Flexible Modeling of Transition Processes via Bayesian Spline Rate Models

with Application to Estimating and Projecting Modern Contraceptive Prevalence

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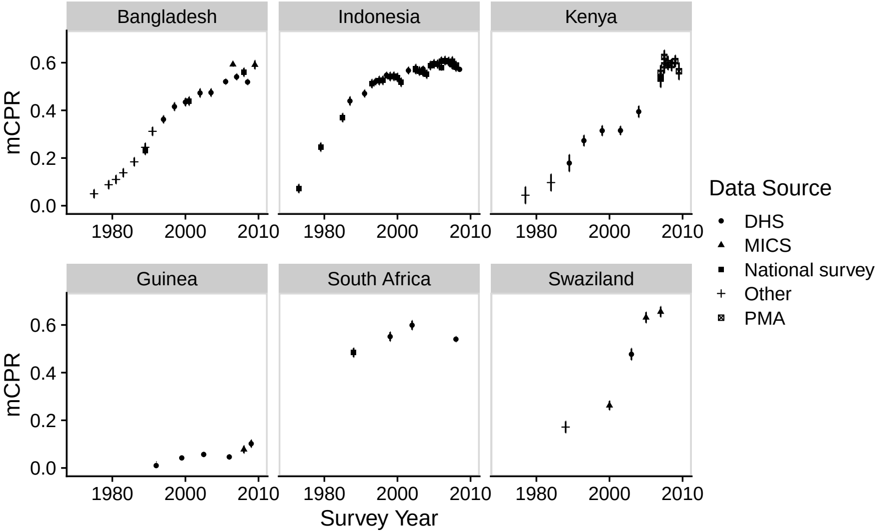
Background

- Increasing interest in estimates and projections of demographic and health indicators.
- Some indicators have been observed to evolve similarly across populations.
  - They tend to follow a *transition* between stable states.
- Classic example: demographic transition.
  - Transition from high total fertility rate and high under-5 mortality to low fertility, low mortality.
- Existing statistical models for estimating and projecting trends in these indicators draw on these patterns.
- **This presentation:** We propose a new type of model, called *B-spline Transition Models*, for flexibly estimating indicators that follow transitions.

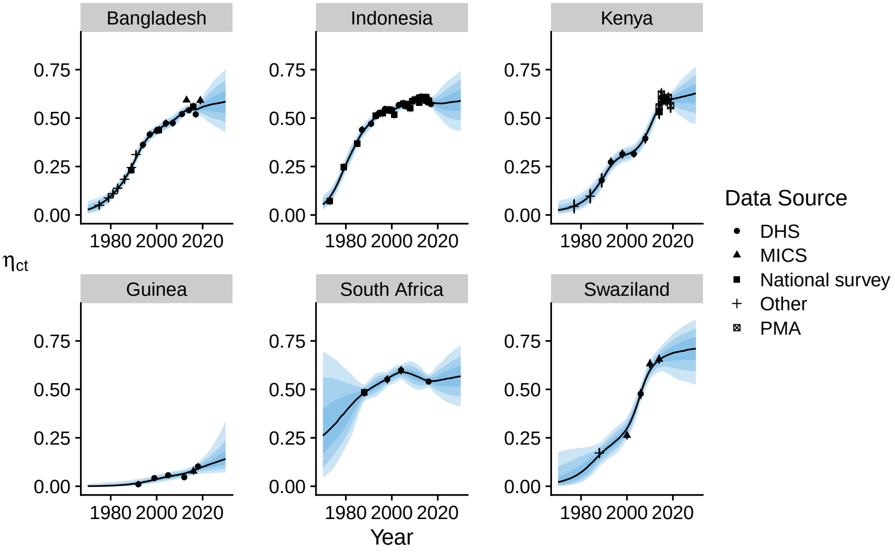
Case Study

- Modern Contraceptive Prevalence Rate (mCPR) for married or in-union women: proportion of married or in-union women of reproductive age using (or with partner using) a modern contraceptive method.
- Transition: low to high mCPR.
- Existing model: Family Planning Estimation Model (FPEM, Cahill et al. 2018).
- Goal: estimate and project mCPR in countries from 1970-2030.
- Dataset aggregated by United Nations Population Division (UNPD) from surveys conducted by governments or international organizations.

