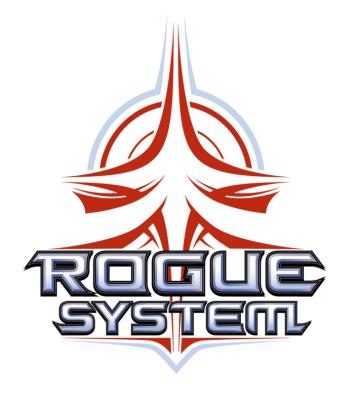
Rogue System



FireArc Prototype
Operations Manual

This page should have the version crap on it.

The version of the doc is Alpha 4.0

The version of the game this doc goes with is 0.1.9.21.15

Version history

Alpha 1

Rough test

Alpha 2

Proper layout with page numbers and everything

Alpha 2.1

Did you know the MFD was called the HMD?

Added some of the HMD panels

Alpha 3

Added Tuturial 3 checklist (Style 1)

Alpha 3.1

Added Tutorial 5 checklist (Style 2)

Added Version history like a dork

Alpha 3.2

Changed Tutorial 3 to single column Split Forward panel into F1-F3

Alpha 3.3

Added Tutorial 4 checklists

Added panel and button information to tutorial 5

Alpha 4.0

Cleaned up Tutorial 3

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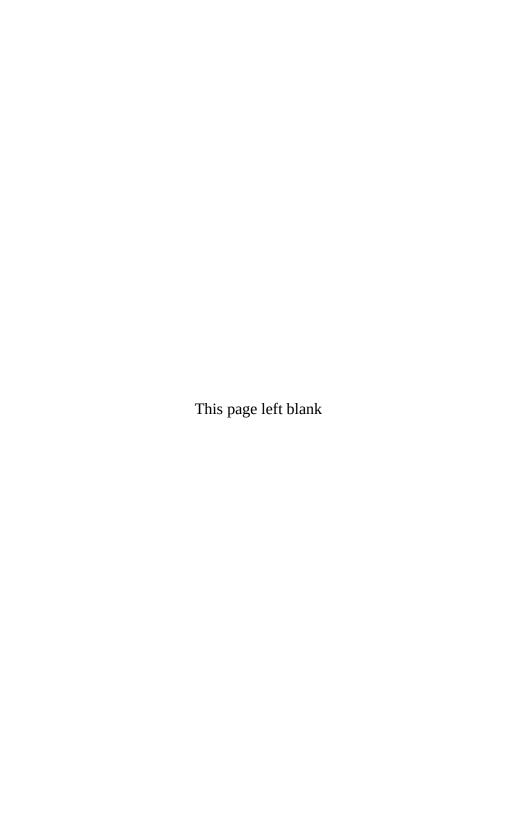
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1 How To Use This Document

How To Use This Document 1-2

In order to make everyone's lives easier this document is designed to provide a standard control panel scheme.

The panels are labeled forward to aft, top to bottom.

F= Forward

L=Left

R=Right

A=Aft

The buttons are labeled top to bottom, left to right.

The labels I am using for the buttons are from the tool tip hoover text.

An example of how I would use this is the first few steps of the docking tutorial

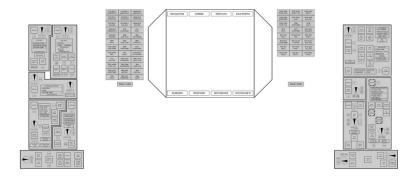
(The tutorial chunk that was here previously has been deleted because I wrote the whole thing in a later section)

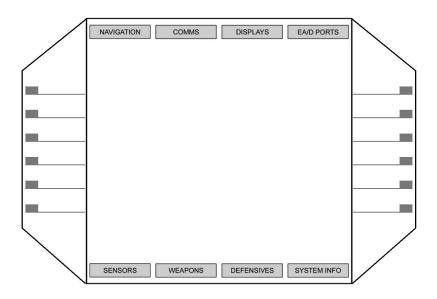
You can be all NASA with their cool checklists and tack on some useful information at the same time.

Sherpa

2 CONTROL PANEL OVERVIEW

2.1 F2 Hard-Mounted Display (HMD)

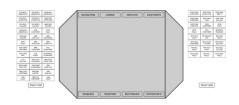




The HMD has an entire section devoted to the individual screens. Check the table of contents.

2.2 F1/F3 Caution And Warning (CAW)







SYS BUS 1	SYS BUS 2	MAIN BUS
UNDERVOLT	UNDERVOLT	UNDERVOLT
SYS BUS 1	SYS BUS 2	MAIN BUS
OVERLOAD	OVERLOAD	OVERLOAD
SYS BUS 1	SYS BUS 2	MAIN BUS
FAILURE	FAILURE	FAILURE
WPN BUS	ECS	ECS
UNDERVOLT	OVERTEMP	FAULT
WPN BUS	BMS	BMS
FAILURE	LOW VOLT	RECHARGE
BMS	BMS	BMS
FAULT	ACID LEAK	CAPACITY
FCS CORE	BMS	FCS
LOW TEMP	OVERTEMP	OVERTEMP
FCS CORE	FCS	FCS REACT
MCL	FAULT	FLOW RATE
FCS	TMS COOL	TMS COOL
SOV FAIL	PRESSURE	LEVEL LOW
TMS LASER	TMS PUMP	TMS
COOL FAIL	OVERSPEED	PUMP FAIL
TMS LOOP	TMS RAD	TMS
OVERTEMP	MOTOR	RAD FAIL
TMS	TMS SYS	VMS
FAULT	OVERTEMP	FAULT

RCM TANK	RCM TANK	RCM TANK
FLOW RATE	LEVEL LOW	EMPTY
RCM TANK	RCM TANK	RCM TANK
OVERTEMP	LEAK	SOV FAIL
RCM TANK	RCM	RCM
PUMP FAIL	OVERTEMP	FAULT
MTS	MTS	MTS DEFL
FAULT	OVERTEMP	ENGAGED
MTS RCS	MTS BOOST	MTS NOZ
FAULT	FAIL	FAULT
FAULT MTS NOZ	FAIL MTS SLOW	FAULT MTS AUTO-

