## **Convergence Analysis**

## **Basic Setup** 1.1

Theoretical guarantees for the convergence of optimization towards the satisfaction of correctness properties are desired but very difficult to derive. In this section, we take a first step by proving the convergence theorem for a basic but non-trivial case over the interval domain.

Consider a 2-layer neural network N with input dimension d, output dimension 1, and m neurons in the hidden layer. The weight matrix of the hidden layer is W, where  $\mathbf{w}_r$  is the weight vector connecting hidden neuron r and the input layer. The weight vector of the output layer is denoted by a. The ReLU function is used as the activation function, defined as

$$\sigma(x) = \max(x, 0) = x \mathbb{1}_{x > 0},$$

where  $\mathbb{1}_A$  is the event indicator function

$$\mathbb{1}_A = \begin{cases} 1 & \text{if } A \text{ is true} \\ 0 & \text{otherwise.} \end{cases}$$

For each input variable x, we assume  $x_j, j \in [d]$  are bounded by intervals  $[xl_j, xu_j]$ . For a safety property  $\phi$  whose input predicate  $\phi_{in} = [xl^{safe}, xu^{safe}], xl_j \le xl_j^{safe} < xu_j^{safe} \le xu_j, j \in [d]$  must hold. We normalize each interval by

$$xl_{j} = \frac{1}{\sqrt{d}} \frac{xl_{j}^{safe} - (xu_{j} + xl_{j})/2}{(xu_{j} - xl_{j})/2}$$

$$xu_{j}^{safe} - (xu_{j} + xl_{j})/2$$

$$xu_{j} = \frac{1}{\sqrt{d}} \frac{xu_{j}^{safe} - (xu_{j} + xl_{j})/2}{(xu_{j} - xl_{j})/2}$$

for  $i \in [d]$ .

The inputs of N are vectors  $x_i^{[w_r]}$ ,  $i \in [n]$ ,  $r \in [m]$ , where  $x_i$  is composed by elements from  $xl_i$  and  $xu_i$ . The selection of elements depends on the signs of  $w_r$  and the desired safety property. For example, to find the lower bounds of wx, we define for  $j \in [d]$ ,

$$x_j^{[w]} = \begin{cases} xl_j & \text{if } w_j \ge 0\\ xu_j & \text{if } w_j < 0. \end{cases}$$

From the normalization of xl and xu, we have  $\left\|x^{[w]}\right\|_2 \le 1$ .

Given the above definition, the output of N can be written as

$$f(W, \mathbf{x}, \mathbf{a}) = \frac{1}{\sqrt{m}} \sum_{r=1}^{m} a_r \sigma(\mathbf{w}_r^{\mathsf{T}} \mathbf{x}^{[\mathbf{w}_r]}).$$

We consider the general 2-norm loss function

$$L(W) = \frac{1}{2} \sum_{i=1}^{n} (y_i - f(W, x_i, a))^2$$

where  $y_i$  is the label of  $x_i$ . A fixed step gradient descent algorithm is used to optimize W, which is

$$W(k+1) = W(k) - \eta \frac{\partial L(W(k))}{\partial W(k)}$$

where  $\eta$  is a preset step size and  $k \in \mathbb{N}$  is the number of iterations. We use u(k) to represent the output prediction at iteration k, i.e.,

$$u(k) = f(W(k), \mathbf{x}, \mathbf{a}).$$

**Assumption 1.** We assume the network N satisfies the following properties:

- 1.  $\mathbf{w}_{r}(0) \sim \mathcal{N}(0, I), r \in [m]$

2. 
$$a_r = 1, r \in [m]$$
  
3.  $\left\| \mathbf{x}_i^{[w]} \right\|_2 \le 1, i \in [n]$ 

where  $\mathcal{N}(0,I)$  represents normal distribution.

