

Week 5

Deep Learning II

Convolutional Neural Networks

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AI Application at Woolworth

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PRODUCE PLUS

Woolworths scans fresh produce with AI

By Liam O'Callaghan | 18 February 2020



Woolworths is aiming to speed up scanning for shoppers with a new artificial intelligence (AI) powered scale that automatically identifies loose fresh produce.



The scales, developed by Australian company Tilter, are currently being trialled in three Sydney stores in conjunction with the retailer's Scan&Go app.

Consumers can place their fruit or vegetables on the scale surface and then the technology will detect the type of produce and identify the variety.



Woolworths is aiming to speed up scanning for shoppers with a new artificial intelligence (AI) powered scale that automatically identifies loose fresh produce.

Discussion Question

How can Machine identify the correct type of fruits?

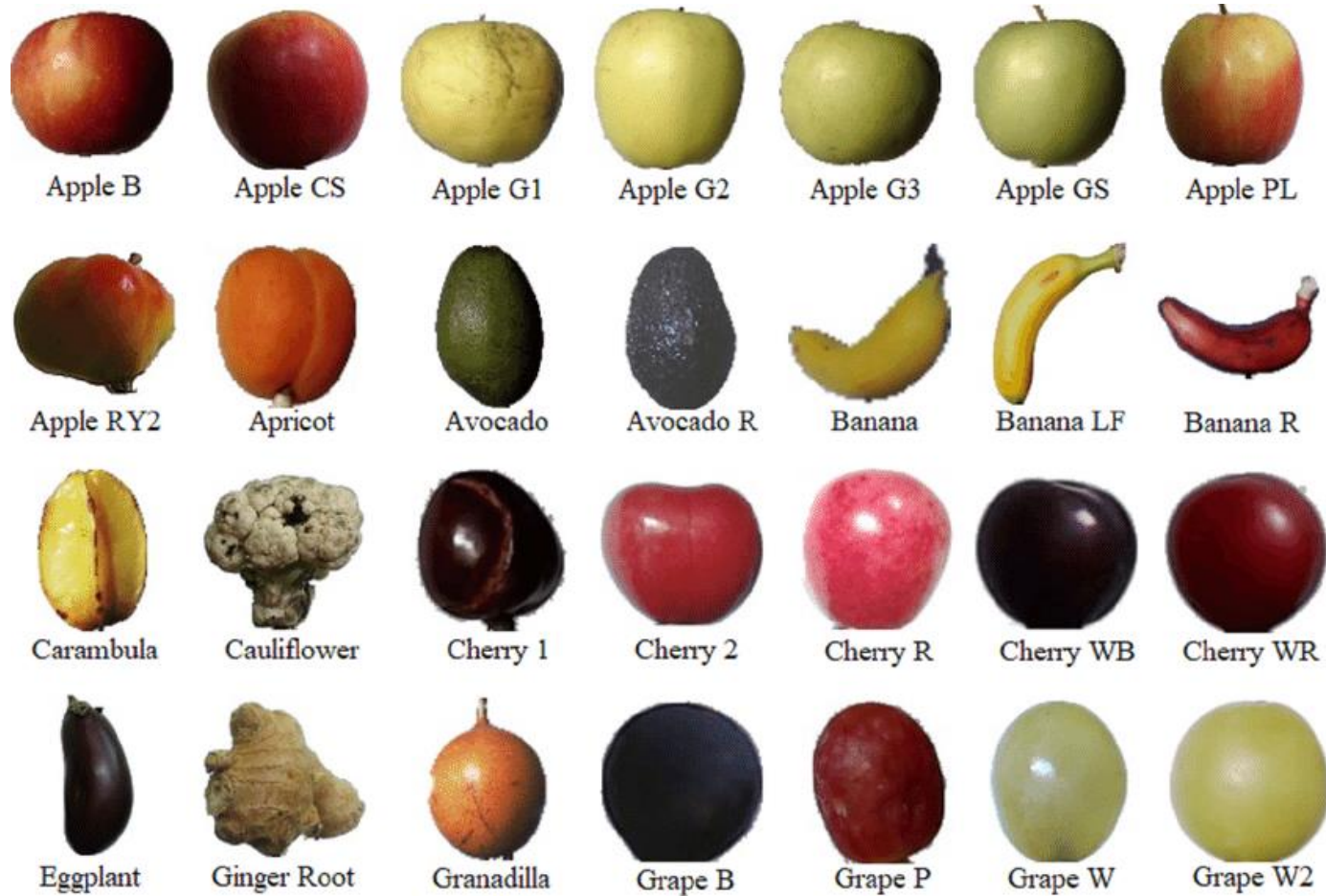
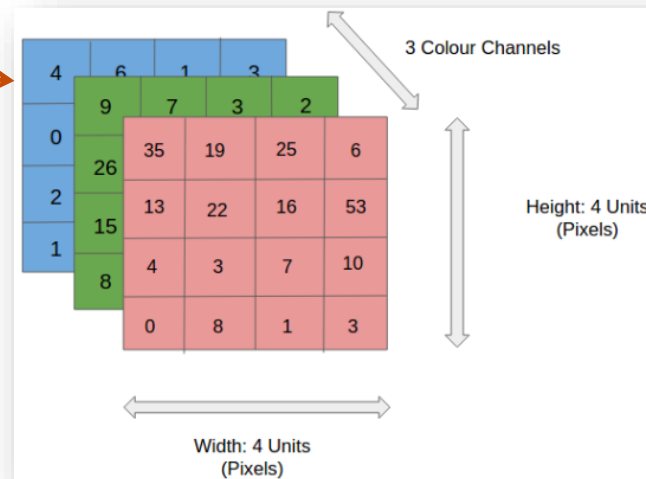
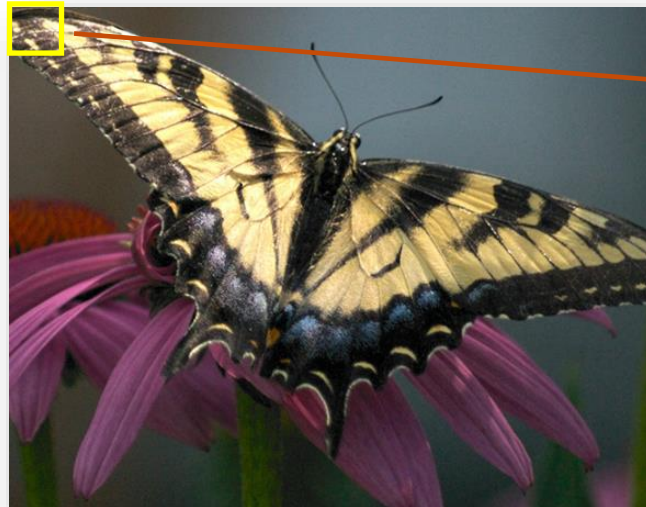
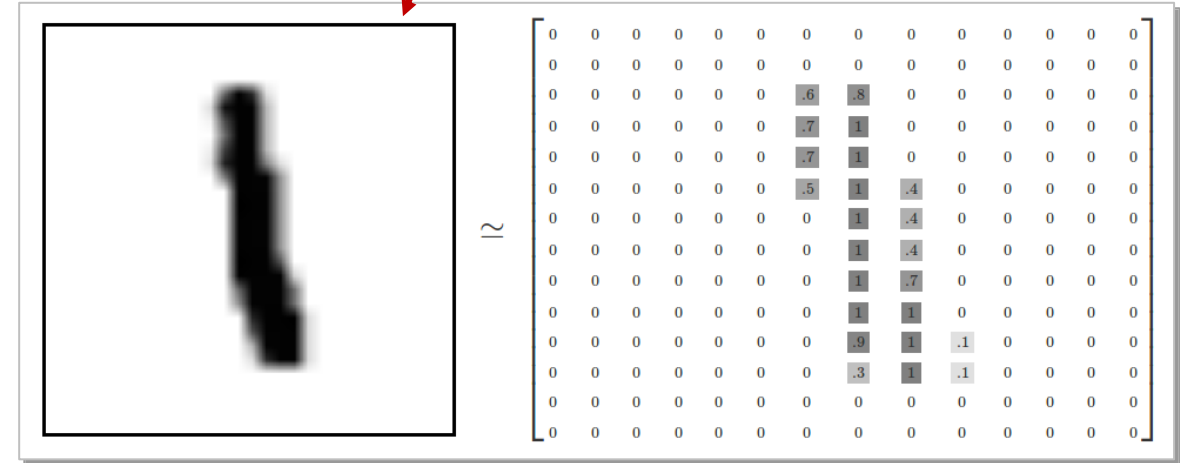


