

## An Improved Numerical Approximation of the Horizontal Gradients in a Terrain-Following Coordinate System

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### ABSTRACT

The use of a fine vertical grid resolution near the surface may lead to a numerically inconsistent approximation of the horizontal gradient terms in a terrain-following coordinate system. This occurs when the distance between two vertical grid points is smaller than the elevation difference between two horizontally adjacent (in the terrain-following coordinate system) points. In this paper an improved numerical procedure is proposed which eliminates this inconsistency and significantly increases the accuracy of the numerical approximation. Results are compared with those obtained with the conventional forward and centered schemes.

### 1. Introduction

The use of the terrain-following coordinate system (TFCS), in meteorological numerical models, has been shown to be very effective when topographic features are considered. Generally, this coordinate system is defined by using the transformation

$$x^* = x, \quad y^* = y, \quad z^* = s \frac{z - Z_G}{s - Z_G}$$

where  $x$ ,  $y$  and  $z$  are the horizontal and vertical coordinates in a Cartesian coordinate system;  $x^*$ ,  $y^*$ , and  $z^*$  are the horizontal and vertical coordinates in the TFCS;  $Z_G$  is the terrain height and  $s$  is a reference height (usually the top of the model). This form of a TFCS has been used in recent years in large-scale and mesoscale numerical models (e.g., Kasahara, 1974; Mahrer and Pielke, 1975; Gal-Chen and Somerville, 1975; McNider and Pielke, 1981; Yamada, 1983; among others).

It will be shown in Section 2, that when using a numerical scheme for the horizontal gradients in the TFCS, care must be taken that the distance between two vertical grid points will not be less than the elevation difference between two horizontally (in the TFCS) adjacent points. This situation is mostly pertinent in mesoscale models that use a relatively fine vertical grid resolution in the atmospheric boundary layer.

It is also worth noting that models which use the  $\sigma$  coordinate system, where the vertical co-

ordinate  $\sigma$  is defined as a function of pressure are subject to a similar minimum vertical grid size requirement. The  $\sigma$  coordinate system was first introduced by Phillips (1957) and has been adopted in mesoscale models by Anthes and Warner (1978), Alpert *et al.* (1982), among others.

In some of the aforementioned models, the investigators have used relatively fine grid resolution near the surface, assuming implicitly that the variables vary linearly with height within the elevation difference between two horizontally adjacent points. For example: in Mahrer and Pielke (1975) the smallest grid interval was 50 m while the maximum elevation difference between two horizontal grid points was 400 m; in Yamada (1983) the corresponding values were 2 m and 100 m, while in Gal-Chen and Somerville (1975) they were approximately 100 m and 120 m respectively.

Several investigators (e.g., Smagorinsky *et al.*, 1967; Gary, 1973; Janjic, 1977) have recognized, in the  $\sigma$  coordinate system, an increased truncation error in the pressure gradient terms in the presence of very steep topography. Janjic (1977) specifically pointed out the inconsistency in the pressure gradient calculation in cases of very steep slopes of surfaces and thin layers. This inconsistency, however, could be tolerated in Janjic's experiments because his smallest vertical spacing was 100 mb ( $\sim 1000$  m).

Although the errors associated with a TFCS are most significant in the pressure gradient terms, they may be also important in other horizontal gradient terms, mainly within the planetary boundary layer.

In the present study, it is demonstrated that by using an improved numerical expression for the horizontal gradient terms in the TFCS, errors in the horizontal gradients of the meteorological fields are reduced substantially when the vertical grid interval is very small.

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Results are compared with those obtained by the forward and centered conventional schemes.

## 2. Evaluation of the numerical difference scheme for the horizontal gradients in TFCS

The transform equations of the partial derivatives with respect to  $x$  and  $z$  from the Cartesian coordinate system to the TFCS are:

$$\begin{aligned} \frac{\partial}{\partial x} \Big|_z &= \frac{\partial}{\partial x} \Big|_{z^*} + \frac{\partial z^*}{\partial x} \Big|_z \frac{\partial}{\partial z^*} \\ &= \frac{\partial}{\partial x} \Big|_{z^*} + \frac{z^* - s}{s - Z_G} \frac{\partial Z_G}{\partial x} \frac{\partial}{\partial z^*}, \end{aligned} \quad (1)$$

$$\frac{\partial}{\partial z} = \frac{\partial z^*}{\partial z} \frac{\partial}{\partial z^*}. \quad (2)$$

A commonly used finite differencing scheme for (1) in TFCS is a forward-in-space approximation, namely:

$$\begin{aligned} \frac{\partial F}{\partial x} \Big|_z &= \frac{F(i+1, j) - F(i, j)}{\Delta x} \\ &+ \frac{\partial z^*}{\partial x} \Big|_{i,j} \frac{F(i+1, j) - F(i+1, j-1)}{\Delta z^*}, \end{aligned} \quad (3)$$

where  $F$  represents the meteorological field, and

$$\frac{\partial z^*}{\partial x} \Big|_{i,j} = \frac{z^*(j) - s}{s - Z_G(i+1)} \frac{Z_G(i+1) - Z_G(i)}{\Delta x}.$$