**Remark 1.** Assumption 1 (2) is for clarity of the proof. We can adapt our result to  $a_r \sim unif[-1,1], r \in [m]$ , as used in [?]. Assumption 1 (3) follows the normalization of xl and xu.

**Definition 1.1.** (Definition 1.1 in [?]) We define the following functions. Given  $x_i^{[w]} \in \mathbb{R}^d$  and  $w \in \mathbb{R}^d$ , we define the continuous Gram matrix  $H^{cts} \in \mathbb{R}^{n \times n}$  as

$$H_{i,j}^{cts} = \mathbb{E}_{w \sim N(0,I)} \left[ \boldsymbol{x}_i^{[\boldsymbol{w}]\mathsf{T}} \boldsymbol{x}_j^{[\boldsymbol{w}]} \mathbb{1}_{\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_i^{[\boldsymbol{w}]} \geq 0, \, \boldsymbol{w}^\mathsf{T} \boldsymbol{x}_j^{[\boldsymbol{w}]} \geq 0} \right], i,j \in [n]$$

and the discrete Gram matrix  $H^{dis} \in \mathbb{R}^{n \times n}$  as

$$H_{i,j}^{dis} = \frac{1}{m} \sum_{r=1}^{m} \left[ x_i^{[w_r]\mathsf{T}} x_j^{[w_r]} \mathbb{1}_{w_r^\mathsf{T} x_i^{[w_r]} \geq 0, w_r^\mathsf{T} x_j^{[w_r]} \geq 0} \right], i, j \in [n].$$

By the definition of  $x_i^{[w_r]}$ , we can write it as a function of  $w_r$ 

$$\mathbf{x}_{i}^{[w_{r}]} = \mathbb{D}_{w_{r} \geq 0} \mathbf{x} \mathbf{l}_{i} + \mathbb{D}_{w_{r} < 0} \mathbf{x} \mathbf{u}_{i}$$

where  $\mathbb{D}_{w_r \geq 0} \in \mathbb{R}^{d \times d}$  is a diagonal matrix composed by  $\mathbb{1}_{w_r, i \geq 0}, j \in [d]$ . Similarly, we have

$$\mathbf{x}_{i}^{[w_{r}]\mathsf{T}}\mathbf{x}_{j}^{w_{r}} = (\mathbb{D}_{w_{r}\geq0} \mathbf{x} \mathbf{l}_{i})^{\mathsf{T}} \mathbb{D}_{w_{r}\geq0} \mathbf{x} \mathbf{l}_{j} \\
+ (\mathbb{D}_{w_{r}\geq0} \mathbf{x} \mathbf{l}_{i})^{\mathsf{T}} \mathbb{D}_{w_{r}<0} \mathbf{x} \mathbf{u}_{j} \\
+ (\mathbb{D}_{w_{r}<0} \mathbf{x} \mathbf{u}_{i})^{\mathsf{T}} \mathbb{D}_{w_{r}\geq0} \mathbf{x} \mathbf{l}_{j} \\
+ (\mathbb{D}_{w_{r}<0} \mathbf{x} \mathbf{u}_{i})^{\mathsf{T}} \mathbb{D}_{w_{r}<0} \mathbf{x} \mathbf{u}_{j} \\
= \mathbf{x} \mathbf{l}_{i}^{\mathsf{T}} \mathbb{D}_{w_{r}\geq0} \mathbf{x} \mathbf{l}_{j} + \mathbf{x} \mathbf{u}_{i}^{\mathsf{T}} \mathbb{D}_{w_{r}<0} \mathbf{x} \mathbf{u}_{j}, \tag{1}$$

so  $H^{cts}$  and  $H^{dis}$  are functions of variable W.

**Assumption 2.** (Assumption 1.2 in [?]). We make the following data-dependent assumption:

let 
$$\lambda = \lambda_{\min}(H^{cts})$$
, and  $\lambda \in (0, 1]$ .

