

An Introduction to DOS FAT Volume and File Structure

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1. Introduction

When the first personal computers with disks became available, they were very small (a few megabytes of disk and a few dozen kilobytes of memory). A file system implementation for such machines had to impose very little overhead on disk space, and be small enough to fit in the BIOS ROM. BIOS stands for **BASIC I/O Subsystem**. Note that the first word is all upper-case. The purpose of the BIOS ROM was to provide run-time support for a BASIC interpreter (which is what Bill Gates did for a living before building DOS). DOS was never intended to provide the features and performance of real timesharing systems.

Disk and memory size have increased in the last thirty years. People now demand state-of-the-art power and functionality from their PCs. Despite the evolution that the last decades have seen, old standards die hard. Much as European train tracks maintain the same wheel spacing used by Roman chariots, most modern OSs still support DOS FAT file systems. DOS file systems are not merely around for legacy reasons. The ISO 9660 CDROM file system format is a descendant of the DOS file system.

The DOS FAT file system is worth studying because:

- It is heavily used all over the world, and is the basis for more modern file system (like 9660).
- It provides reasonable performance (large transfers and well clustered allocation) with a very simple implementation.
- It is a very successful example of "linked list" space allocation.

2. Structural Overview

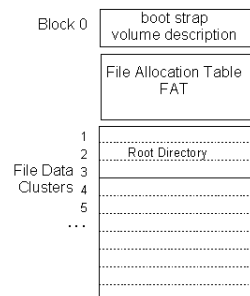
All file systems include a few basic types of data structures:

- **bootstrap**
code to be loaded into memory and executed when the computer is powered on. MVS volumes reserve the entire first track of the first cylinder for the boot strap.
- **volume descriptors**
information describing the size, type, and layout of the file system ... and in particular how to find the other key meta-data descriptors.
- **file descriptors**
information that describes a file (ownership, protection, time of last update, etc.) and points where the actual data is stored on the disk.
- **free space descriptors**
lists of blocks of (currently) unused space that can be allocated to files.
- **file name descriptors**
data structures that user-chosen names with each file.

DOS FAT file systems divide the volume into fixed-sized (physical) blocks, which are grouped into larger fixed-sized (logical) block clusters.

The first block of DOS FAT volume contains the bootstrap, along with some volume description information. After this comes a much longer **File Allocation Table** (FAT from which the file system takes its name). The File Allocation Table is used, both as a free list, and to keep track of which blocks have been allocated to which files.

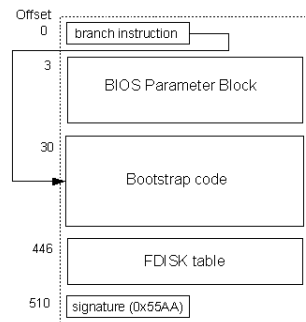
The remainder of the volume is data clusters, which can be allocated to files and directories. The first file on the volume is the root directory, the top of the tree from which all other files and directories on the volume can be reached.



3. Boot block BIOS Parameter Block and FDISK Table

Most file systems separate the first block (pure bootstrap code) from volume description information. DOS file systems often combine these into a single block. The format varies between (partitioned) hard disks and (unpartitioned) floppies, and between various releases of DOS and Windows ... but conceptually, the boot record:

- begins with a branch instruction (to the start of the real bootstrap code).
- followed by a volume description (BIOS Parameter Block)
- followed by the real bootstrap code
- followed by an optional disk partitioning table
- followed by a signature (for error checking).



3.1 BIOS Parameter Block

After the first few bytes of the bootstrap comes the BIOS parameter block, which contains a brief summary of the device and file system. It describes the device geometry:

- number of bytes per (physical) sector
- number of sectors per track
- number of tracks per cylinder
- total number of sectors on the volume

It also describes the way the file system is laid out on the volume:

- number of sectors per (logical) cluster
- the number of reserved sectors (not part of file system)
- the number of Alternate File Allocation Tables
- the number of entries in the root directory

These parameters enable the OS to interpret the remainder of the file system.

3.2 FDISK Table

As disks got larger, the people at MicroSoft figured out that their customers might want to put multiple file systems on each disk. This meant they needed some way of partitioning the disk into logical sub-disks. To do this, they added a small partition table (sometimes called the FDISK table, because of the program that managed it) to the end of the boot strap block.

This FDISK table has four entries, each capable of describing one disk partition. Each entry includes

- A partition type (e.g. Primary DOS partition, UNIX partition).
- An ACTIVE indication (is this the one we boot from).
- The disk address where that partition starts and ends.
- The number of sectors contained within that partition.

Partn	Type	Active	Start (C:H:S)	End (C:H:S)	Start (logical)	Size (sectors)

1	LINUX	True	1:0:0	199:7:49	400	79,600
2	Windows NT		200:0:0	349:7:49	80,000	60,000
3	FAT 32		350:0:0	399:7:49	140,000	20,000
4	NONE					

In older versions of DOS the starting/ending addresses were specified as cylinder/sector/head. As disks got larger, this became less practical, and they moved to logical block numbers.

The addition of disk partitioning also changed the structure of the boot record. The first sector of a disk contains the Master Boot Record (MBR) which includes the FDISK table, and a bootstrap that finds the active partition, and reads in its first sector (Partition Boot Record). Most people (essentially everyone but Bill Gates :-)) make their MBR bootstrap ask what system you want to boot from, and boot the active one by default after a few seconds. This gives you the opportunity to choose which OS you want to boot. Microsoft makes this decision for you ... you want to boot Windows.

The structure of the Partition Boot Record is entirely operating system and file system specific ... but for DOS FAT file system partitions, it includes a BIOS Parameter block as described above.

4. File Descriptors (directories)

In keeping with their desire for simplicity, DOS file systems combine both file description and file naming into a single file descriptor (directory entries). A DOS directory is a file (of a special type) that contains a series of fixed sized (32 byte) directory entries. Each entry describes a single file:

- an 11-byte name (8 characters of base name, plus a 3 character extension).
- a byte of attribute bits for the file, which include:
 - Is this a file, or a sub-directory.
 - Has this file changed since the last backup.
 - Is this file hidden.
 - Is this file read-only.
 - Is this a system file.
 - Does this entry describe a volume label.
- times and dates of creation and last modification, and date of last access.
- a pointer to the first logical block of the file. (This field is only 16 bits wide, and so when Microsoft introduced the FAT32 file system, they had to put the high order bits in a different part of the directory entry).
- the length (number of valid data bytes) in the file.

