

# High Dynamic Range Imaging and Tone Mapping

# Capturing, Representing, and Manipulating High Dynamic Range Imagery (HDRI)



Paul Debevec's SIGGRAPH Course

# Dynamic Range in the Real World



Office interior  
Indirect light from  
window  
1/60<sup>th</sup> sec shutter  
f/5.6 aperture  
0 ND filters  
0dB gain

Sony VX2000 video camera

# Dynamic Range in the Real World



Outside in the shade

1/1000<sup>th</sup> sec shutter

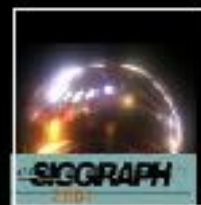
f/5.6 aperture

0 ND filters

0dB gain

16 times the light as inside

# Dynamic Range in the Real World



Outside in the sun

$1/1000^{\text{th}}$  sec shutter

f/11 aperture

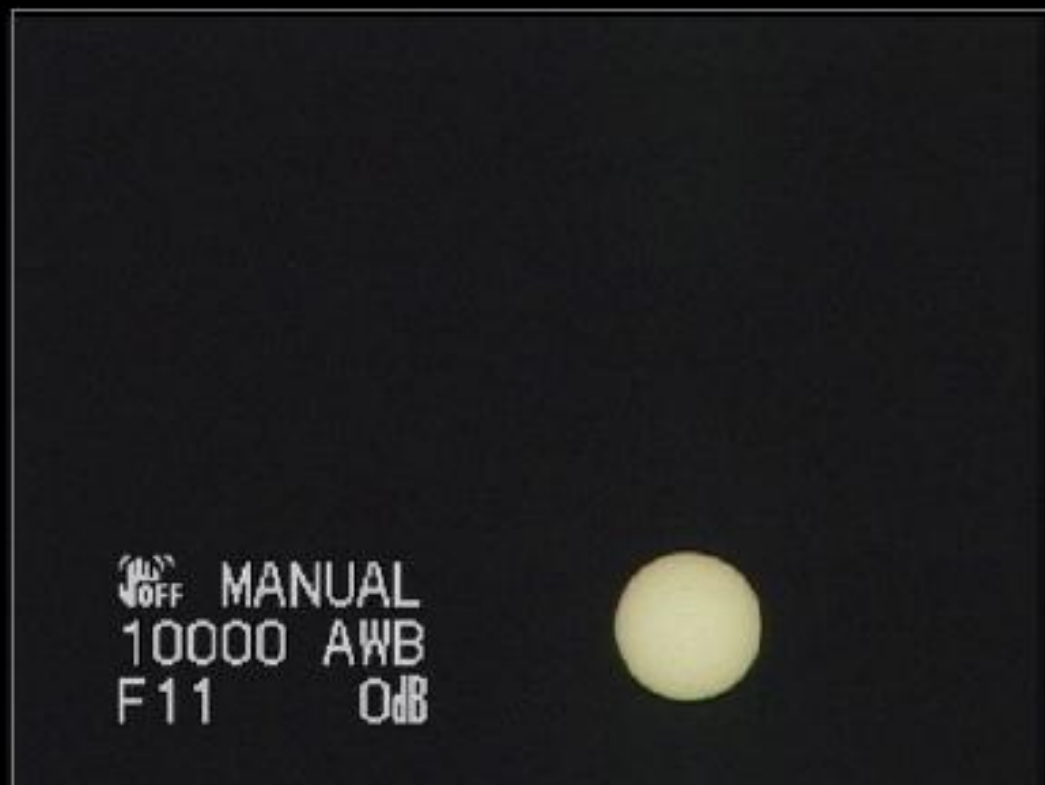
0 ND filters

0dB gain

64 times the light as inside