As illustrated in Fig. 1, in which the vertical reso-

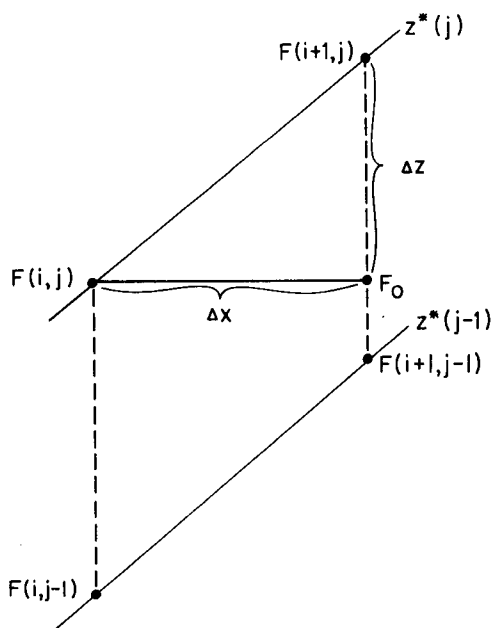


FIG. 1. A schematic illustration of the geometry involved in the calculation of the horizontal derivative in the terrain-following coordinate system.

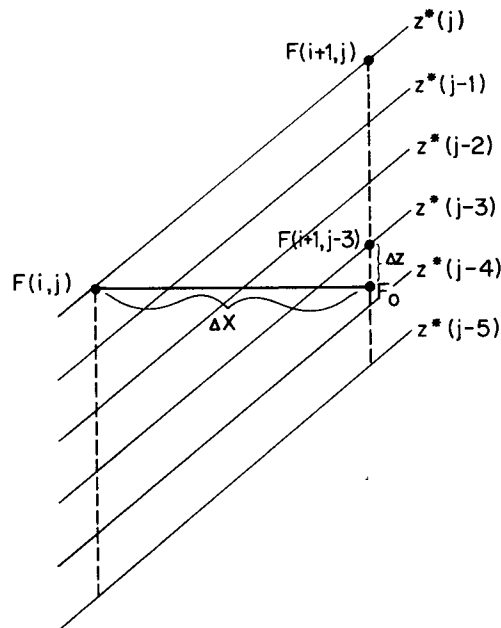


FIG. 2. As in Fig. 1, but with a five times finer vertical resolution.

lution is relatively coarse, the first-order approximation for  $F_0$  can be written as

$$F_0 = F(i+1, j) - \frac{\partial F}{\partial z} \Big|_{i+1,j} \Delta z. \quad (4)$$

Since the forward difference scheme for the horizontal gradient in the Cartesian coordinate system is given by

$$\frac{\partial F}{\partial x} \Big|_z = \frac{F_0 - F(i, j)}{\Delta x}, \quad (5)$$

Eq. (4) can be written as

$$\begin{aligned} \frac{\partial F}{\partial x} \Big|_z &= \frac{F(i+1, j) - F(i, j)}{\Delta x} \\ &+ \frac{\Delta z}{\Delta x} \frac{F(i+1, j) - F(i+1, j-1)}{z(j) - z(j-1)}. \end{aligned} \quad (6)$$

After substituting  $z^*$  for  $z$  in Eq. (6) we obtain Eq. (3).

However, let us consider now a case in which a finer vertical resolution, as illustrated in Fig. 2, is adopted. Here  $\Delta x$  is the same as in Fig. 1 but, the vertical grid distances were reduced five times. In this situation the best first-order approximation for  $F_0$  will be

$$F_0 = F(i+1, j-3) - \frac{\partial F}{\partial z} \Big|_{i+1,j-3} \Delta z \quad (7)$$

and not the relation given in Eq. (4). Under the current refined vertical grid resolution, Eq. (4) provides a first-order approximation to  $F_0$  only when the field is linear

between the points  $j$  and  $j - 4$ . Eq. (4), however, is indirectly commonly used in numerical models over complex terrain, since, in general the numerical scheme given by Eq. (3) is utilized.