Name (8+3)	Attributes	Last Changed	First Cluster	Length
.	DIR	08/01/03 11:15:00	61	2,048
..	DIR	06/20/03 08:10:24	1	4,096
MARK	DIR	10/15/04 21:40:12	130	1,800
README.TXT	FILE	11/02/04 04:27:36	410	31,280

If the first character of a files name is a NULL (0x00) the directory entry is unused. The special character (0xE5) in the first character of a file name is used to indicate that a directory entry describes a deleted file. (See the section on Garbage collection below)

Note on times and dates:

DOS stores file modification times and dates as a pair of 16-bit numbers:

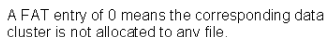
- All file systems use dates relative to some epoch (time zero). For DOS, the epoch is midnight, New Year's Eve, January 1, 1980. A seven bit field for years means that the the DOS calendar only runs til 2107. Hopefully, nobody will still be using DOS file systems by then :-)

Many file systems have very compact (e.g. bitmap) free lists, but most of them use some per-file data structure to keep track of which blocks are allocated to which file. The DOS File Allocation Table is a relatively unique design. It contains one entry for each logical block in the volume. If a block is free, this is indicated by the FAT entry. If a block is allocated to a file, the FAT entry gives the logical block number of the **next** logical block in the file.

Space is allocated to files, not in (physical) blocks, but in (logical) multi-block clusters. The number of clusters per block is determined when the file system is created.

The maximum number of clusters a volume can support depends on the width of the FAT entries. In the earliest FAT file systems (designed for use on floppies, and small hard drives), an 8-bit wide FAT entry would have been too small ($256 * 512 = 128K$ bytes) to describe even the smallest floppy, but a 16-bit wide FAT entry would have been ludicrously large (8-16 Megabytes) ... so Microsoft compromised and adopted 12-bit wide FAT entries (two entries in three bytes). These were called FAT-12 file systems. As disks got larger, they created 2-byte wide (FAT-16) and 4-byte wide (FAT-32) file systems.

A file's directory entry contains a pointer to the first cluster of that file. The File Allocation Table entry for that cluster tells us the cluster number **next** cluster in the file. When we finally get to the last cluster of the file, its FAT entry will contain a -1, indicating that there is no next block in the file.



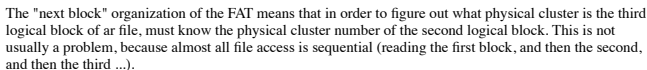
Older versions of FAT file systems did not bother to free blocks when a file was deleted. Rather, they merely crossed out the first byte of the file name in the directory entry (with the reserved value 0xE5). This had the advantage of greatly reducing the amount of I/O associated with file deletion ... but it meant that DOS file systems regularly ran out of space.

This "feature" was probably motivated by a combination of laziness and a desire for performance. It did, however, have an advantage. Since clusters were not freed when files were deleted, they could not be reallocated until after garbage collection was performed. This meant that it might be possible to recover the contents of deleted files for quite a while. The opportunity this created was large enough to enable Peter Norton to start a very successful company.

The DOS file system has evolved with time. Not only have wider (16- and 32-bit) FAT entries been used to support larger disks, but other features have been added. The last stand-alone DOS product was DOS 6.x. After this, all DOS support was under Windows, and along with the change to Windows came an enhanced version of the FAT file system called Virtual FAT (or simply VFAT).

Most DOS and Windows systems were used for personal productivity, and their users didn't demand much in the way of file system features. Their biggest complaints were about the 8+3 file names. Windows users demanded longer and mixed-case file names.

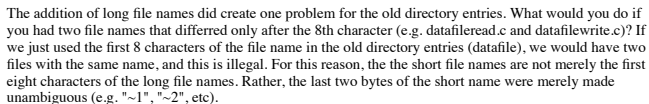
The 32 byte directory entries didn't have enough room to hold longer names, and changing the format of DOS directories would break hundreds or even thousands of applications. It wasn't merely a matter of



If we had to go to disk to re-read the FAT each time we needed to figure out the next block number, the file system would perform very poorly. Fortunately, the FAT is so small (e.g. 512 bytes per megabyte of file system) that the entire FAT can be kept in memory as long as a file system is in use. This means that successor block numbers can be looked up without the need to do any additional disk I/O. It is easy to imagine

The notion of "next block" is only meaningful for clusters that are allocated to a file ... which leaves us free to use the FAT entries associated with free clusters as a free indication. Just as we reserved a value (-1) to mean **end of file** we can reserve another value (0) to mean **this cluster is free**.

To find a free cluster, one has but to search the FAT for an entry with the value -2. If we want to find a free cluster near the clusters that are already allocated to the file, we can start our search with the FAT entry after the entry for the first cluster in the file.



The File Allocation Table is a very concise way of keeping track of all of the next-block pointers in the file system. If anything ever happened to the File Allocation Table, the results would be disastrous. The directory entries would tell us where the first blocks of all files were, but we would have no way of figuring out where the remainder of the data was.

Events that corrupt the File Allocation Table are extremely rare, but the consequences of such an incident are catastrophic. To protect users from such eventualities, Microsoft added support for alternate FATs. Periodically, the primary FAT would be copied to one of the pre-reserved alternate FAT locations. Then if something bad happened to the primary FAT, it would still be possible to read most files (files created before the copy) by using the back-up FAT. This is an imperfect solution, as losing new files is bad ... but losing all files is worse.

6.3 ISO 9660



Security and trust issues in Fog computing: A survey

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HIGHLIGHTS

- We discuss and analyze the architectures of Fog computing, and indicate the related potential security and trust issues.
- We analyze how such issues have been tackled in the existing investigations.
- We indicate the open challenges, research trends and future topics of security and trust in Fog computing.

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ABSTRACT

Fog computing uses one or more collaborative end users or near-user edge devices to perform storage, communication, control, configuration, measurement and management functions. It can well solve latency and bandwidth limitation problems encountered by using cloud computing. First, this work discusses and analyzes the architectures of Fog computing, and indicates the related potential security and trust issues. Then, how such issues have been tackled in the existing literature is comprehensively reported. Finally, the open challenges, research trends and future topics of security and trust in Fog computing are discussed.