# Dynamic Range in the Real World



Straight at the sun

1/10,000<sup>th</sup> sec shutter

f/11 aperture

13 stops ND filters

0dB gain

5,000,000 times the light as inside

# Dynamic Range in the Real World



Very dim room

1/4<sup>th</sup> sec shutter

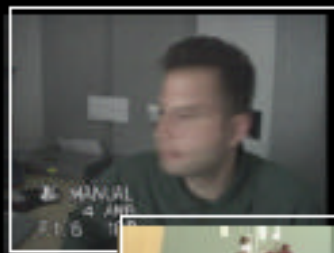
f/1.6 aperture

0 stops ND filters

18dB gain

1/1500<sup>th</sup> the light than inside

# Dynamic Range in the Real World



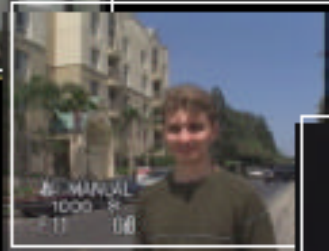
1



1500



25,000



400,000



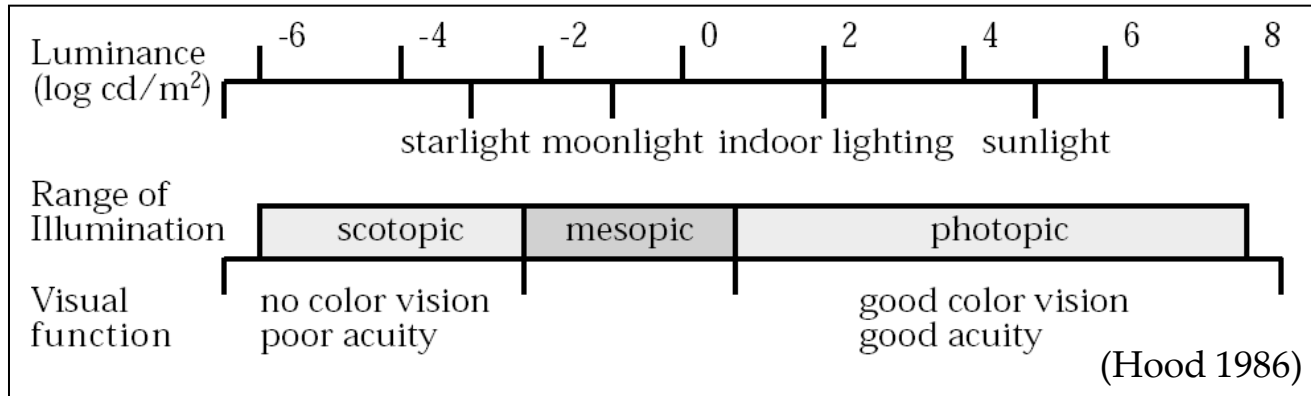
2,000,000,000

The real world is high dynamic range.

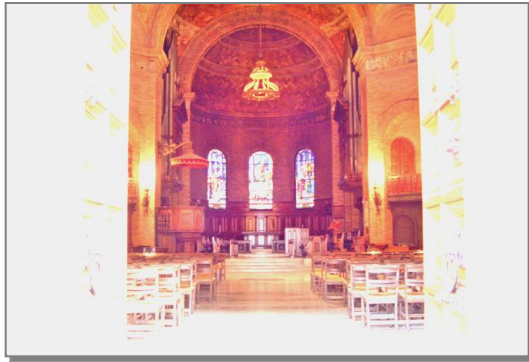


# The Problem of Dynamic Range

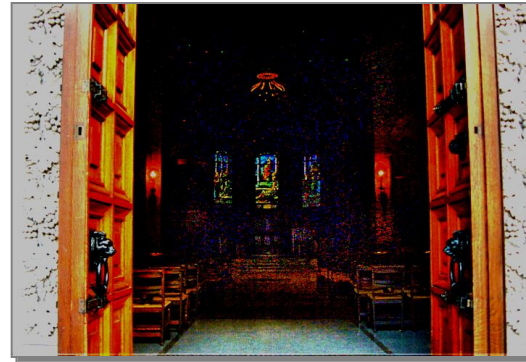
- Dynamic Range: Range of brightness values measurable with a camera