Raw Data


Bangladesh
Indonesia
Kenya
Guinea
South Africa
Swaziland
mCPR
0.0
0.2
0.4
0.6
1980
2000
2010
Survey Year
Data Source
DHS
MICS
National survey
Other
PMA

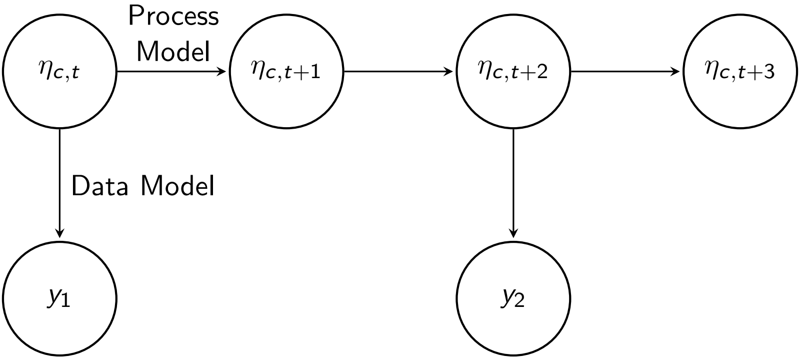
Example Fits



Modeling Framework

- Let $\eta_{c,t}$ be the true value of the indicator in country c at time t $(c = 1, \ldots, C,\ t = 1, \ldots T)$.
- Observed data y_i, $i = 1, \ldots, n$ with associated properties $c[i]$, $t[i]$, ...
- *Process model* describes evolution of $\eta_{c,t}$.
- *Data model* describes relationship between y_i and $\eta_{c[i],t[i]}$.

Modeling Framework



Transition Models

- **Our contribution:** a model class for indicators that follow a transition.
- *Transition Models* have a process model given by

$$g_1(\eta_{c,t}) = \underbrace{g_3(t, \boldsymbol{\eta}_{c,s\neq t}, \boldsymbol{\alpha}_c)}_{\text{systematic}} + \underbrace{\epsilon_{c,t}}_{\text{smoothing}} .$$

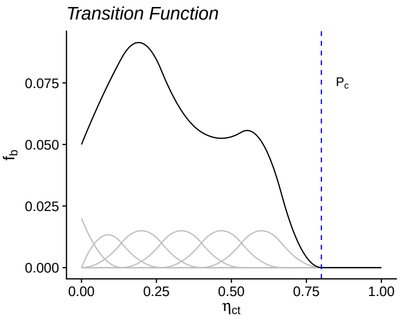
- The systematic component has the following form:

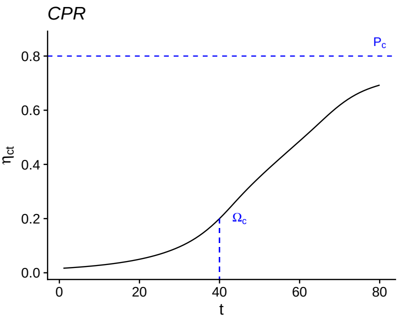
$$g_3(t, \boldsymbol{\eta}_{c,s\neq t}, \boldsymbol{\alpha}_c) = \begin{cases} \Omega_c, & t = t_c^*, \\ g_1(\eta_{c,t-1}) + f(\eta_{c,t-1}, P_c, \boldsymbol{\beta}_c), & t > t_c^*, \\ g_1(\eta_{c,t+1}) - f(\eta_{c,t+1}, P_c, \boldsymbol{\beta}_c), & t < t_c^*, \end{cases}$$

where $\boldsymbol{\alpha}_c = \{\Omega_c, P_c, \boldsymbol{\beta}_c\}$.