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1. Introduction

Cloud computing (the Cloud in brief) has drastically changed the landscape of information technology (IT) by providing some major benefits to IT users, including eliminating upfront IT investment, scalability, proportional costs, and so on [1–5]. However, as more and more devices are connected, latency-sensitive applications seriously face the problem of large latency. In addition, Cloud computing is unable to meet the requirements of mobility support and location awareness. To overcome these problems, a new paradigm called Fog computing (the Fog in brief) was proposed in 2012 [6,7].

According to Bonomi et al. [8], the Fog is a highly virtualized platform that provides storage, computing and networking services between the Cloud data centers and end devices. Both Cloud and Fog provide data, computation, storage and application services to end users [9]. However, the latter is distinguished from the former by its decentralization, processing large amounts of

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Network equipment like switches and gateways is provided by Cisco, Huawei, Ericsson, etc. The current research trends reflect the tremendous potential of the Fog.

The Fog features with location awareness, low latency and edge location [13]. It fits to a scenario where a huge number of heterogeneous ubiquitous and decentralized devices communicate, need to cooperate, and perform storage and processing tasks [6]. Users can visit their Fog anytime by using any device that can be connected to the Fog network. The Fog has many applications in such areas as smart city [14–16] and healthcare [17–20]. It can also provide better Quality of Service (QoS) in terms of fast response and small energy consumption [21,22].

The Fog uses network devices (named Fog nodes in this paper) for latency-aware processing of data collected from Internet of Things (IoT) [23]. Fog nodes are denoted as heterogeneous components deployed in an edge network in Fog environment. They include gateways, routers, switches, access points, base stations, and specific Fog servers [24]. The Fog facilitates uniform and seamless resource management including computation, networking and storage allocation [25]. Fog nodes are often the first set of processors that data encounter in IoT, and have the resources to implement a full hardware root of trust. This root of trust can be extended to all the processes and applications running on them, and then to the Cloud [26]. Without a hardware root of trust, various attack scenarios can compromise the software infrastructures of the Fog, allowing hackers to gain a foothold. The requirements of life safety-critical systems mandate the sorts of security capabilities available on the Fog [27]. Hence, new security and trust challenges emerge with the rise of the Fog. The existing methods cannot be directly applied to the Fog because of its mobility, heterogeneity, large-scale geo-distribution [12]. This work reviews these concerns in the Fog and the existing solutions. Differing from other survey papers about Fog computing, this paper focuses on its security and trust issues, especially in the region of the Fog.

The rest of this paper is organized as follows. Section 2 reveals a Fog architecture as well as related security and trust issues. Section 3 summarizes the related work to cope with security and trust issues. Section 4 presents open research problems. Section 5 discusses the future work. Finally, Section 6 concludes this survey paper.

2. Fog computing architecture

2.1. General architecture

Based on the modern computing architecture with three layers [11,21]: the Cloud, the Fog and the Edge, we provide a comprehensive fog architecture as shown in Fig. 1. Between the Cloud and the Fog lies a core network to offer network services. From it we can see that the Cloud lies at the upper core level and is far away from edge devices. The Fog lies at the middle level and is closer to edge devices than the Cloud. Each Fog node is connected to the Cloud. Each edge device is connected to a Fog node [28]. In addition, we can see that Fog nodes can be connected to each other. Communications between Fog-Fog, Fog-Cloud, and Fog-Edge are all bi-directional.

The Cloud: It includes high-performance servers and storage devices for broadcasting, data warehousing and big data analysis [19]. It is the remote control and management center that can store large data, and process highly complex but often non-urgent tasks. The data is sent to the Cloud through high-speed wireless or wired communications. The Cloud provides ultimate and global coverage. As a repository, it provides data storage to meet users' long-term needs and intelligent data analysis.

The Fog: It consists of a network of interconnected Fog nodes [19,24]. It provides geo-distributed, low latency and urgent computation as well as location awareness. Each Fog node is a resource

data locally, software installation on heterogeneous hardware [10], proximity to end-users, dense geographical distribution, and support for mobility [11].

Here, we show an example of a traffic light system to discuss the relationship between them when dealing with latency. In a traffic light system without the Fog, there may be 3–4 hops from the monitoring probe to the server in the Cloud. Hence, real-time decisions cannot be made immediately and the system faces the challenge of network latency. However, by using the Fog, the monitoring probe acts as a sensor, and the traffic lights act as an actuator. The Fog node can send conventional compressed video that may endure some time latency to the Cloud. When the Fog node detects an ambulance's headlight flashing, it makes an immediate decision to turn on the corresponding traffic lights, so as to let the ambulance go through without any delay. However, the Fog cannot replace the Cloud but supplements it.

Many companies and institutes, such as ARM, Cisco, Dell, Intel, Microsoft Corp., Cloudlet, Intelligent Edge by Intel and the Princeton University Edge Laboratory are devoted to research and development of the Fog. OpenFog (Founded in 2015) Consortium workgroups are working towards creating an open architecture for the Fog to enable its interoperability and scalability [12].

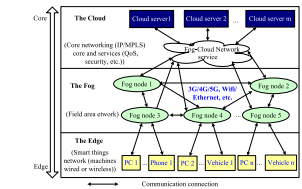


Fig. 1. A comprehensive Fog architecture.

center for ephemeral storage. Its functions include network transform, data collection, communications, data upload, data storage, computation and management. Compared with the edge devices, Fog nodes have more memory or storage ability for computing, which makes it possible to process a significant amount of data from edge devices. On the other hand, when needing a more complex and long-time computation, the computation work should be sent to the Cloud by Fog nodes through various available communications technologies, e.g., 3G/4G/5G cellular networks and WiFi. Fog nodes are bridges between Cloud and edge devices.

Fog nodes are independent and can be interconnected for collaboration. Management and collaborative procedures are applied on Fog nodes to implement management and control. The collaboration among Fog nodes can be executed via remote or local communications among them.

The Edge: It consists of several physical devices (edge devices) enabled with their ubiquitous identification, sensing, and communication capacity [19], such as vehicles, machines and cell phones. Each edge device is connected to one of the Fog nodes. Edge devices have a large variety of sensors and local data. It is very expensive and time-consuming to send all the data from terminal edge devices to the Cloud through a network. Hence, by connecting them to Fog nodes, one can deal with the urgent data but not transfer from edge devices to the cloud immediately.

