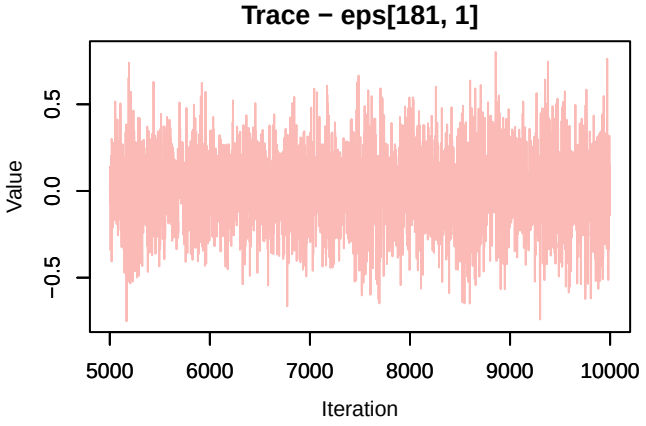
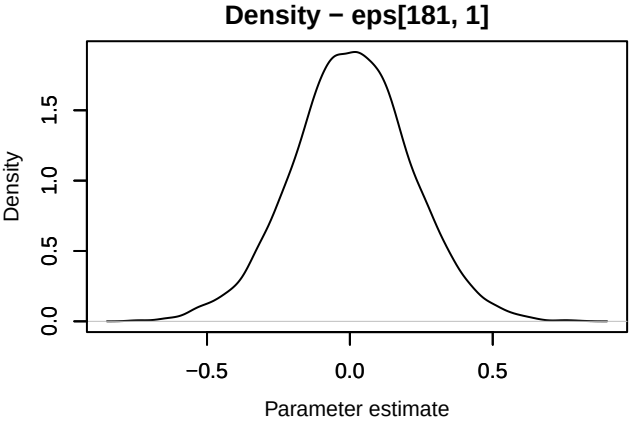
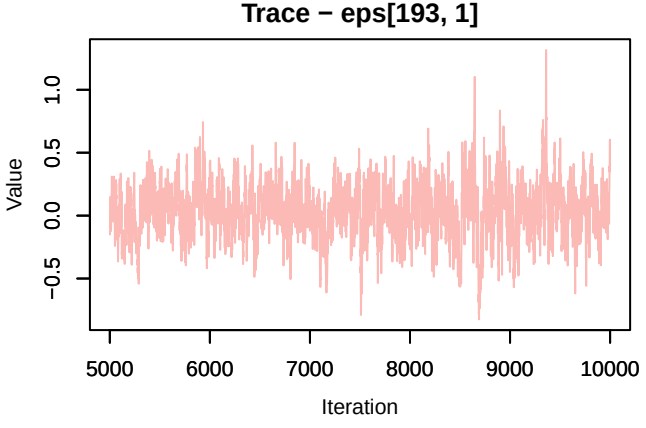
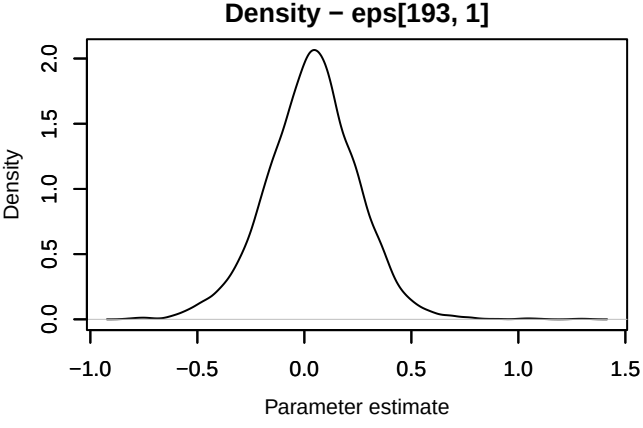
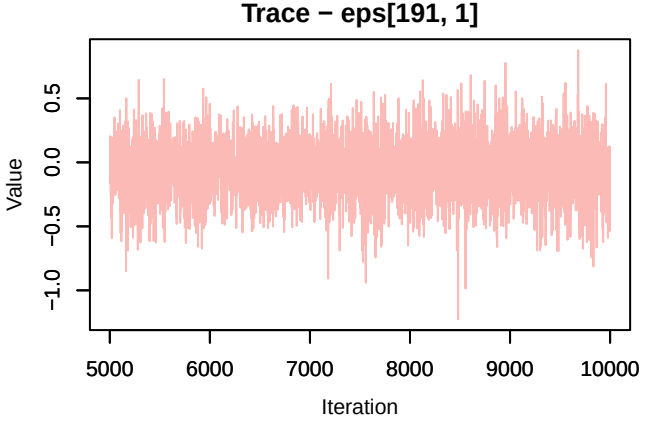
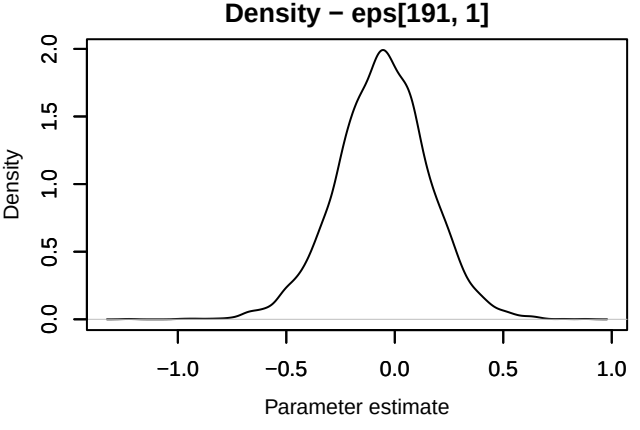

