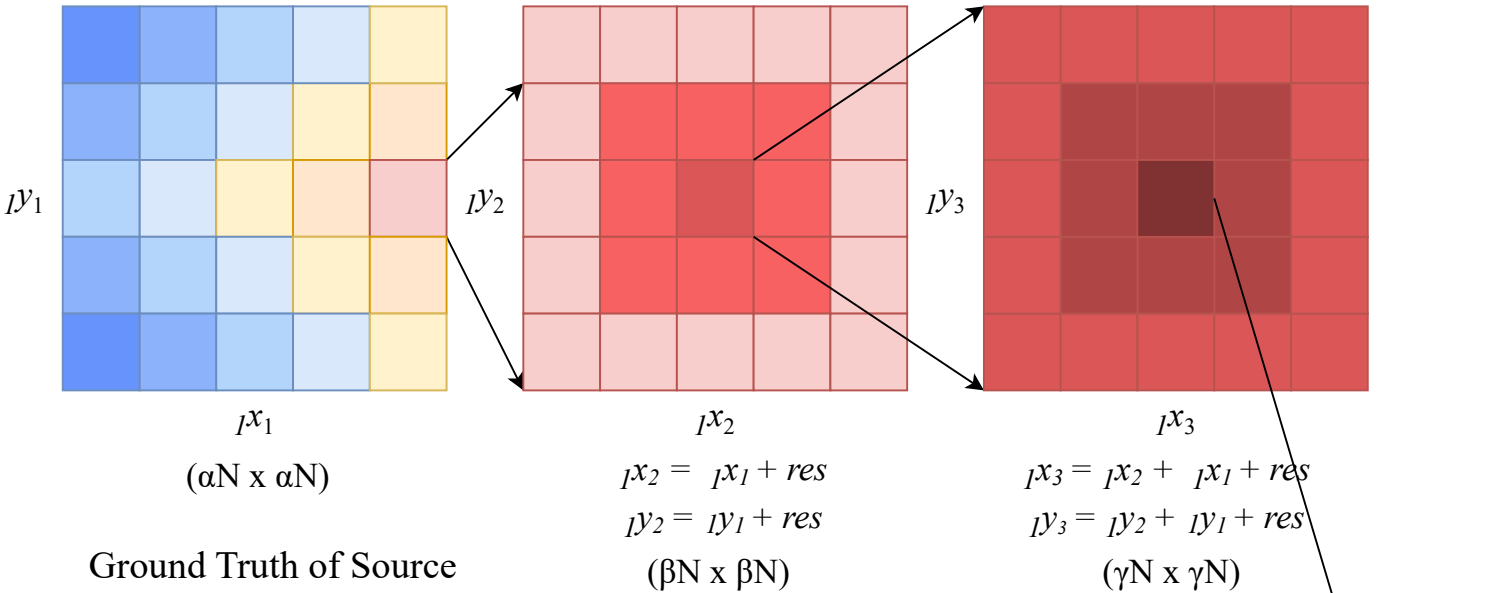


# Hierarchical GP Inferencing with robot 1's frame of reference with three levels

Level<sub>1</sub> GP

Level<sub>2</sub> GP

Level<sub>3</sub> GP



Ground Truth of Source Signal Propagation