Some easily misunderstood concepts are discussed in the following.

Edge computing vs. the Fog: Edge computing is different from the Fog in that the latter is a highly virtualized platform that provides computation, storage, and networking services between end devices and Cloud computing data centers [11]. Both of them need to push intelligence and processing capabilities out of centralized data centers and down closer to edge devices, such as IoT sensors, relays, and motors. The key difference between them is where intelligence and computing power are placed [12]. The Fog pushes intelligence down to the local area network (LAN) level, processing data in Fog nodes. While Edge computing pushes the intelligence, processing power, and communication capabilities further down to edge devices [29]. More details between them are discussed in [24]. In [30], Endpoint computing is regarded as Edge computing. Other similar concepts such as Cloudlets and Micro-data centers are discussed in [31].

Wireless sensor networks (WSNs) vs. the Fog: WSNs are designed to operate at very low power to extend battery life or use energy harvesting to sustain themselves. Most of them face the problems of small memory nodes, low processing power, and

When CDs were proposed for digital storage, everyone recognized the importance of a single standard file system format. Dueling formats would raise the cost of producing new products ... and this would be a lose for everyone. To respond to this need, the International Standards Organization chartered a sub-committee to propose such a standard.

The failings of the DOS file system were widely known by this time, but, as the most widely used file system on the planet, the committee members could not ignore it. Upon examination, it became clear that the most idiomatically features of the DOS file system (the File Allocation Table) were irrelevant to a CDROM file system (which is written only once):

- We don't need to keep track of the free space on a CD ROM. We write each file contiguously, and the next file goes immediately after the last one.
- Because files can be written contiguously, we don't need any "next block" pointers. All we need to know about a file is where its first block resides.

It was decided that ISO 9660 file systems would (like DOS file systems) have tree structured directory hierarchies, and that (like DOS) each directory entry would describe a single file (rather than having some auxiliary data structure like and l-node to do this). 9660 directory entries, like DOS directory entries, contain:

- file name (within the current directory)
- file type (e.g. file or directory)
- location of the file's first block
- number of bytes contained in the file
- time and date of creation

They did, however, learn from DOS's mistakes:

- Realizing that new information would be added to directory entries over time, they made them variable length. Each directory entry begins with a length field (giving the number of bytes in this directory entry, and thus the number of bytes until the next directory entry).
- Recognizing the need to support long file names, they also made the file name field in each entry a variable length field.
- Recognizing that, over time, people would want to associate a wide range of attributes with files, they also created a variable length extended attributes section after the file name. Much of this section has been left unused, but they defined several new attributes for files:
 - file owner
 - owning group
 - permissions
 - creation, modification, effective, and expiration times
 - record format, attributes, and length information

But, even though 9660 directory entries include much more information than DOS directory entries, it remains that 9660 volumes resemble DOS file systems much more than they resemble any other file system format. And so, the humble DOS file system is reborn in a new generation of products.

7. Summary

DOS file systems are very simple. They don't support multiple links to a file, or symbolic links, or even multi-user access control. They are also and very economical in terms of the space they take up. Free block lists, and file block pointers are combined into a single (quite compact) File Allocation Table. File descriptors are incorporated into the directory entries. And for all of these limitations, they are probably the most widely used file system format on the planet. Despite their primitiveness, DOS file systems were used as the basis for much newer CD ROM file system designs.

What can we infer from this? That most users don't need a lot of fancy features, and that the DOS file system

(primitive as it may be) covers their needs pretty well.

It is also noteworthy that when Microsoft was finally forced to change the file system format to get past the 8.3 upper case file name limitations, they chose to do so with a klugy (but upwards compatible) solution using additional directory entries per file. The fact that they chose such an implementation clearly illustrates the importance of maintaining media interchangeability with older systems. This too is a problem that all (successful) file systems will eventually face.

8. References

DOS file system information

- PC Guide's [Overview of DOS FAT file systems](#). (this is a pointer to the long filename article ... but the entire library is nothing short of excellent).
- Free BSD sources, PCFS implementation, [BIOS Parameter block format](#), and (Open Solaris) [FDISK table format](#).
- Free BSD sources, PCFS implementation, [Directory Entry format](#)

9660 file system information

- Wikipedia Introduction to [ISO 9660 file systems](#)
- Free BSD sources, ISOFS implementation, [ISO 9660 data structures](#).

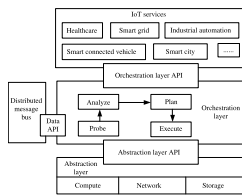


Fig. 2. The fog architecture implementation [13].

sometimes unreliable sensors. The fog is a suitable platform to support WSNs [11]. In addition, Romana et al. differentiate the features among Mobile Edge computing, Mobile Cloud computing, Fog and Cloud computing [32].

From Fig. 1 and the above analysis, we reveal the following security and trust issues for the fog: Since the fog is designed upon traditional networking components, it is highly vulnerable to security attacks. It is hard to ensure authenticated access to services and maintenance of privacy in a large fog [28]. We can also see that the distributed and open nature of its hierarchical structure makes it vulnerable to security threats. Traditional security and trust issues, such as wiretapping, tampering, loss of information, and Trojan horses, still exist. The new ones caused by fog characteristics are listed as follows:

- For an edge device, it may have to switch the connection to its nearby fog node when faults happen. This may need to build a new connection and transfer data from the former fog node to the new one, which may bring about more chance for new security when such connection fails.
- It also faces the crisis of re-locating a new fog node for communications if its connected fog node malfunctions when building a new connection from a fog node to the Cloud.

2.2. Detailed architecture design

Based on the architecture in Fig. 1, the topological structures enable communications among fog nodes and include net-like and bus topology as shown in [28] and [33], respectively. The former is more complex and may cause more communication overhead, security and trust risk. The shortcomings of bus topology include data collision, limited communication distance and limited range. It is also difficult to diagnose and isolate faults with it.

From the communication relationship among the fog nodes, we reveal the following security and trust issues:

- Each fog node is not only independent, but also can be collaborative with other ones through message passing. If fog nodes fail to be well integrated into the network and work together to create meaningful services, trust problems may happen.
- When a new fog node comes or an old one cannot provide its service and has to quit, the other fog nodes potentially have to change their topology and rebuild their communication structure so as to enable communications among them. This may bring about new security issues as caused by such a topology rebuilding process.

