

Flexible Modeling of Transition Processes via Bayesian Spline Rate Models

with Application to Estimating and Projecting Modern Contraceptive Prevalence

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- **This presentation:** We propose a new type of model, called *B-spline Transition Models*, for flexibly estimating indicators that follow transitions.

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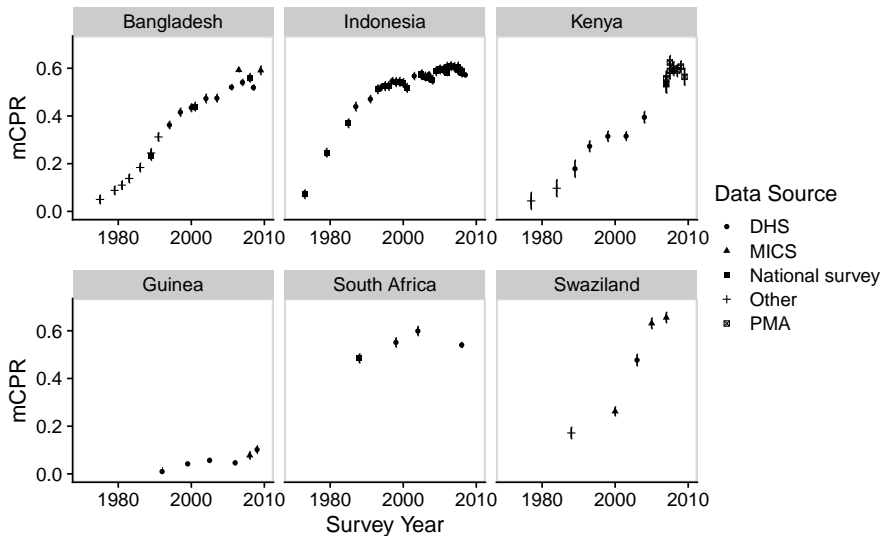
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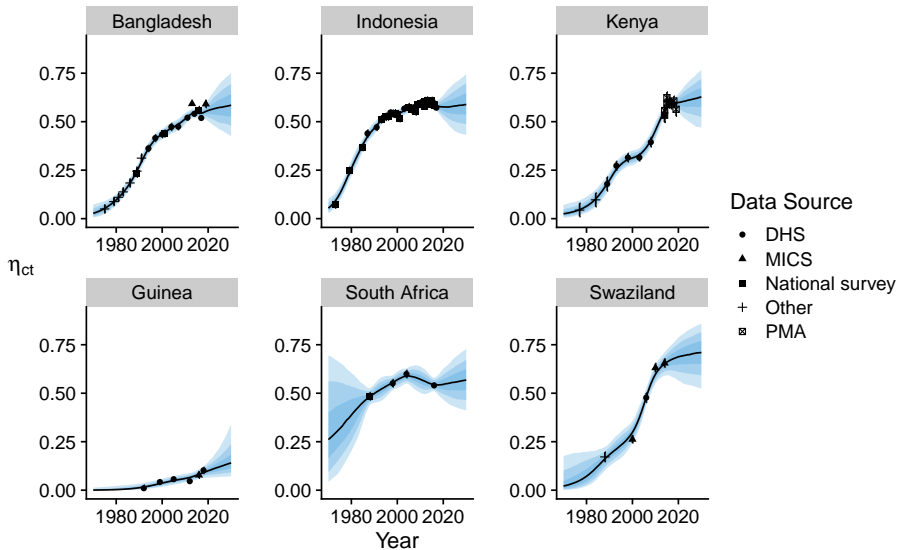
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- Dataset aggregated by United Nations Population Division (UNPD) from surveys conducted by governments or international organizations.

