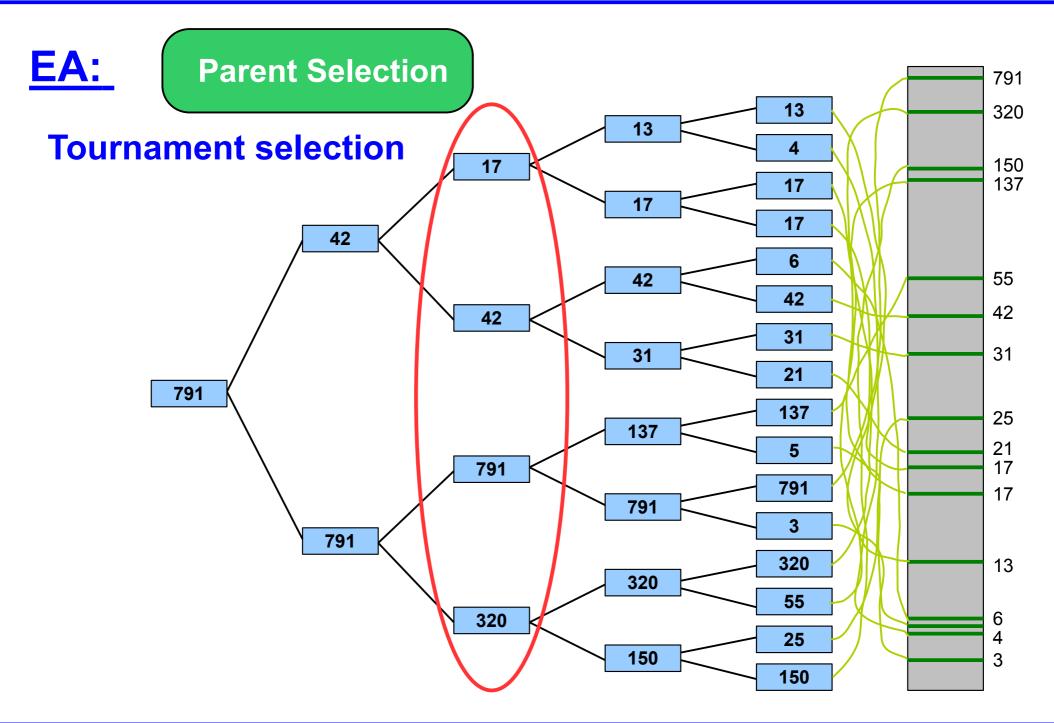




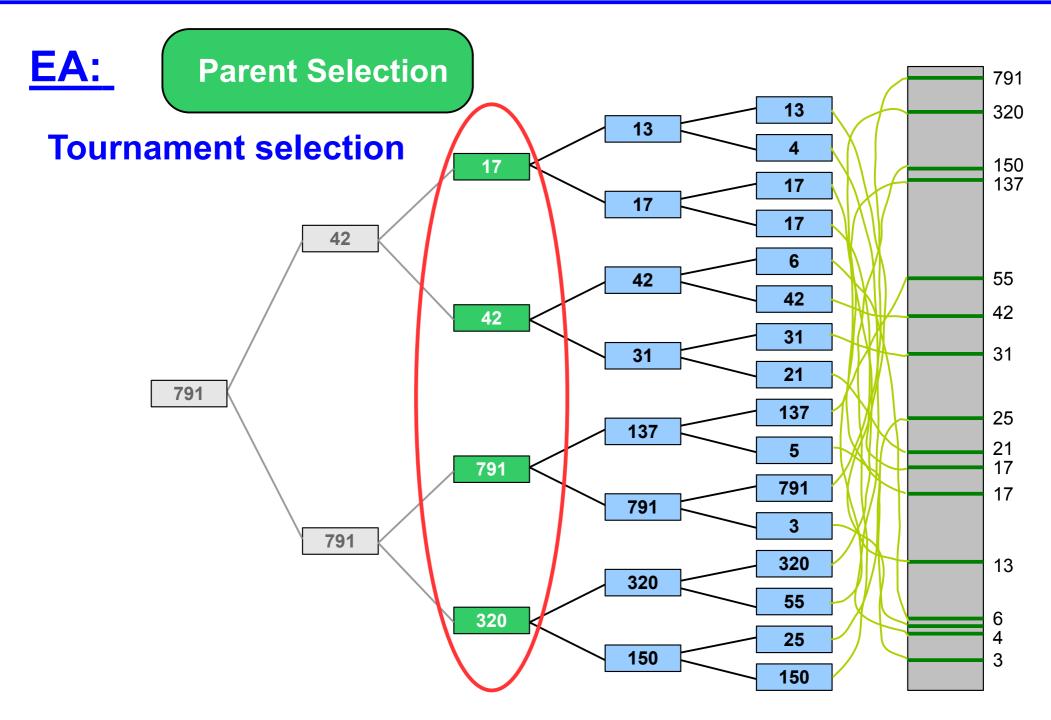








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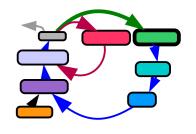
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It showed to be feasible to make up the set of parents with those individuals, that have shown a good fitness f(g), and explicitly include additional individuals that have not performed as good.

A probabilistic parent selection, depending on the reached fitness values f(g) is a common way to implement this.

Common probabilistic, fitness based parent selection:

- Wheel of Fortune, (Roulette-Wheel Selection)
- Boltzmann Selection, Softmax-Selection
- Tournament selection

# **Overview**

- Genome structure
- Example: 8 queens
- Super-individuals
- External-selection and parent-selection combined
- Probabilistic parent-selection
  - Wheel of fortune
  - Softmax selection
  - Tournament selection
- Genetic programming
- Co-evolution

# **Historic Remarks, Different Approaches**

# **Evolutionary Computation (EC)**

Swarm Behavior / Swarm Intelligence

- Ant Algorithm
- Ant Colony Optimization
- Particle Swarm Optimization

# **Evolutionary Algorithms (EA)**

- Genetic Algorithms (GA)
- Genetic Programming (GP)
- Evolutionary Strategies (ES)
- Evolutionary Programming (EP)

# Historic Remarks, Different Approaches

**Evolutionary Computation (EC) Evolutionary Algorithms (EA)** 

- Genetic Algorithms (GA)
   John Henry Holland (1975)
