

Foundation of ML

Week 1

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Introductory overview of:

- Real-world applications of Machine Learning (ML)
- Definitions of ML
- Types of ML
 - Unsupervised learning
 - Supervised learning
 - Linear models
 - Nonlinear models
- Model assessment and selection
- Vector, Matrix and operations

What is learning?

See

Listen

Study

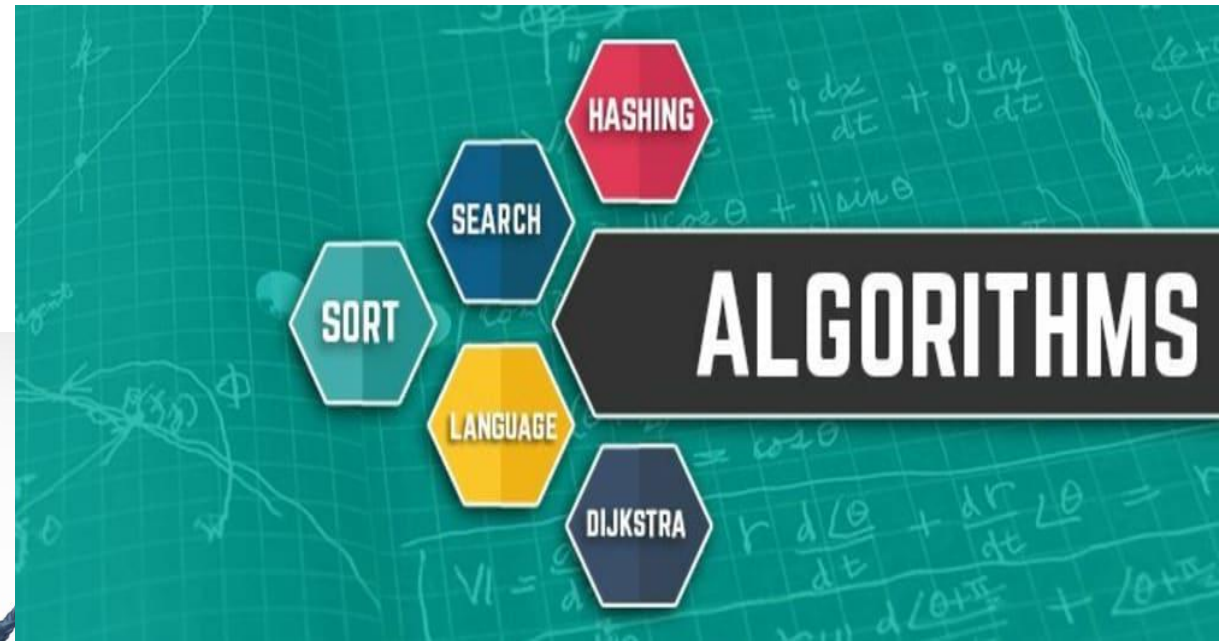
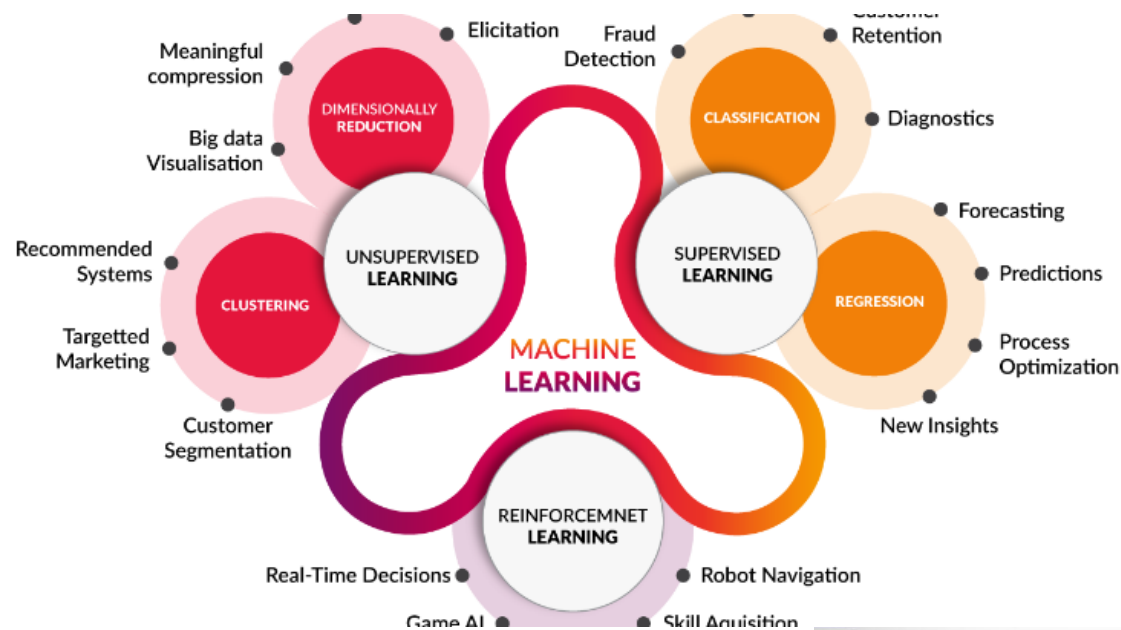
Experience

Do

Taste

Touch





What is machine learning?