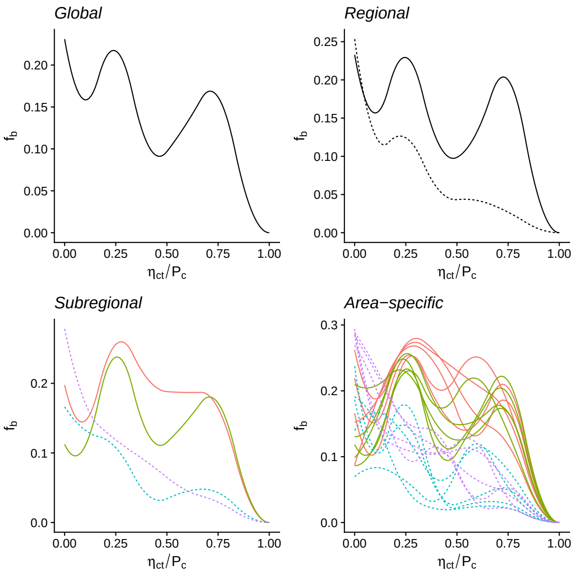
- The function f is called the *transition function*.

Example B-spline Transition Function





Sharing information on shape of transition function



Smoothing component

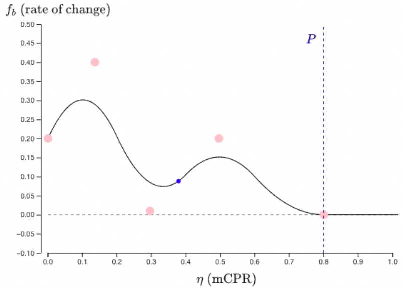
- Recall the process model has two components:

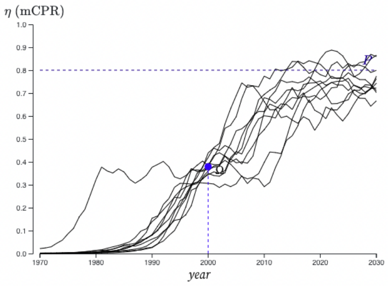
$$g_1(\eta_{c,t}) = \underbrace{g_3(t, \boldsymbol{\eta}_{c,s\neq t}, \boldsymbol{\alpha}_c)}_{\text{systematic}} + \underbrace{\epsilon_{c,t}}_{\text{smoothing}} .$$

- Smoothing component: AR(1) process of the form

$$\epsilon_{c,t} | \epsilon_{c,t-1}, \tau, \rho \sim N(\rho * \epsilon_{c,t-1}, \tau^2)$$

Smoothing component





Data Model: connection to observed data

- Let y_i, $i = 1, \ldots, n$ be the observed mCPR for country $c[i]$ and year $y[i]$ from data source $d[i]$.
- For each observation we have an estimate s_i^2 of the sampling error.
- We also expect each data source to have additional non-sampling error $\sigma^2_{d[i]}$.
- Truncated normal data model:

$$y_i | \eta_{c[i],t[i]}, \sigma^2_{d[i]} \sim N_{(0,1)} \left(\eta_{c[i],t[i]}, s_i^2 + \sigma^2_{d[i]} \right).$$

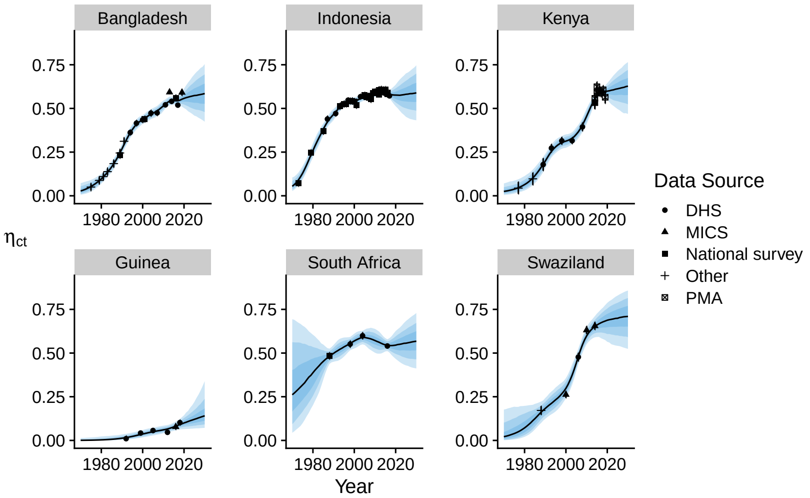
Choosing a spline specification

Validation exercise: hold out all observations after a cutoff year $L = 2010$.