Trace − eps[181, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−0.5
0.0
0.5

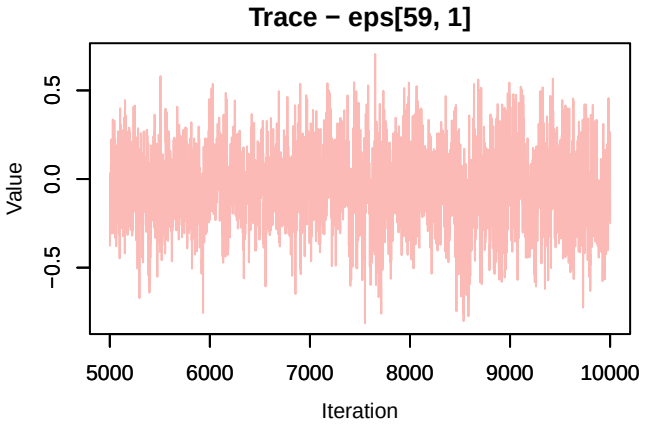

Density − eps[181, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
−0.5
0.0
0.5

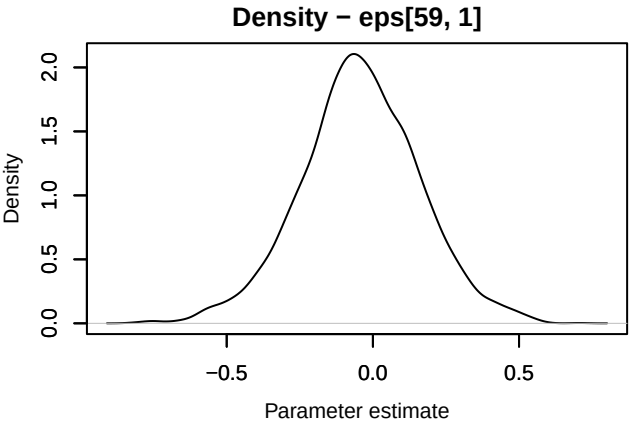

Trace − eps[193, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−0.5
0.0
0.5
1.0

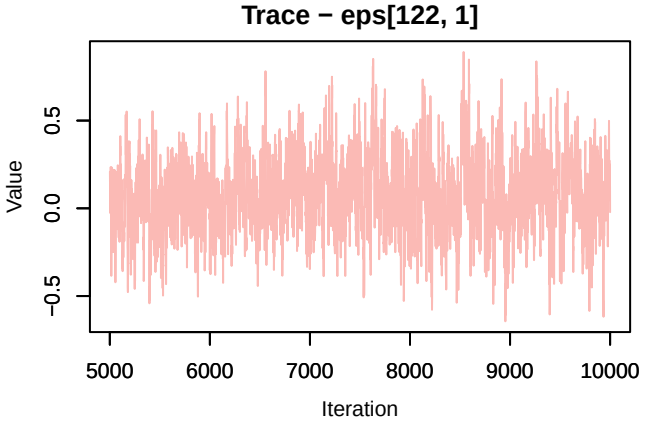

Density − eps[193, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
2.0
−1.0
−0.5
0.0
0.5
1.0
1.5

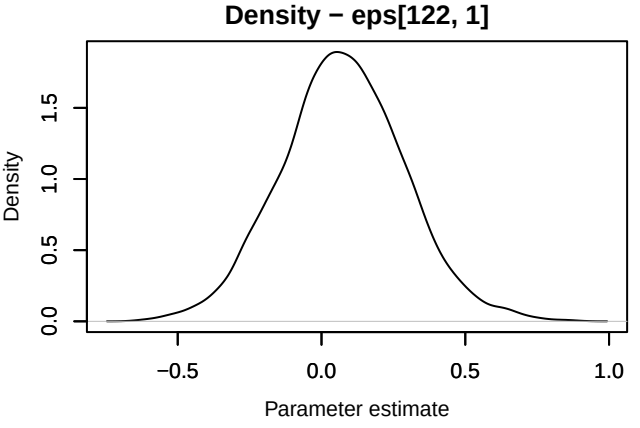

Trace − eps[191, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−1.0
−0.5
0.0
0.5

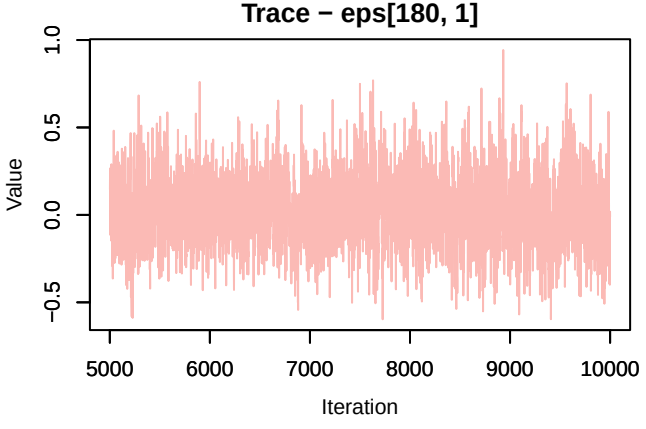

Density − eps[191, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
2.0
−1.0
−0.5
0.0
0.5
1.0

