$$\frac{\partial y_{i}}{\partial x_{j}} = \frac{\partial}{\partial x_{j}} \sum_{k=1}^{n} A_{ik} x_{k}$$

$$= \frac{\partial}{\partial x_{j}} A_{ij} x_{j}$$

$$= A_{ij}$$

$$\frac{\partial}{\partial x_{j}} A_{ik} x_{k}$$

$$\frac{\partial}{\partial x_{j}} A_{ik} = A$$

(b)
$$\frac{\partial x_i}{\partial x_i} w_i x = \frac{\partial x_i}{\partial x_i} \sum_{k=1}^{k=1} w_k x_k$$

$$= w_i$$

$$= w_i$$

$$\nabla_{x} x^{T} A x = \nabla_{x} u^{T} v$$

$$= \left(\frac{\partial u}{\partial x}\right)^{T} v + \left(\frac{\partial v}{\partial x}\right)^{T} u$$

$$= \left(\frac{\partial}{\partial x} x\right)^{T} A x + \left(\frac{\partial}{\partial x} A x\right)^{T} x$$

$$= \left(\frac{\partial}{\partial x} x\right)^{T} A x + \left(\frac{\partial}{\partial x} A x\right)^{T} x$$

$$= \left(\frac{\partial}{\partial x} x\right)^{T} A x + A^{T} x$$

$$= \left(\frac{\partial}{\partial x} x\right)^{T} A x + A^{T} x$$

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(4) ax x10

$$\nabla_{x} \sigma^{T} x x^{T} b = \nabla_{x} u^{T} V$$

$$= \left(\frac{\partial u}{\partial x}\right)^{T} V + \left(\frac{\partial v}{\partial x}\right)^{T} U$$

$$= \left(\frac{\partial u}{\partial x}\right)^{T} V + \left(\frac{\partial v}{\partial x}\right)^{T} U$$

$$= \left(\frac{\partial u}{\partial x}\right)^{T} + \left(\frac{\partial v}{\partial x}\right)^{T} U$$

$$= \left(\frac{\partial v}{\partial x}\right)^{T} + \left(\frac{\partial v}{\partial x}\right)^{T} U$$

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$$= \left(\frac{\partial v}{\partial x}\right)^{T} + \left(\frac{\partial v}{\partial x}\right)^{T} U$$

2. (a) We compute the derivative first:

$$\frac{\partial}{\partial x} \| Ax - b \|_{2} = \frac{\partial}{\partial x} \sqrt{\| Ax - b \|_{2}^{2}}$$

$$= \frac{1}{2 \| Ax - b \|_{2}} \cdot \frac{\partial}{\partial x} \| Ax - b \|_{2}^{2}$$

$$= \frac{1}{2 \| Ax - b \|_{2}^{2}} \cdot \frac{\partial}{\partial x} \| Ax - b \|_{2}^{2}$$

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$$= \frac{1}{2 \| Ax - b \|_{2}} \cdot \frac{\partial}{\partial x} \| Ax - b \|_{2}^{2}$$

$$= \frac{1}{2 \| Ax - b \|_{2}} \cdot \frac{\partial}{\partial x} \| Ax - b \|_{2}^{2}$$

$$= \frac{2 (Ax - b)^{T} A}{2 \| Ax - b \|_{2}}$$

$$= \frac{2 (Ax - b)^{T} A}{2 \| Ax - b \|_{2}}$$

$$= \frac{2 (Ax - b)^{T} A}{2 \| Ax - b \|_{2}}$$

$$\therefore \nabla_{\mathbf{x}} \| \mathbf{A} \mathbf{x} - \mathbf{b} \|_{2} = \frac{1}{\| \mathbf{A} \mathbf{x} - \mathbf{b} \|_{2}} \mathbf{A}^{\mathsf{T}} (\mathbf{A} \mathbf{x} - \mathbf{b})$$

$$\nabla_{x} \|x\|_{2}^{u} = \nabla_{x} (x^{T} I_{x})^{2}$$

$$= 2 \|x\|_{2}^{2} \cdot \nabla_{x} (x^{T} I_{x}) \qquad (gradient chain rule)$$

$$= 4 \|x\|_{2}^{2} x$$

$$\int_{\text{Sum to get the gradient of the entire expression}} \int_{\text{Gradient class, this is}} \nabla_{x} \|x\|_{2}^{u} dx$$

if you've taken a linear algorial taken a linear sis just (A xxi)

(b)
$$\nabla_x \operatorname{tr} (A \times x^T) = \nabla_x \operatorname{tr} (X^T A \times) \leftarrow \operatorname{cyclic} \operatorname{property}$$

$$= \nabla_x X^T A \times A \times \operatorname{ascalar!}$$

$$= (A + A^T) \times$$

(c)
$$\frac{\partial}{\partial x_{i}} - y^{T} \ln x = \frac{\partial}{\partial x_{i}} - \sum_{k=1}^{n} y_{k} \ln x_{k}$$

$$= \frac{\partial}{\partial x_{i}} - y_{i} \ln x_{i}$$

$$= -\frac{y_{i}}{x_{i}} \qquad \therefore \nabla_{x} - y^{T} \ln x = -\frac{y_{i}}{\sqrt{x}}$$
elementwise
function

(d) This one is annoying ...

let
$$\begin{cases} f(x) = y \ln \hat{y} + (1-y) \ln(1-\hat{y}) \\ \frac{df}{d\hat{y}} = \frac{y}{\hat{y}} - \frac{1-y}{1-\hat{y}} \end{cases}$$
will use this to apply chain rule.