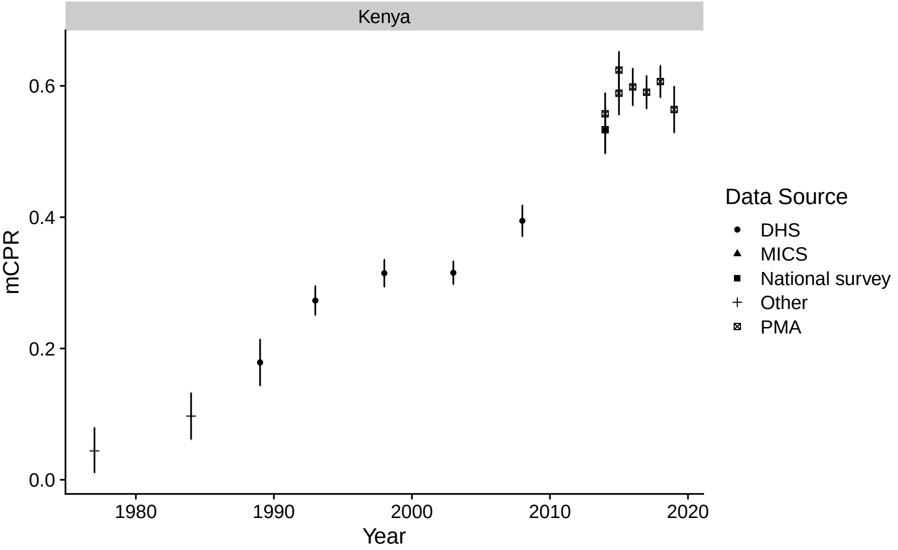
	95% UI				Error	
	% Below	% Included	% Above	CI Width $\times 100$	ME $\times 100$	MAE $\times 100$
Model Check 2 ($L = 2010$), $n = 133$						
B-spline ($d = 2,\ K = 5$)	3.76%	94.7%	1.5%	32.0	-1.670	4.64
B-spline ($d = 2,\ K = 7$)	6.02%	91.7%	2.26%	31.5	-1.260	4.68
B-spline ($d = 3,\ K = 5$)	3.76%	94.7%	1.5%	32.4	-1.630	4.48
B-spline ($d = 3,\ K = 7$)	3.76%	94%	2.26%	31.6	-0.965	4.57

95% UI: 95% uncertainty interval. ME: median error. MAE: median absolute error.
Measures calculated using the last held-out observation within each area.