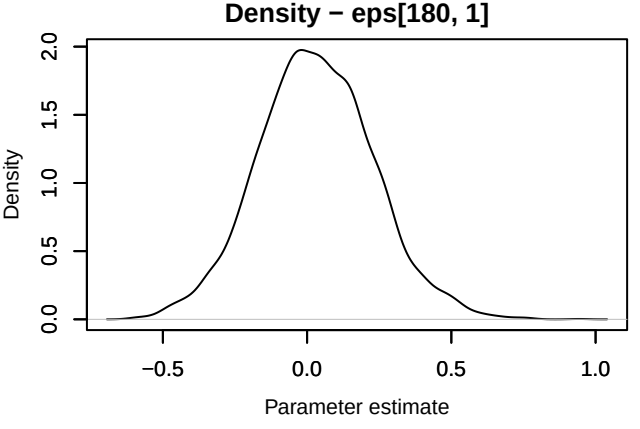

Trace − eps[59, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

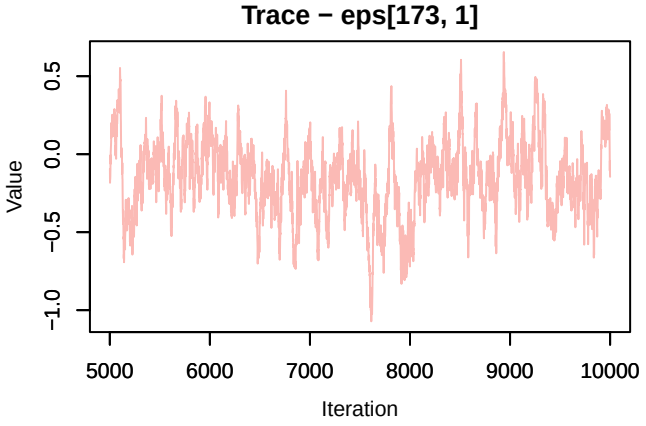

Density − eps[59, 1]
Density
2.0
1.5
1.0
0.5
0.0
−0.5
0.0
0.5
Parameter estimate

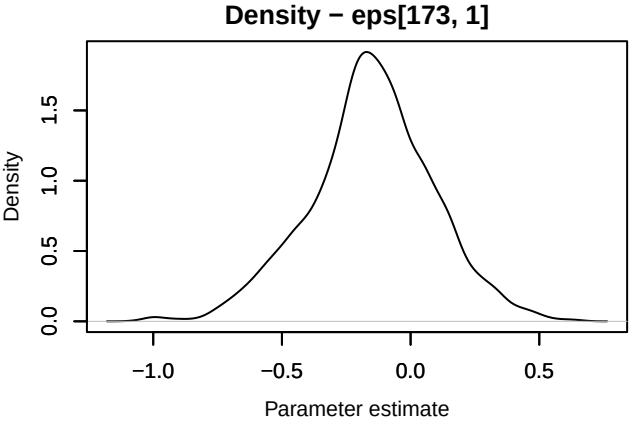

Trace − eps[122, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

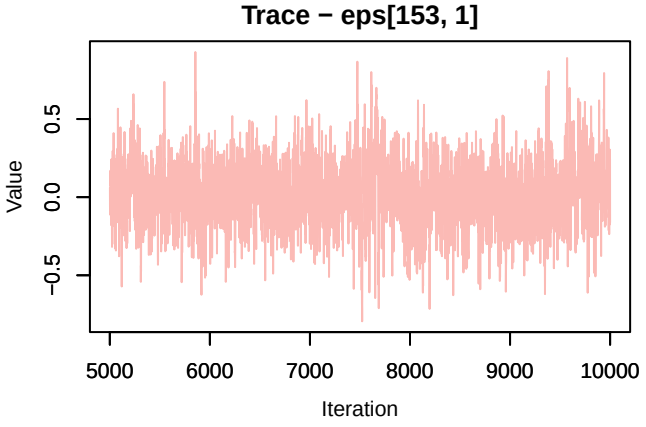

Density − eps[122, 1]
Density
1.5
1.0
0.5
0.0
−0.5
0.0
0.5
1.0
Parameter estimate

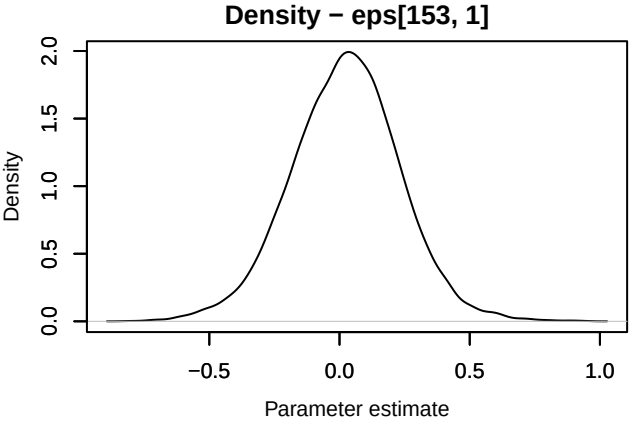

Trace − eps[180, 1]
Value
1.0
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

