

HW1

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1 Task 1

define $\mathbf{Z} = \{\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_n\}$. Then the function to minimize is:

$$\begin{aligned} J(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{z}_n^\top \mathbf{w} - t_n)^2 \\ &= \frac{1}{2} \|\mathbf{Z}\mathbf{w} - \mathbf{t}\|^2 \end{aligned}$$

Using chain rule to differentiate the cost function against \mathbf{w} with the variable declaration:

$$\begin{aligned} \mathbf{u} &= \mathbf{Z}\mathbf{w} - \mathbf{t} \\ \mathbf{J} &= \frac{1}{2} \|\mathbf{u}\|^2 \end{aligned}$$

Then we have that:

$$\begin{aligned} D_{\mathbf{u}}(\mathbf{J}) &= D_{\mathbf{u}}\left(\frac{1}{2}\|\mathbf{u}\|^2\right) = \mathbf{u}^\top \\ D_{\mathbf{w}}(\mathbf{u}) &= D_{\mathbf{w}}(\mathbf{Z}\mathbf{w} - \mathbf{t}) = \mathbf{Z} \\ D_{\mathbf{w}}(\mathbf{J}(\mathbf{w})) &= D_{\mathbf{u}}(\mathbf{J})D_{\mathbf{w}}(\mathbf{u}) = \mathbf{u}^\top \mathbf{Z} = (\mathbf{Z}\mathbf{w} - \mathbf{t})^\top \mathbf{Z} \end{aligned}$$

Set gradient to zero to find the point of minimal cost function:

$$\begin{aligned} D_{\mathbf{w}}\mathbf{J}(\mathbf{w}) &= 0 \\ \implies 0 &= (\mathbf{Z}\mathbf{w} - \mathbf{t})^\top \mathbf{Z} \\ \implies 0 &= (\mathbf{Z}\mathbf{w})^\top \mathbf{Z} - \mathbf{t}^\top \mathbf{Z} \\ \implies 0 &= \mathbf{w}^\top \mathbf{Z}^\top \mathbf{Z} - \mathbf{t}^\top \mathbf{Z} \\ \implies \mathbf{t}^\top \mathbf{Z} &= \mathbf{w}^\top \mathbf{Z}^\top \mathbf{Z} \\ \implies \mathbf{Z}^\top \mathbf{t} &= \mathbf{Z}^\top \mathbf{Z}\mathbf{w} \end{aligned}$$

so we know that we can write $\nabla J(\mathbf{w}) = \mathbf{0}$ in $\mathbf{A}\mathbf{w} = \mathbf{b}$, where $\mathbf{A} = \mathbf{Z}^\top \mathbf{Z}$ and $\mathbf{b} = \mathbf{Z}^\top \mathbf{t}$.

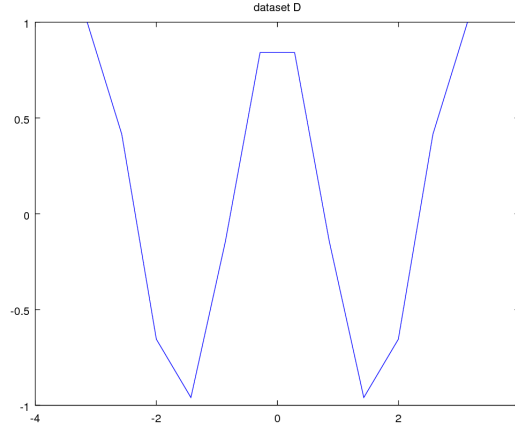


Figure 1: dataset-D

2 Task 2

the solution for the equation in Task 1 gives the solution:

$$\mathbf{w} = (\mathbf{Z}^\top \mathbf{Z})^{-1} \mathbf{Z}^\top \mathbf{t}$$

the solution always exist (i.e. there are always more than one solutions), since $(\mathbf{Z}^\top \mathbf{Z})^{-1} \mathbf{Z}^\top$ is the Moore-Penrose pseudoinverse and exists for all matrices (page 142, PRML). The solution is unique only when \mathbf{Z} is of full rank, or equivalently $\mathbf{Z}^\top \mathbf{Z}$ is invertible. Since Z is a $n \times (m+1)$ matrix, we have $\mathbf{Z}^\top \mathbf{Z}$ with dimension $(M+1) \times (M+1)$. we have $\text{rank}(\mathbf{Z}^\top \mathbf{Z}) = \text{rank}(\mathbf{Z})$. So that if $M < N$, we always have unique solution. If $M \geq N$ we have more than one solutions.

