

cubicFit and highOrderFit matrix equations

James Shaw

October 26, 2017

Here we make a comparison between two transport schemes: cubicFit (Shaw et al., 2017) and highOrderFit, which is based on the high-order formulation by Devendran et al. (2017). Both schemes form a matrix equation that is solved to find coefficients used to calculate the flux. We define a one-dimensional, four-point, upwind-biased stencil (figure 1) with equispaced cell centres. For cubicFit we approximate a field ϕ using a cubic polynomial

$$\phi = a_1 + a_2x + a_3x^2 + a_4x^3 \quad (1)$$

that interpolates the four stencil points. A matrix equation is formed in order to calculate the unknown coefficients $a_1 \dots a_4$,

$$\begin{bmatrix} 1 & x_{uuu} & x_{uuu}^2 & x_{uuu}^3 \\ 1 & x_{uu} & x_{uu}^2 & x_{uu}^3 \\ 1 & x_u & x_u^2 & x_u^3 \\ 1 & x_d & x_d^2 & x_d^3 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} \phi_{uuu} \\ \phi_{uu} \\ \phi_u \\ \phi_d \end{bmatrix}. \quad (2)$$

If the equispaced cell centres are positioned at $x_{uuu} = -2.5$, $x_{uu} = -1.5$, $x_u = -0.5$, $x_d = 0.5$ then

$$\begin{bmatrix} 1 & -2.5 & 6.25 & -15.625 \\ 1 & -1.5 & 2.25 & -3.375 \\ 1 & -0.5 & 0.25 & -0.125 \\ 1 & 0.5 & 0.25 & 0.125 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} \phi_{uuu} \\ \phi_{uu} \\ \phi_u \\ \phi_d \end{bmatrix}. \quad (3)$$

For highOrderFit, we solve the matrix equation

$$\begin{bmatrix} m_{uuu}^0/m_{uuu}^0 & m_{uuu}^1/m_{uuu}^0 & m_{uuu}^2/m_{uuu}^0 & m_{uuu}^3/m_{uuu}^0 \\ m_{uu}^0/m_{uu}^0 & m_{uu}^1/m_{uu}^0 & m_{uu}^2/m_{uu}^0 & m_{uu}^3/m_{uu}^0 \\ m_u^0/m_u^0 & m_u^1/m_u^0 & m_u^2/m_u^0 & m_u^3/m_u^0 \\ m_d^0/m_d^0 & m_d^1/m_d^0 & m_d^2/m_d^0 & m_d^3/m_d^0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} \phi_{uuu} \\ \phi_{uu} \\ \phi_u \\ \phi_d \end{bmatrix} \quad (4)$$

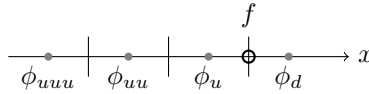


Figure 1: One-dimensional four-point upwind-biased stencil used to approximate the flux at face f .

where $\mathbf{m}_V^p = \int_V x^p dV$ is the p th moment of volume V , and the zeroth moment \mathbf{m}_V^0 is equal to the volume. If the equispaced cells each have $\mathbf{m}^0 = 1$ with the cell centres positioned as before, then

$$\begin{bmatrix} 1 & -2.5 & 6.\dot{3} & -16.25 \\ 1 & -1.5 & 2.\dot{3} & -3.75 \\ 1 & -0.5 & 0.\dot{3} & -0.25 \\ 1 & 0.5 & 0.\dot{3} & 0.25 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} \phi_{uuu} \\ \phi_{uu} \\ \phi_u \\ \phi_d \end{bmatrix}. \quad (5)$$

Notice how the matrix in equation 5 is similar to, but not equal to, the matrix in equation 3.

References

- Devendran, D., D. Graves, H. Johansen, and T. Ligocki, 2017: A fourth-order Cartesian grid embedded boundary method for Poisson’s equation. *Comm. App. Math. Comp. Sci.*, **12** (1), 51–79, doi:[10.2140/camcos.2017.12.51](https://doi.org/10.2140/camcos.2017.12.51).
- Shaw, J., H. Weller, J. Methven, and T. Davies, 2017: Multidimensional method-of-lines transport for atmospheric flows over steep terrain using arbitrary meshes. *J. Comp. Phys.*, **344**, 86–107, doi:[10.1016/j.jcp.2017.04.061](https://doi.org/10.1016/j.jcp.2017.04.061).