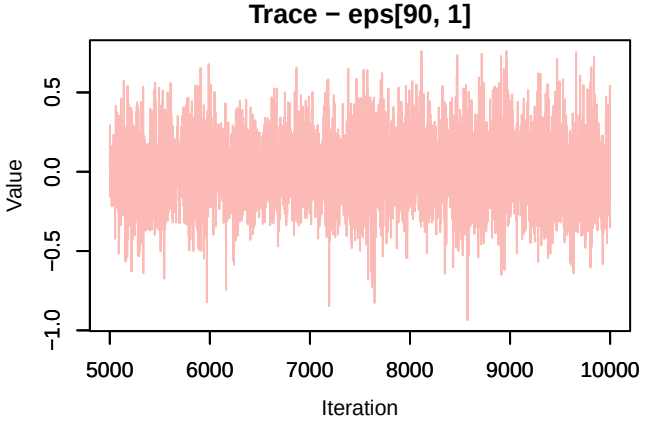

Density − eps[180, 1]
Density
2.0
1.5
1.0
0.5
0.0
−0.5
0.0
0.5
1.0
Parameter estimate

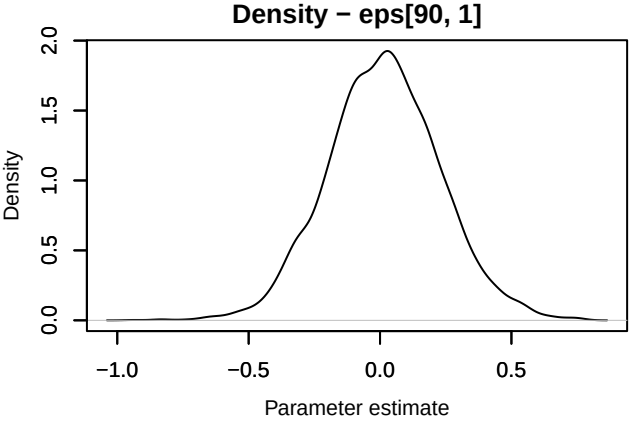

Trace − eps[173, 1]
Value
0.5
0.0
−0.5
−1.0
5000
6000
7000
8000
9000
10000
Iteration

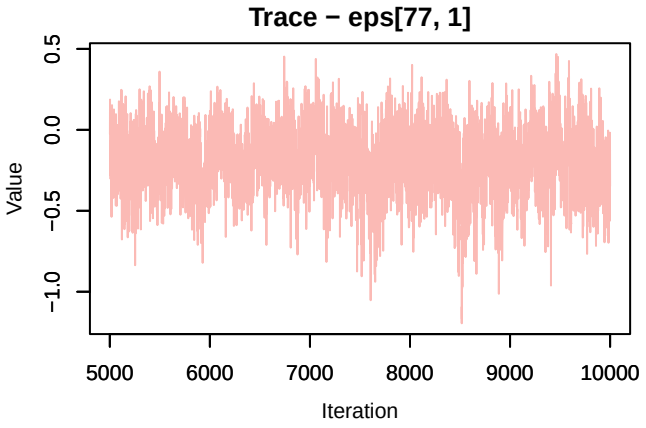

Density − eps[173, 1]
Density
0.0
0.5
1.0
1.5
−1.0
−0.5
0.0
0.5
Parameter estimate

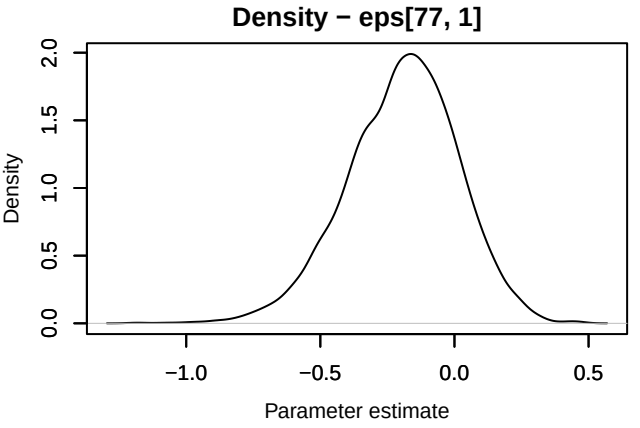

Trace − eps[153, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

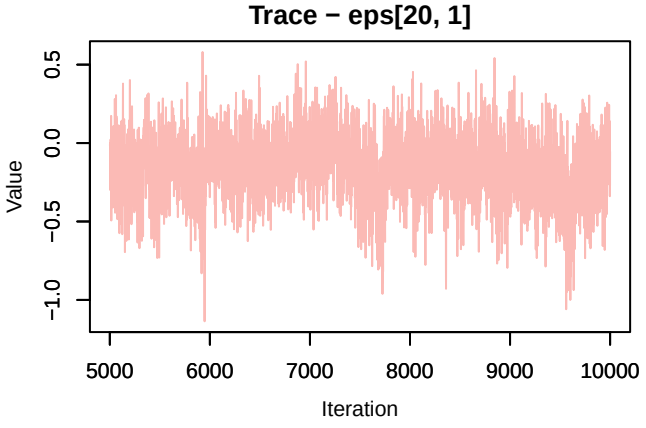

Density − eps[153, 1]
Density
0.0
0.5
1.0
1.5
2.0
−0.5
0.0
0.5
1.0
Parameter estimate

