

# Introduction to synthetic homotopy theory

Quick intro to fundamental math

- We are interested in objects + morphisms  
(aka category)

→ Holy grail Classification.

List of non-isomorphic objects s.t.  
any object is isomorphic to one in the list

Strategy Have invariant, i.e "things"  
unchanged by isomorphisms (aka functors)

Example the dimension of vector space,

→ Usually this is not possible

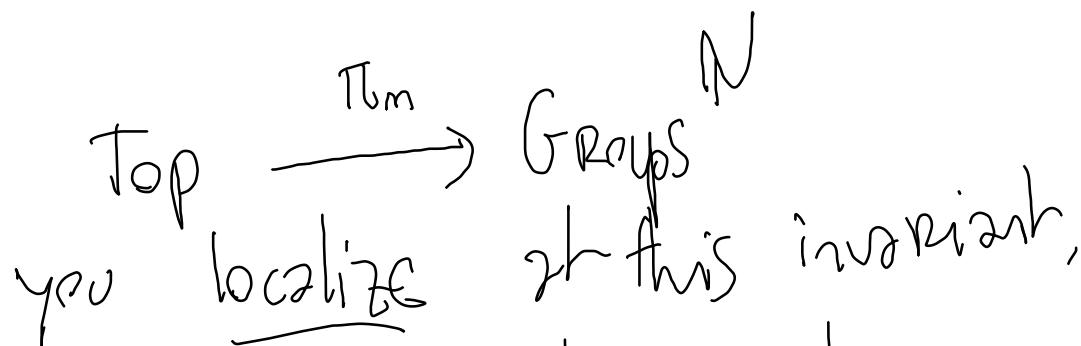
2 solutions

- restricts to 'well-behaved' objects. (aka sub-category)
- consider a weaker notion of 'being the same'  
than iso (aka localisation of a category)

## Main example

- Topological spaces cannot be classified
- Topological spaces up to weak equivalences can be partially classified.

Drawing



you localize at this invariant,

Def Spaces up to weak equivalences  
are called homotopy types

- Theorem Homotopy types are equivalently:
- Spaces up to weak equivalences [historical]
  - Simplicial sets up to weak equivalences. [Vniz defintion]
  - Kan simplicial sets up to equivalences
  - $\infty$ -groupoids up to equivalences [relevant this class.]

Theorem (Rozouk, Lumsdaine, Voevodsky)

Types from type theory can be interpreted as homotopy types.

Ry lucky coincidence that types occur twice

Homotopy Type Theory (Steve Awodey)

HoTT

Synthetic homotopy theory

We prove theorems about types  
→ we conclude it is true for homotopy types.

## References

• HoTT book

- Egbert Rijke      Lecture notes
- Lecture notes for this class.

## EPIT spring school this week

Friday 14th → Lecture by Egbert on  
synthetic homotopy theory.

$\infty$ -groupoids (classical point of view)  
→ The model for homotopy types closest  
to type theory.

'Definition'

An  $\infty$ -groupoid consists of

- A set of points  $A_0$
- For  $x, y \in A_0$ , a set of paths between them  $A_1(x, y)$
- For  $p, q \in A_1(x, y)$ , a set of deformations from  $p$  to  $q$  denoted  $A_2(p, q)$
- ...

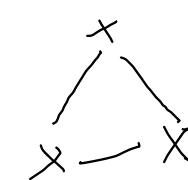


x

x

x → x

x → x



Together with the relevant compositions.

E.g

$$x \xrightarrow{a} x \\ a \quad \text{refl}_a$$

$$a \xrightarrow{p} b \xrightarrow{q} x \\ \vdots \quad \vdots \quad \vdots$$

$$a \xrightarrow{p} b \\ \vdots$$

$$a \xrightarrow{p \cdot q} c \\ x \quad \quad \quad x$$

$$b \xrightarrow{p^{-1}} a \\ x \quad \quad \quad x$$

$$a \xrightarrow{p} b \xrightarrow{q} c \xrightarrow{r} d \\ x \quad \quad \quad x \quad \quad \quad x$$

$$a \xrightarrow{p} b \\ x \quad \quad \quad x$$

$$\begin{matrix} & \downarrow & \\ a & \xrightarrow{\quad} & d \\ & \downarrow & \\ d & \xrightarrow{\quad} & d \end{matrix}$$

$p \cdot (q \cdot r)$

$$\begin{matrix} & \downarrow & \\ a & \xrightarrow{\quad} & a \\ & \downarrow & \\ a & \xrightarrow{\quad} & a \end{matrix}$$

$p \cdot p^{-1}$   
refl<sub>a</sub>

# PART I : Type formers

①

## Identity type

$$\frac{\begin{array}{c} A \text{ type} \\ a, b : A \end{array}}{a =_A b \text{ type}}$$

$$\frac{\begin{array}{c} A \text{ type} \\ a : A \end{array}}{\text{refl}_a : a =_A a}$$

Intuition  $a =_A b$  is a proposoid of paths  
from  $a$  to  $b$  in  $A$ .