Steps in ML



Data Collection



Clean and
Prepare data



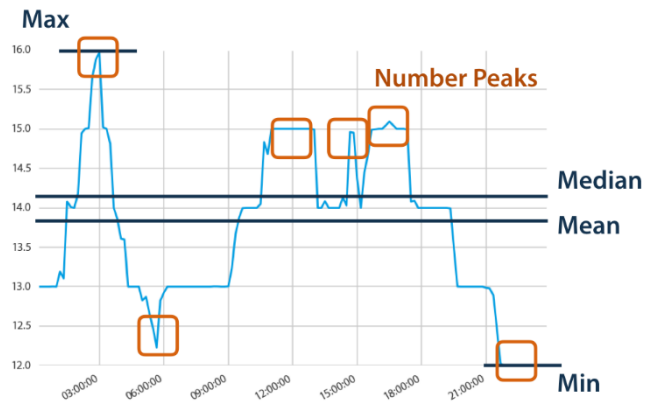
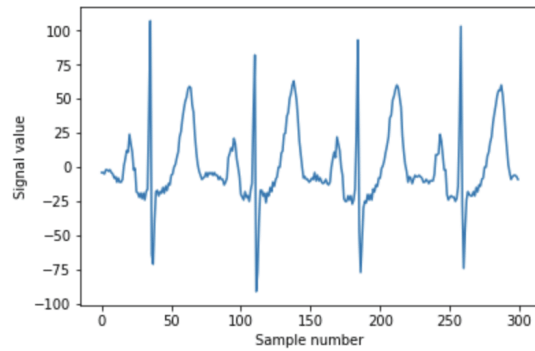
Train or Build
Model