- Evolutionary Strategies (ES)
   Ingo Rechenberg (1965), Hans-Paul Schwefel (1970)
- Evolutionary Programming (EP)
   Lawrence J. Fogel (1964)
- Genetic Programming (GP)
   N.A.Barricelli (1954), R.M.Friedberg (1958)





Although proposed as an alternative approach to "normal computer programming", the subject of **Genetic or Evolutionary Programming** refers to EA applications where the genome is regarded as a sequence of commands (a program).



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The fitness f(g) of the genome g is the quality the program achieves within the given application.

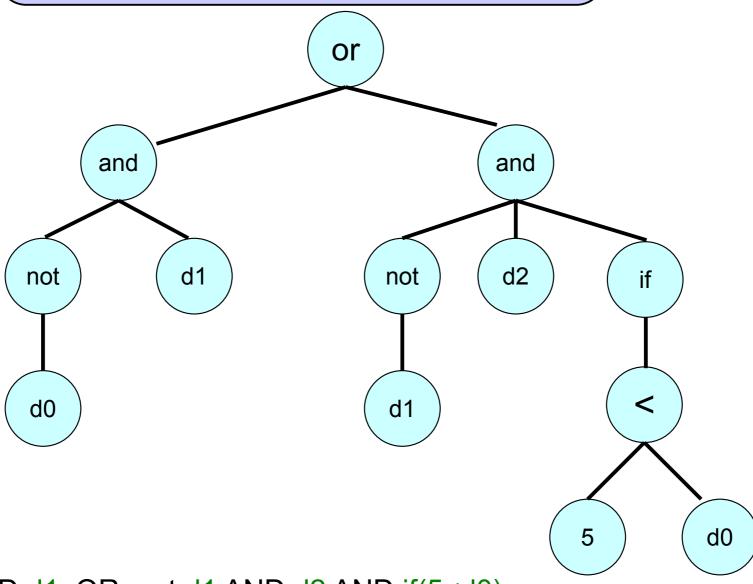


Although proposed as an alternative approach to "normal computer programming", the subject of **Genetic or Evolutionary Programming** refers to EA applications where the genome is regarded as a sequence of commands (a program).

The fitness f(g) of the genome g is the quality the program achieves within the given application.

The basis for genetic programming is typically not the source code level, but a genome that is representing a formal description of the code (syntax graph, prefix notation of functions, ...).





not d0 AND d1 OR not d1 AND d2 AND if(5<d0)

# **Overview**

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Now these two populations are interconnected via their fitness functions **f** and **h**, where one population is creating the fitness for the other population, and vice versa.