## Path induction

To prove/define  $t(x, y, p) : B(x, y, p)$   
for all  $x, y : A$  and  $p : x = y$

It is enough to define

$$t(x, x, \text{refl}_x) : B(x, x, \text{refl}_x)$$

Idea This implies all  $\infty$ -groupoid compositions  
for type  $A$ .

## Example

- For all  $a, b, c : A$  and  $p : a = b$  and  $q : b = c$   
we want to define

It is enough to define

- For all  $a, b, c, d : A$  and

It is enough to define

$$:= \text{refl}_{q \cdot R}$$

$$:= (\text{refl}_a \cdot q) \cdot R = \text{refl}_q \cdot (q \cdot R)$$

iii

$$q \cdot R$$

iii

$$q \cdot R$$

$$p \cdot q : a = c$$

$$\boxed{\text{refl}_q \cdot q := q}$$

(CohDott)

$$p : a = b, q : b = c, r : c = d$$

$$\text{assoc}(p, q, r) : (p \cdot q) \cdot r = p \cdot (q \cdot r)$$

$$\text{assoc}(\text{refl}_a, q, r)$$

iii

$$q \cdot R$$

iii

$$q \cdot R$$

⚠ very important

We cannot use path induction to prove  
for all  $x:A$  and  $p:x=x$  we have  $P(x,p)$

# Dependent functions (Sections, $\Pi$ -types, dependent products)

A type

$B(n)$  type depending

on  $x : A$

$$\frac{}{(x:A) \rightarrow B(x)}$$

$$\left( \text{Alt: } \prod_{n:A} B(n) \right)$$

$t(x) : B(x)$  depending

on  $x : A$

$$\frac{}{\lambda n. t(n) : (n:A) \rightarrow B(n)}$$

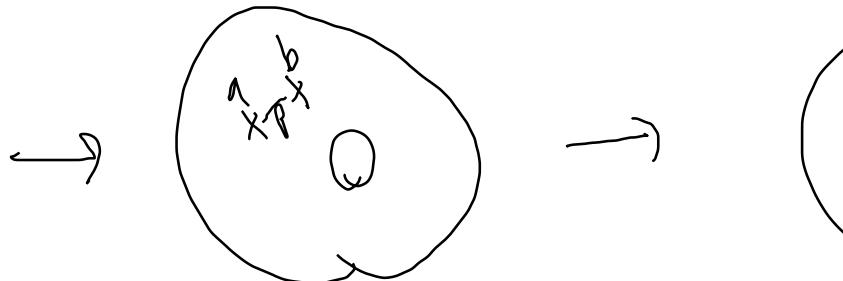
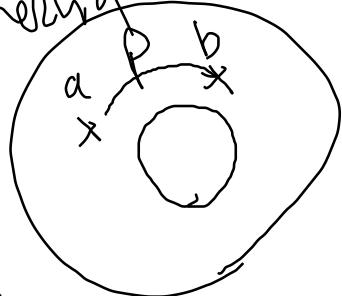
$$\left( \text{Alt } x \mapsto t(x) \right)$$