Image Representation

Representation of visual data (images) is based on matrices of pixels

Pixel: Is the smallest unit of an image

- Has an address in the matrix (row, column)
- Has an intensity...
 - **Greyscale images:** 0 for black and 255 for white
 - **RGB images:** 256 shades of red, green, and blue colors



Resolution of the screen (image container): Is the size of the matrix in terms of the number of rows and columns (pixels)

How do Convolutional Neural Networks (CNN) work?

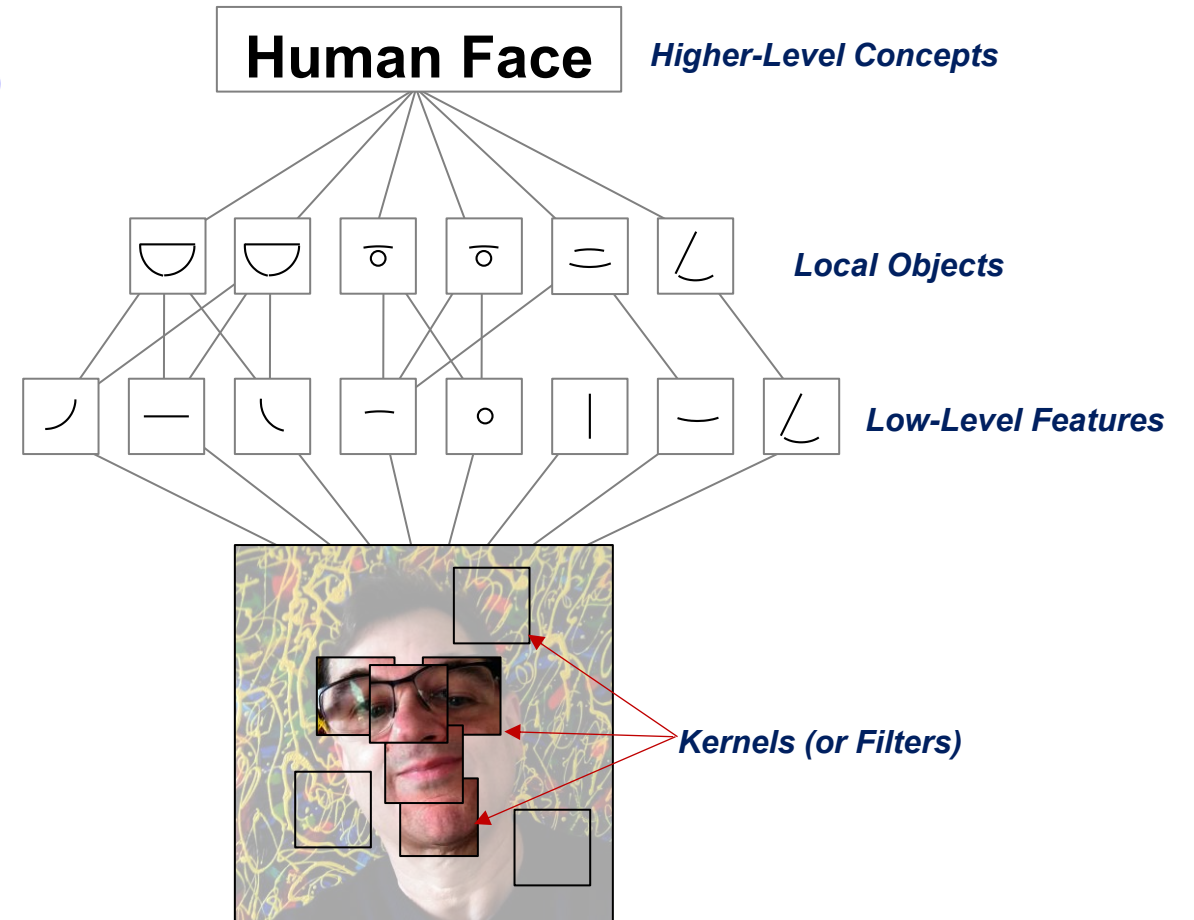
*The Deep Learning magic is in meaning (**representation**) forming at different neural network layers*