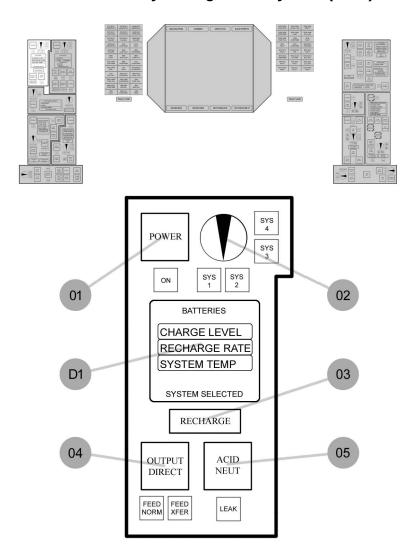
FAULT ACK

01

FAULT ACK

01) Fault Ack

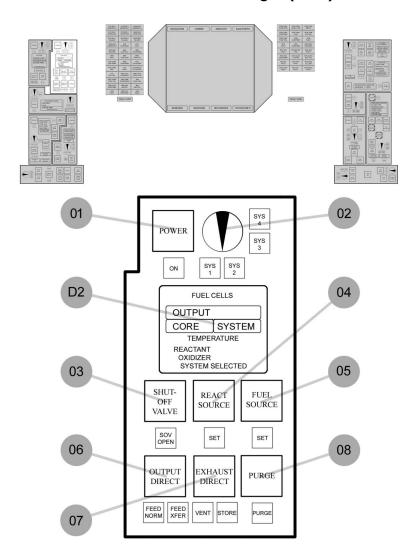
2.3 L1 Battery Management System (BMS)



- 01) BMS Battery Enable
- 02) BMS Battery Select
- 03) BMS Battery Recharge
- 04) BMS Battery Output Select
- 05) BMS Acid Neutralizer
- D1) BMS Display

 The display will be covered in section XX

2.4 L2 Fuel Cell Manager (FCM)



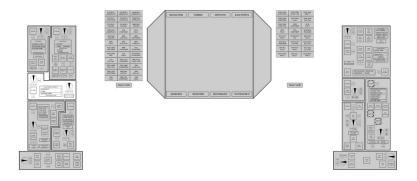
- 01) FCS Cell Enable *
- 02) FCS Cell Select *
- 03) FCS Shut-Off Valve *
- 04) FCS Reactant Source Select *
- 05) FCS Fuel Select *
- 06) FCS Power Output Select *
- 07) FCS Bi-Product Disposal *
- 08) FCS Contamination Purge *
- D2) FCM Display

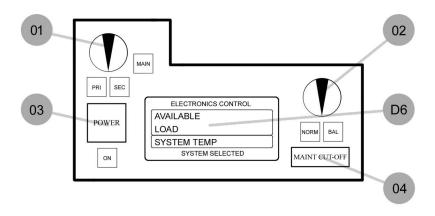
 The display will be covered in section XX

NOTE:

* The tool tips use FCS however on the F1 HMD Systems Info page the sub system is called FCM so....yeah. That's a thing that should probably be changed one way or the other.

2.5 L3 Electronic Control System (ECS)

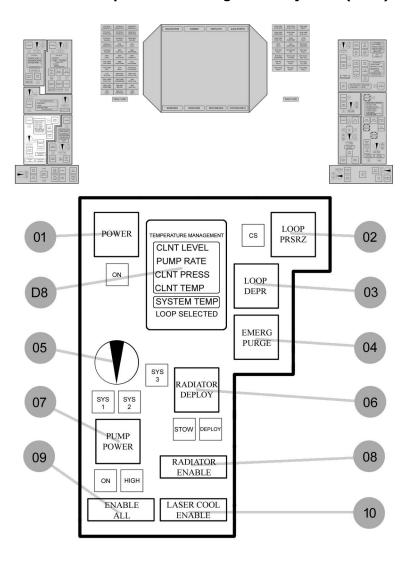




- 01) ECS Bus Select
- 02) ECS Bus Distribution Mode
- 03) ECS Bus Enable
- 04) ECS Maintenance Cut-Off
- D6) ECS Display

 The display will be covered in section XX

2.6 L4 Temperature Management System (TMS)



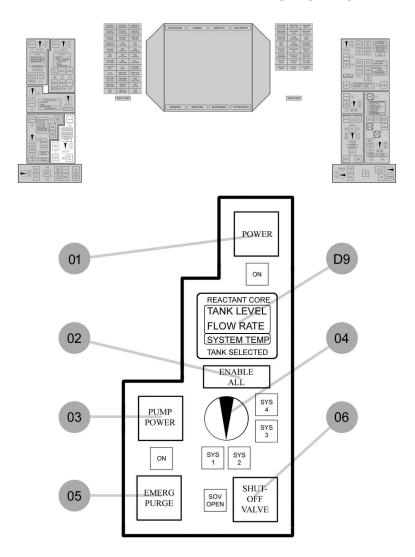
- 01) TMS Loop Enable
- 02) TMS Loop Pressurize
- 03) TMS Loop Depressurize
- 04) TMS Flash Cool (Vent) Loop
- 05) TMS Loop Select
- 06) TMS Loop Radiator Deploy
- 07) TMS Loop Power *
- 08) TMS TMS Loop Radiator Enable
- 09) TMS Enable All Pumps
- 10) TMS Loop Laser Cooling Enable
- D8) TMS Display

 The display will be covered in section XX

NOTE:

* The TMS Loop Power button is a three position toggle. If anyone has a good suggestion on how I can draw that, I'm listening.

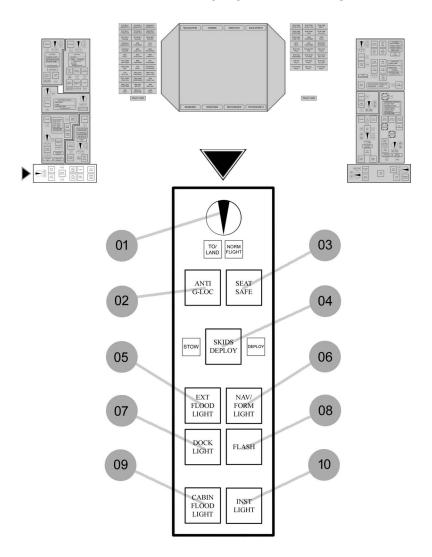
2.7 L5 Reactant Core Manager (RCM)



- 01) RCM System Enable
- 02) RCM Enable All Pumps
- 03) RCM Tank Pump Power
- 04) RCM Tank Select
- 05) RCM Tank Emergency Overboard Dump
- 06) RCM Tank Shut-Off Valve

D9) RCM Display The display will be covered in section XX

2.8 L6 Core Ship Systems Manager



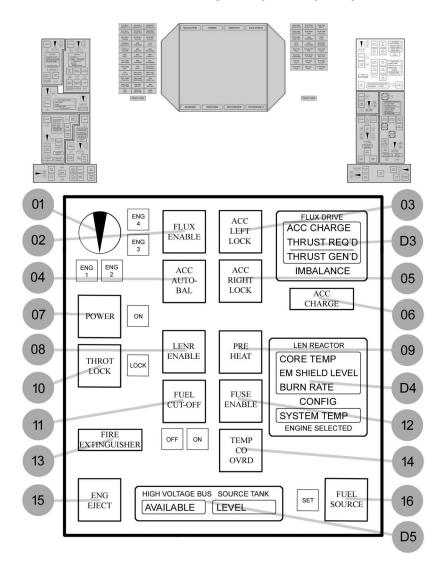
- 01) Seat Flight Mode Select
- 02) Seat Anti-G Enable
- 03) Seat Safe For Flight
- 04) CSSM Skids Deploy *
- 05) CSSM Exterior Flood Lighting
- 06) CSSM Navigation/Formation Lighting
- 07) CSSM Docking Port Lighting
- 08) CSSM Strobe Beacon Lighting
- 09) CSSM Cabin Flood Lighting
- 10) CSSM Instrument Lighting

NOTE:

* The tool tip for Skids Deploy incorrectly shows as CSSM Navigation/Formation Lighting. Be careful which one you click on when internally docked.