The population is not evaluated against a static fitness function, but against a changing other population. The performance of one population is the fitness for the others population.



#### **Co Evolution**

Two populations are interconnected via their fitness functions where one population is creating the fitness for the other population, and vice versa.

The performance of one population is the fitness for the other population.

0

P

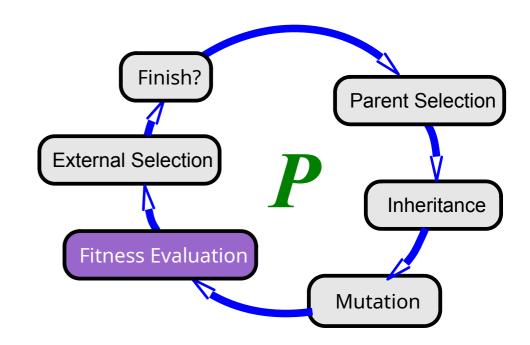


#### Co Evolution

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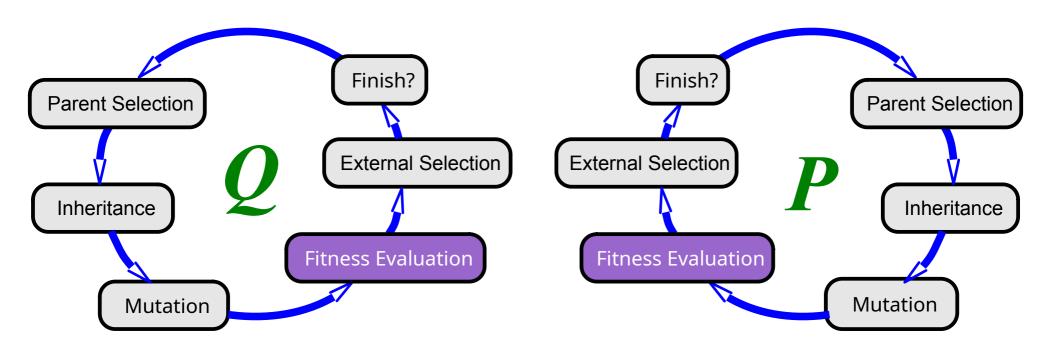
**Q** 





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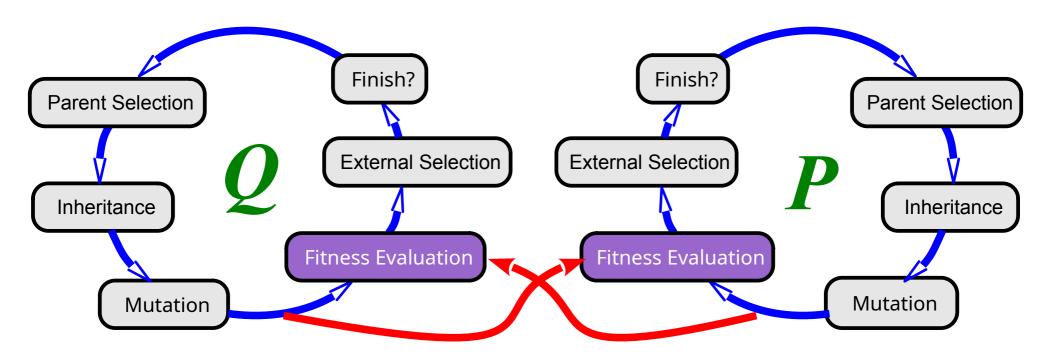
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#### Co Evolution

Co evolution can be used to simulate the development of two species interacting:

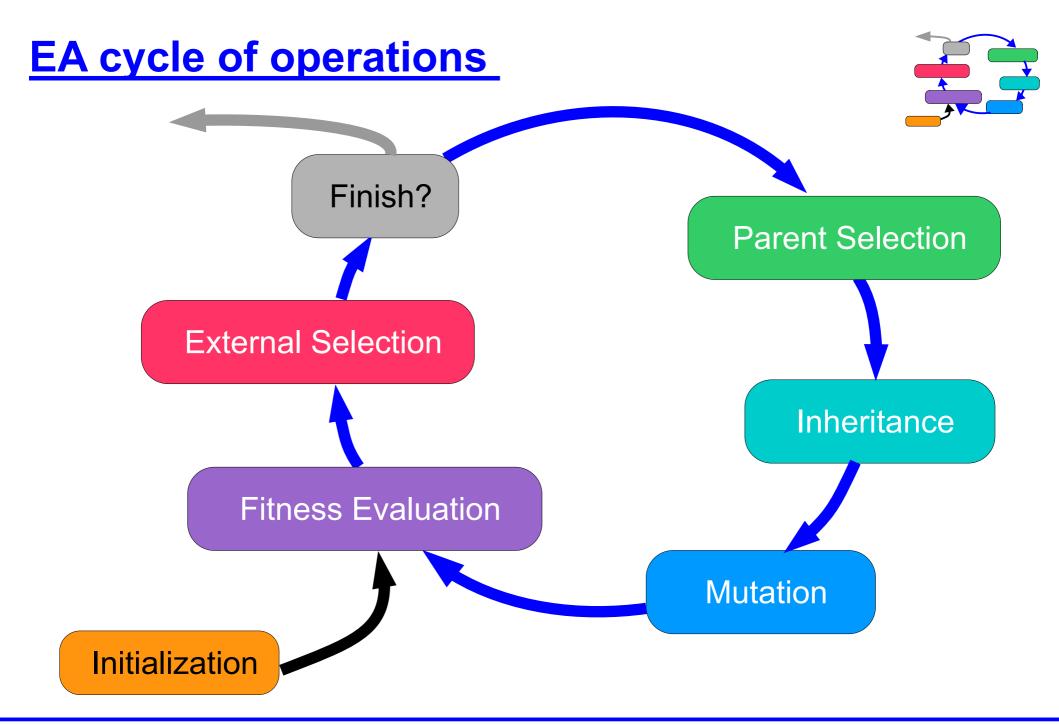
e.g. a predator-prey system or two agents, or two players in games, ...

Since both fitness functions, are not static but changing over time, a final objective is sometimes hard to determine.

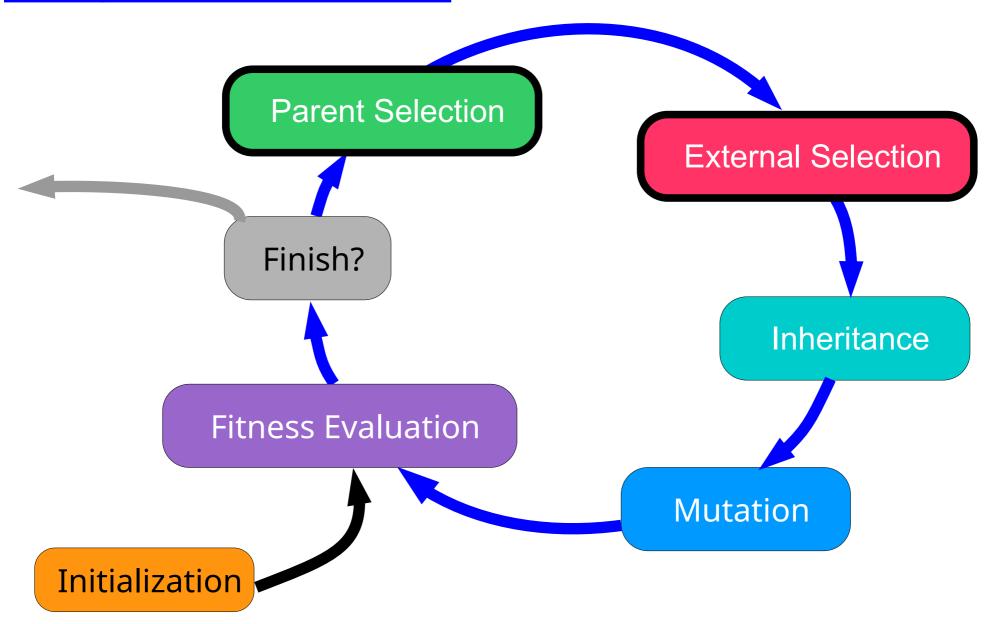
The achieved results in co evolution for one population is only use-able in interaction with the other population.