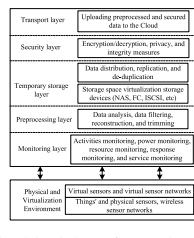


Fig. 3. The layered architecture of a gateway in the fog [37].

- When fog nodes collaborate with other nodes, if one node is attacked by malicious users and is infected, the infected one may attack or infect other nodes. This induces security or trust crisis among all the collaborative nodes.
- Fog nodes can communicate via a network. The communication overhead among them may be large. For latency-sensitive applications, it can be a serious problem. It will slow the system reliability and then cause trust crisis for users when their task deadlines are missed. Hence, how to decrease the communication overhead to an acceptable level is a significant issue.

2.3. Architecture implementation

A three-layer fog architecture [13] is realized as shown in Fig. 2. It has IoT services, orchestration layer and distributed message bus, and abstraction layer.

IoT services: The fog platform hosts a set of diverse service applications, such as smart city. An IoT service is viewed as a way for users to access their needed functionality/application [34].

Orchestration layer and distributed message bus: Orchestration is the process through which the fog systems determine how the virtualized resources are allocated and inter-operated. It is essential that orchestration is aware of the instantaneous state of the fog network, and reacts quickly to any changes in its configuration, load, or status [27]. The core issues, changes, and future research directions in fog-enabled orchestration for IoT services is overviewed in [35]. Because its services and infrastructure are distributive, the fog should provide necessary means for distributed policy-based orchestration, which results in the scalable management of individual systems and the overall services. The orchestration functionality is distributed across the fog deployment while distributed control provides better resiliency, higher scalability, and faster orchestration for geographically distributed deployments than centralized control [35]. The messaging bus is used for communications. The layer provides policy-based and dynamic life cycle management for fog services. There are four parts in the life cycle: probing, analyzing, planning, and executing a task.

Abstraction layer: It provides uniformity in a heterogeneous infrastructure environment over various access, control and management of resources through customized Application Programming

Table 1
The summary of security and trust issues in major survey papers.

Ref.	Security and trust issues in the fog	Characteristics
[10]	(1) Virtualization issues (2) Web security issues (3) Internal/external communication issues (4) Data security related issues (5) Wireless security issues (6) Malware protection	Detailed definition and discussion of potential security issues of a fog platform inherited from Cloud computing are given: (1) Access to services: persistent threats, access control issues, account hijacking and denial of services; (2) Platform or system: insecure APIs, system and application vulnerabilities, malicious insiders, insufficient due diligence, abuse and nefarious use, and shared technology issues; (3) Data: data loss and data breaches.
[12]	(1) Trust (2) Authentication (3) Secure communications in the fog (4) End user's privacy (5) Malicious attacks	Challenges about the following issues are presented: (1) Malicious or malfunctioning in fog nodes (2) Malicious insider attack (3) Mutual authentication (4) Privacy preservation (5) Fog forensics (6) Authentication and key agreement in fog computing-based radio access networks.
[42]	(1) Man-in-the-middle (MitM) Attack (2) Intrusion detection (3) Malicious detection technique in the fog environments (4) Malicious fog node problem (5) Data protection (6) Data management issues	Several unique security threats are introduced to the fog.
[40]	(1) Trust issue (2) Preserving integrity (3) Logs-related issues (4) Dependability for data acquisition (5) Compliance issue (6) Low forensics issues (7) Multi-tenancy issues (8) Chain of custody	More extensive researches in fog security and fog forensics are promoted.
[28]	(1) Authentication (2) Privacy (3) Encryption (4) Denial of service (DoS) attack	Reliability in the fog can be discussed in terms of consistency of fog nodes, availability of high-performance services, secured interactions and fault tolerance [28].
[43]	(1) Network security (2) Data security (3) Access control (4) Privacy	Location privacy and data confidentiality are focused. The greatest risk comes from the outside attack.
[44,45]	(1) Intrusion detection (2) Authentication	Stealthy features of MitM attack is investigated by checking the CPU and memory consumption of a fog node. Authentication of connection between the fog and the cloud.

Table 2
The summary of the references.

	2014	2015	2016	2017	2018	Total
Trust	1	0	3	5	0	9
Authentication and Access Control	2	0	0	5	3	10
Attack	1	3	0	0	0	4
Privacy preservation	0	1	5	9	3	18
Secure communications	0	0	5	5	1	6
The others	0	0	1	8	1	11
Total	5	3	10	35	9	62

an event's location. Koo et al. present a hybrid secure deduplication protocol by taking untrustworthy fog storage environments into account [47]. The work [48] introduces a trusted third party (TTP) into its privacy preservation. Because malicious attacks can cause sensor communications to be unreliable, a trust evaluation method is needed to ensure the reliability relationship among sensors to resist malicious attacks. Fog nodes are adopted to help the system compute trust values [49].

3.2.2. Collision detection

Wang et al. [50] study the trust scheme of a publish-subscribe system (PSS) [51] in the fog, so as to defend trust against collusion attack. PSS has been widely applied in many modern large-scale critical systems, for example, traffic monitoring. A generic broker-based PSS is given in [52].

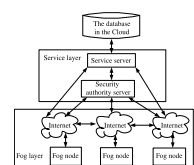


Fig. 4. Service middleware in the fog [18].

Interfaces (APIs) and User Interfaces. Generic APIs concern security, isolation and privacy to various tenants.

In Fig. 2, from the fog nodes themselves, we observe the following security and trust issues:

- New security and trust issues are raised because of service orchestration: It needs to specify how and what services must be chained before delivery. Highly trusted services should be chosen to execute the entire service.
- At the abstraction layer, security is related with isolation and privacy in multi-tenancy.

Because a gateway can be a fog node in the fog, which is different from the gateway in [36]. A five-layer architecture of the fog gateway as a fog node is shown in Fig. 3 [37]. Below the five layers are many things, sensors and WSNs in a physical and virtualization environment. The following five layers are on the top of the environment:

Monitoring layer: It monitors activities, power, responses, and services when performing tasks. Effective measures are taken in time.

Preprocessing layer: It analyzes, filters, reconstructs and trims data.

Temporary storage layer: It supports data distribution, replication and storage space virtualization. It stores preprocessed data in fog nodes and passes them to the Cloud.

Security layer: Some private data may be generated via IoT devices and WSNs, such as ubiquitous health care data. Location-aware data sometimes is sensitive when security and privacy issues are concerned.