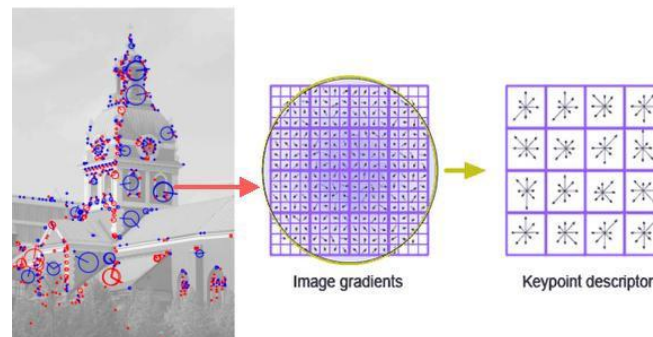
Evaluate the
model



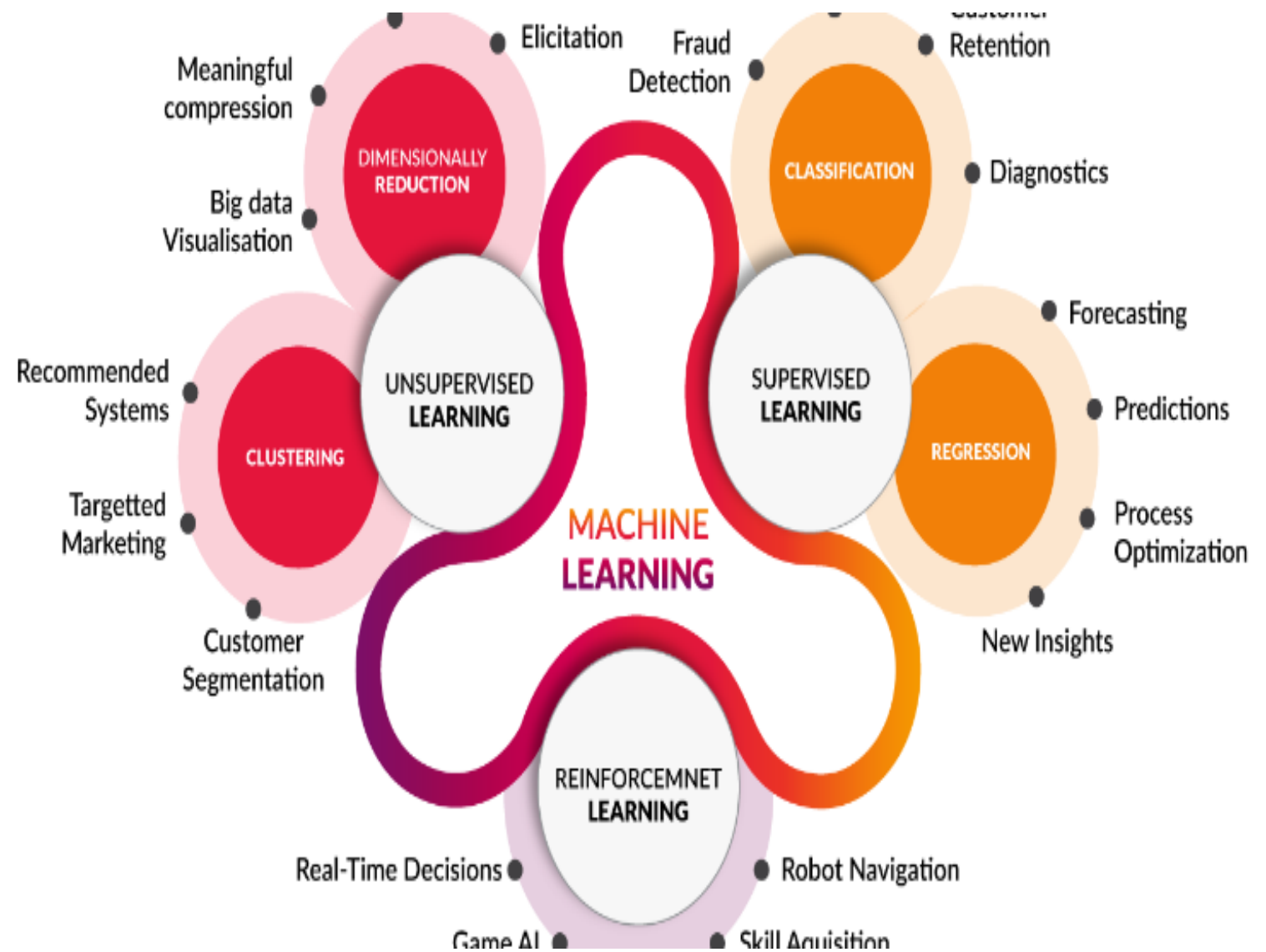
Improve/Deploy

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Understanding Data



Types of Machine Learning Algorithm

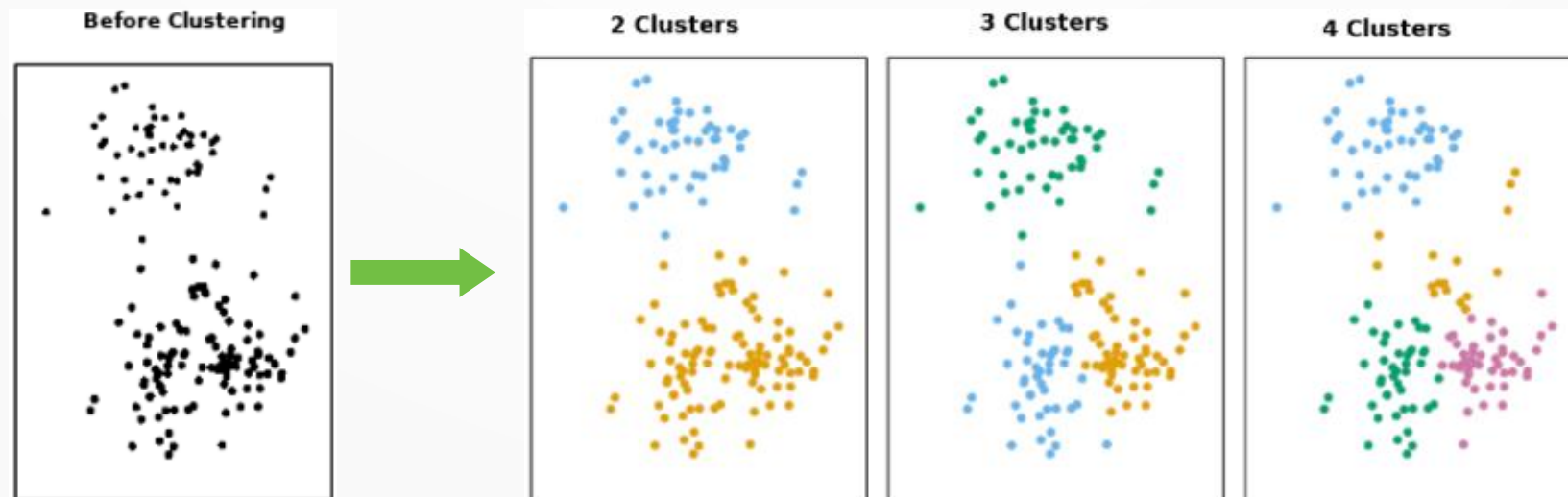


Unsupervised algorithm

How do you find the underlying structure of a dataset which is unlabelled?