- Today's Cameras: Limited Dynamic Range



High Exposure Image

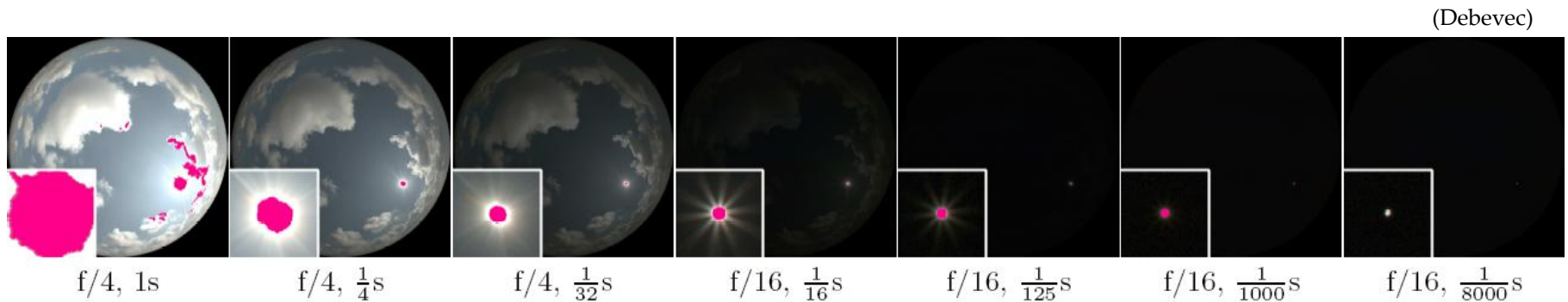


Low Exposure Image

- We need about 5-10 million values to store all brightnesses around us.
- But, typical 8-bit cameras provide only 256 values!!

# High Dynamic Range Imaging

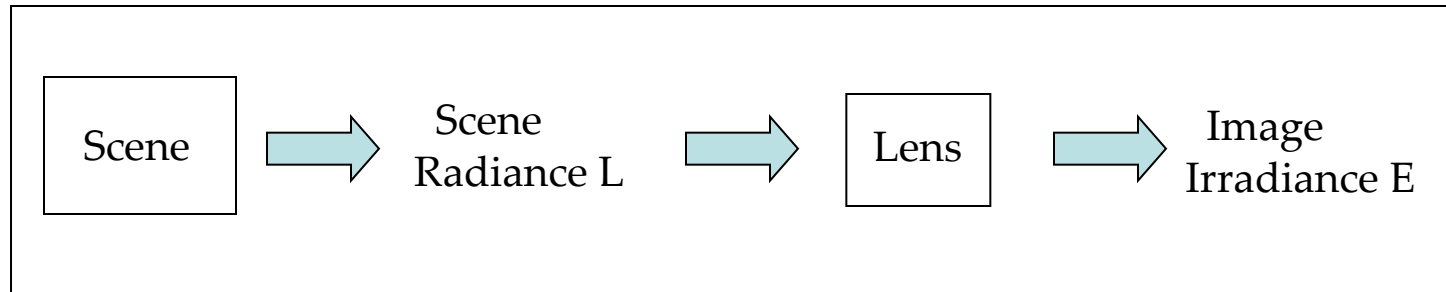
- Capture a lot of images with different exposure settings.
- Apply radiometric calibration to each camera.
- Combine the calibrated images (for example, using averaging weighted by exposures).



Images taken with a fish-eye lens of the sky show the wide range of brightnesses.

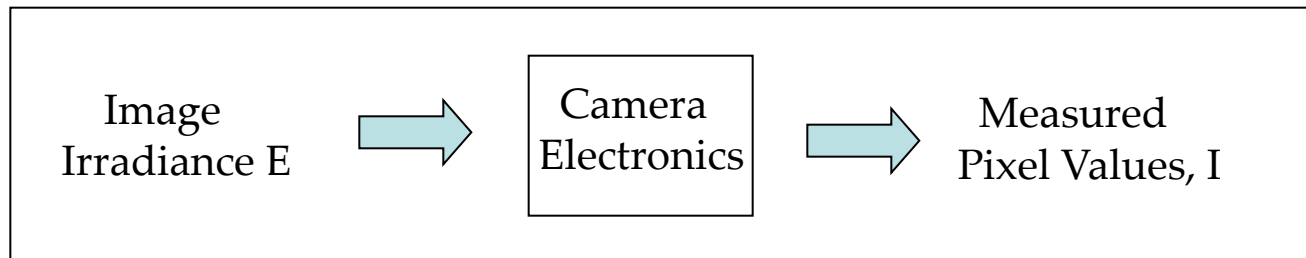
# Relationship between Scene and Image Brightness

- Before light hits the image plane:



Linear Mapping!

- After light hits the image plane:



Non-linear Mapping!

