

# Meccano four frame

<https://github.com/heptagons/meccano/frames/four>

## Abstract

Four frame is a group of four rigid meccano <sup>1</sup> strips.

## 1 Four frame

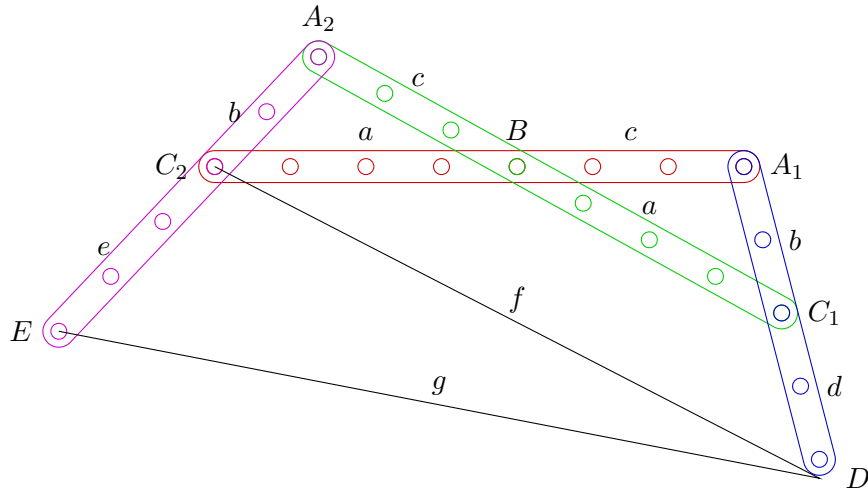


Figure 1: Antisymmetric four frame.

Figure 1 show the antisymmetric four-strips frame. From the figure we define  $\alpha \equiv \angle BA_1C_1$  and define integers  $m = b^2 + c^2 - a^2$  and  $n = 2bc$  using the law of cosines, then we calculate  $\cos \alpha$  and  $\sin \alpha$ :

$$(\alpha, m, n) \equiv (\angle BA_1C_1, b^2 + c^2 - a^2, 2bc) \quad (1)$$

$$\cos \alpha = \frac{m}{n} \quad (2)$$

$$\sin \alpha = \frac{\sqrt{n^2 - m^2}}{n} \quad (3)$$

We calculate the distance  $f = \overline{C_2D}$  with the law of cosines using angle  $\alpha$  and defining integers  $x = a + c$  and  $y = b + d$ :

$$(x, y) \equiv (a + c, b + d) \quad (4)$$

$$f^2 = (a + c)^2 + (b + d)^2 - 2(a + c)(b + d) \cos \alpha \quad (5)$$

$$= x^2 + y^2 - \frac{2mxy}{n} \quad (6)$$

$$f = \frac{\sqrt{n^2(x^2 + y^2) - 2mnxy}}{n} \quad (7)$$

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<sup>1</sup> Meccano mathematics by 't Hooft

We define a new integer  $z \equiv n^2(x^2 + y^2) - 2mnxy$  so we have:

$$z \equiv n^2(x^2 + y^2) - 2mnxy \quad (8)$$

$$f = \frac{\sqrt{z}}{n} \quad (9)$$

We define angle  $\theta \equiv \angle A_1C_2D$  and calculate  $\cos \theta$  and  $\sin \theta$ :

$$\theta \equiv \angle A_1C_2D \quad (10)$$

$$\begin{aligned} \cos \theta &= \frac{(a+c)^2 + f^2 - (b+d)^2}{2(a+c)f} \\ &= \frac{x^2 + f^2 - y^2}{2xf} \\ &= \frac{x^2 + x^2 + y^2 - \frac{2mxy}{n} - y^2}{2x \frac{\sqrt{z}}{n}} \\ &= \frac{nx - my}{\sqrt{z}} \end{aligned} \quad (11)$$

$$\begin{aligned} \sin^2 \theta &= 1 - \cos^2 \theta = \frac{z - (nx - my)^2}{z} \\ &= \frac{n^2(x^2 + y^2) - 2mnxy - (nx - my)^2}{z} \\ &= \frac{n^2(x^2 + y^2) - 2mnxy - n^2x^2 + 2nxdm - m^2y^2}{z} \\ \sin \theta &= \frac{y\sqrt{n^2 - m^2}}{\sqrt{z}} \end{aligned} \quad (12)$$