Transport layer: It uploads the ready-to-send data to the Cloud. After being uploaded, the data is removed from fog nodes.

From Fig. 3, we find the following security and trust issues:

- Storage is needed in the fog. Regarding the storage, some problems may be faced. For example, after an edge device sends data to its connected fog node, what data is chosen to be stored in the fog node and in the Cloud? If the urgent data is large and not permitted to be stored in the Cloud, how can we use the fog node's orchestration to realize security and high efficient storage? A hybrid storage approach for IoT in Paas cloud federation [38] is proposed. The issues about secure data storage and search for industrial IoT by integrating Fog Computing and Cloud Computing [39] are investigated.
- How can we realize cost-effectiveness and high resiliency against failures in crucial applications [30]?
- If a large job is needed to be processed at the preprocessing layer and is beyond the computation ability of the connected fog node, how should it do? Those measures should be taken for it.
- Gateways serving as fog nodes may be compromised or taken over by fake ones [40].

From the above analysis of the fog computing architecture, we can see many trust and security issues to be addressed. The related work is discussed next.

3. Trust and security in fog computing

3.1. Existing surveys and their overview

We have retrieved 86 references about security and trust in the fog, including eight survey papers. We summarize their covered security issues and characteristics in Table 1. These studies mainly

focus on the security issues. Since their publications, we have seen some new security issues emerging, e.g., context-aware and data-dependent security ones. As a vitally important issue, trust has drawn much attention. Hence, this work intends to write a new survey paper about the security and trust issues related to fog computing and its architectures.

We classify security and trust issues of current researches into six types: (1) trust, (2) authentication and access control, (3) attack, (4) privacy, (5) secure communications and (6) the others (include service availability, secure applications and secure sharing technology). According to these types, the number of the references is listed in Table 2 from 2014. In Table 2, the first column denotes the research topic types. The first row denotes years. The entries indicate the number of references per topic in a year. We can see that there are 10 papers in 2016 and 35 ones in 2017. The number of papers increases clearly. We note that only the papers in the first two months of 2018 are retrieved. As the classic security issues, authentication and access control as well as privacy preservation have drawn more researchers' attention. There are eight papers about trust issue, which is relatively significant. There are only two papers about service availability, eight about secure applications and one about secure sharing technology.

3.2. Trust

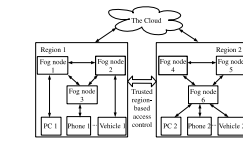
Trust plays a major role in fostering relations based on previous interactions among fog nodes and edge devices. A fog node is considered as the most critical component as it is in charge of ensuring privacy and anonymity for end-users [18]. Moreover, this component must be trusted for delegation, as they must be assured that the fog node implements the global concealment process on their related data and triggers non-malicious activities only. This requires all nodes that are part of the fog network to have a certain level of trust on one another.

3.2.1. Trust middleware and model

Elmisyri et al. propose a fog-based middleware, where trust agents calculate the approximated interpersonal trust between a fog node and the Cloud [18]. The trust computation is done in a decentralized fashion by using the entropy definition in [41]. The local concealment agent implements the local concealment process to achieve user privacy. The global concealment agent only exists in a fog node. It executes the global concealment process on the aggregated user profile. A service layer is adopted in the fog architecture to improve and manage trust [18], as shown in Fig. 4.

The difference between the middle parts in Figs. 4 and 1 is that a service layer is added on the top of the fog in [18]. At the service layer, there are two main components: (1) Security authority center: This center is used to select fog nodes with the highest reputation to act as members for trust computation. It is a trusted third party responsible for making an assessment on those fog nodes according to the latter's reports. Moreover, it records the calculated reputation scores for various fog nodes and trust levels for different Clouds. (2) Service server: A fog node can seamlessly interact with the service server which is in the Cloud.

Soleymann et al. point out that trust establishment among vehicles is important to secure integrity and reliability of applications [46]. A secure trust model can deal with uncertainties and risks taking from unreliable information in vehicular environments. However, inaccurate, incomplete, and imprecise information collected by vehicles as well as movable/immovable obstacles yield interrupting effects. A fuzzy trust model based on experience and plausibility is proposed to secure a vehicular network [46]. It executes a series of security checks to ensure the correctness of the information received from authorized vehicles. Moreover, fog nodes are adopted as a facility to evaluate the level of accuracy of



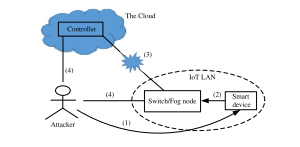


Fig. 6. A MitM model [65].

IoT devices for security enhancement [62]. It consists of a certificate authority (CA), a back-end Cloud, Fog nodes, and IoT devices. Douza et al. propose a policy-based resource access control in the Fog to support secure collaboration and interoperability among heterogeneous resources [53]. They adopt eXtensible Access Control Markup Language to define formalized and refined operational, security and network policy specifications.

3.4. Attacks

Because Fog nodes are usually deployed in some places with relatively weak protection, they may encounter various malicious attacks [24]. In addition, a malicious user can either tamper with its own smart meter, report false readings, or spoof IP addresses [45].

3.4.1. Malicious nodes and their attacks

Attacks from malicious Fog nodes: Lee et al. examine the components and several unique security threats of IoT Fog [42]. As one of the potential threats, a malicious Fog node problem is serious. In their research, the heavy workloads in the Fog are divided into several jobs and processed by Fog nodes. If some of these nodes are attacked by malicious users, it is hard to ensure the security of the data. However, they fail to give a detailed solution to solve such attack problem. In [21], the propagation of malicious nodes in the Fog is studied. The interaction between vulnerable nodes and malicious nodes in the Fog is first investigated as a non-cooperative differential game. The complex decision making process is then reviewed, analyzed and realized.

Attacks from malicious edge devices of users: Identifying malicious devices is crucial in data security in the Fog. However, it is difficult to prevent the attack because of certain privileges granted to them to use and process the data. Sohal et al. propose a framework by using a Markov model, intrusion detection system and virtual honeypot device to solve the problem [64].

3.4.2. MitM attack

Secure transmission channels protect all the traffic between edge devices and their Fog nodes. However, a user's released data can be eavesdropped or altered by an external attacker before the Fog node implements a global concealing process [18]. MitM is the typical kind of attack whose model is shown in Fig. 6.