- **Clustering** (similarity-based)
 - the process of grouping similar points together
 - gives insight into underlying patterns of different groups



ML Type - Unsupervised learning...

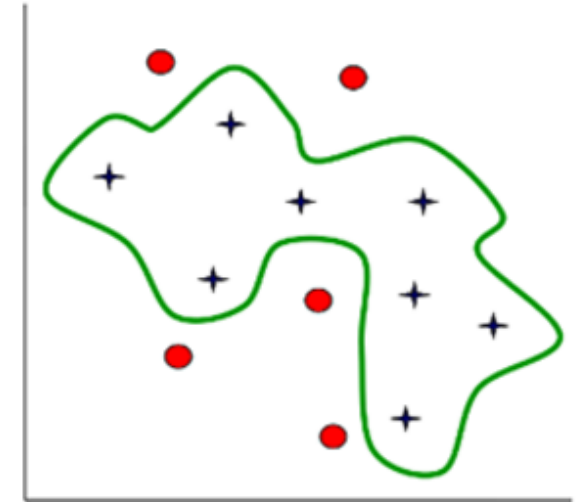
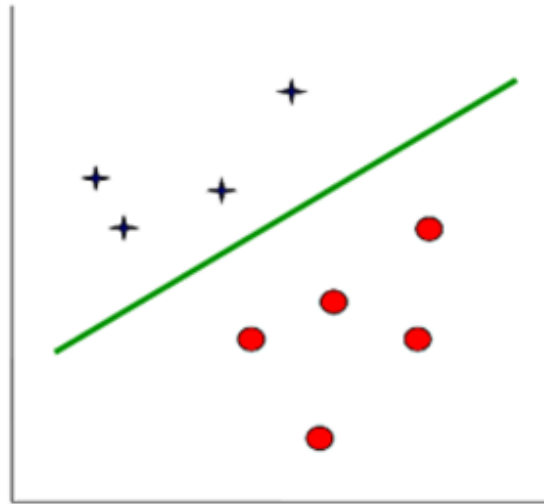
- Common examples -
 - Data understanding and visualization
 - Anomaly detection
 - Information retrieval
 - Data compression (reduction)

ML Type - Supervised learning

- “Learn a function (model) from data to relate the inputs with outputs.”
- In supervised learning, the training data includes output information (labels/targets)
- **Target function:** $f:X \rightarrow Y$
- **Examples:** It is in the form of (x,y) , denoted as $(x_1,y_1), \dots, (x_n,y_n)$
- **Hypothesis** $g:X \rightarrow Y$ such that $g(x)=f(x)$
 - x = set of attribute values
 - y = discrete label (*classification*), real valued number (*regression*)

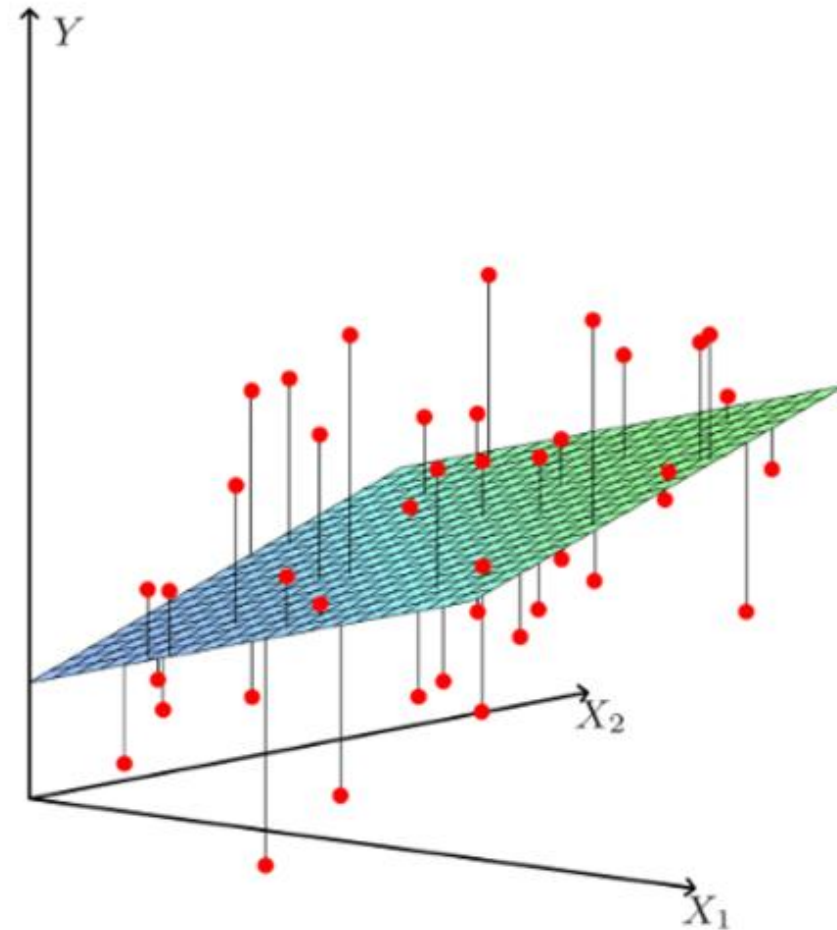
ML Type - Supervised learning..