### **Overview**

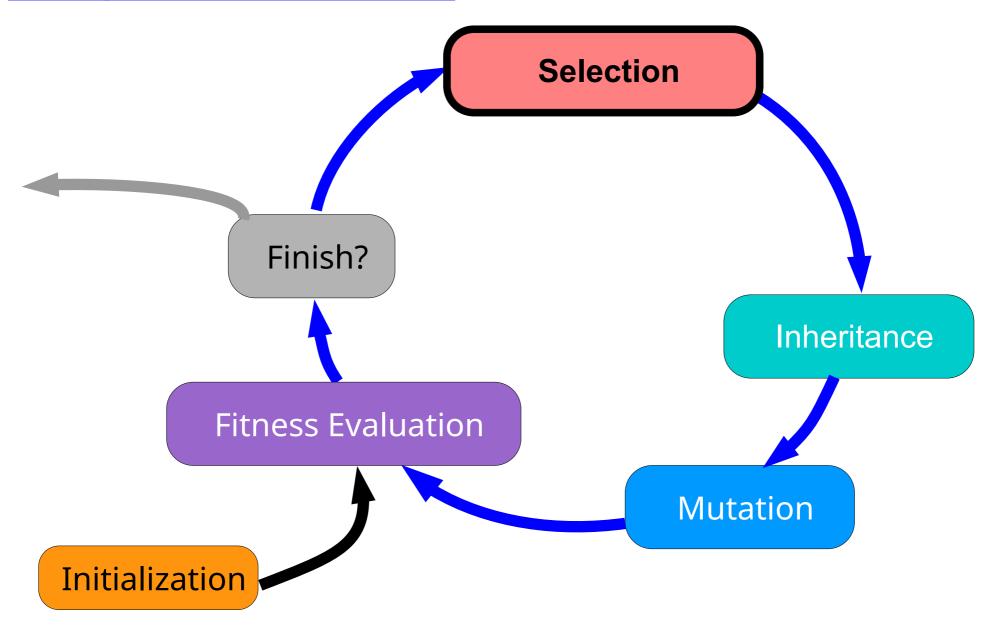
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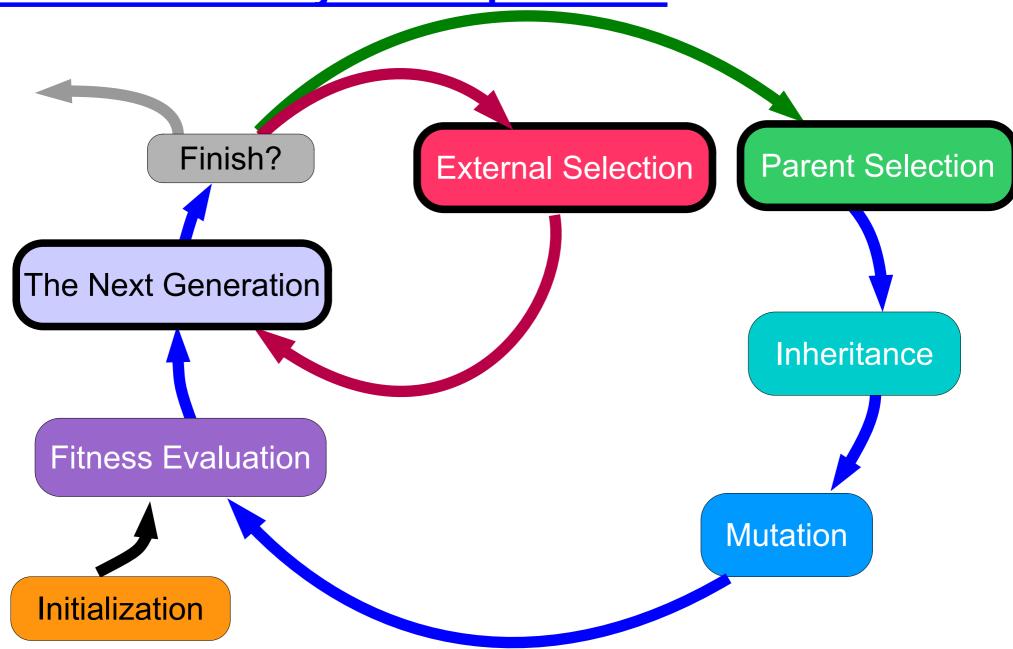
#### **EA** cycle of operation