$$f : (x:A) \rightarrow B(x)$$

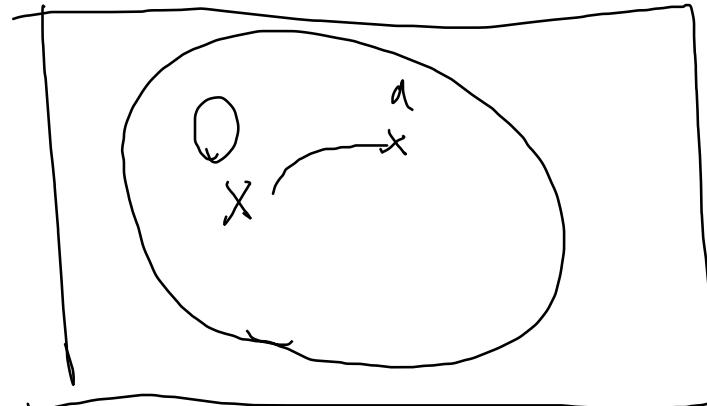
$$a : A$$

$$\frac{}{f(a) : B(a)}$$

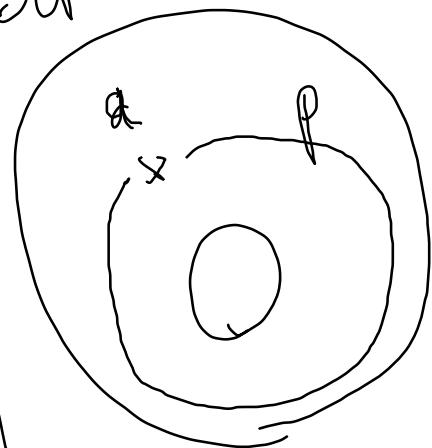
Inheriting



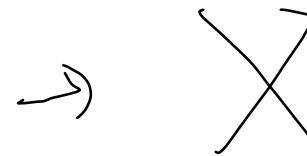
A



But



A



Rq if  $B$  does depend on  $A$ , we write

$$A \rightarrow B.$$

Intuition  $A \rightarrow B$  is  $\infty$ -groupoid of

morphism of  $\infty$ -groupoid from  
 $A$  to  $B$

As spaces such morphisms are continuous.

Example For  $a, b : A$  and  $p : a =_A b$  and  $f : A \rightarrow B$

we have  $apf(p) : f(a) =_B f(b)$ .  
defined by  $[apf(\text{not } a) := \text{refl } f(a)] \dots$

Dependent products ( $\Sigma$ -types), dependent sums)

A type

$B(n)$  type on  $n:A$

$(x:A) \times B(x)$

(Aft.  $\Sigma(n:A). B(n)$ )

$a:A$

$b: B(a)$

$\frac{}{(a,b): (n:A) \times B(n)}$

If  $B$  does not depend on  $A$  we write  $A \times B$ .

Induction We can assume any  $z: (n:A) \times B(n)$   
of the form  $(n,y)$  where  $n:A$   
 $y: B(n)$

Universe

inhabitants of  $\mathcal{U}$  are  
types

$\mathcal{U}$  type

Intuition  $\mathcal{U}$  is the  $\infty$ -groupoid of  $\infty$ -groupoids

Rq  $\mathcal{U}:\mathcal{U}$  is inconsistent

Example  $B: A \rightarrow \mathcal{U}$  is a family of type indexed by  $A$ .

We can define  $\text{transport}_p^B(y) : B(b)$

for  $a, b : A$ ,  $y : B(a)$ ,  $p : a = b$

by  $\text{transport}_{\text{refl}_a}^B(y) := y : B(a)$

$$u: A + x =_A x \rightarrow M$$

$$\cancel{u}, \cancel{x =_A x \rightarrow M} : M$$

$$\lambda x. x =_A x \rightarrow M \quad \cancel{A \rightarrow \boxed{M}}$$

$M$  does not depend  
on  $m:N$  inherently

$\forall m: M_m$  is constraint  
types  $M_0, M_1, M_2, \dots$  for not  $m:N \not\models M_m$  type

## Universality

Def A map  $f: A \rightarrow B$  is an equivalence if:

- We have  $g_1: B \rightarrow A$  s.t.  $g_1 \circ f = \text{id}$
- We have  $g_2: B \rightarrow A$  s.t.  $f \circ g_2 = \text{id}$

Intuition An equivalence is an equivalence of  
 $\mathcal{G}$ -groupoid.

Notation  $A \underset{\mathcal{G}}{\approx} B$  is the type of equivalence  
from  $A$  to  $B$ .

## Universality

## Univalence axiom

The map  $A =_{\mathcal{U}} B \rightarrow A \simeq B$   
is an equivalence.

## Corollary

We have a map  $A \simeq B \rightarrow A =_{\mathcal{U}} B$

## Corollary

We have  $p : \text{Bool} =_{\mathcal{U}} \text{Bool}$   
such  $p \neq \text{Refl}_{\text{Bool}}$

Proof  $(\text{Bool} \simeq \text{Bool}) \simeq \{\text{id}, \text{not}\}$

Theorem Univalence axiom is validated  
by the interpretation of types as  
 $\infty$ -groupoids.

From now on we assume univalence

It is surprising, as it means  
that path induction is compatible  
with non-constant paths,

$m \in \mathbb{N}$ , we have  $M_m$  univalent.

Déf  $M$  is impredicative

if ~~not~~  $P(A) : \mathcal{U}$  depending on  $A : \mathcal{V}$

$$(A : \mathcal{U}) \rightarrow P(A) : \mathcal{V}$$

In this class this is never <sup>the</sup> case.