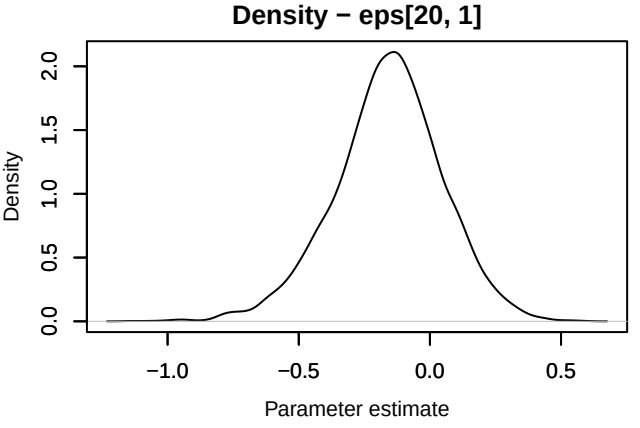

Trace − eps[90, 1]
Value
0.5
0.0
−0.5
−1.0
5000
6000
7000
8000
9000
10000
Iteration

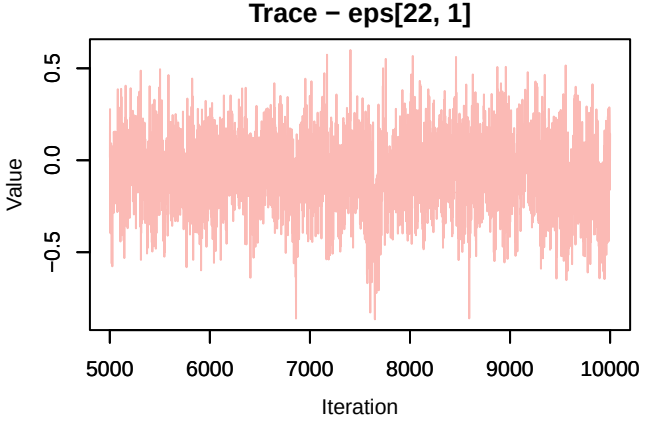

Density − eps[90, 1]
Density
0.0
0.5
1.0
1.5
2.0
−1.0
−0.5
0.0
0.5
Parameter estimate