Images are scanned by tiny **filters** (also called **kernels**).

They are responsible for matching and identifying **low-level visual features**, such as edges of different direction, shades or colours.

Once detected at the next level these features are being combined into **local objects**, such as eyes, mouths, noses or glasses.

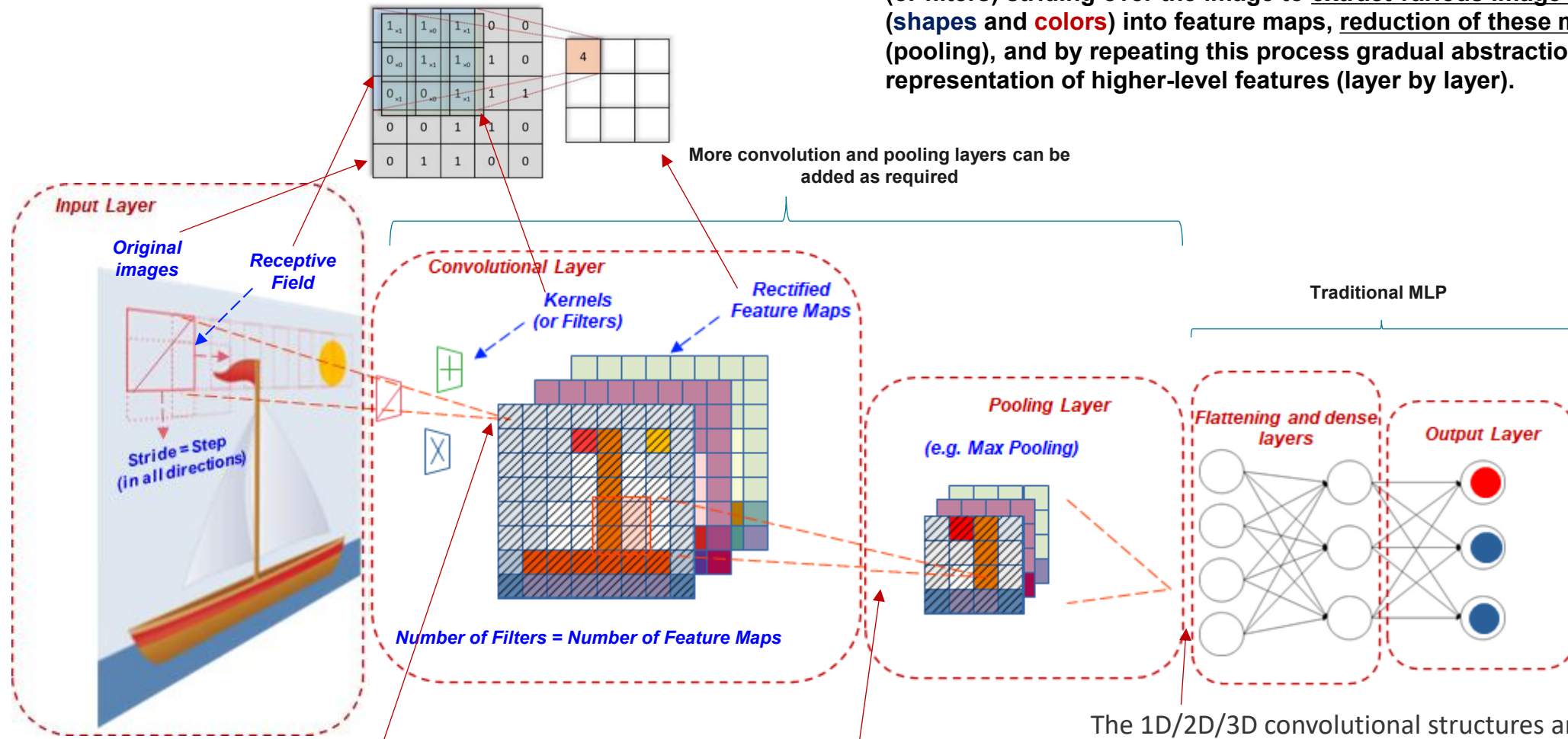
These local objects in turn combine into **high-level concepts**, such as a "human face".