- Classification problem
 - with two classes, decision boundaries are a hyper-surface that partitions data space into two sets
 - each of these sets represents one of the classes
 - linear vs non-linear decision boundary

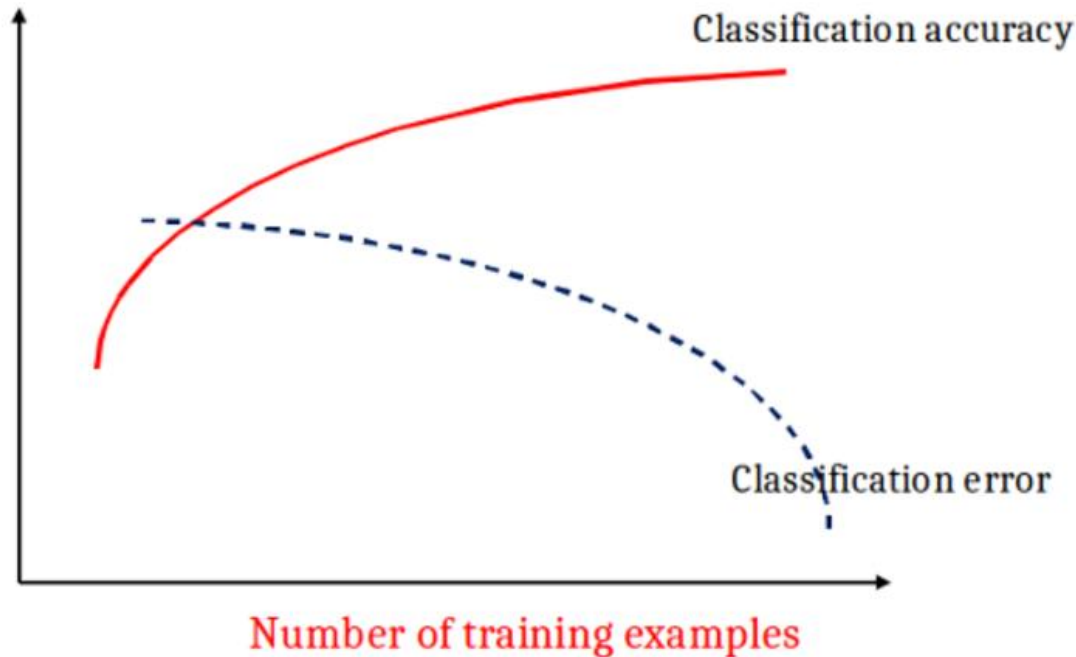


ML Type - Supervised learning...

- Regression problem
 - to examine the relationship between response variables and one or more predictor variables
 - examination can result in a hyperplane, representing the regression analysis
 - regression problem in 2 dimensions