:.
$$\nabla_w \quad g \quad \text{In } g(x) + (i-y) \quad \text{in } (i-y) = \left(\frac{y}{g(x)} - \frac{1-y}{1-g(x)}\right) \quad \nabla_w \left(\frac{1}{1+e^{-w^2x}}\right)$$

note: this notation is

a b-t annoying because
here we are treating
$$g(x) \text{ as a function of}$$

$$w \quad \text{In not } X, \text{ which}$$

$$\text{Is held constant...} = \left(\frac{y}{g(x)} - \frac{1-y}{1-g(x)}\right) \left[g(x)\left(1-g(x)\right)\right] \quad \nabla_w \left(w^Tx\right)$$

ac g(x) since it represents a decision function which maps x to a probability

$$\frac{d}{du} \sigma(u) = \frac{d}{du} \frac{1}{(1+e^{-u})}$$

$$= \frac{1}{(1+e^{-u})^2} \left[\frac{d}{du} \frac{1}{(1+e^{-u})} - \frac{d}{(1+e^{-u})} \cdot 1 \right]$$

$$= \frac{e^u}{(1+e^{-u})^2}$$

$$= \frac{1}{1+e^{-u}} \frac{e^{-u}}{1+e^{-u}}$$

$$= \frac{1}{1+e^{-u}} \left(1 - \frac{1}{1+e^{-u}} \right)$$

$$= \sigma(u) \left[1 - \sigma(u) \right]$$

3. First we establish the following property of the traces

$$tr(X) := \sum_{i=1}^{n} X_{ii}$$

$$\therefore tr(X^{T}Y) = \sum_{i=1}^{n} (X^{T}Y)_{ii}$$

$$assume X \in \mathbb{R}^{m \times n}$$

$$Y \in \mathbb{R}^{m \times n}$$

$$X^{T} \in \mathbb{R}^{n \times m}$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{m} X_{ji} Y_{ji}$$

$$= \sum_{i=1}^{m} \sum_{j=1}^{n} X_{ij} Y_{ij}$$

(a)
$$\frac{\partial}{\partial X_{ij}}$$
 $\text{tr}(A^TX) = \frac{\partial}{\partial X_{ij}} \sum_{i=1}^{n} \sum_{j=1}^{n} X_{ij} A_{ij}$

$$= \frac{\partial}{\partial X_{ij}} X_{ij} A_{ij}$$

$$= A_{ij} \qquad \therefore \nabla_X \text{tr}(A^TX) = A$$

enotice this says $\nabla_x (AX) = A$ which is as expected!

$$= (ba_{\perp})_{\perp}$$

$$= (ba_{\perp})_{\perp}$$

$$= ab_{\perp}$$

$$= \frac{\partial X_{ij}}{\partial X_{ij}} \|X\|_{F}^{2} = \frac{\partial}{\partial X_{ij}} \sum_{i=1}^{i=1} \sum_{j=1}^{i=1} X_{ij}^{2}$$

$$= \frac{\partial}{\partial X_{ij}} X_{ij}^{2}$$

$$= \frac{\partial}{\partial X_{ij}} X_{ij}^{2}$$

$$\therefore \nabla_{X} \|X\|_{F}^{2} = 2X$$

(d) This one is a bit annoying ...

$$X := \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$1et \quad X : \in \mathbb{R}^{m} \text{ denote the columns of the}$$

$$AX = \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ X_1 & X_2 & \dots & X_n \end{bmatrix} = \begin{bmatrix} A_1 & A_1 & A_2 & \dots & A_n \\ A_n & A_n & A_n \end{bmatrix}$$

$$\therefore \|AX\|_F^2 = \sum_{i=1}^n \|AX_i\|_2^2$$
all verters

so
$$\nabla_{x} \|AX_{F}\|_{2}^{2} = \begin{bmatrix} 1 & 1 & 1 \\ 2A^{T}Ax_{1} & 2A^{T}Ax_{2} & \cdots & 2A^{T}Ax_{n} \end{bmatrix}$$

$$= 2A^{T}A\begin{bmatrix} 1 & 1 & 1 \\ X_{1} & X_{2} & \cdots & X_{n} \\ 1 & 1 & 1 \end{bmatrix}$$

$$= 2A^{T}AX$$

```
W= arg min f(w; PQ W wo)

take gradient of objective & set it equal to 0:
```

$$\nabla_{w} f(w) = \nabla_{w} (xw - y)^{T} P(xw - y) + (w - w_{0})^{T} Q(w - w_{0})$$

$$= \left(\frac{\partial}{\partial w} Xw - y\right)^{T} 2P(xw - y) + \left(\frac{\partial}{\partial w} w - w_{0}\right)^{T} 2Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 T^{T} Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 Q(w - w_{0})$$

$$= 2 X^{T} P(xw - y) + 2 Q(w - w_{0})$$

$$2 \times^{T} P(Xw-y) + 2Q(w-w_{0}) = 0$$

$$(X^{T}PX + Q) w - (X^{T}Py + Qw_{0}) = 0$$

$$(X^{T}PX + Q) w - (X^{T}Py + Qw_{0}) = 0$$

$$(X^{T}PY + Q) w = (X^{T}Py + Qw_{0})$$

$$P \neq 0 \text{ then } X^{T}PX \neq 0$$

$$Q \neq 0$$

$$matrix positive definite definite so an inverse exists
$$\begin{cases} w \neq 1 & (X^{T}PX + Q)^{-1} (X^{T}Py + Qw_{0}) \\ \text{optimal} \end{cases}$$

$$\begin{cases} v = 1 & (X^{T}PX + Q)^{-1} (X^{T}Py + Qw_{0}) \\ \text{optimal} \end{cases}$$$$