A **kernel** is a numeric matrix, used to identify lines and edges in different direction, sharpening or blurring lines, identifying colours, etc. Kernels are discovered automatically.

Architecture of CNN

CNNs link different types of layers which aim at using small kernels (or filters) striding over the image to extract various image features (shapes and colors) into feature maps, reduction of these maps (pooling), and by repeating this process gradual abstraction and representation of higher-level features (layer by layer).

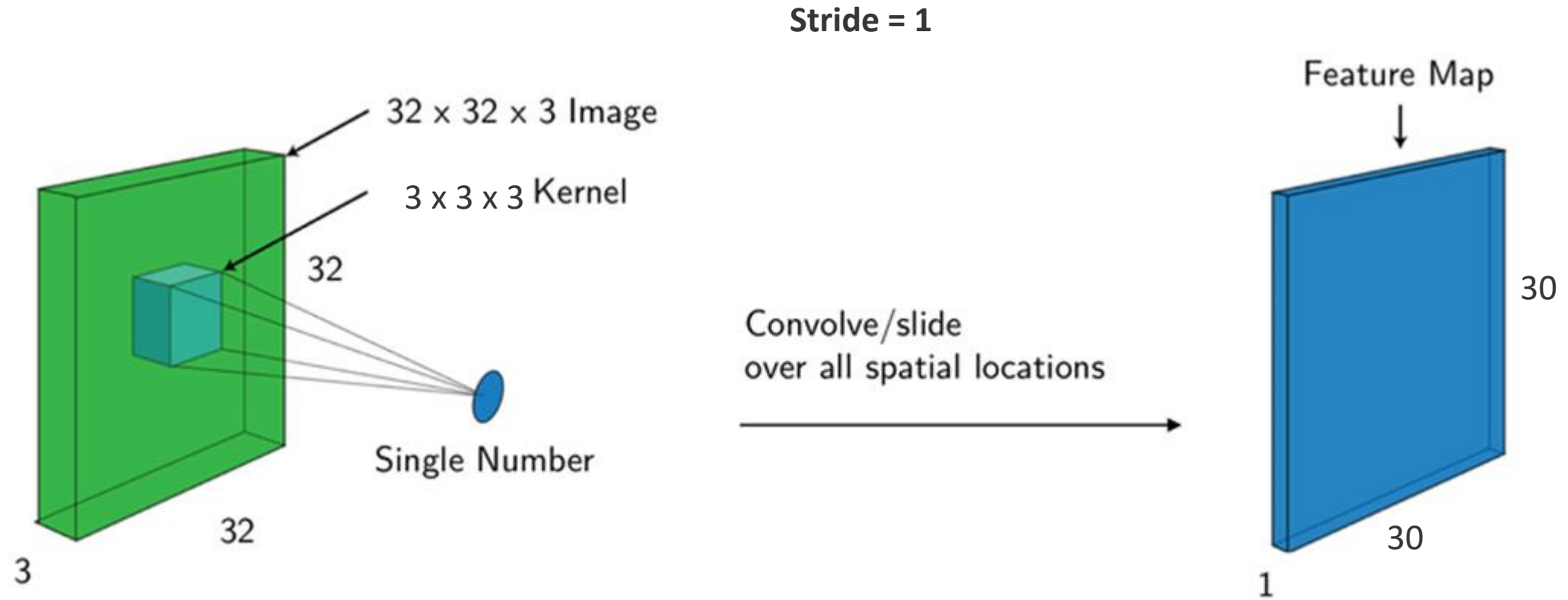