Raw Data



Example Fits



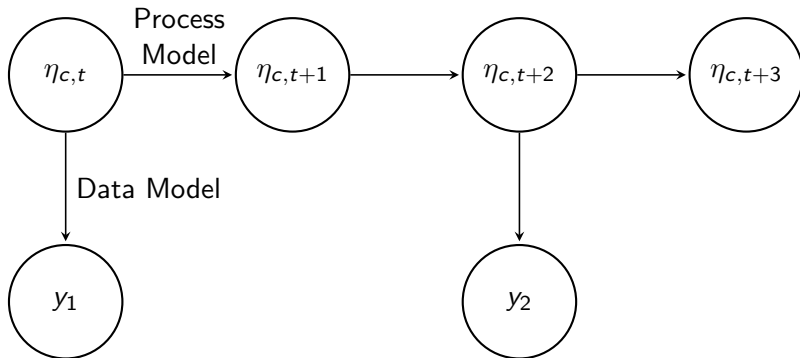
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- Observed data y_i , $i = 1, \dots, n$ with associated properties $c[i]$, $t[i]$, ...
- *Process model* describes evolution of $\eta_{c,t}$.
- *Data model* describes relationship between y_i and $\eta_{c[i],t[i]}$.

Modeling Framework



- **Our contribution:** a model class for indicators that follow a transition.

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- *Transition Models* have a process model given by

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- The systematic component has the following form:

$$g_3(t, \eta_{c,s \neq t}, \alpha_c) = \begin{cases} \Omega_c, & t = t_c^*, \\ g_1(\eta_{c,t-1}) + f(\eta_{c,t-1}, P_c, \beta_c), & t > t_c^*, \\ g_1(\eta_{c,t+1}) - f(\eta_{c,t+1}, P_c, \beta_c), & t < t_c^*, \end{cases}$$

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where $\alpha_c = \{\Omega_c, P_c, \beta_c\}$.

- The function f is called the *transition function*.

- Define a transition function f_b as:

$$f_b(\eta_{c,t}, P_c, \beta_c) = \sum_{j=1}^J \underbrace{h_j(\beta_{c,j})}_{\text{coefficient}} \cdot \underbrace{B_j(\eta_{c,t}/P_c)}_{\text{basis function}},$$

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B-spline Transition Model

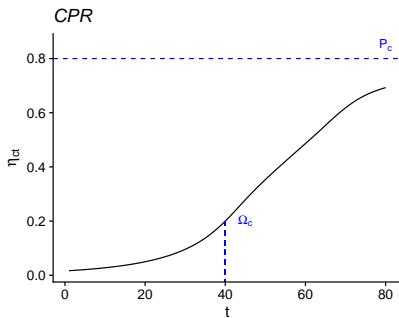
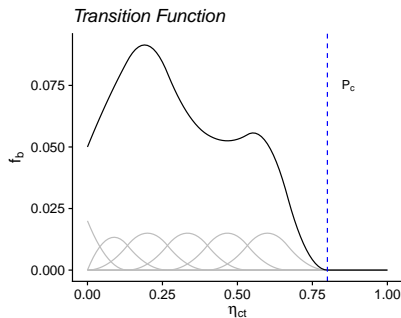
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- Flexibility of f_b can be tuned through the spline degree and number and positioning of knots.

Example B-spline Transition Function



Smoothing component

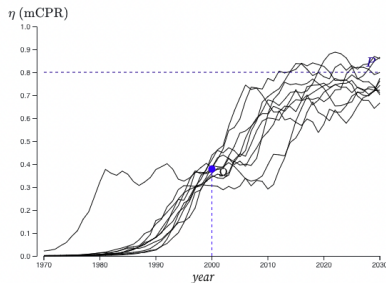
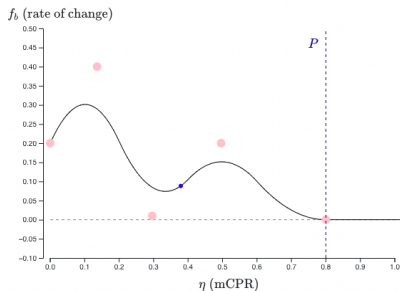
- Recall the process model has two components:

$$g_1(\eta_{c,t}) = \underbrace{g_3(t, \eta_{c,s \neq t}, \alpha_c)}_{\text{systematic}} + \underbrace{\epsilon_{c,t}}_{\text{smoothing}} .$$