This panel has been rotated clockwise from its actual orientation It seemed like a good idea at the time?

2.9 R1 Main Engine System (MES)



- 01) MES Engine Select
- 02) MES Flux Drive Enable
- 03) MES Accumulator (Left) Lock
- 04) MES Accumulator Auto Balance
- 05) MES Accumulator (Right) Lock
- 06) MES Accumulator Charge
- 07) MES System Enable
- 08) MES LENR Enable
- 09) MES Chamber Pre-Heater
- 10) MES Throttle Lock
- 11) MES Fuel Cut-Off
- 12) MES LENR Fuse Enable
- 13) MES Extinguisher
- 14) MES Temperature Cut-Off Override
- 15) MES Engine Jettison
- 16) MES LENR Fuel Source Select

D3 MES Flux Drive Display

The display will be covered in section XX

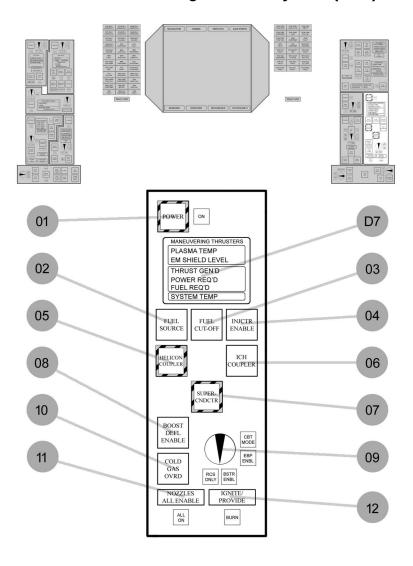
D4 MES LEN Reactor Display

The display will be covered in section XX

D5 MES Display

The display will be covered in section XX

2.10 R2 Maneuvering Thruster System (MTS)



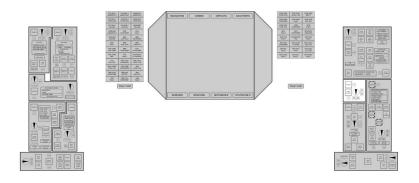
- 01) MTS System Enable *
- 02) MTS Fuel Source Select
- 03) MTS Fuel Cut-Off Valve
- 04) MTS Fuel Injector Enable **
- 05) MTS Helicon Ionize-Enable *
- 06) MTS ICH Cyclotron Enable
- 07) MTS Superconductor Enable *
- 08) MTS Boost Deflector
- 09) MTS Thrust Mode Select
- 10) MTS Cold Gas Override
- 11) MTS Nozzle All Enable
- 12) MTS Core Ignitor/Thrust Provide ***

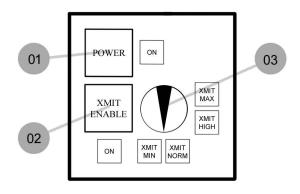
NOTE:

- * These switches have safety covers on them. It is probably for a good reason
- ** Insert VTEC Kicked in Yo joke here
- *** This is a press and hold button.

If anyone has a good suggestion on how I can draw that, I'm listening.

2.11 R3 Communication System (COMMS)

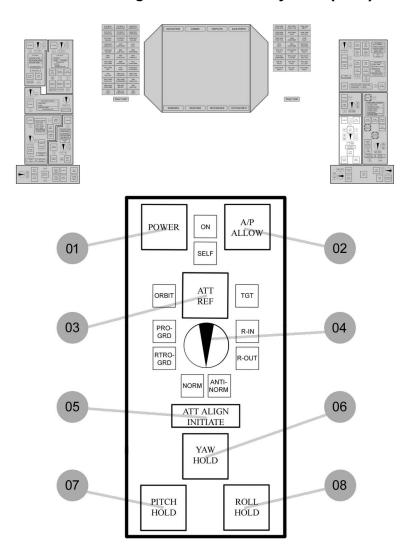




- 01) COMMS System Enable
- 02) COMMS Transmitter Enable
- 03) COMMS Transmission Power Select

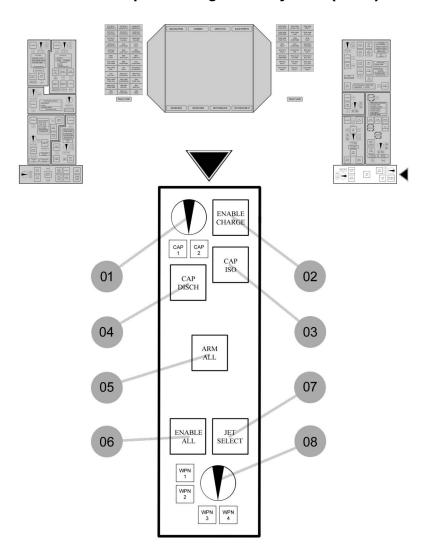
I bet some lore fluff would fit nicely here. Or Comms war stories, whatever. I'm easy.

2.12 R4 Navigation/Auto-Pilot System (NAS)



- 01) NAS System Enable
- 02) NAS Auto Pilot Allow
- 03) NAS Attitude Reference Select
- 04) NAS Attitude Mode Select
- 05) NAS Align Initiate
- 06) NAS Yaw Hold
- 07) NAS Pitch Hold
- 08) NAS Roll Hold

2.13 R5 Weapon Management System (WMS)



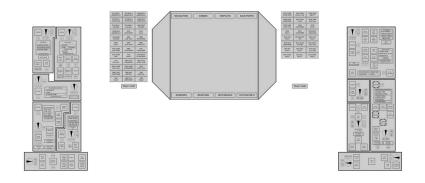
- 01) WMS Weapon Select
- 02) WMS Weapon Capacitor Enable/Charge
- 03) WMS Weapon Capacitor Isolate
- 04) WMS Weapon Capacitor Discharge
- 05) Weapon Arm All *
- 06) Weapon Enable All *
- 07) Weapon Jettison Selected
- 08) Weapon Selected

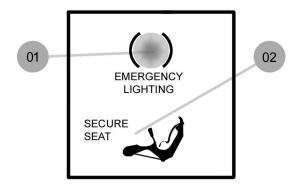
NOTE:

* None of these switches have a cover so watch your step when entering or exiting the seat when the ship is operational

This panel has been rotated counterclockwise from its actual orientation
It seemed like a good idea at the time?