Model assessment and adjustment

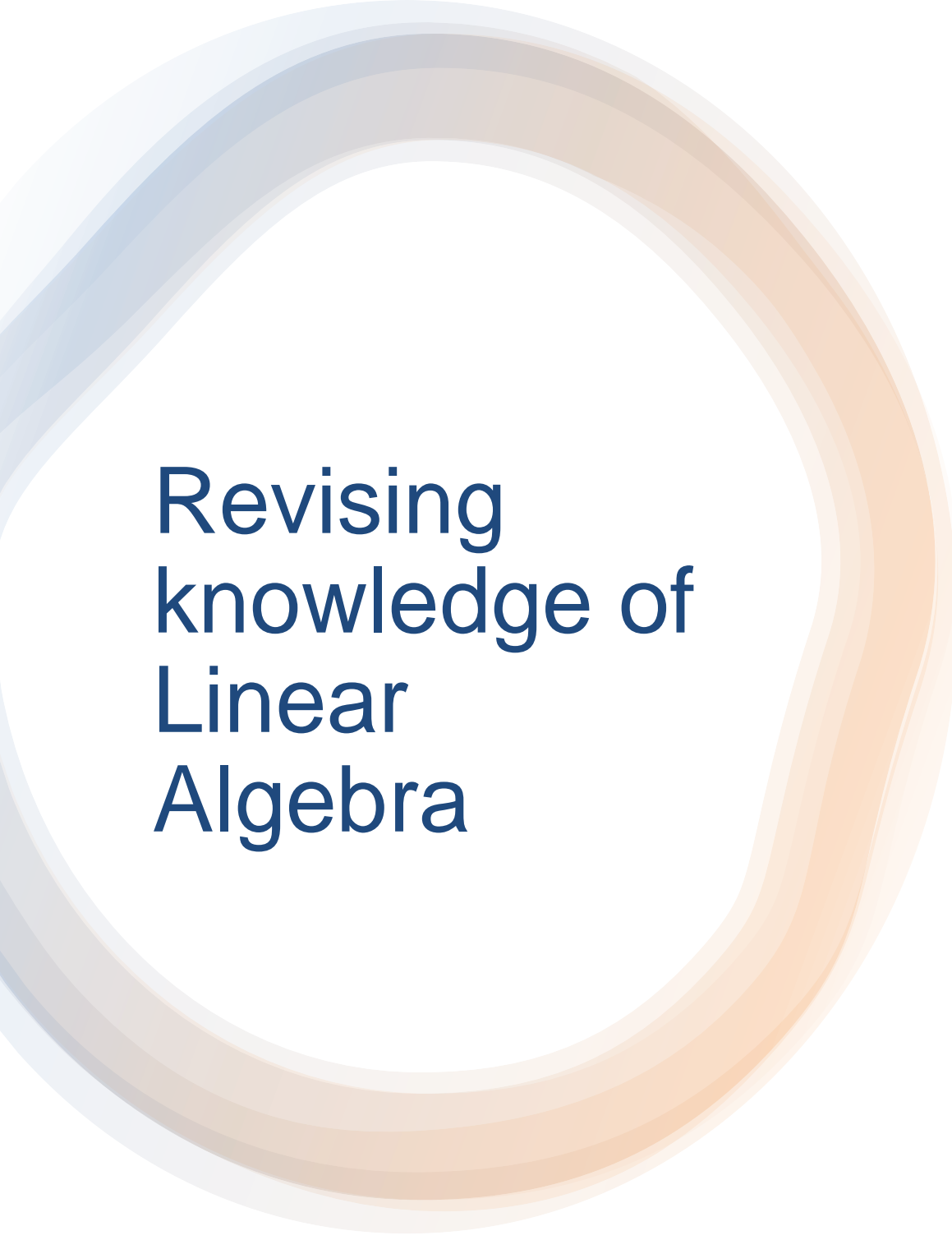


- Model evaluation
 - to determine if it will do a perfect job of predicting the labels on new and future test data
 - randomly split examples into a training set and test set
 - use training set to learn a model
 - evaluate the model using test set and a measurement (such as accuracy of prediction)
 - repeat for different random splits and average results
 - more training data, more accuracy

Model assessment and adjustment.

..

- Model selection
 - how to find the BEST model (hypothesis)?
 - There are often many knobs (parameters and hyper-parameters) that we can use to vary its fitness to the data
 - effective ways in which people approach this problem
 - look at averaged evaluation score on many random test sets
 - cross-validation (train using one set and test on the other, rotate them) etc.
 - be aware of *Over-fitting*