3 Task 4, 5

Task 3 is missing in the lab assignment.

the plot result is shown in Figure 1. The matlab code for task 5 is shown below:

```

1 function w = hw1_task5(X,t,n)
2 % Z matrix is of dimension: N x (M+1)
3 Z = ones(12,n+1);
4 for i = 2:(n+1) %modify column vectors
5     Z(:,i)= X.^(i-1);
6 end
7 % after computing the Z matrix apply the formula
8 % a should be of dimension: (M+1)x(M+1)
9 a = inv(transpose(Z)*Z);
10 Z
11 % w should be of dimension (M+1) x 1: a column vector
12 w = a * transpose(Z) * transpose(t);
13 end

```

4 Task 6

the plots are shown with their corresponding value of dimension N: From the plots, it is clear

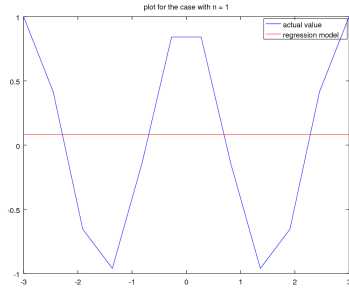


Figure 2: M=1

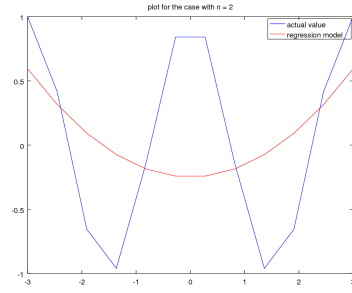


Figure 3: M=2

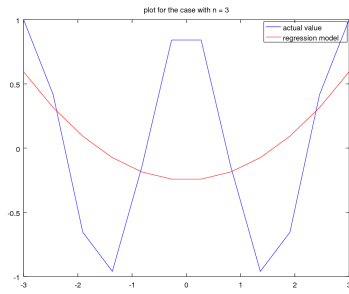


Figure 4: M=3

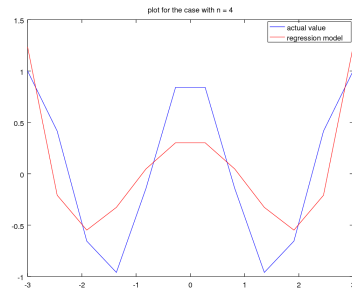


Figure 5: M=4

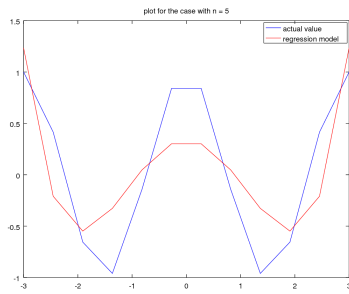


Figure 6: M=5

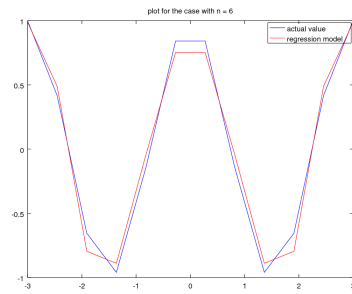


Figure 7: M=6

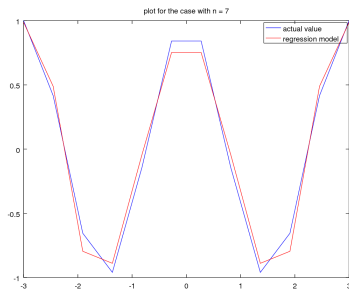


Figure 8: M=7

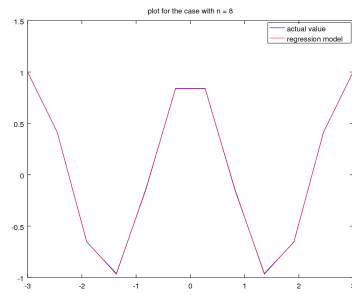


Figure 9: M=8

that approximation is more and more precise as higher dimension terms are introduced, from M