2.14 A1 Access Panel



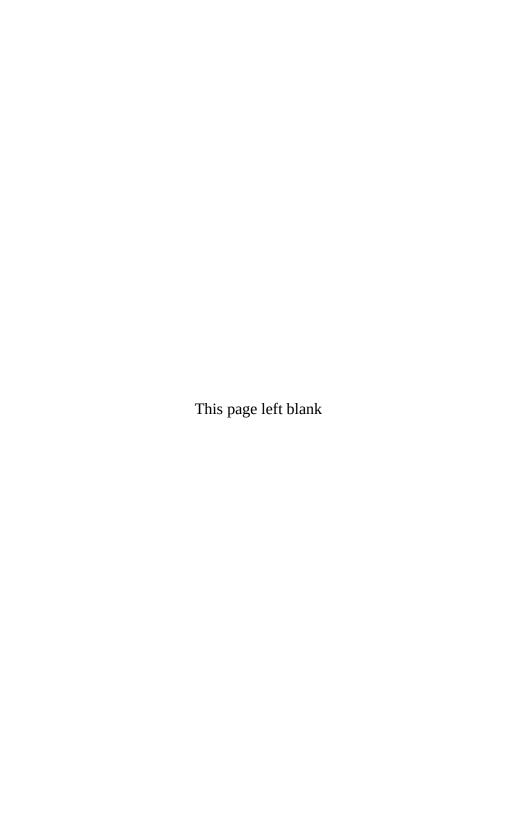


Control Panel Overview 2-29

- 01) CSM Cabin Flood Lights*
- 02) SEAT Safe/Unsafe

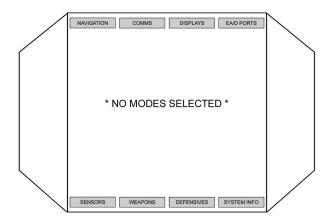
Note:

* I think we're missing an S from CSSM here.