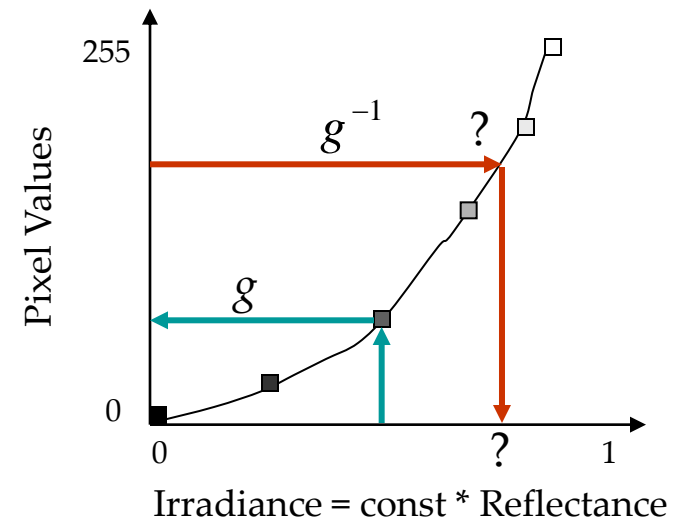
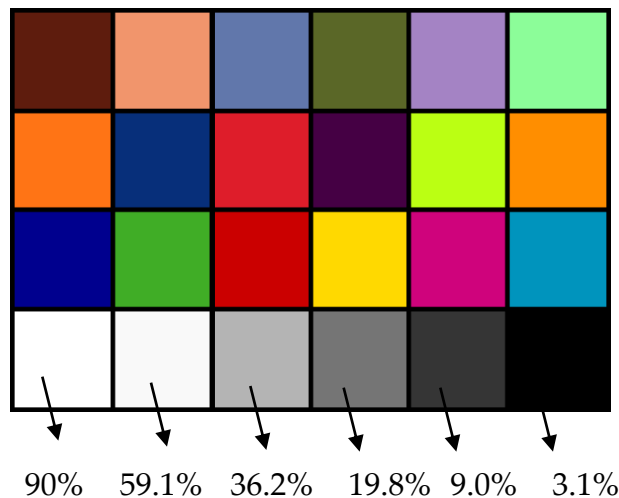
Can we go from measured pixel value,  $I$ , to scene radiance,  $L$ ?

# Radiometric Calibration

- Important preprocessing step for many vision and graphics algorithms such as photometric stereo, invariants, de-weathering, inverse rendering, image based rendering, etc.

$$g^{-1} : I \rightarrow E$$

- Use a color chart with precisely known reflectances.



- Use more camera exposures to fill up the curve.
- Method assumes constant lighting on all patches and works best when source is far away (example sunlight).
- Unique inverse exists because  $g$  is monotonic and smooth for all cameras.



# Ways to vary exposure

- Shutter Speed
- F/stop (aperture, iris)
- Neutral Density (ND) Filters
- Gain / ISO / Film Speed



# RADIANCE Format



Greg Ward's "Real Pixels" format



$$\begin{aligned}(145, 215, 87, 149) &= \\(145, 215, 87) * 2^{(149-128)} &= \\(1190000, 1760000, 713000) &\end{aligned}$$

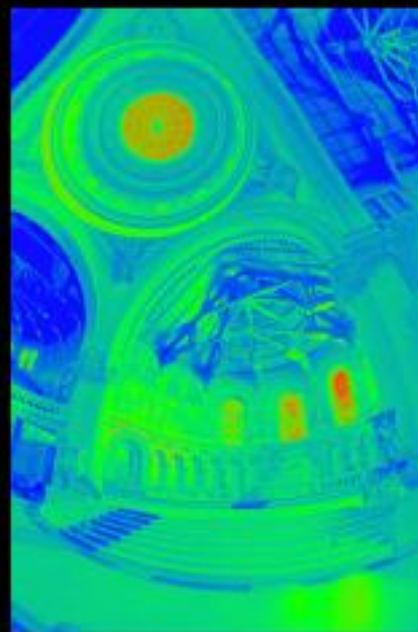
$$\begin{aligned}(145, 215, 87, 103) &= \\(145, 215, 87) * 2^{(103-128)} &= \\(0.00000432, 0.00000641, 0.00000259) &\end{aligned}$$



# 8-bit Images (TIF, BMP, TGA, JPG, etc.)

- Useful for representing images to be output on a computer monitor or printer
  - Less useful for representing images for film
  - Inadequate for representing HDR images
  - Usually nonlinearly encoded with a gamma curve, i.e.
- 
- Amount of light = (pixel value)<sup>2.2</sup>