- Smoothing component: AR(1) process of the form

$$\epsilon_{c,t} | \epsilon_{c,t-1}, \tau, \rho \sim N(\rho * \epsilon_{c,t-1}, \tau^2)$$

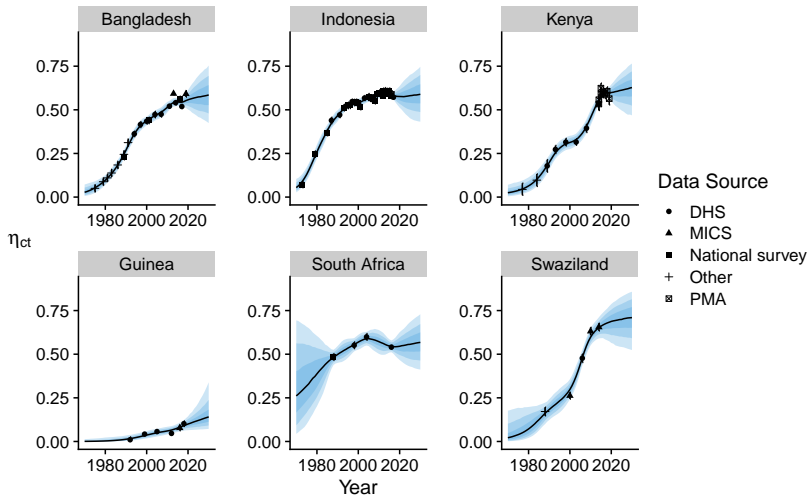
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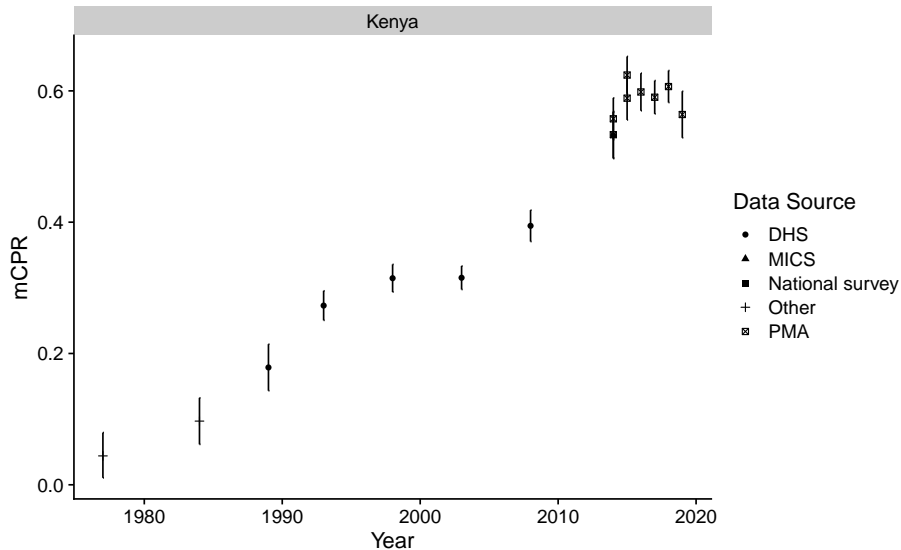
- Let y_i , $i = 1, \dots, n$ be the observed mCPR for country $c[i]$ and year $y[i]$ from data source $d[i]$.
- For each observation we have an estimate s_i^2 of the sampling error.
- We also expect each data source to have additional non-sampling error $\sigma_{d[i]}^2$.
- Truncated normal data model:

$$y_i | \eta_{c[i], t[i]}, \sigma_{d[i]}^2 \sim N_{(0,1)} \left(\eta_{c[i], t[i]}, s_i^2 + \sigma_{d[i]}^2 \right).$$