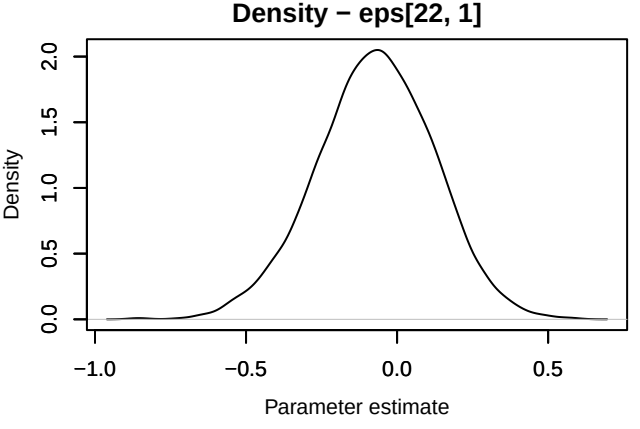

Trace − eps[77, 1]
Value
Iteration

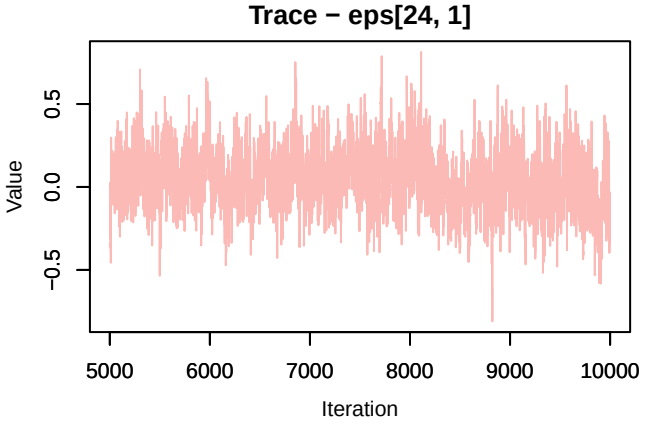

Density − eps[77, 1]
Density
Parameter estimate

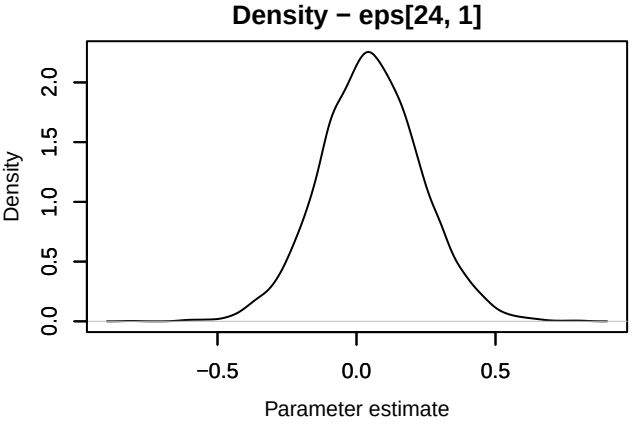

Trace − eps[20, 1]
Value
Iteration

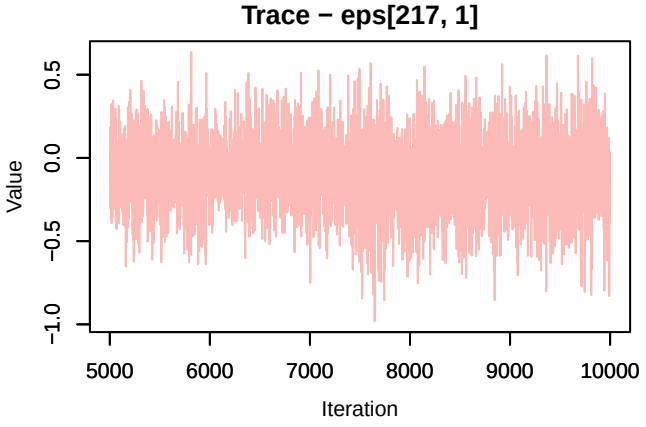

Density − eps[20, 1]
Density
Parameter estimate

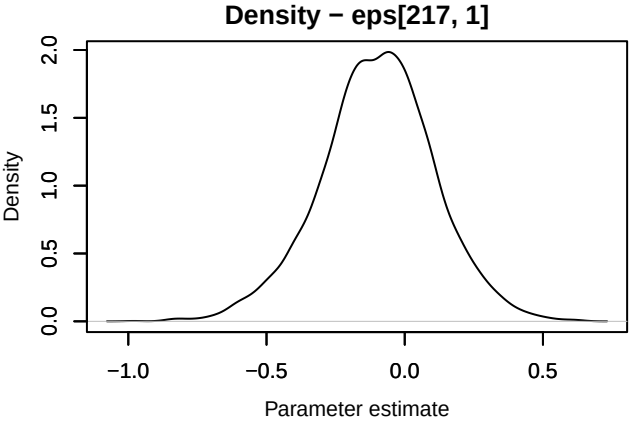

Trace − eps[22, 1]
Value
Iteration

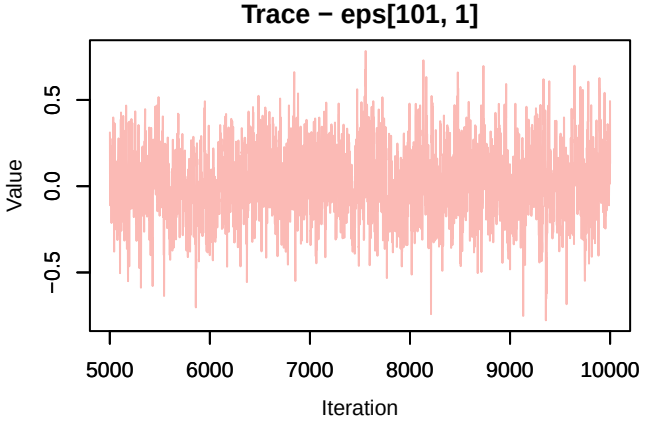

Density − eps[22, 1]
Density
Parameter estimate

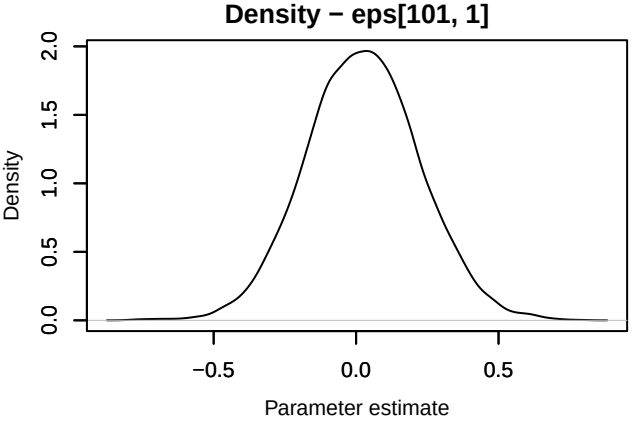

Trace − eps[24, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