# High-Dynamic Range Photography



W/sr/m2

121.741

28.869

6.846

1.623

0.384

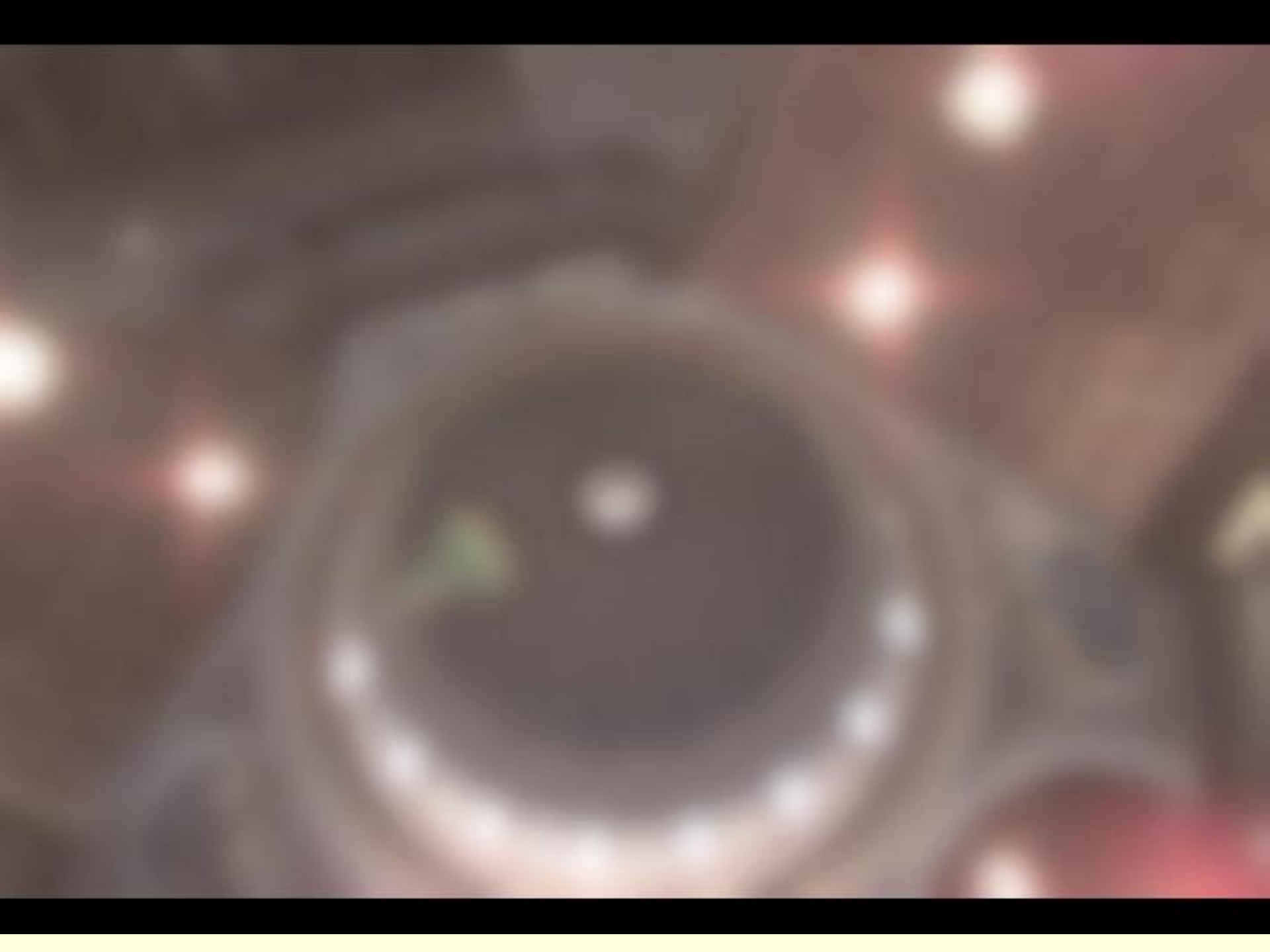
0.091

0.021

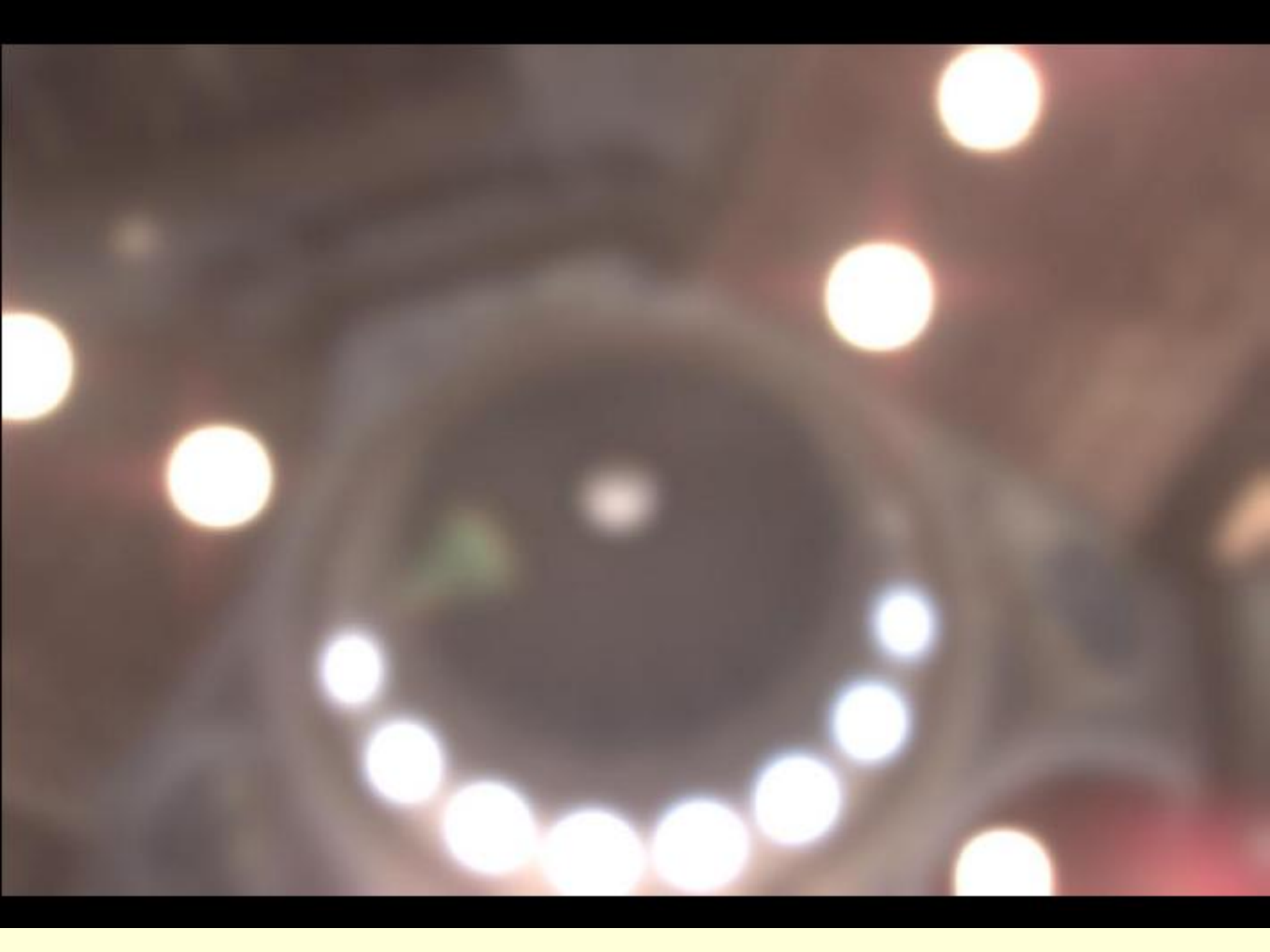
0.005

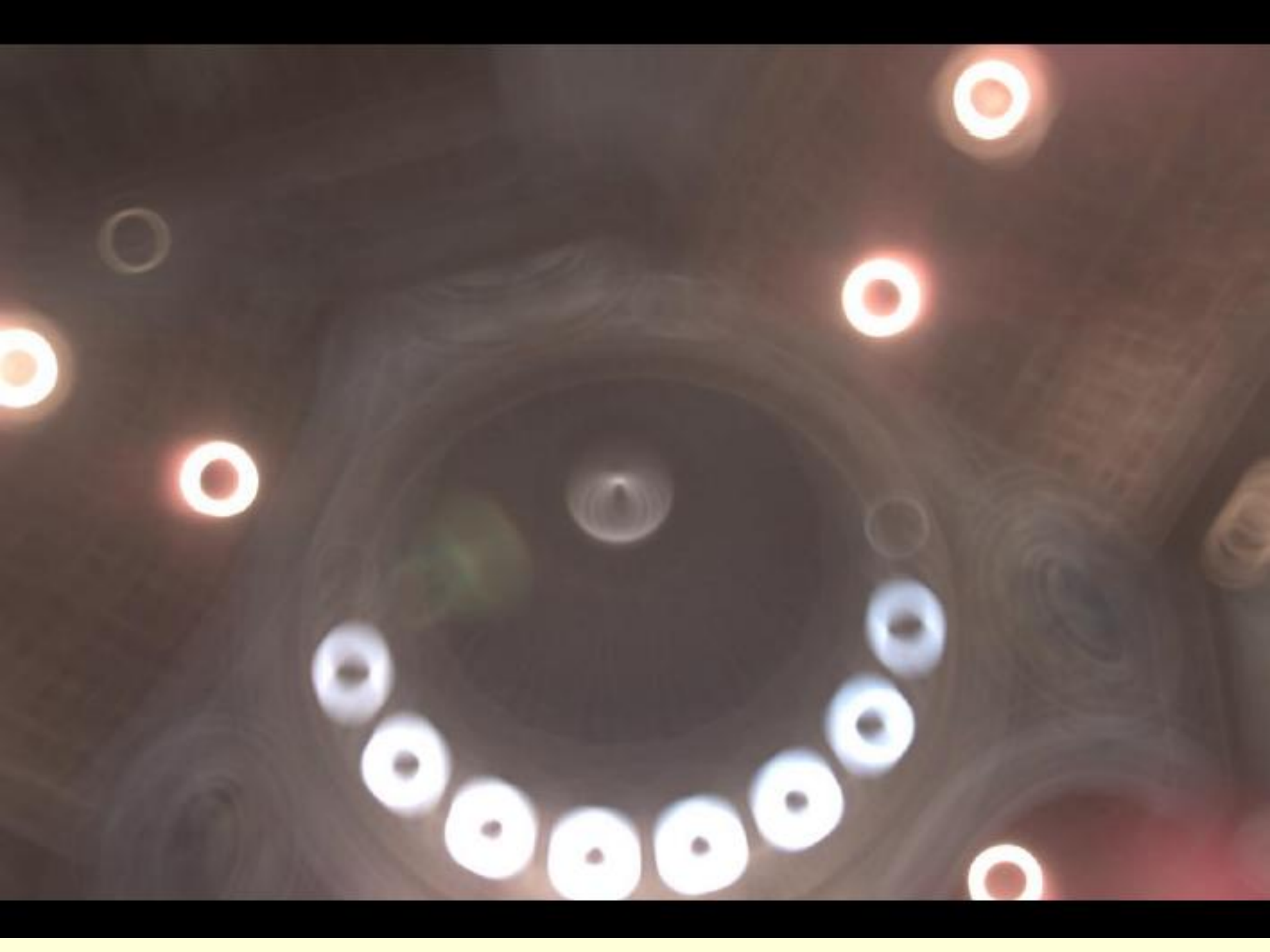
300,000 : 1











# HDR Tone-mapping



Linear tone-mapping



Non-linear tone-mapping

# Veiling Glare Simulation



+