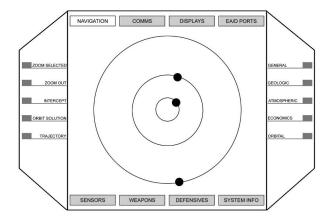


3 HMD PANELS

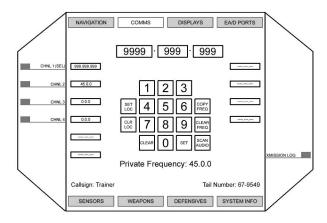
3.1 HMD No Modes Selected



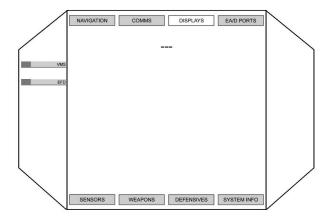
3.2 HMD Navigation





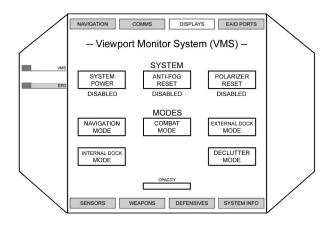


3.4 HMD Displays

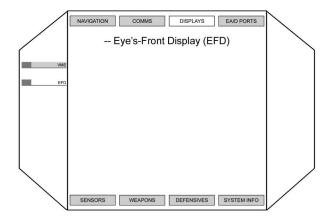


HMD Panels 3-4

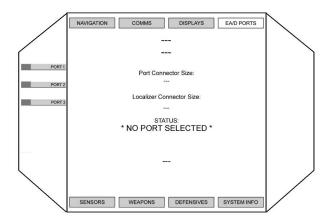
3.5 HMD Displays – VMS



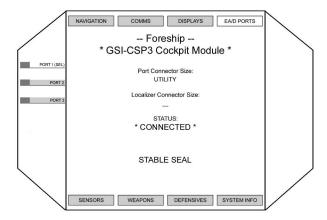
3.6 HMD Displays – EFD



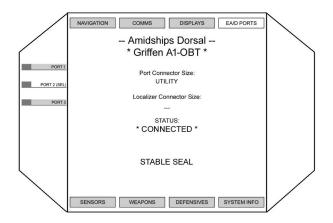




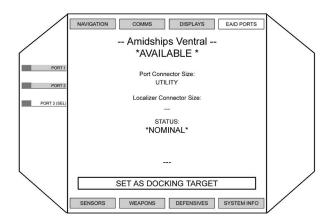
3.8 HMD EA/D Ports – Port 1



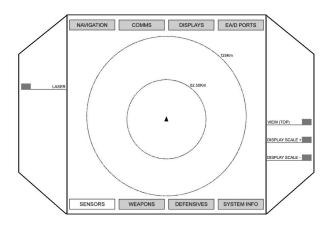
3.9 HMD EA/D Ports – Port 2



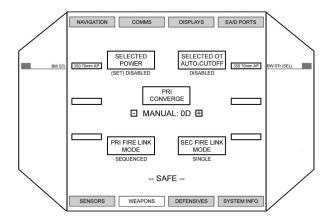
3.10 HMD EA/D Ports – Port 3



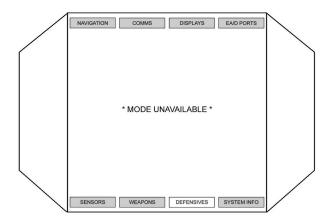
3.11 HMD Sensors



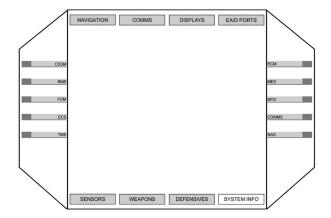
3.12 HMD Weapons



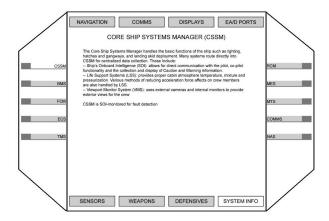
3.13 HMD Defensives

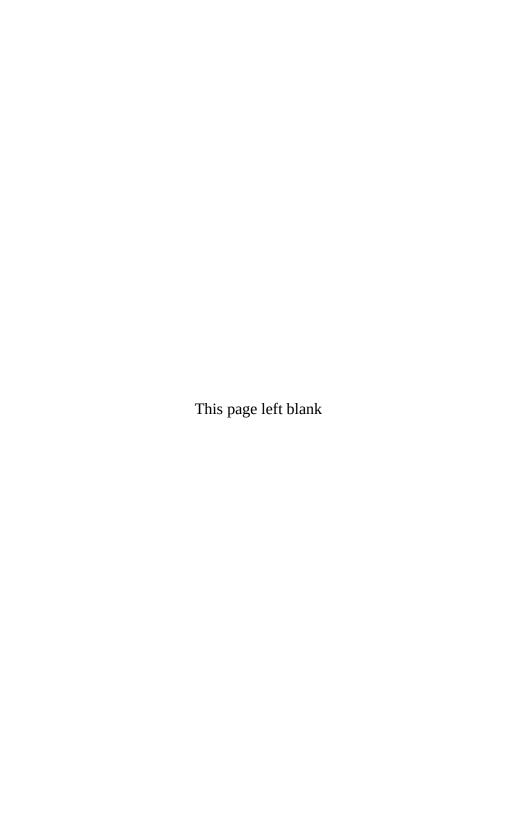


3.14 HMD Systems Info



3.15 HMD Systems Info – CSSM





4 TUTORIAL CHECKLIST

4.1 Tutorial 3 System Startup

Entering Cockpit

There is a panel right outside the cockpit hatch but I haven't drawn it yet

MDR-01 Mid Deck Right Panel One

01 COCKPIT HATCH - OPEN

A1 Aft Panel

02 SECURE SEAT - UNSECURE

Enter Pilot's Seat

L6 CSSM Panel

03 SEAT SAFE - ENABLE

09 CABIN FLOOD LIGHT - DISABLE

10 INST LIGHT - ENABLE

Switch Check

✓ All Panels Powered Down

L5 RCM Panel

04 TANK SELECT - SYS 1

L4 TMS Panel

05 LOOP SELECT - SYS 1

L3 ECS Panel

01 BUS SELECT - PRI

02 BUS DISTRIBUTION MODE - NORM

L2 FCM Panel

02 CELL SELECT - SYS 1

L1 BMS Panel

02 BATTERY SELECT - SYS 1

R1 MES Panel

01 ENGINE SELECT - SYS 1

R2 MTS Panel

09 THRUST MODE SELECT - RCS ONLY

R3 COMMS Panel

03 TRANSMISSION POWER SELECT - XMIT NORM

Primary Bus Enable

- L1 BMS Panel
 - **01** POWER ON
- L3 ECS Panel
 - 03 POWER ON
- F1 CAW Panel
 - **01** fault acknowledge
- L3 ECS Panel
 - **04** MAINT CUT-OFF DISABLE (green)
- **D6** ECS Display
 - ✓ AVAILABLE is GREEN
- ✓ F1 CAW SYS BUS 1 lights out
- L1 BMS Panel
 - **03** RECHARGE ENABLE
- **D1** BMS Display
 - ✓ RECHARGE RATE is RISING

Secondary Bus Enable

- L1 BMS Panel
 - **02** BATTERY SELECT SYS 2
 - **01** POWER ON
 - **03** RECHARGE ENABLE
- **D1** BMS Display
 - ✓ RECHARGE RATE is RISING

If SYS 1 battery is enabled and has charge SYS 2 battery will not show RECHARGE RATE This is expected

- L3 ECS Panel
 - **01** BUS SELECT SEC
 - 03 POWER ON
 - **02** BUS DISTRIBUTION MODE BAL
- ✓ F1 CAW SYS BUS 2 lights out

There will be a delay on SYS BUS 2 OVERLOAD
This is expected

Fuel Cell Preheat

- **L2** FCM Panel
 - **01** POWER ON
 - 02 CELL SELECT SYS 2
 - 01 POWER ON

Standard TMS Enable

- **L4** TMS Panel
 - 01 POWER ON
 - 02 LOOP PRSRZ CS
 - **07** PUMP POWER ON

CAUTION L4-07 is a three position switch avoid running pumps in HIGH mode

- **D8** TMS Display
 - ✓ CLNT LEVEL is RISING
 - CLNT PRESS is RISING
- **L4** TMS Panel
 - **02** ✓ LOOP PRSRZ is DISABLED
 - 05 LOOP SELECT SYS 2
 - 02 LOOP PRSRZ CS
 - **07** PUMP POWER ON

CAUTION L4-07 is a three position switch avoid running pumps in HIGH mode

- **D8** TMS Display
 - ✓ CLNT LEVEL is RISING.
 - ✓ CLNT PRESS is RISING
- L4 TMS Panel
 - 02 ✓ LOOP PRSRZ is DISABLED
 - **09** ✓ ENABLE ALL is ENABLED
- F1 CAW TMS lights out

SYS BUS 2 OVERLOAD will illuminate.
This is expected

Alternate TMS Enable

WARNING!

This procedure will automatically enable TMS SYS 1 and SYS 2
Use the **standard procedure** if you are unaware
of the spacecrafts condition or are unable to communicate
with STC Emergency Crews

- L4 TMS Panel
 - 01 POWER ON
 - **02** LOOP PRSRZ CS
 - **05** LOOP SELECT SYS 2
 - 02 LOOP PRSRZ CS
 - **09** ENABLE ALL ENABLE
- **D8** TMS Display
 - ✓ CLNT LEVEL is RISING
 - ✓ CLNT PRESS is RISING
- L4 TMS Panel
 - **02** ✓ LOOP PRSRZ is DISABLED
 - **05** LOOP SELECT SYS 2
- **D8** TMS Display
 - ✓ CLNT LEVEL is RISING
 - ✓ CLNT PRESS is RISING
- L4 TMS Panel
 - **02** ✓ LOOP PRSRZ is DISABLED
- ✓ F1 CAW TMS lights out

SYS BUS 2 OVERLOAD will illuminate.
This is expected

COMMS Enable

R3 COMMS Panel

01 POWER - ON

02 XMIT ENABLE - ON

Check in with STC

TAB

- 5) Space Traffic Control
- 1) Check In

Control this is 10-3889 (YOU) checking in.

10-3889 (YOU), this is Control. We have you checked in. Over.

TAB

- 5) Space Traffic Control
- 2) Request Departure Clearance

Control, this is 10-3889 (YOU). Requesting departure clearance.

10-3889 (YOU), this is Control. Departure approved. Notify Control before LENR initiation. Over.

Standard RCM Enable

L5 RCM Panel

01 POWER - ON

03 TANK SELECT cycle SYS 1 to SYS 4

03 PUMP POWER - ON

06 SHUT-OFF VALVE - SOV OPEN

✓ 02 ENABLE ALL is ENABLED

✓ F3 CAW RCM lights out

Alternate RCM Enable

WARNING!

This procedure will automatically enable RCM SYS 1 to SYS 4
Use the **standard procedure** if you are unaware
of the spacecrafts condition or are unable to communicate
with STC Emergency Crews

L5 RCM Panel

01 POWER - ON

02 ENABLE ALL - ENABLE

03 TANK SELECT cycle SYS 1 to SYS 4

D9 RCM display

✓ TANK LEVEL

L5 RCM Panel

03 ✓ PUMP POWER is ON

06 ✓ SHUT-OFF VALVE is SOV OPEN

F3 CAW RCM lights out

MES Preliminary Enable

R1 MES Panel

07 POWER - ON

08 LENR ENABLE - ENABLE

D4 LEN REACTOR Display

✓ EM SHIELD LEVEL is GREEN

R1 MES Panel

09 PRE HEAT - ENABLE

D4 LEN REACTOR Display

✓ CORE TEMP is ORANGE

R1 MES Panel

16 FUEL SOURCE - SET

HMD Enable

F2 HMD

HMD DISPLAYS

VMS

SYSTEM POWER

wait for screen to power on

EXTERNAL DOCK MODE

LENR Pre Enable Check

R1 MTS Panel

09 ✓ PRE HEAT is GREEN

Request LENR activation from STC

TAB

- 5) Space Traffic Control
- 1) Ready for LENR Initiation

Control, this is XX-XXXX (YOU). Requesting LENR reaction.