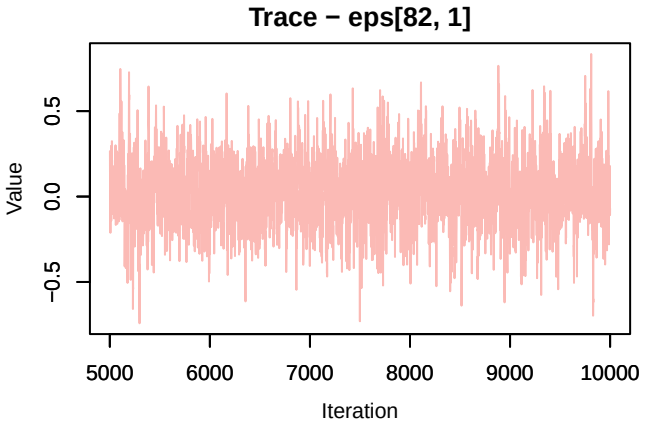

Density − eps[24, 1]
Density
0.0
0.5
1.0
1.5
2.0
−0.5
0.0
0.5
Parameter estimate

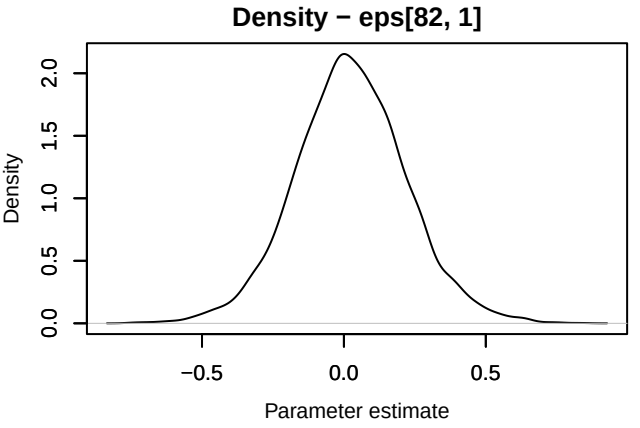

Trace − eps[217, 1]
Value
0.5
0.0
−0.5
−1.0
5000
6000
7000
8000
9000
10000
Iteration

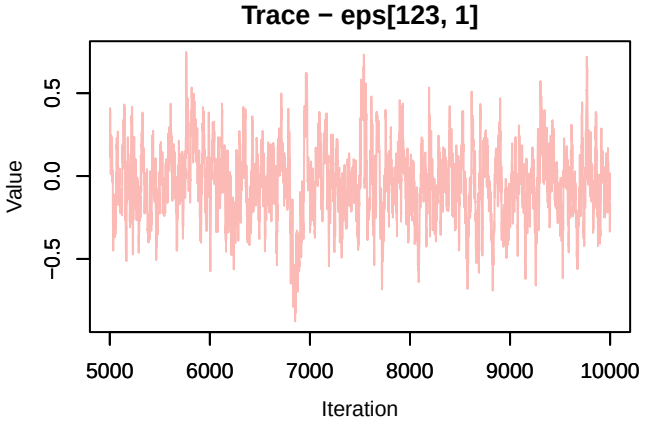

Density − eps[217, 1]
Density
0.0
0.5
1.0
1.5
2.0
−1.0
−0.5
0.0
0.5
Parameter estimate

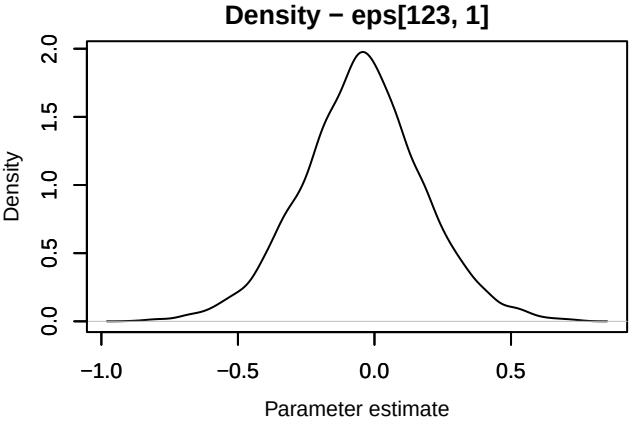

Trace − eps[101, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration

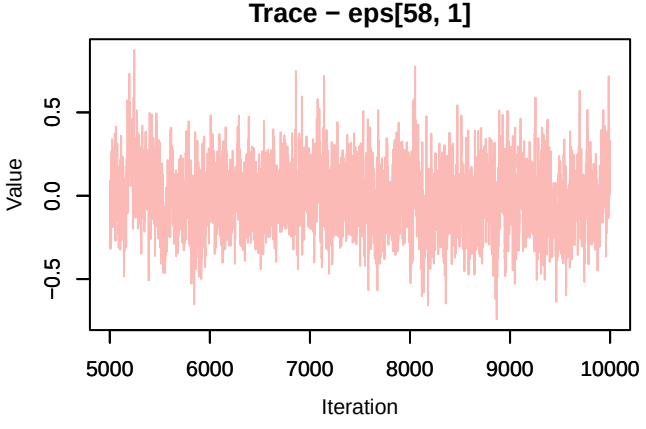

Density − eps[101, 1]
Density
0.0
0.5
1.0
1.5
2.0
−0.5
0.0
0.5
Parameter estimate