=



# H D R S h o p

High Dynamic Range Image Processing and Manipulation



**[www.debevec.org/HDRShop](http://www.debevec.org/HDRShop)**

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# Capturing Real-World Illumination



# Mirrored Ball - Records light in all directions



kitchen scene

Brightest regions  
are **saturated**



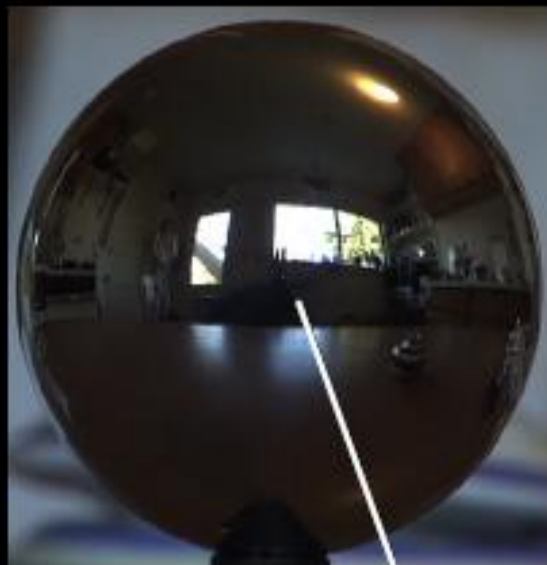
**Intensity** and **color**  
information lost

# HDR Image of a Mirrored Ball



(60,40,35)

(18,17,19)



(620,890,1300)



(5700,8400,11800)

(11700,7300,2600)

Assembled from ten digital images,

$\Delta t = 1/4$  to  $1/10000$  sec





# Sources of Mirrored Balls



2-inch chrome balls < \$20 ea.