The **convolution operation** is the weighted sum of the receptive field and the kernel (usually 3x3 or 5x5), across all channels (RGB).

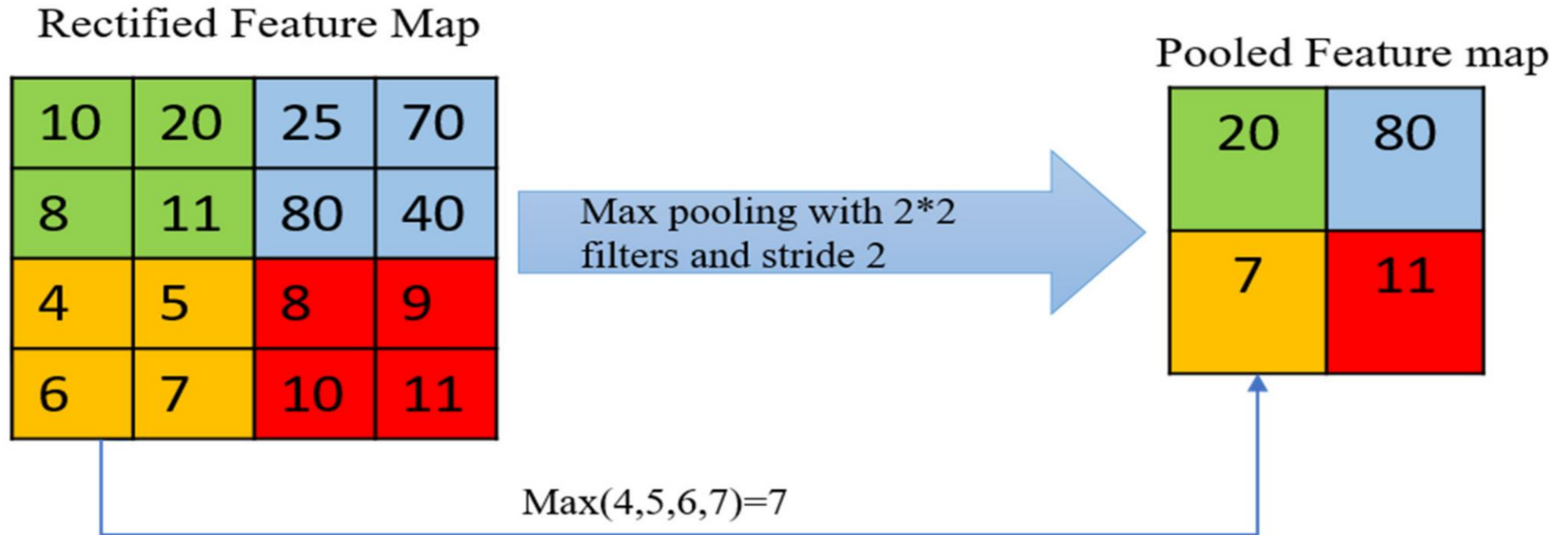
Max-pooling operation takes the maximum value from each channel within a window (usually 2x2) of the feature map, which is sliding over it (with a stride/step of 2 pixels), thus reducing the image dimension (by half).

The 1D/2D/3D convolutional structures are **flattened**, and a series of dense layers are used to output classification, estimation or decision making.