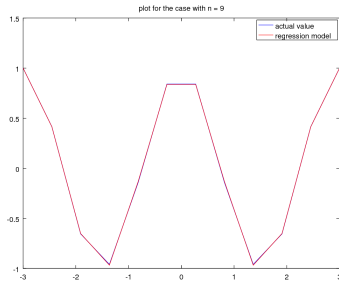


Figure 10: M=9

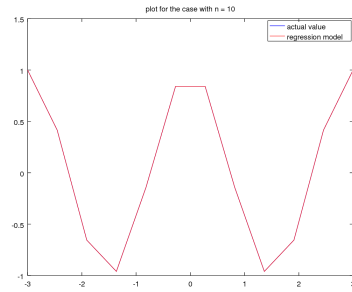


Figure 11: M=10

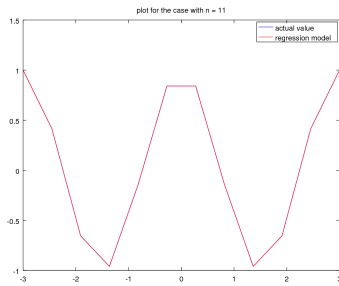


Figure 12: M=11

= 9 and on, the plot is almost exactly the same as f . The matlab code is shown below:

```

1 domain = linspace(-3,3,12);
2 x = linspace(-pi, pi, 12);
3 t = cos(2.*x);
4 %case
5 for n = 1:11
6     w = hw1_task5(x,t,n);
7     Z = ones(12,n+1);
8     for i = 2: (n+1) %modify column vectors
9         Z(:,i)= x.^(i-1);
10    end
11    % dimension check:
12    % w' of 1 by (M+1)
13    % Z' of (M+1) by N
14    y = (transpose(w)* transpose(Z) );
15    %plot
16    fig = figure;
17    plot(domain, t, 'color', 'b');
18    hold on;
19    plot(domain, y, 'color', 'r');
20    title(sprintf('plot for the case with n = %d',n));
21    legend('actual value', 'regression model');
22    saveas(fig, sprintf("hw1_task6_fig%d.png",n))
23 end

```

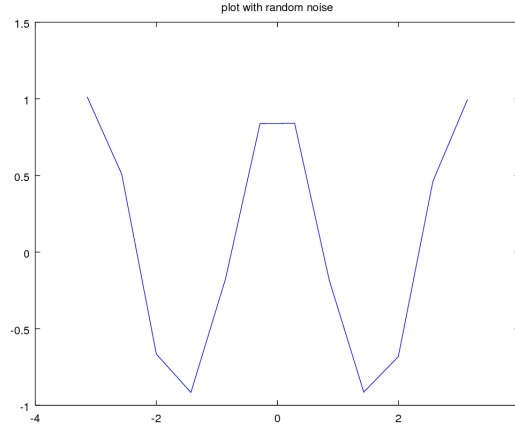


Figure 13: random noise plot $\cos(x)$

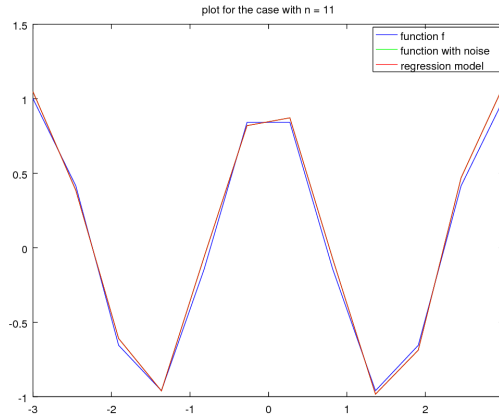


Figure 14: $M=11$

5 Task 7

the random noise here is uniform random noise, the plot is shown in figure 13.

6 Task 8

The comparison shows that with value of M approach N , the result is generally more and more similar to f . However, it takes larger value of M when random noise is introduced in the model. And in our case, when $M = 10$, we have a better approximation than $M = 11$ for function f . The result for $M = 11$ is shown in figure 14.