XX-XXXX (YOU) Control. Copy. You are cleared to initiate LENR. Notify Control when ready for departure. Over.

Enable LENR and Main System Bus

R1 MES Panel

- 11 FUEL CUT-OFF ENABLE
- 12 FUSE ENABLE ENABLE
- **D4** LEN REACTOR Display
 - ✓ CORE TEMP is GREEN

L3 ECS Panel

- **01** BUS SELECT MAIN
- 03 POWER ON
- **D6** ECS Display
 - ✓ AVAILABLE is RISING
- L3 ECS Panel
 - 01 BUS SELECT cycle PRI, SEC, MAIN
- **D6** ECS Display
 - ✓ AVAILABLE
 - ✓ LOAD
 - ✓ F1 CAW Main Bus lights out
 - ▼ F1 CAW SYS 2 OVERLOAD light out

Enable NAS

R4 NAS Panel **01** POWER - ON

MTS Enable

R2 MTS

- **01** POWER toggle SAFETY
- **01** POWER ON
- **02** FUEL SOURCE ENABLE
- **03** FUEL CUT-OFF ENABLE
- **04** INJECTR ENABLE ENABLE
- 11 NOZZLES ALL ENABLE ALL ON

FCM Enable

CAUTION you can damage the fuel cells by allowing flow when the core temp is low.

- **L2** FCM Panel
 - 02 CELL SELECT cycle SYS 1 SYS 2
- **D2** FCM display
 - ✓ CORE is GREEN
- **L2** FCM Panel
 - 03 ✓ SHUT-OFF VALVE is YELLOW
 - **05** FUEL SOURCE SET
 - **04** REACT SOURCE SET
- ✓ F1 CAW FCM (FSC) lights out

Undock Check List

L6 CSSM Panel

01 FLIGHT MODE SELECT - NORM FLIGHT

F2 HMD

HMD COMMS

L3 ECS Panel

04 MAINT CUT-OFF - ENABLE (yellow)

Request to Undock from STC

TAB

- 5) Space Traffic Control
- 2) Ready for departure

Control, this is XX-XXXX (YOU). Ready to depart.

XX-XXXX (YOU) this is Control. Clearance granted. Over.

XX-XXXX (YOU), Control. Maintenance power disabled. Stand by for departure frequencies.

XX-XXXX (YOU), Control. Tune ST Departure on 45.2.3

XX-XXXX YOU), Control. Tune localizer for exterior collar 3 using 45.2.202

XX-XXXX (YOU), Control. Umbilicals disconnected. Stand by for release.

All previous transmissions can be viewed using 'XMISSION LOG' from the COMMS sub-menu.

Configure COMMS Channels before release

```
F2 HMD
 HMD COMMS
       CHNL 3
        select Left Channel Box
        select Center Channel Box
        select Right Channel Box
        SET
       CHNL 4
        select Left Channel Box
         45 (if unset)
        select Center Channel Box
         2 (if unset)
        select Right Channel Box
         202
        SET
        SET LOC
```

After Station Release

F2 HMD HMD NAVIGATION

Maneuver away from station. The tutorial suggests Aft Translation (Down Arrow)

When Clear of the Station Deploy Radiators

L4 TMS Panel

05 LOOP SELECT cycle SYS 1 - SYS 2

06 RADIATOR DEPLOY - DEPLOY

06 ✓ DEPLOY INDICATOR is GREEN

D8 TMS Display

✓ CLNT TEMP is FALLING

When beyond STC Limiter range – 200 meters

R2 MTS Panel

07 SUPER-CNDCTR toggle SAFETY

05 HELICON COUPLER toggle SAFETY

07 SUPER-CNDCTR - ENABLE

D7 MTS Display

✓ EM SHIELD LEVEL is GREEN

R2 MTS Panel

05 ✓ HELICON COUPLER is WHITE

05 HELICON COUPLER - ENABLE

12 IGNITE/PROVIDE hold until BURN INDICATOR is GREEN

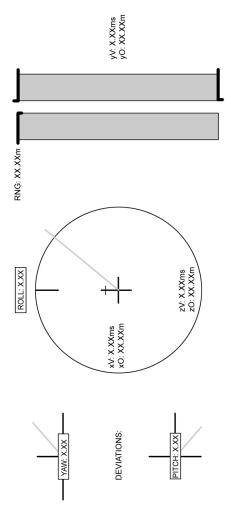
CAUTION!

If the BURN INDICATOR does illuminate after five (5) seconds something has gone very wrong with your procedure or the spacecraft.

06 ICH COUPLER - ENABLE

✓ F3 CAW MTS lights

4.2 Tutorial 4 External Docking



Docking HUD

Note: About Tutorial 3

Because this tutorial involves flying to the test platform and docking, most of this section will be generalities and my own bad habits. I will include as many facts as possible but ultimately your personal flying style will determine how useful this section of the manual becomes. At the end of the day, all that matters is a safe and successful dock.

Sherpa

Entering Cockpit

MDR1

CSM: cockpit hatch Open MDR1-01

The first thing I do after entering the cockpit is listen for clicks from the proximity sensor. I have had the tutorial start me between 200m and 5km. The proximity sensor has a range of 500m so if you hear clicking it is important to get the spacecraft under control ASAP.

A1 Panel

SECURE SEAT - UNSECURE A1-02

Enter Pilot's Seat

L6 CSSM

SEAT SAFE - ENABLE **L6-03**INST LIGHT - ENABLE **L6-10**CABIN FLOOD LIGHT - DISABLE **L6-09**

HMD Enable

F2 HMD

HMD DISPLAYS

VMS

SYSTEM POWER EXTERNAL DOCK MODE

While waiting for the VMS to power on, use the external cameras (F2) and try and locate the station. This is especially important if you are within 500m. You will not have accurate positional data until you have comms set up with the station but you can use the translational controls (The arrow keys and []) to slow your approach or departure. F1 will return you to the cockpit view.

Contact the Local STC

TAB

- 1) Open Chanel
- 3) Local STC
- 1) Announce

Control, this is XX-XXXX (YOU). Come in. Over. XX-XXXX (YOU) this is control. We copy you, Over.