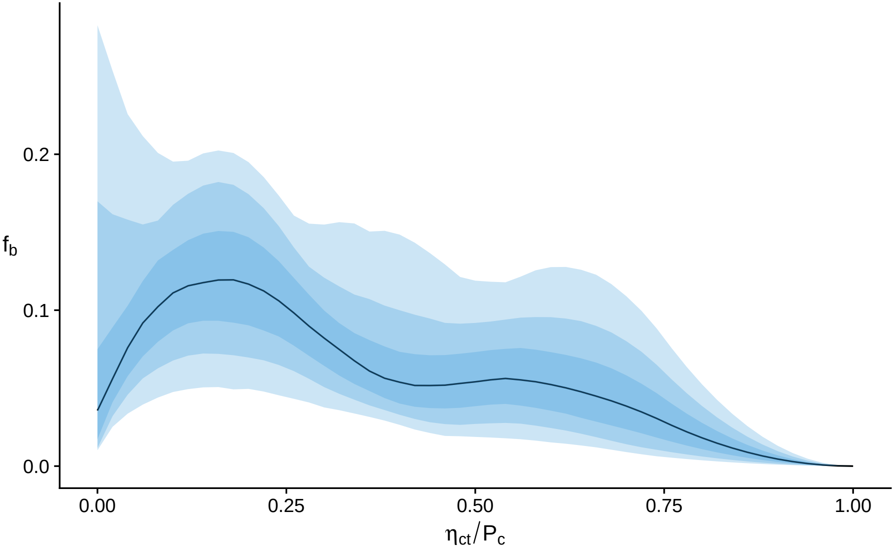
Illustrative Fits



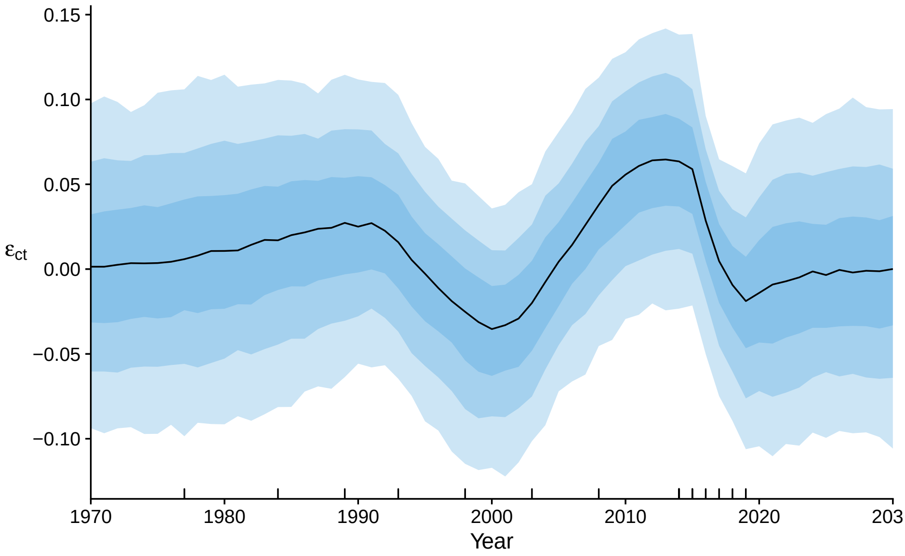
Kenya Raw Data



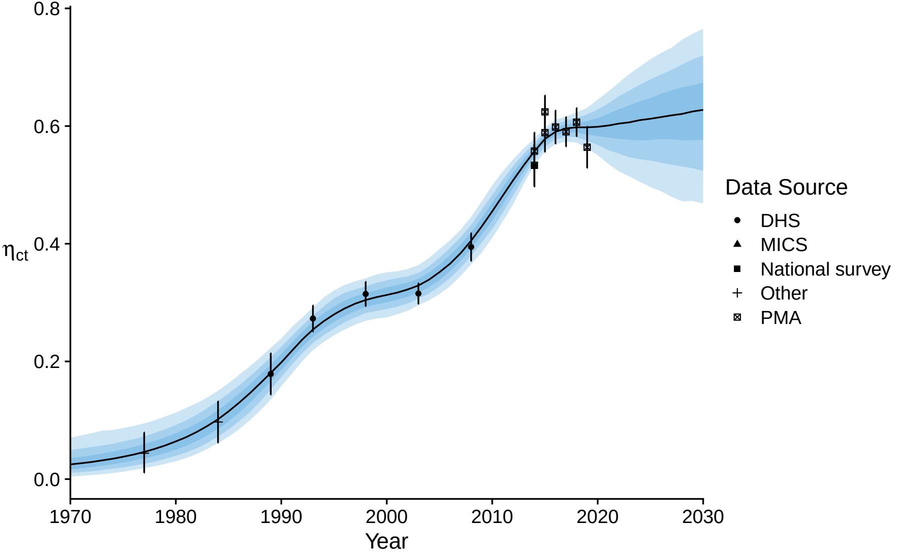
Kenya Transition Function



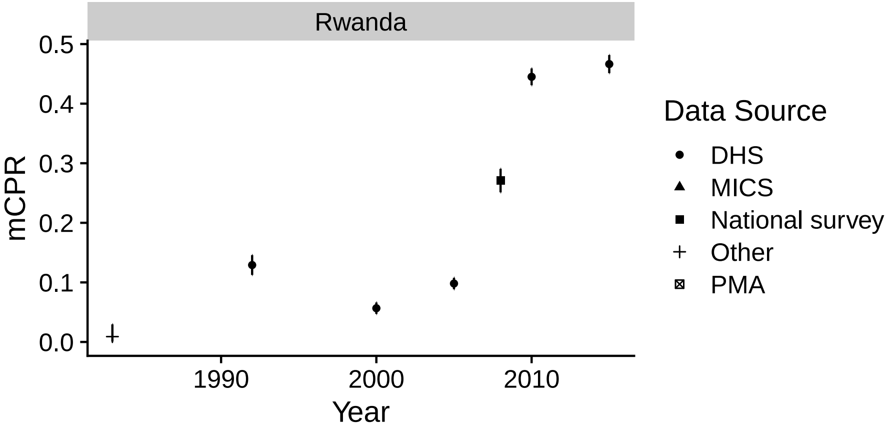
Kenya Smoothing Component



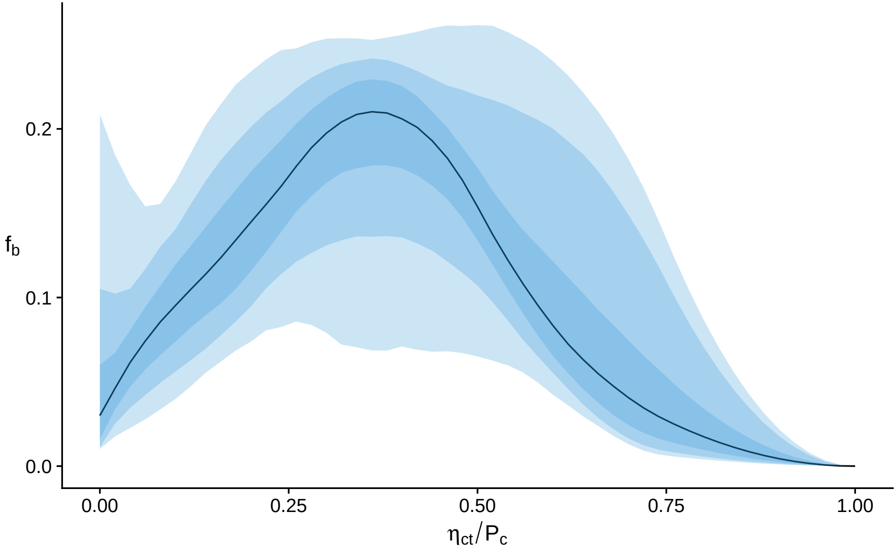
Kenya mCPR Estimates