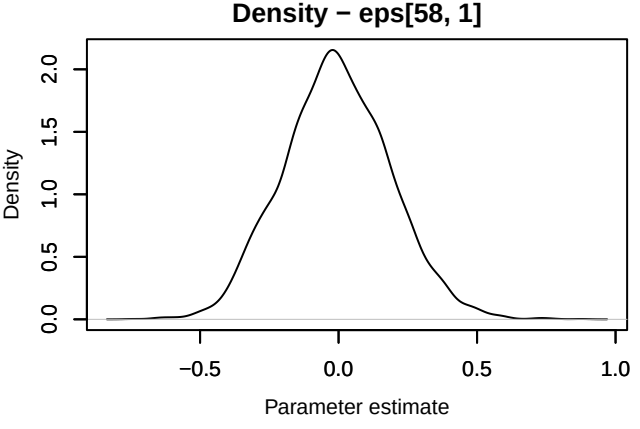

Trace − eps[82, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−0.5
0.0
0.5

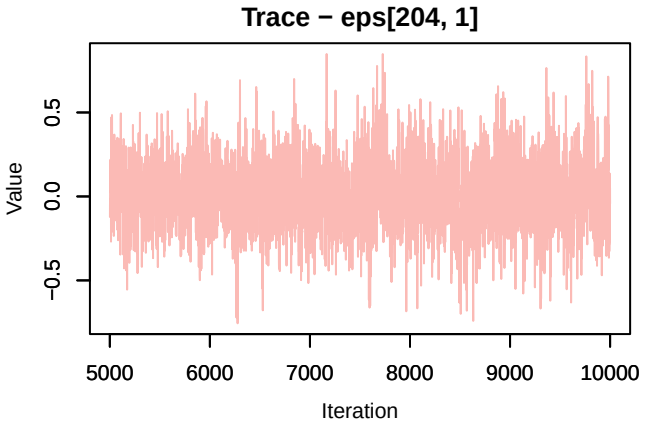

Density − eps[82, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
2.0
−0.5
0.0
0.5

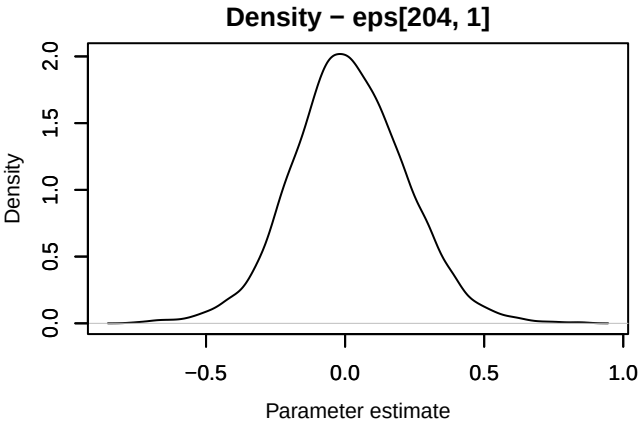

Trace − eps[123, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−0.5
0.0
0.5

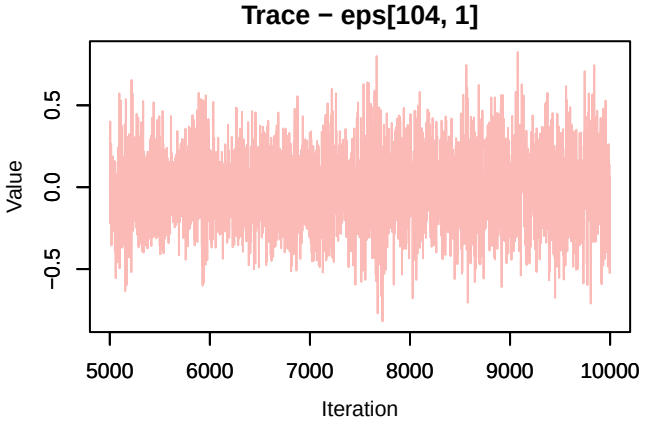

Density − eps[123, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
2.0
−1.0
−0.5
0.0
0.5

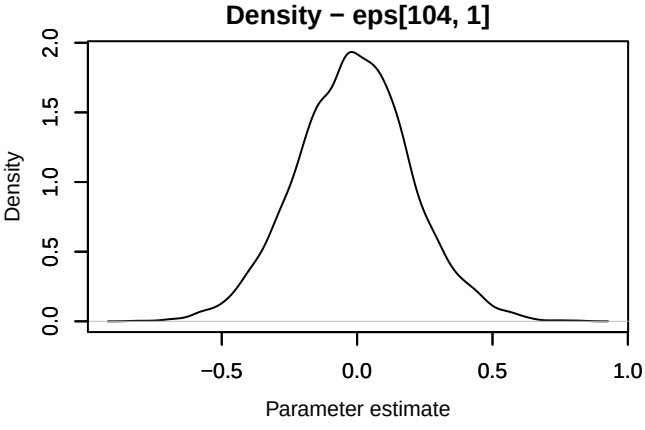

Trace − eps[58, 1]
Value
Iteration
5000
6000
7000
8000
9000
10000
−0.5
0.0
0.5


Density − eps[58, 1]
Density
Parameter estimate
0.0
0.5
1.0
1.5
2.0
−0.5
0.0
0.5
1.0


Trace − eps[204, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration


Density − eps[204, 1]
Density
2.0
1.5
1.0
0.5
0.0
−0.5
0.0
0.5
1.0
Parameter estimate


Trace − eps[104, 1]
Value
0.5
0.0
−0.5
5000
6000
7000
8000
9000
10000
Iteration


Density − eps[104, 1]
Density
2.0
1.5
1.0
0.5
0.0
−0.5
0.0
0.5
1.0
Parameter estimate