TAB

- 1)Open Chanel
- 3)Local STC
- 2) On Approach

Control, this is XX-XXXX (YOU). On approach. Over. XX-XXXX (YOU), Control. Copy. Continue inbound and contact ST Approach on 45.2.2

NOTE:

You can review all communications by checking the COMMS recorder

F2 HMD

HMD COMMS

XMISSION LOG

Configure ST Approach Channel

F2 HMD

HMD COMMS

CHNL 3

select Left channel box

15

select Center channel box

2

select Right channel box

2

SET

Check In With ST Approach and Request Docking

TAB

- 2) Private Channel
- 2) 45.2.2
- 1) STC
- 1) Check In: ST Approach

ST Approach, this is XX-XXXX (YOU). Checking in. XX-XXXX (YOU), this is ST Approach. We have you checked in. Over.

Note:

Docking requests should be made within 100km of the station

TAR

- 2) Private Channel
- 2) 45.2.2
- 1) STC
- 1) Request Docking

ST Approach, this is XX-XXXX (YOU). Request docking with you. Over

XX-XXXX (YOU), this is Control, Clearance granted. Over. XX-XXXX (YOU), Control. Tune localizer for exterior collar 1 using 45.2.200

Configure STC Docking Channel

```
F2 HMD
HMD COMMS (if unset)
CHNL 4
select Left channel box
45 (if unset)
select Center channel box
2 (if unset)
select Right channel box
200
SET
SET LOC
```

Configure HUD for Docking

F2 HMD

HMD EA/D PORTS
PORT 2 (Amidships Dorsal)
SET AS DOCKING TARGET

✓ HUD *VALID*

Enable NAS

R4 NAS

✓ POWER - ON R4-01 A/P ALLOW - ENABLE R4-02 YAW HOLD - ENABLE R4-06 PITCH HOLD - ENABLE R4-07 ROLL HOLD - ENABLE R4-08

Maneuvering in Space

There are four systems on the spacecraft for maneuvering.
FLUX Drive
MTS Booster
Hot Plasma Maneuvering Jets
Cold Plasma Maneuvering Jets

Note:

This tutorial will not be covering FLUX Drive operation

The MTS Booster system will provide \sim .8m/s per throttle "click" Forward (normal operation) or Aft (Thrust Deflection Enabled **R2-08**) of acceleration.

The Hot Plasma Maneuvering Jets can provide ~ 1.3 m/s of translational or rotational velocity.

The Cold Plasma Maneuvering Jets can provide $\sim .1 \text{m/s}$ of translational or rotational velocity.

Which of these systems you use will depend on the distances involved and your ability to ensure the safety of your spacecraft and any other vessels in the area.

Rule of thumb: No faster than .04m/s per 100m from the target

Translational Velocity moves the spacecraft in any of the six cardinal directions (Up, Down, Left, Right, Forward, Aft) regardless of the current orientation. You can think of this in terms of the WASD keys used in most first or third person video games.

Rotational Velocity changes the orientation of the spacecraft with out affecting its current Translational Velocity (Roll, Pitch, Yaw). You can think of this in terms of mouse-look as used in most first or third person video games.

Note:

Auto Pilot (NAS) will only help you control your rotational velocity at this time. You will have to manually correct your flight to control your translational velocities.

STC Requirements by Distance

Greater than 1500m (1.5km)

Distance Meter will read FAR APPROACH and be GREEN No special considerations

1500m (1.5km)

Distance Meter will read FAR APPROACH and be GREEN STC will ask you to reduce velocity to under 40m/s

1000m (1km)

Distance Meter will read FAR APPROACH and be GREEN At 100m the Distance Meter will begin to decrease

800m

Distnace Meter will read FAR APPROACH and be GREEN STC will ask you to reduce velocity to under 20m/s

500m

Distance Meter will read NEAR APPROACH and be GREEN At 500m the proximity sensor will begin to click. The faster the clicking to closer you are to the target

300m

XX-XXXX (YOU), this is Control. You're under 300 meters. Cease closure and shut-down your MTS CORE. Over.

R2 MTS

ICH COUPLER - DISABLE **R2-06**✓ D7 PLASMA TEMP - COLD PLASMA LEVEL
TOGGLE HELICON COUPLER SAFETY **R2-05 SAFETY**HELICON COUPLER - DISABLE **R2-05**

200m

Distance Meter will read COURSE ALIGN and be ORANGE

100m

STC will ask you to stow any radiators that may be damaged while docking

XX-XXX (YOU), this is Control. You're within 100 meters. Stow all obstructions immediately. Over.

50m

Distance Meter will read FINE ALIGN and be ORANGE

5m

Distance Meter will read PRECISE ALIGN and be RED Height Meter will Reset

2.5m

Distance Meter will read FOR CAPTURE and be RED Height Meter will Reset

0.0m

CONNECTED

In order to successfully dock your spacecraft must:

Be within +/- 4 degrees in Roll, Pitch and Yaw

Be within \pm .05m in the Z and X axis and .03 in the Y axis Be moving no faster than .08m/s

XX-XXXX (YOU), Control. Reading solid contact. Stand by one... Over.

XX-XXXX (YOU) Control. Connection locked and stable. Engaging umbilical. Over

There is more but I can't scroll down :(

That's Great But How Do I Do That?

Some of this will depend on your distance from the target. Once you have channel 4 localized to the docking port (which you can do at any time during the tutorial however you need to talk to STC before you can dock) you can see how far from the station you are and what directions you are moving in. Typically when I start I'm within 500m of the station so I don't have to worry about firing up the engines but your kilometerage(?) may vary.

What to do if you are far from the target

The first thing I do is zero out my velocities in the Z, Y and Z axis

The orientation of your spacecraft probably doesn't line up with the test platform so I wouldn't worry about the O half of the three O V combinations (xO, yO and zO).

xV (Left / Right)

if X is positive translate Right (Right Arrow) to bring it to 0.0

if X is negative translate Left (Left Arrow) to bring it to 0.0 zV (Forward / Aft)

if Z is positive translate Aft (Down Arrow) to bring it to 0.0

if Z is negative translate Forward (Up Arrow) to bring it to 0.0 yV (Up / Down)

if Y is positive translate Down ([) to bring it to 0.0

if Y is negative translate Up (]) to bring it to 0.0

If you are having a difficult time zeroing out your velocities enabling Cold Gas Override (**R2-10**) should help.

Note:

If you need to use the main engines to close distance remember to disable Cold Gas Override (**R2-10**) and switch Thrust Mode Select (**R2-09**) to BSTR ENBL

Point the spacecraft towards to test platform using the rotational controls

Yaw Left (Insert) Yaw Right (PgUp) Pitch Up (End) Pitch Down (Home)

Note:

The x, y and z V indicators will bounce around as you add rotational forces to the spacecraft. This is expected behavior.

The Pitch, Roll and Yaw indicators will be corrected when closer to the station.

Accelerate towards the test platform with a few clicks of the throttle (=) until vZ is \sim 40m/s then throttle back down to zero (-).

Note:

If you cross the 1Km boundary throttle back to zero regardless of speed.

Enable Boost Defl Enable (yuck **R2-08**) and slow the spacecraft down as STC calls out your speed at distance.