Convolution Layer



Max Pooling



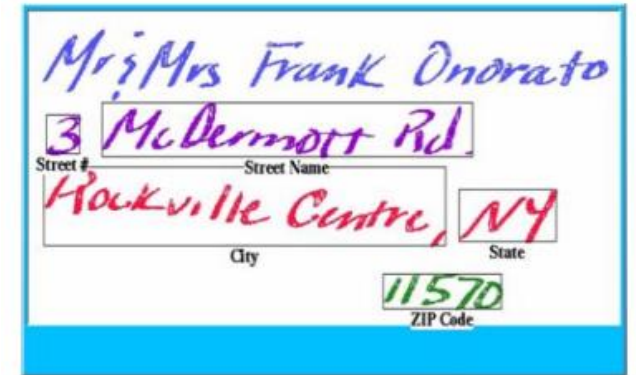
CNN Applications

Applications of CNN include:

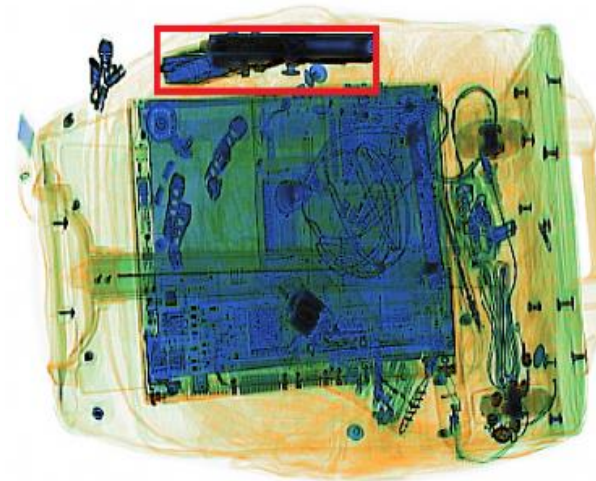
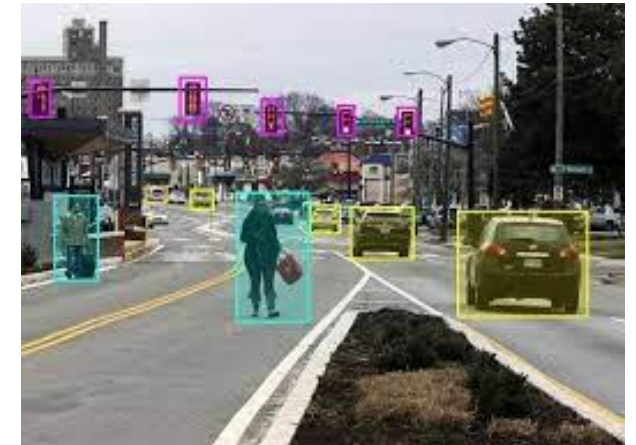
- ❑ Object Detection (e.g., fruits)
- ❑ Hand-writing recognition (e.g. transcription)
- ❑ Facial recognition (e.g. social media tagging)
- ❑ Emotion recognition (e.g. in lie detectors)
- ❑ Scene labelling (e.g. self-driving cars)
- ❑ Action recognition (e.g. suspicious behaviour)
- ❑ Motion detection (e.g. security cameras)
- ❑ MRI / CT diagnosis (e.g. cardiac imaging)
- ❑ Satellite image processing (e.g. for planning)
- ❑ Land feature recognition (e.g. missile systems)
- ❑ Echo-sound processing (e.g. oil prospecting)
- ❑ Object detection (e.g. airport scanners)
- ❑ Object tracking (e.g. players/ball in sport)
- ❑ Colouring and noise removal (e.g. photography)

...

Handwriting
recognition for
postal automation



Scene labelling
self-driving car



Threaten Object-Detection
in Bag Scanning at Airport

CNN in Python

□ Data Set:

CIFAR10 data sets includes images of consists of 60000 **32x32** colour images in 10 classes, with 6000 images per class

Your task is to:

Recognize the corresponding object in the images.