King Bearing, Inc. / Applied Industrial Technologies

(many locations nationally, check [www.bigbook.com](http://www.bigbook.com))

6-12 inch large gazing balls

- Baker's Lawn Ornaments  
570 Berlin Plank Road  
Somerset, PA 15501-2413  
814-445-7028
- [www.amazon.com](http://www.amazon.com) - \$8





# Types of Omnidirectional Images

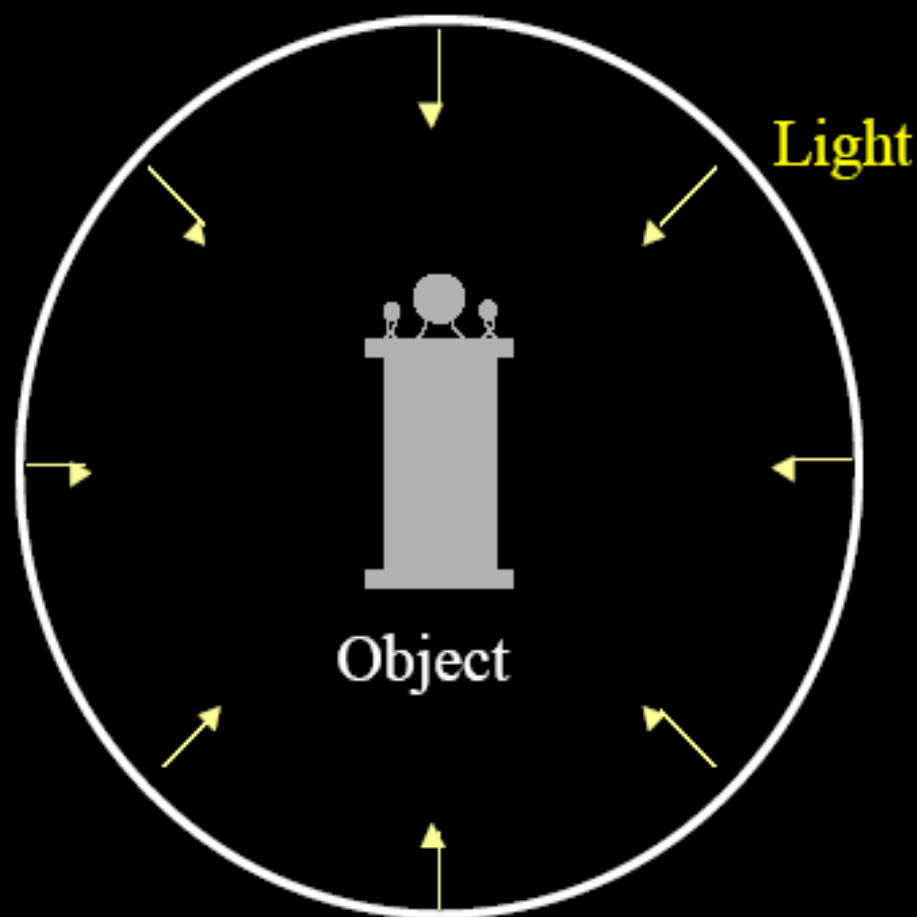


Latitude/Longitude



Cube Map

# Illuminating Objects using Measurements of Real Light



*Environment  
assigned “glow”  
material  
property in  
Greg Larson’s  
**RADIANCE**  
system.*

<http://radsite.lbl.gov/radiance/>

See also: Larson and Shakespeare, “Rendering with Radiance”, 1998

## 5. Illuminating Synthetic Objects with Real Light



# Comparison: Radiance map versus single image





# Making *Rendering with Natural Light*



SIGGRAPH 98 Electronic Theater

# Light Probe Images



Eucalyptus Grove  
UC Berkeley



Uffizi Gallery  
Florence



St. Peter's Basilica  
Rome



Grace Cathedral  
San Francisco

Light Probe Image Gallery:  
[www.debevec.org/Probes](http://www.debevec.org/Probes)