Our main result is

**Theorem 1.2.** (Theorem 4.6 in [?]) Suppose network N satisfies Assumption 1 and 2. Let  $m = \Omega(\lambda^{-4} n^4 \log(\frac{n}{\lambda}))$ , and step size  $\eta = O(\frac{\lambda}{n^2})$ , then with probability at least  $1 - \delta$ , we have

$$||u(k) - y||_2^2 \le (1 - \frac{\eta \lambda}{2})^k ||u(0) - y||_2^2$$

In other words, under the over-parameterization of *m*, the optimization algorithm has linear convergence rate.

## 1.2 Detailed Proofs

The proof of Theorem 1.2 can be done by mathematical induction as used in [?]. Most proofs in our paper are similar to those in [?], except when  $x^w$  is involved. Conclusions of depending theorems, lemmas, and claims are the same as [?] with our setup. But some proof details need to be modified. Here we list all necessary modifications in the proofs.

**Lemma 1.3** (Lemma 4.1 in [?]). We define  $H^{cts}$ ,  $H^{dis} \in \mathbb{R}^{n \times n}$  as follows:

$$\begin{split} & H_{i,j}^{cts} = \mathbb{E}_{w \sim N(0,I)} \left[ \boldsymbol{x}_i^{[w]\mathsf{T}} \boldsymbol{x}_j^{[w]} \mathbb{1}_{w^\mathsf{T} \boldsymbol{x}_i^{[w]} \geq 0, w^\mathsf{T} \boldsymbol{x}_j^{[w]} \geq 0} \right], i, j \in [n] \\ & H_{i,j}^{dis} = \frac{1}{m} \sum_{r=1}^m \left[ \boldsymbol{x}_i^{[w_r]\mathsf{T}} \boldsymbol{x}_j^{[w_r]} \mathbb{1}_{w_r^\mathsf{T} \boldsymbol{x}_i^{[w_r]} \geq 0, w_r^\mathsf{T} \boldsymbol{x}_j^{[w_r]} \geq 0} \right], i, j \in [n]. \end{split}$$

Let  $\lambda = \lambda_{\min}(H^{cts})$ . If  $m = \Omega(\lambda^{-2}n^2\log(n/\delta))$ , we have

$$\left\|H^{dis} - H^{cts}\right\|_{F} \le \frac{\lambda}{4}, \ and \ \lambda_{\min}(H^{dis}) \ge \frac{3}{4}\lambda.$$

*Proof.* The key step in this proof is to use Hoeffding inequality to bound distance between  $H^{dis}$  and  $H^{cts}$ . To use Hoeffding inequality, we need to show that  $E[H_{ij}^{dis}] = H_{ij}^{cts}$ .

$$z_r = \frac{1}{m} x_i^{[w_r]\intercal} x_j^{w_r} \mathbb{1}_{w_r^\intercal x_i^{[w_r]} \geq 0, w_r^\intercal x_j^{[w_r]} \geq 0}, r \in [m].$$

From Eq. (1),

$$z_r = \frac{1}{m} (\boldsymbol{x} \boldsymbol{l}_i^\mathsf{T} \, \mathbb{D}_{\boldsymbol{w}_r \geq 0} \, \boldsymbol{x} \boldsymbol{l}_j + \boldsymbol{x} \boldsymbol{u}_i^\mathsf{T} \, \mathbb{D}_{\boldsymbol{w}_r < 0} \, \boldsymbol{x} \boldsymbol{u}_j) \mathbb{1}_{\boldsymbol{w}_r^\mathsf{T} \boldsymbol{x}_i^{[\boldsymbol{w}_r]} \geq 0, \, \boldsymbol{w}_r^\mathsf{T} \boldsymbol{x}_j^{[\boldsymbol{w}_r]} \geq 0}, r \in [m].$$

Therefore,  $z_r$  is a random variable of  $w_r$ .