From the figure 1 we define  $\gamma \equiv \angle BA_2C_2$  and define integers  $s = a^2 + b^2 - c^2$  and  $t = 2ab$  and calculate  $\cos \gamma$  and  $\sin \gamma$ :

$$(\gamma, s, t) \equiv (\angle BA_2C_2, a^2 + b^2 - c^2, 2ab) \quad (13)$$

$$\cos \gamma = \frac{s}{t} \quad (14)$$

$$\sin \gamma = \frac{\sqrt{t^2 - s^2}}{t} \quad (15)$$

We define angle  $\phi \equiv \angle A_2C_2D$  and we note is the sum of angles  $\theta + \gamma$  and we calculate  $\cos \phi$ :

$$\phi \equiv \angle A_2C_2D \quad (16)$$

$$= \theta + \gamma \quad (17)$$

$$\cos \phi = \cos(\theta + \gamma) \quad (18)$$

$$\begin{aligned} &= \cos \theta \cos \gamma - \sin \theta \sin \gamma \\ &= \frac{(nx - my)s}{\sqrt{zt}} - \frac{(y\sqrt{n^2 - m^2})\sqrt{t^2 - s^2}}{\sqrt{zt}} \\ &= \frac{(nx - my)s - y\sqrt{(n^2 - m^2)(t^2 - s^2)}}{\sqrt{zt}} \end{aligned} \quad (19)$$

From the figure we define angle  $\psi \equiv \angle DC_2E$  and we note equals angle  $\pi - \phi$ , so we have:

$$\psi \equiv \angle DC_2E \quad (20)$$

$$= \pi - \phi \quad (21)$$

$$\cos \psi = \cos(\pi - \phi) \quad (22)$$

$$= -\cos \phi$$

$$= \frac{-(nx - my)s + y\sqrt{(n^2 - m^2)(t^2 - s^2)}}{\sqrt{zt}} \quad (23)$$

Finally with  $\cos \psi$ ,  $e$  and  $f$  we can calculate distance  $g = \overline{ED}$ :

$$g^2 = e^2 + f^2 - 2ef \cos \psi \quad (24)$$

$$= e^2 + x^2 + y^2 - \frac{2mxy}{n} - 2e \left( \frac{\sqrt{z}}{n} \right) \left( \frac{-(nx - my)s + y\sqrt{(n^2 - m^2)(t^2 - s^2)}}{\sqrt{zt}} \right) \quad (25)$$

$$= e^2 + x^2 + y^2 - \frac{2mxy}{n} - 2e \left( \frac{-(nx - my)s + y\sqrt{(n^2 - m^2)(t^2 - s^2)}}{nt} \right) \quad (26)$$

$$= \frac{(e^2 + x^2 + y^2)nt - 2mxyt + 2es(nx - my) - 2ey\sqrt{(n^2 - m^2)(t^2 - s^2)}}{nt}$$

$$g = \frac{\sqrt{(e^2 + x^2 + y^2)n^2t^2 - 2mnxyt^2 + 2esnt(nx - my) - 2eynt\sqrt{(n^2 - m^2)(t^2 - s^2)}}}{nt} \quad (27)$$

### 1.1 Antisymmetric four frame software

From the last equation of  $g$  we identify three **input** integers  $i_1, i_2, i_3$  which are used to get  $g(i)$ . Then the nested radicals software will return square-free **output** integers  $z_1, z_2, z_3, z_4, z_5$  as  $g(z)$ :

$$i_1 = nt \quad (28)$$

$$i_2 = (e^2 + x^2 + y^2)i_1^2 - 2mxyti_1 + 2esi_1(nx - my) \quad (29)$$

$$i_3 = -2eyi_1 \quad (30)$$

$$i_4 = (n^2 - m^2)(t^2 - s^2) \quad (31)$$

$$g(i) = \frac{\sqrt{i_2 + i_3\sqrt{i_4}}}{i_1} \quad (32)$$

$$g(z) = \frac{z_2\sqrt{z_3 + z_4\sqrt{z_5}}}{z_1} \quad (33)$$

where  $m, n$  are calculated with equations 1,  $x, y$  are calculated with equations 4 and  $s, t$  are calculated with equations 13.