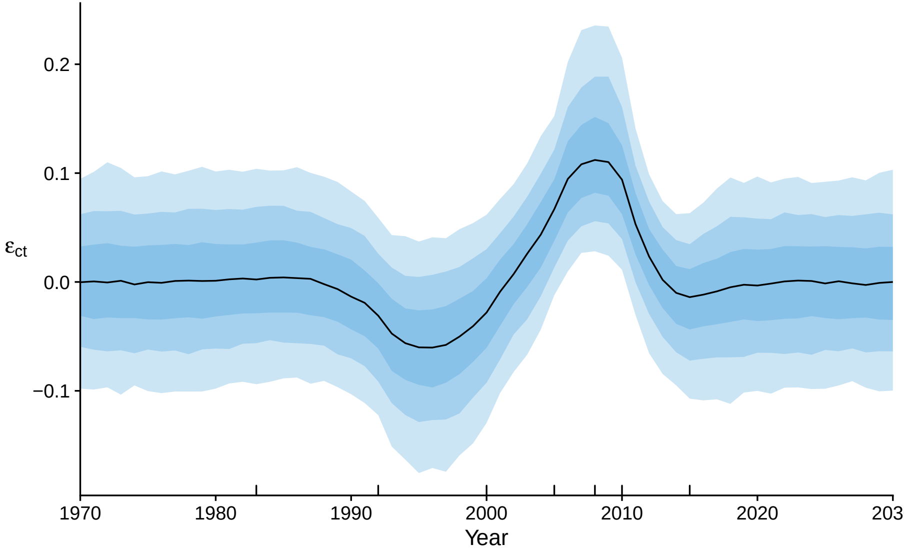
Rwanda Raw Data



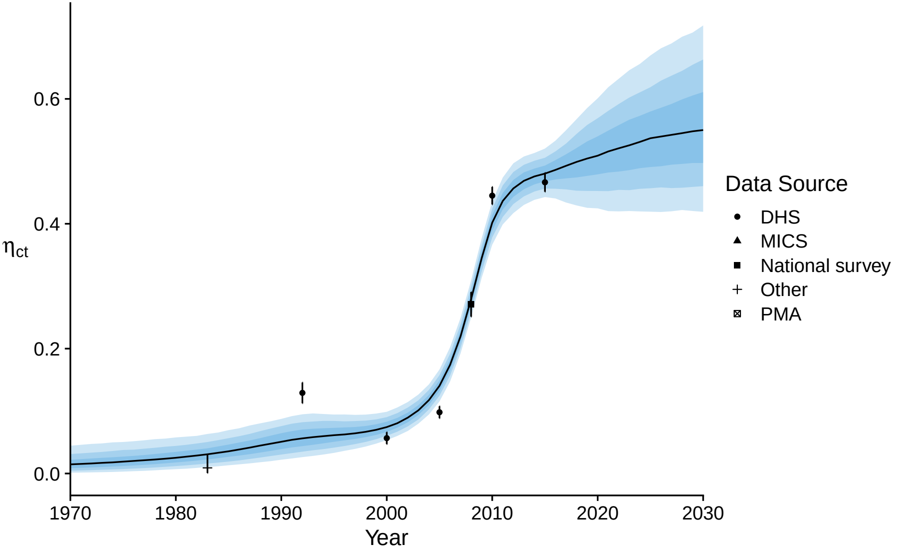
Rwanda Transition Function



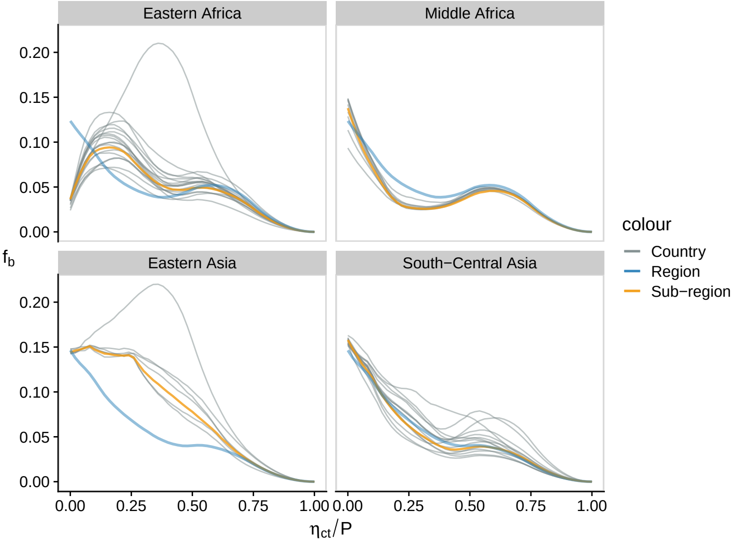
Rwanda Smoothing Component



Rwanda mCPR Estimates



Trends can be seen in regional and subregional transition functions



Summary

- Subclass of *Transition Models* for indicators that follow transitions.
- B-spline Transition Model: flexible modelling approach based on B-splines.
- Generated estimations and projections of mCPR in countries from 1970-2030.
- Found systematically different transitions in countries across regions.
- Flexible model framework that can be easily extended to new settings and use cases.