$$\begin{split} E[H_{ij}^{dis}] &= \sum_{r=1}^{m} E_{\boldsymbol{w_r} \sim \mathcal{N}(0,I)} z_r \\ &= E_{\boldsymbol{w} \sim \mathbb{N}(0,I)} \frac{1}{m} (\boldsymbol{x} \boldsymbol{l_i^{\mathsf{T}}} \ \mathbb{D}_{\boldsymbol{w} \geq 0} \ \boldsymbol{x} \boldsymbol{l_j} + \boldsymbol{x} \boldsymbol{u_i^{\mathsf{T}}} \ \mathbb{D}_{\boldsymbol{w} < 0} \ \boldsymbol{x} \boldsymbol{u_j}) \mathbb{1}_{\boldsymbol{w^{\mathsf{T}} \boldsymbol{x}_i^{[w]} \geq 0, \, \boldsymbol{w^{\mathsf{T}} \boldsymbol{x}_j^{[w]} \geq 0}} \\ &= H^{cts} \end{split}$$

The second equation holds because  $w_r$ ,  $r \in [m]$  follows the same distribution, therefore the Expectations of  $z_r$  are the same. The subsequent the proof is the same starting from this step.

## 1.3 Extension to DeepPoly

$$f(W,x,a) = \frac{1}{\sqrt{m}} \sum_{r=1}^{m} a_r \Phi(\overline{g_i}, \underline{g_i})$$

$$\frac{g_i}{\overline{g_i}} = W^+ L + W^- U = w_r (\mathbb{1}_{w_r > 0} L + \mathbb{1}_{w_r < 0} U)$$

$$\overline{g_i} = W^+ U + W^- L = w_r (\mathbb{1}_{w_r < 0} L + \mathbb{1}_{w_r > 0} U)$$

$$\Phi(\overline{g_i}, \underline{g_i}) = \frac{\mathbb{1}_{w_r < 0} L + \mathbb{1}_{w_r > 0} U}{(\mathbb{1}_{w_r < 0} L + \mathbb{1}_{w_r > 0} U) - (\mathbb{1}_{w_r > 0} L + \mathbb{1}_{w_r < 0} U)} w_r^{\mathsf{T}} (\mathbb{1}_{w_r > 0} L + \mathbb{1}_{w_r < 0} U)$$
Denote  $\mathbb{1}_{w_r < 0} = \alpha$ , then  $\mathbb{1}_{w_r > 0} = 1 - \alpha$ .

$$\underline{\Phi(\overline{g_i}, g_i)} = w_r^{\mathsf{T}} \frac{\alpha L + (1 - \alpha)U}{\left[\alpha L + (1 - \alpha)U\right] - \left[(1 - \alpha)L + \alpha U\right]}$$

Since  $\alpha^2 - \alpha = 0$ ,

$$\frac{\Phi(\overline{g_i}, \underline{g_i})}{= w_r^{\mathsf{T}} \frac{LU}{(L - U)(2\alpha - 1)}}$$

$$= w_r^{\mathsf{T}} \frac{LU}{(L - U)(2\mathbb{1}_{w_r < 0} - 1)}.$$

$$\frac{\partial f}{\partial w_r} = \frac{1}{\sqrt{m}} a_r \frac{LU}{(L - U)(2\mathbb{1}_{w_r < 0} - 1)}.$$

Therefore,

$$H_{i,j}^{dis} = \frac{1}{m} \sum_{r=1}^{m} \left[ \frac{L_i U_i}{(L_i - U_i)(2\mathbb{1}_{w_r < 0} - 1)} \frac{L_j U_j}{(L_j - U_j)(2\mathbb{1}_{w_r < 0} - 1)} \right]$$
$$= \frac{1}{m} \sum_{r=1}^{m} \left[ \frac{L_i U_i L_j U_j}{(L_i - U_i)(L_j - U_j)} \right]$$

since  $(2\mathbb{1}_{w_n \le 0} - 1)^2 = 1$ .