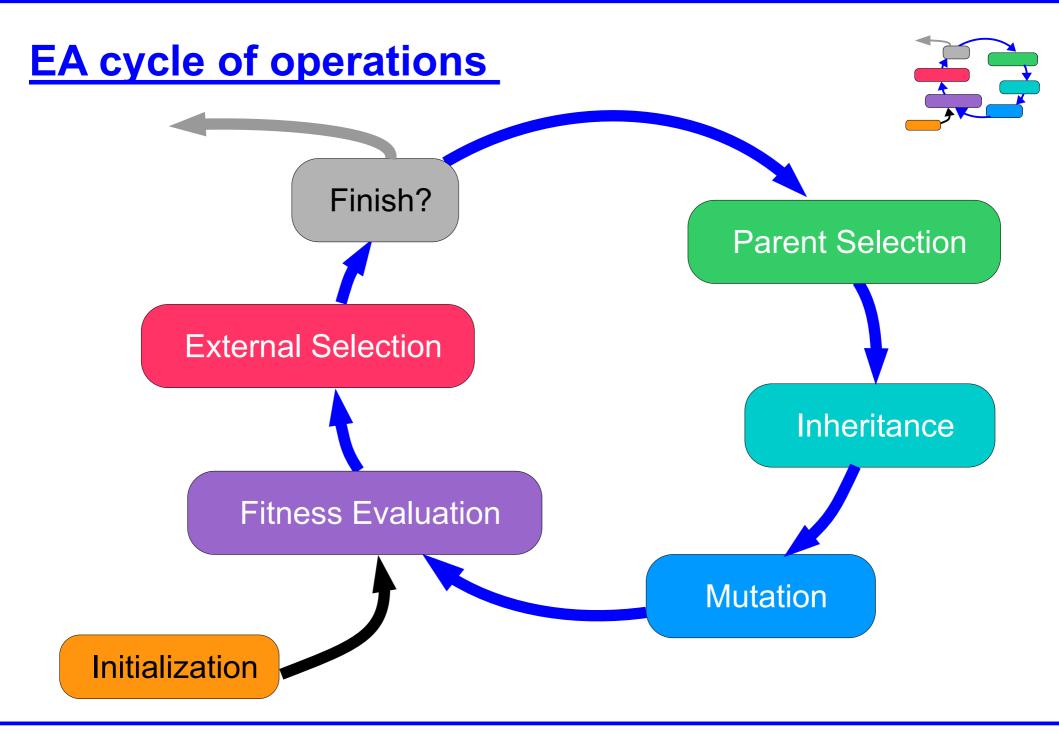


### **EA cycle of operation**



## **EA** alternative cycle of operation





#### Some important dates

Wed 14.5.25: Dies Academicus, special talks, no regular teaching

Thu 29.5.25: Ascension Day, no lectures, no exercises, ...

Sun 8.6. - 9.6.25 : Pentecost, Whitsun, Pfingsten, Public holiday Tue 10.6.25 - Fri 13.6.25 : Excursion week, no lectures, exercises, ...

Thu 19.6.25: Feast of Corpus Christi, no lectures, exercises, ...

#### **Programming Assignment PA-E**

Write a Python Programm, that implements an evolutionary algorithm to **maximize the length** of a route going **twice** through a given set of *N* points (cities) in 2-dimensions.

Starting, and ending point are open to be determined by the algorithm; each point (city) must be visited **exactly twice**.

The *N* points  $X_n = (x_1, x_2)_n$  shall be read in from the text-file Positions\_PA-E.txt

This list are the positions of European Capitals w.r.t. a map: http://upload.wikimedia.org/wikipedia/commons/6/64/Europe\_capitals\_map\_de.png

There is an additional new file: Positions2\_PA-E.txt augmented with the names of the European Capitals.

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```
#Artificial Life Lecture SS25 Programming Assignment PA E List of 46 Positions of European Capitals in 2D
#Positions are according to map http://upload.wikimedia.org/wikipedia/commons/6/64/Europe capitals map de.png
                    #Amsterdam
     446 621
     328 913
                    #Andorra la Vella
     1062 966 #Ankara
     857 1071 #Athens
4
     755 884
                    #Belgrade
     606 627
                    #Berlin
     477 798
                    #Bern
     684 764
                    #Bratislava
8
9
     430 671
                    #Brussels
10
     889 857
                    #Bucharest
11
     720 786
                    #Budapest
12
     927 780
                    #Chisinau
13
     592 535
                    #Copenhagen
14
     249 548
                    #Dublin
     788 383
15
                    #Helsinki
16
     940 667
                    #Kiew
17
          960
                    #Lisbon
      51
18
     627 831
                    #Ljubljana
19
```



http://upload.wikimedia.org/wikipedia/commons/6/64/Europe\_capitals\_map\_de.png

# **Artificial Life Summer 2025**

# **Evolutionary Algorithms 3**

Master Computer Science [MA-INF 4201] Mon 14:15 – 15:45, HSZ, HS-2

Dr. Nils Goerke, Autonomous Intelligent Systems, Department of Computer Science, University of Bonn

# **Artificial Life Summer 2025**

**Evolutionary Algorithms 3** 

Thank you for your patience

Dr. Nils Goerke, Autonomous Intelligent Systems, Department of Computer Science, University of Bonn