In Fig. 6, after implementing four following steps, the outside attacker successfully intercepts the OpenFlow channel and controls the gateway as follows.

- For a device inside the IoT LAN, the outside attacker can take control of it by launching firmware updating attack because embedded smart devices are vulnerable to attacks.
- The smart device installs a client certificate at the Fog node, claiming that the Fog node needs to use this certificate to identify itself in the future communications.

- After the Fog node installs the client certificate, the outside attacker breaks the connection between the controller and the Fog node.
- The attacker performs MitM attack on the OpenFlow control channel.

In IoT Fog, the security issue of an OpenFlow channel between the controller and its switches is addressed in [65]. Because all the controller commands are sent through this channel, once attacked, the network is completely controlled by an attacker. It is a disaster for both the network service providers and their users. A countermeasure using the Bloom filter to detect MitM attack is thus proposed [65]. Stojmenovic et al. study MitM attack and investigate its stealthy features by examining its CPU and memory consumption of Fog devices [44]. One can also solve the problem by adopting encryption and decryption [24].

3.5. Privacy preservation

Privacy preservation is important because of users' many concerns about their sensitive data [47]. Different privacy preservation policies, schemes and methods are proposed, especially in healthcare systems [17–20]. Based on different technologies for access control, we summarize the current related work into Table 4 and discuss it next.

3.5.1. Location privacy preservation

A location privacy issue remains a challenge in the Fog [68]. Location-based services are popular and can achieve low-latency with the help of the Fog. A privacy preservation scheme for locations in the Fog is studied in [68]. Kang et al. address location privacy issues for the Fog supporting Internet of Vehicles (IoV), which aims to overcome big latency and high cost [23]. Hence, a privacy-preserving pseudonym is presented for effective pseudonym management. The work [48] realizes trajectory privacy preservation based on the Fog for Cloud location services. The paper [66] presents a redundant Fog loop-based scheme to preserve the source node location privacy and achieve energy efficiency in the Fog. The study [67] proposes a position cryptography protocol for preserving location privacy. Fog nodes are specifically to meet the requirements for location-specific applications and location-aware data management, such as in vehicular ad hoc networks [23,48,66].

3.5.2. Other data privacy preservation

Du et al. concern the privacy issue inherent in a Fog platform, and propose a differential privacy-based query model [69]. Wang et al. propose a privacy-preserving scheme by using differential privacy in the Fog, which can simultaneously ensure users' privacy and confidentiality [50]. In [70], most privacy-preserving data aggregation schemes support data aggregation for homogeneous IoT devices only and cannot aggregate hybrid IoT devices' data into one. Hence, a lightweight privacy-preserving data aggregation scheme for the Fog-enhanced IoT is presented. Al Hamid et al. formulates a secure privacy data and authenticated key agreement protocol based on the bilinear pairing cryptography [71]. Elmehry et al. study and reveal the disclosure boundary between privacy and publicity as well as the identity boundary between self and other [18]. Basudan et al. propose a privacy-preserving protocol for enhancing security in a vehicular crowdsensing-based road surface condition monitoring system by using the Fog [72]. He et al. propose a privacy-preserving scheme for identifying face by using the Fog [73]. Fog-based Vehicular ad hoc network is a new paradigm with the advantages of both vehicular cloud and the Fog, a secure and privacy-preserving navigation scheme is proposed for it [74].

4. Open research issues

Offering high security and trust is important to the Fog customers. Several open research issues remain.

4.1. Trusted execution environment

Devices in the Fog are often deployed without strict monitoring and protection, thereby facing all kinds of security threats. How to increase the trust in the Fog is the primary challenge. Public key infrastructure (PKI) based technique could partially solve this problem. Trusted execution environment (TEE) technique may have its potential in the Fog [18,62,84,85]. The open network environment of the Fog makes a malicious procedure easily spread to intelligent devices and bring heavy threat to user data [21]. How to control and avoid such spread of a malicious procedure is very important in trusted execution environment.

4.2. Trust and security during Fog orchestration

Achieving inter-nodal secure collaboration and trusted resource provisioning is an important issue [63]. Fog nodes are distributed, virtualized and shared. Fog orchestration should be optimized for a multi-tenant model. Complete isolation should be maintained among tenants through a virtualization system to avoid cross-disclosure and privacy compromise of application-specific data [27]. Based on policy-driven security management for the Fog, the work [63] studies resource management expanding the current Fog platform to support secure collaboration and interoperability among different user-requested resources in the Fog. However, multi-level collaboration results in large security and trust issues, mainly including identity management, authentication, access control, information sharing and QoS, for example, when a Fog node experiences a failure, nearby Fog nodes on the same or adjacent layers should step in to carry the load [77], which deserve further studies.

4.3. Access control

It is hard but important to improve confidentiality in accessing largely distributed Fog. Confidentiality [33,50,52,55] in the Fog needs to be scalable and efficient to cope with resource-constrained Fog devices. Traditional methods lack efficiency for the Fog. Lightweight encryption algorithms should be helpful for Fog nodes and edge devices [62]. In the Fog, we can also raise questions like how to design new access control methods spanning user-Fog-Cloud, to overcome the limitations of edge devices at different levels [53]. The Fog is visualized as an ideal candidate to grant access tokens to authorized parties. A centralized architecture may be used to authorize access and relay data between authorized parties and edge devices [IoT devices] [31]. However, in a distributed Fog environment, a centralized architecture may fail and result in information leakage. Hence, new mechanisms providing consistent guarantee need to be designed.

4.4. Collision attack

Collusion attackers may be disguised. New technologies should be developed to protect user privacy when facing a possible collision attack [50]. In [50], there are two kinds of collision attacks:

- Brokers collude with service providers: Malicious brokers and providers may spread the fake or duplicate events to the Fog network. Moreover, the latter can leak confidential information.
- Brokers collude with users: Malicious brokers and users may deny admitting any match accomplishing or utilizing data and services from legal providers.

However, the current work has not considered the attack from providers colluding with users. Malicious providers may leak confidential information to users for some profit from the latter. Colluding users may deny admitting obtaining any confidential information from the former. Hence, how to build high-security and low-cost collision attack detection countermeasure is one of the key problems in the Fog. New methods, such as collaborative detection, may be used to observe and detect this kind of challenging attacks.