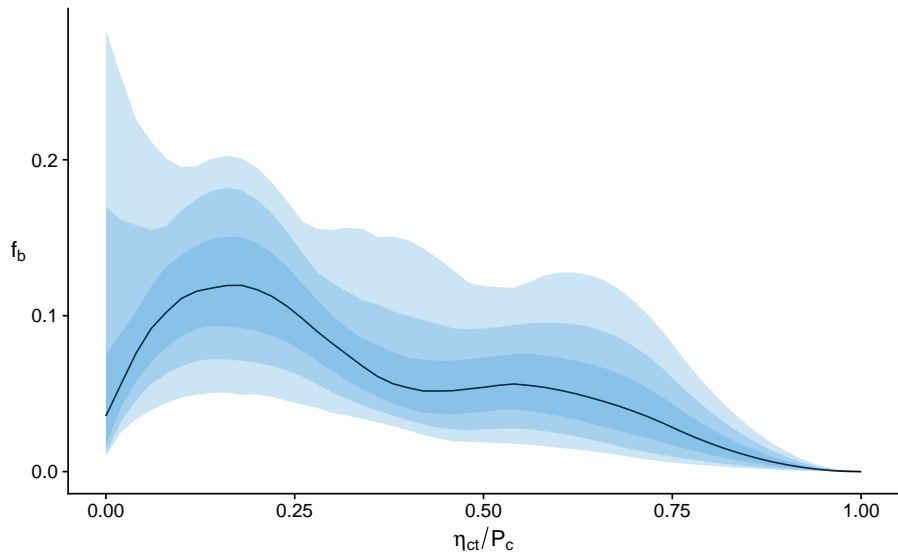
Illustrative Fits



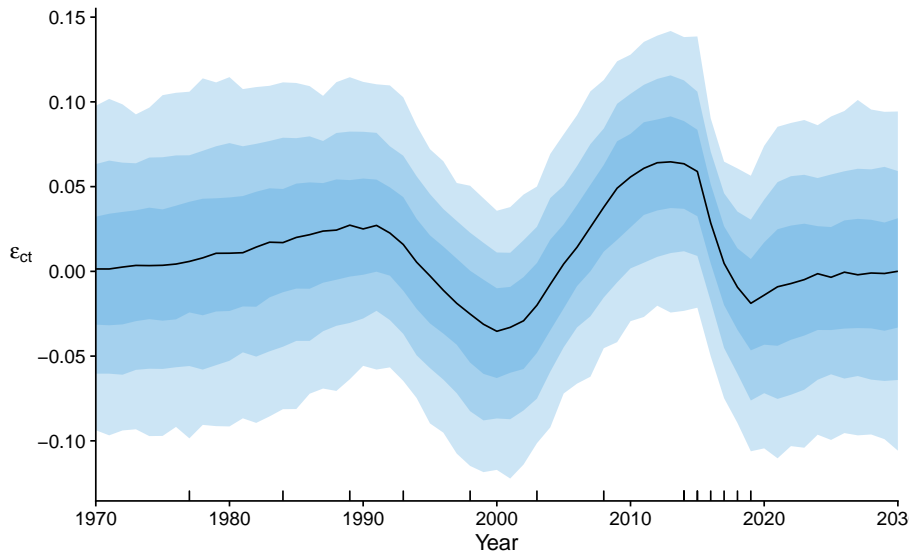
Kenya Raw Data



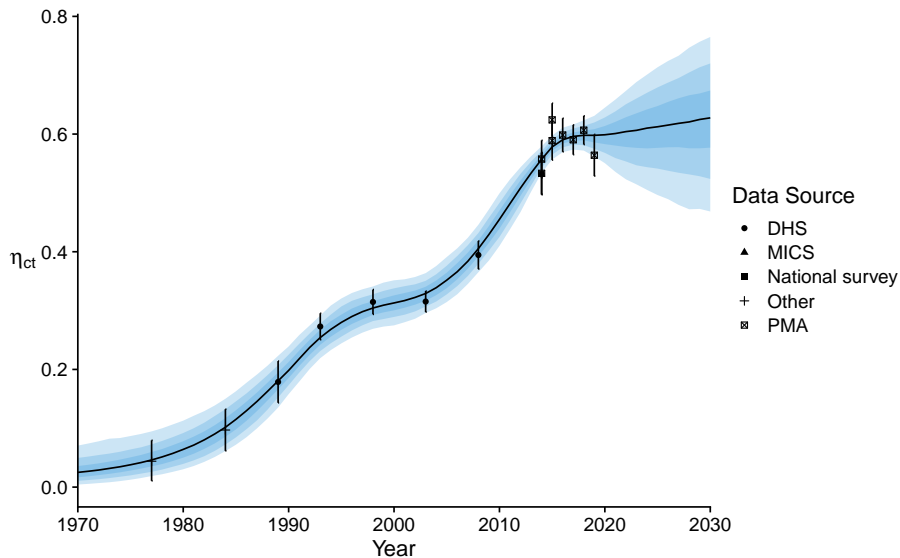
Kenya Transition Function



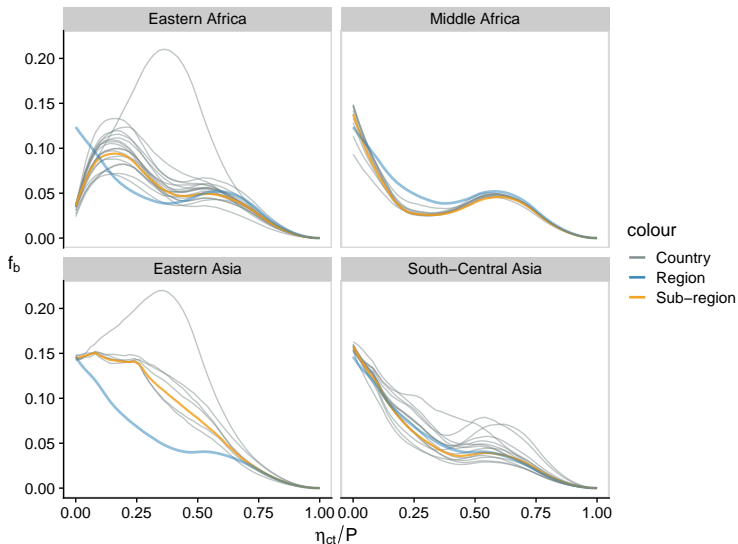
Kenya Smoothing Component



Kenya mCPR Estimates



Trends can be seen in regional and subregional transition functions



- Subclass of *Transition Models* for indicators that follow transitions.
- B-spline Transition Model: flexible modelling approach based on B-splines.
- Generated estimations and projections of mCPR in countries from 1970-2030.
- Found systematically different transitions in countries across regions.
- Flexible model framework that can be easily extended to new settings and use cases.

Choosing a spline specification

Validation exercise: hold out all observations after a cutoff year $L = 2010$.

	95% UI				Error	
	% Below	% Included	% Above	CI Width $\times 100$	ME $\times 100$	MAE $\times 100$
Model Check 2 ($L = 2010$), $n = 133$						
B-spline ($d = 2, K = 5$)	3.76%	94.7%	1.5%	32.0	-1.670	4.64
B-spline ($d = 2, K = 7$)	6.02%	91.7%	2.26%	31.5	-1.260	4.68
B-spline ($d = 3, K = 5$)	3.76%	94.7%	1.5%	32.4	-1.630	4.48
B-spline ($d = 3, K = 7$)	3.76%	94%	2.26%	31.6	-0.965	4.57

95% UI: 95% uncertainty interval. ME: median error. MAE: median absolute error.

Measures calculated using the last held-out observation within each area.

Sharing information on shape of transition function