1500m 40m/s or less 800m 20m/s or less 300m STC will call for you to stop 300-200m disable ICH and Helicon Couplers

R2 MTS

ICH COUPLER - DISABLE **R2-06**✓ D7 PLASMA TEMP - COLD PLASMA LEVEL
TOGGLE HELICON COUPLER SAFETY **R2-05 SAFETY**HELICON COUPLER - DISABLE **R2-05**

Note:

This will put the spacecraft into Cold Gas Override mode. You should be moving slower than 3 m/s in all three axis before you disable hot plasma production.

What to do if you are near the target

Now that the spacecraft is in a stable position it is time to align the Pitch, Yaw and Roll indicators for docking

The spacecraft needs to be within +/- 4 degrees to successfully dock. The indicators will shift from Red to Orange to Green as your alignment improves.

Pitch

If Pitch is positive pitch down (Home)

if Pitch is negative pitch up (End)

Yaw

if Yaw is positive yaw left (Insert)

if Yaw is negative yaw right (PgUp)

Roll

if Roll is < 180 roll left (Delete)

if Roll is <180 roll right (PgDn)

Alignment Tones:

As you change your alignment you will hear two tones. Tone one is position relative to the two intended docking ports. Tone two is relative to rotational orientation. As you improve alignment both tones will rise. When you are aligned they will harmonize

Now that you are aligned with the docking port check the Height indicator (Z Axis) to insure you are arriving below the target. The indicator should be Green and read a positive number of meters. +10m will insure you do not collide with the training platform regardless of radiator deployment.

vO (Up / Down)

if Y is positive translate Up (])

if Y is negative translate Down ([)

xO (Left / Right)

If X is positive translate Left (Left Arrow)

if X is negative translate Right (Right Arrow)

zO (Forward / Aft)

if Z is positive translate Forward (Up Arrow)

if Z is negative translate Aft (Down Arrow)

Note:

I prefer to set my Y (Up/ Down) height, correct my X (Left/Right) axis, correct my Z (Forward/Aft) axis and finally reduce Y height until docked

Once you are below the station correct the X and Z axis with the translation controls to within \pm -.05m. Check for traffic and docking orientation using the external cameras (F2) to insure you close safely with the station.

Note:

The distance indicators are relative to the docking port and not the edges of the spacecraft!

The FireArc is 30m long and 16m wide with the dorsal docking port centered left to right (8m from each side) and 16m from the front of the spacecraft(14m aft).

You should now be sitting 10m below the docking port with xV, yV and zV reading 0.00m/s and yO and xO reading 0.00m If you have not already stowed the radiator on cooling loop one do so now.

L4 TMS

✓ LOOP SELECT - SYS 1 L4-05 RADIATOR DEPLOY - STOW L4-06

Translate upward to complete the docking maneuver (]) while checking that the spacecraft does not drift in the X and Z axis.

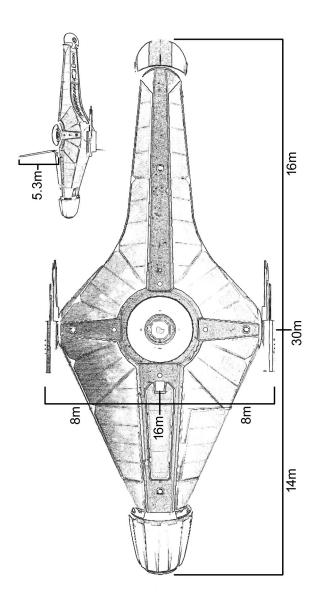
Note:

Docking ports are rated to handle closing speeds up to .08m/s however the nominal closing speed is.03m/s

At .03m in the Y axis, assuming nominal deviation in translation and rotation the spacecraft should dock with the station.

Yay?

Tutorial Checklist 4-24



4.3 Tutorial 5 System Shutdown

If you are doing the tutorial, you need to do this part first

MDR1 COCKPIT HATCH - OPEN MDR1-01
A1 SECURE SEAT - UNSECURE A1-02
enter the seat
L6 SEAT SAFE - ENABLE L6-03 SWITCH - NORM FLIGHT L6-01 CABIN FLOOD LIGHT - DISABLE L6-09 INST LIGHT - ENABLE L6-10

If you are in the seat start from HERE

R2 ICH COUPLER - DISABLE R2-06

✓ D7 PLASMA TEMP – COLD PLASMA LEVEL TOGGLE HELICON COUPLER SAFETY R2-05 SAFETY HELICON COUPLER – DISABLE R2-05

▼ D7 PLASMA TEMP – ZERO

TOGGLE SUPER-CNDCTR SAFETY R2-07 SAFETY SUPER-CNDCTR - DISABLE R2-07

F3 FAULT ACK F3-01

R2 INJCTR ENABLE - DISABLE R2-04
FUEL CUT-OFF - DISABLE R2-03
TOGGLE POWER SAFETY R2-01 SAFETY
POWER OFF R2-01

R4 POWER - OFF R4-01

L3 MAINT CUT-OFF - DISABLE (GREEN) L3-04

R1 FUSE ENABLE - DISABLE R1-12

L2 CYCLE ALL L2-02

✓ SHUT-OFF VALVE - DISABLE L2-03
SHUT-OFF VALVE - DISABLE L2-03
POWER - OFF L2-01

R1 FUEL CUT-OFF - OFF R1-11

L5 CYCLE ALL L5-04

SHUT-OFF VALVE - DISABLE **L5-06** PUMP POWER - OFF **L5-03**

F1 FAULT ACK F1-01

R1 PRE-HEAT - DISABLE R1-09	
L3 SELECT MAIN L3-01 POWER - OFF L3-03	
F2 HMD DISPLAY VMS SYSTEM POWER - DISABLED	
L1 SELECT - SYS 2 L1-02 RECHARGE - DISABLE L1-03 POWER - OFF L1-01	
R1 ✓ D4 CORE TEMP – ZERO LENR ENABLE – DISABLE R1-08 a D4 EM SHIELD – FALLING POWER – OFF R1-07	
R3 XMIT ENABLE - OFF R3-02 POWER - OFF R3-01	
L4 CYCLE ALL L4-05 LOOP DEPR - ENABLE L4-03 ✓ D8 CLNT PRESS - FALLING ✓ PUMP POWER - OFF L4-07	
L3 SELECT - SEC L3-01 POWER - OFF L3-03	
L1 SELECT - SYS 1 L1-02 RECHARGE - DISABLE L1-03 POWER - OFF L1-01	
L3 SELECT - PRI L3-01 POWER - OFF L3-03 MAINT CUT-OFF - ENABLE (YELLOW) L3-04	
L6 INST LIGHT - DISABLE L6-10 CABIN FLOOD LIGHT - ENABLE L6-09 SEAT SAFE - DISABLE L6-03 SELECT TO/LAND L6-01	
A1 SECURE SEAT - SECURE A1-02	
MDR1 COCKPIT HATCH - SEAL MDR1-01	