4.5. Data-dependent security and context-aware security

In the Fog, to improve data-dependent security, backup is needed for vital data. In addition, the data across multiple end-user devices faces larger attack possibility and more challenges [66]. Because an adversary can compromise data integrity by attempting to modify or destroy legitimate data, it is essential to define a security mechanism to provide data integrity verification of the transmitted data between the Fog nodes and the Cloud [33]. The context-aware applications present new and interesting security challenges for emerging applications [34]. The nature of supporting for mobility and proximity to end-users of the Fog calls for a new security approach for transparently and adaptively dealing with context changes, especially for authentication, access control and trust degree in different context-aware environments.

4.6. Service trust

In the Fog, a secure and trustworthy manner for users is needed [18]. However, the Service Level Agreement (SLA) is often affected by many factors such as, service cost, energy usage, application characteristics, data flow, and network status. Therefore, given a particular scenario, it is quite difficult to specify a service trust [84,85], which deserves in-depth study. Trust evaluation mechanisms in the Cloud can be modified to increase the security of Fog services [87]. Based on operational requirements and execution environments, one has to select suitable and trusted Fog nodes, their corresponding resource configuration and places of deployment in the Fog. Current methods [84,85] lack compatibility and scalability to track and verify their trust values and monitor them for the Fog. SLA [12] that has gained success in designing a trust model in Cloud computing may be modified to use in the Fog.

5. Future work

Based on the current research results, we propose the following issues to be addressed in the future:

5.1. Trust management models

A trusted third party is adopted in [18,48,88,89]. It can improve the security. However, the past work fails to consider the region

problem. The method in [53] involves region issues for the Fog, as shown in Fig. 5. However, the Fog node elected as a delegate from a region Fog may be a malicious node, which makes the Fog face a larger trust risk. To solve the problem and improve trust reliability, an improved trust management model is needed. One solution may be proposed as follows:

- Using a trusted third party can decrease the trust management and computation overhead of the Fog through the detailed consideration of the Fog scope. Then using the partition concept similar to [53] can decrease the management and computation overhead in the Fog.
- Managing the inter-region trust values for the Fog nodes via using communication and historical data with each other in the region Fog.
- Managing the region-region trust values for the region Fog by communicating with the Cloud and using historical data in the Cloud.
- Some strategies can be adopted to improve the trust management in a region Fog, healthcare, by using strong identity verification mechanisms for Fog nodes [90].

5.2. Identification of trusted nodes

Fog users with resource-constrained devices can outsource their tasks to their trusted Fog nodes [88]. How to identify such nodes is crucial. Several strategies may be adopted:

- If there are direct or indirect trust evaluations of the goal nodes, trusted nodes are chosen according to their trust values.
- Otherwise, by using a probability model based on historical behavior of the goal nodes, we can assess their trust values and make the choice accordingly.
- Collision detections may be conducted by collaborated users or Fog nodes. It means that collision behavior is initialized and carried out both by users or by malicious Fog nodes. The kind of collision behavior need to be detected to identify trusted nodes in a region Fog.
- Because Fog nodes tend to be resource-constrained, it is necessary to design lightweight solutions [91]. Hence, the trust computation algorithm should be simple and occupy limited memory only. The Fog's dynamic nature brings new challenge for trust computing when facing constrained resources and low latency requirements. A light-weight strategy for trust computation based on a region Fog may be designed for meeting certain constrained resource requirements. If the computation task is large, it may be executed in the Cloud.

5.3. Secure orchestration

Optimized Fog orchestration is needed to avoid cross-disclosure and privacy compromise of application-specific data. QoS and service level agreements (SLA) are needed to ensure that all applications receive the minimum and enough levels of resources for orchestration [27]. Two kinds of orchestration deserve further study.

Application orchestration: Large-scale IoT services within the Fog infrastructures, such as smart cities, healthcare, and marine monitoring are composed of sensors, computing resources and devices. Orchestrating such applications can simplify maintenance and system reliability. However, how to efficiently monitor and process these applications' transient behavior and dynamic changes is a crucial challenge [35]. An agent-based trust computation model

may be used for orchestration. A multi-agent orchestration method may be adopted to monitor the applications and coordinate them securely in real time in the Fog.

Fog nodes' orchestration: The orchestration of Fog nodes can deploy virtual services to Fog infrastructure and facilitate resource collaboration [91]. When Fog nodes collaborate with others, one node may be attacked by malicious users or Fog nodes. If it is infected, the infected one may attack and infect other nodes. This induces security and trust risk spreading among Fog nodes even to a whole region Fog. Some strategies should be taken to decrease this kind of risk, by failing the infected node. If a Fog node is made in a failure status during an orchestration, the other Fog nodes potentially have to change their topology and rebuild their communication structure reliably. The data in the failed node should also be transferred to other reliable Fog nodes such that the orchestration can proceed. A policy-based service orchestration may be adopted.

6. Conclusions

The Fog is a highly virtualized platform but not a replacement of Cloud computing. It provides storage, compute and networking services among edge devices as well as traditional Cloud computing data centers [13]. It mainly solves the problems of low latency, mobility support and location awareness in many cyber-physical systems [92,93]. However, its distributed and open structure makes it vulnerable and weak to security threats.

This work analyzes the architectures of the Fog from a general to detailed ones. The related security and trust research results about the Fog are summarized, and the discussions about open security and trust issues are given, and future work is outlined. A distributed and remotely operated Fog can pose new security and trust challenges, which are not presented in the centralized Cloud. We make some concluding remarks for the Fog.

New methods are needed. Because the Fog is highly distributed, implementation of security mechanisms for data-centric integrity can affect its QoS to a great extent [28]. Hence, we need to find new methods to improve the security and trust of the Fog. Low-latency and a large number of resource-constrained devices in the Fog motivate researchers and engineers to propose new methods such that the Fog can enjoy high security and trust.

New interfaces are needed. Because Fog nodes need to interact with different hardware platforms provided by different vendors, new interfaces are required for Fog software to ensure trusted computing.

New protocols are required. Some protocols have already been designed, such as those in [77,94]. However, novel protocols are lacking to automatically detect security and trust compromises in the Fog.

Considering the limitation of the current researches and research trends, it is critical to develop and carefully design a suite of elaborate security and trust countermeasures. Many security and trust issues seem to remain open and have thus attracted much attention from researchers and engineers. As a final remark, it should be underlined that these issues should be addressed by design [95].

Acknowledgments

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