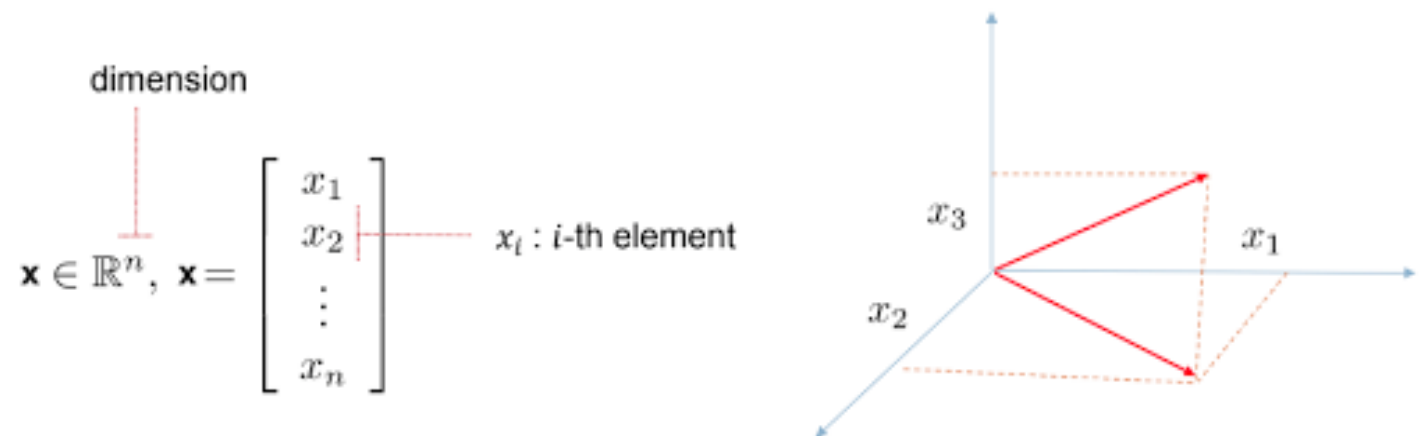
Revising knowledge of Linear Algebra

- Linear Algebra
 - Vector & their operations
 - Matrix & their operations

Vector

In machine learning algorithms:

A **data instance** is represented by a vector,
more precisely, by a **feature vector**.



- Two simple vectors X and Y :

Column vector $\nearrow X = \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ x_n \end{bmatrix}$

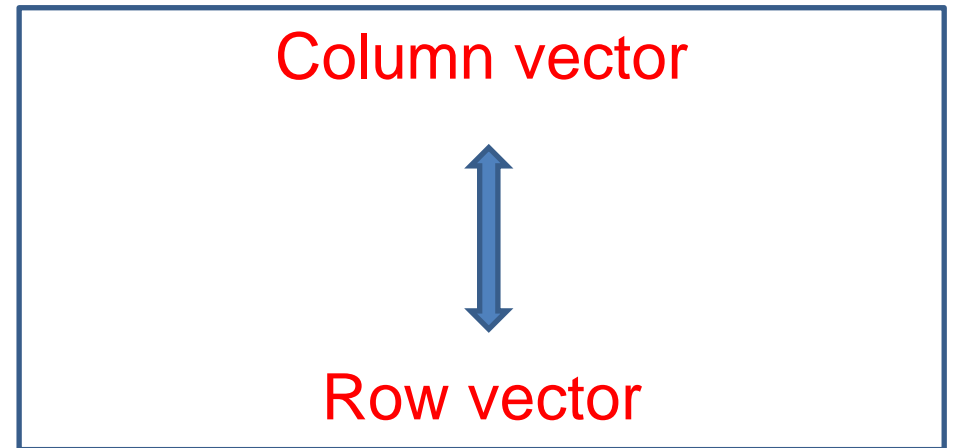
Row vector $\nearrow Y = [y_1 \quad y_2 \quad \cdot \quad y_n]$

Vector operations

- Three main operations in vectors -
 - Transpose
 - Addition
 - Inner product

• Transpose: $X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

$$X^T = [x_1 \quad x_2 \quad \dots \quad x_n]$$



Vector operations

Two vectors X and Y:


$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Addition operation:

$$X + Y = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{bmatrix}$$

Inner product:

$$X^T Y = [x_1 y_1 + x_2 y_2 + \dots + x_n y_n]$$


$$X = [x_1 \quad x_2 \quad \dots \quad x_n]$$
$$XY = [x_1 y_1 + x_2 y_2 + \dots + x_n y_n]$$



Vector operations...

Magnitude of length of a vector:

$$\text{length}(X) = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

2-norm of a vector:

$$\|X\|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

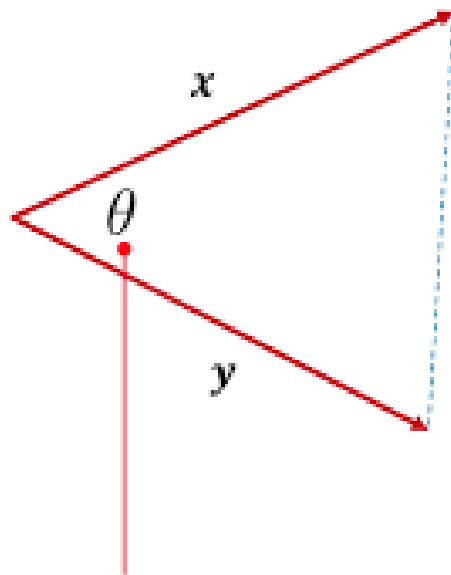
$$\|X\|_2 = (x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}$$

p-norm of a vector:

$$\|X\|_p = (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{\frac{1}{p}}$$