By substituting  $F_0$  according to Eq. (7) into Eq. (5) and replacing  $z$  with  $z^*$  we obtain

$$\left. \frac{\partial F}{\partial x} \right|_z = \frac{F(i+1, j-3) - F(i, j)}{\Delta x} + \left[ \left. \frac{\partial z^*}{\partial x} \right|_{i,j} - \frac{z^*(j-3) - z^*(j)}{\Delta x} \right] \times \frac{F(i+1, j-3) - F(i+1, j-4)}{z^*(j-3) - z^*(j-4)}, \quad (8)$$

and in the general case

$$\left. \frac{\partial F}{\partial x} \right|_z = \frac{F(i+1, M) - F(i, j)}{\Delta x} + \left[ \left. \frac{\partial z^*}{\partial x} \right|_{i,j} - \frac{z^*(M) - z^*(j)}{\Delta x} \right] \times \frac{F(i+1, M) - F(i+1, M-1)}{z^*(M) - z^*(M-1)}. \quad (9)$$

Notice that the elevation at grid point  $(i, j)$  satisfies the condition

$$z(i+1, M-1) \leq z(i, j) \leq z(i+1, M)$$

and that  $M$  may be larger, smaller or equal to  $j$ , depending on the slope of the topography. Eq. (9) will be referred to later as the modified scheme.

Similarly, the expression for the horizontal gradient can be easily modified when using a centered or a backward differencing scheme. For the centered scheme, two points  $M$  and  $N$  (to the left and to the right of the point in question) have to be determined.

In the aforementioned numerical approximations, special care must be taken when  $M = 1$  (Fig. 3), since then,  $F_0$  does not exist (it is an imaginary point inside the topography). Under these conditions the distance of a point to the boundary must be calculated so that

$$\left. \frac{\partial F}{\partial x} \right|_z = \frac{F(i, j) - F_e}{\text{DIS}}.$$

Here  $F_e$  is the boundary value of  $F$ , and DIS is the horizontal distance (in the Cartesian coordinate system) of point  $(i, j)$  to the boundary.

It should be pointed out, that when using a numerical scheme (like Eq. (3), for example) for the horizontal derivative at point  $(i, 3)$ , as illustrated in Fig. 3, a value for  $F_0$  is extrapolated and the actual boundary condition is not imposed.

Conclusion of the evaluation in this section suggests that in order that the numerical approximation given in Eq. (3) will be appropriate, the smallest vertical grid spacing,  $(\Delta z)$ , should satisfy the condition:

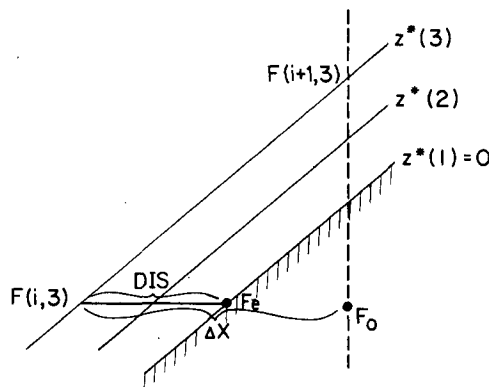


FIG. 3. A schematic illustration of the geometry involved in the calculation of the horizontal derivative in the terrain-following coordinate system near the terrain boundary with a fine vertical grid resolution.

$$\Delta z \geq \frac{s - z^*}{s} \Delta Z_G \quad \text{or} \quad \Delta z^* \geq \frac{s - z^*}{s - Z_G} \Delta Z_G,$$

where  $\Delta Z_G$  is the height change of the terrain per one horizontal grid interval. Thus, at the surface, where  $z^* = 0$ , the smallest vertical grid interval must fulfill the requirement  $\Delta z \geq \Delta Z_G$ .

With the *sigma* coordinate system where  $\sigma$  is defined as

$$\sigma = \frac{P - P_t}{P_s - P_t},$$

where  $P$  is the pressure,  $P_s$  and  $P_t$  are the surface and top pressures respectively. Here, the condition of the minimum vertical grid interval will be

$$\Delta \sigma \geq \frac{\sigma}{P_s - P_t} \Delta P_s,$$

where  $\Delta P_s$  is the change in the surface pressure per one horizontal grid interval.

### 3. Numerical test evaluations

In order to compare the accuracy of the "old" (Eq. 3) and the "modified" (Eq. 9) schemes, the horizontal gradients of hydrostatic pressure and temperature fields were calculated in the presence of topography. The calculations were performed in a two-dimensional ( $x, z$ ) domain, consisting of  $30 \times 20$  grid points. A bell-shaped mountain of the form

$$h(X) = \frac{H}{1 + (X - X_0)^2},$$

with  $H = 1$  km and centered at  $X = X_0$ , was considered. The vertical  $z^*$  grid points were set at the heights of 0, 5, 15, 50, 100, 200, 300, 500, 700, 1000, 1500, 2000, 2500, ..., 4500, and 5000 m. An initial horizontally uniform (in the Cartesian coordinate system) temperature field with a lapse rate of  $0.01^\circ\text{C m}^{-1}$  in the first



TABLE 3. Horizontal pressure differences (mb) along one grid interval at selected heights near the mountain crest as obtained for the coarse vertical grid spacing with: (a) centered differencing scheme, (b) modified centered scheme.

Scheme	Height (m)					
	5	100	300	700	1000	2000
a	0.209	0.174	0.113	0.096	0.150	0.139
b	0.024	0.029	0.050	0.024	0.007	0.003

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