Distances between vectors

Similarity



Euclidean distance

$$\|x - y\| = \sqrt{(x_1 - y_1)^2 + \dots + (x_n - y_n)^2}$$

Cosine similarity

$$\cos(\theta) = \frac{x^T y}{\|x\| \|y\|} = \frac{x^T y}{\sqrt{x^T x} \sqrt{y^T y}}$$

Cosine distance is defined as

$$1 - \cos(\theta)$$

Matrix

Matrix has number of rows and columns:

column
vector

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

row
vector

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

number of columns

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

number of rows

number of columns

$$A \in \mathbb{R}^{m \times n}$$

number of rows

Matrix types

Rectangular and Square Matrices

- If a matrix A has size $m \times n$ such that $m=n$, then it is called a square matrix; otherwise, it is a rectangular matrix

$$\begin{bmatrix} 1 & 6 \\ 2 & 3 \end{bmatrix}$$

square matrix

$$\begin{bmatrix} 1 & 2 & 5 \\ 6 & 2 & 4 \end{bmatrix}$$

rectangular matrix

Type equation here.

Transpose of a Matrix

$$\begin{bmatrix} 1 & 6 & 7 \\ 2 & 3 & 8 \end{bmatrix} \xrightarrow{\text{transpose}} \begin{bmatrix} 1 & 2 \\ 6 & 3 \\ 7 & 8 \end{bmatrix}$$

$A \leftrightarrow A^T$

Symmetric Matrices

- a matrix is symmetric if it is equal to its transpose

$$\begin{bmatrix} 2 & 3 & 7 \\ 3 & 5 & 9 \\ 7 & 9 & 1 \end{bmatrix}$$

- Symmetric matrices are always square.

Diagonal Matrix

- A matrix A is called a diagonal matrix if $A(i,j)=0$ for all $i \neq j$.
- Diagonal matrix is always a square matrix.

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

Identity Matrix

- A matrix I is called an identity matrix if it is a diagonal matrix and $I(i,i)=1$
- denotes $n \times n$ identity matrix.

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Matrix operations

Matrix Addition/Subtraction (two matrices of same size)

$$X + Y = \begin{bmatrix} 2 & 4 \\ 3 & 1 \\ 8 & 5 \end{bmatrix} + \begin{bmatrix} 6 & 7 \\ 4 & 4 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 8 & 11 \\ 7 & 5 \\ 9 & 8 \end{bmatrix}$$

Scalar Multiplication or Division (multiply each element of matrix by the scalar)

$$3x \begin{bmatrix} 6 & 7 \\ 4 & 4 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 18 & 21 \\ 12 & 12 \\ 3 & 9 \end{bmatrix}$$

Element wise Matrix Multiplication (matrices have the same size)

$$\begin{bmatrix} 2 & 4 \\ 3 & 1 \\ 8 & 5 \end{bmatrix} \odot \begin{bmatrix} 6 & 7 \\ 4 & 4 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 12 & 28 \\ 12 & 4 \\ 8 & 15 \end{bmatrix}$$

Matrix operations

Matrix to Matrix Multiplication

- number of columns in the first matrix is equal to the number of rows in the second matrix
- Consider $AB=C$. Now $C(i,j)$ is computed by dot product of $A(i,:)$ and $B(:,j)$

$$\begin{bmatrix} 2 & 4 \\ 5 & 6 \\ 1 & 7 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 6 & 16 \\ 11 & 28 \\ 8 & 23 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 \\ 5 & 6 \\ 1 & 7 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 11 \\ 8 \end{bmatrix}$$

- Matrix multiplication is NOT commutative. Multiplication order matters. In general $AB \neq BA$.



Matrix operations

- Inverse Matrix

- Matrix A is called as inverse of matrix B, if and only if $BA=AB=I$.
- Since $AB=BA$, both A and B need to be a square matrix
- If A is inverse of B, we denote it as

$$A = B^{-1}$$

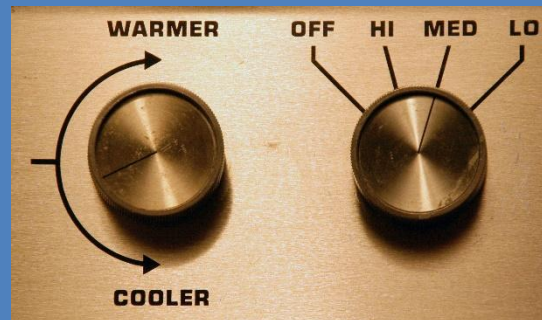
- Inverse of a matrix A exists only if it's determinant is nonzero

Summary

Data



Model



Decision



Thank You.