□ Tool:

Python + Tensorflow (with Keras)

□ Method:

Convolutional Neural Nets (CNN)

airplane



automobile



bird



cat



deer



dog



frog



horse



ship



truck



CNN in Python

Data Loading

```
from tensorflow.keras.datasets import cifar10

# Data parameters
img_rows, img_cols = 32, 32
channels = 3

num_classes = 10
class_names = ['airplane', 'automobile', 'bird', 'cat', 'deer',
               'dog', 'frog', 'horse', 'ship', 'truck']

# the data, shuffled and split between train and test sets
(x_train, y_train), (x_test, y_test) = cifar10.load_data()
```

```
plot_images(x_train[0:20], cols=5, figsize=[7,7])
```



Data Preparation

```
x_train /= 255
x_test /= 255
```

Why?

```
# convert class vectors to binary class matrices
y_train = to_categorical(y_train, num_classes)
y_test = to_categorical(y_test, num_classes)

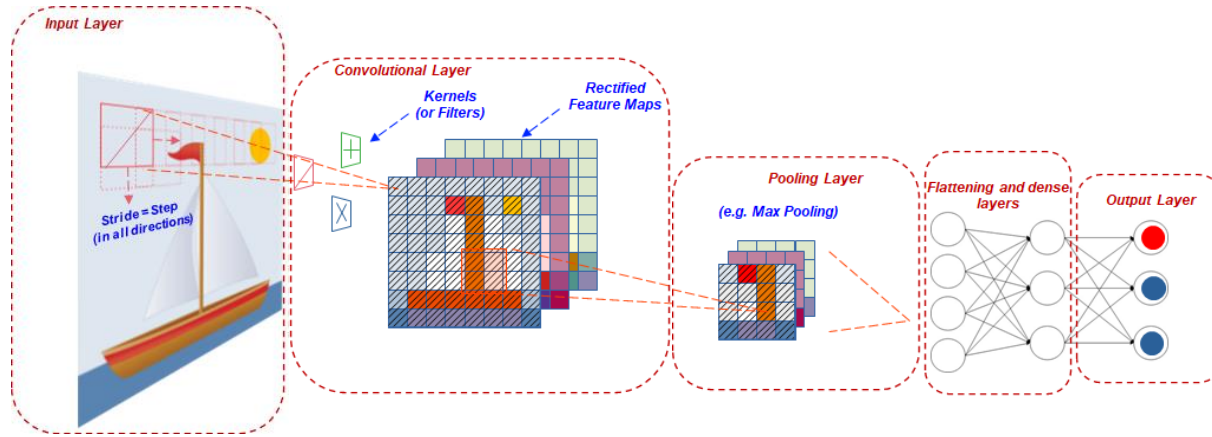
print('Train shape: x=', x_train.shape, ', y=', y_train.shape)
print('Test shape: x=', x_test.shape, ', y=', y_test.shape)
```

```
Train shape: x= (50000, 32, 32, 3) , y= (50000, 10)
Test shape: x= (10000, 32, 32, 3) , y= (10000, 10)
```

Why 3?

Why 10?

CNN in Python (cont.)



```
def model_2():
    model = Sequential()
    model.add(Conv2D(32, kernel_size=(3, 3),
                    strides=(1, 1),
                    activation='relu',
                    input_shape=(img_rows, img_cols, channels)))
    model.add(MaxPooling2D(pool_size=(2, 2)))
    model.add(Dropout(0.25))
    model.add(Flatten())
    model.add(Dense(128, activation='relu'))
    model.add(Dropout(0.5))
    model.add(Dense(num_classes, activation='softmax'))
    model.summary()
    return model
```

Annotations for the code:

- Number of filter**: Points to the value 32 in the Conv2D layer.
- Reduced to a quarter**: Points to the pool_size=(2, 2) in the MaxPooling2D layer.
- Prevent overfitting, randomly dropping some connections with preceding layer**: Points to the Dropout(0.25) and Dropout(0.5) layers.

1 Convolution and
1 Pooling Layers

1 Flattening and
1 Dense Layers

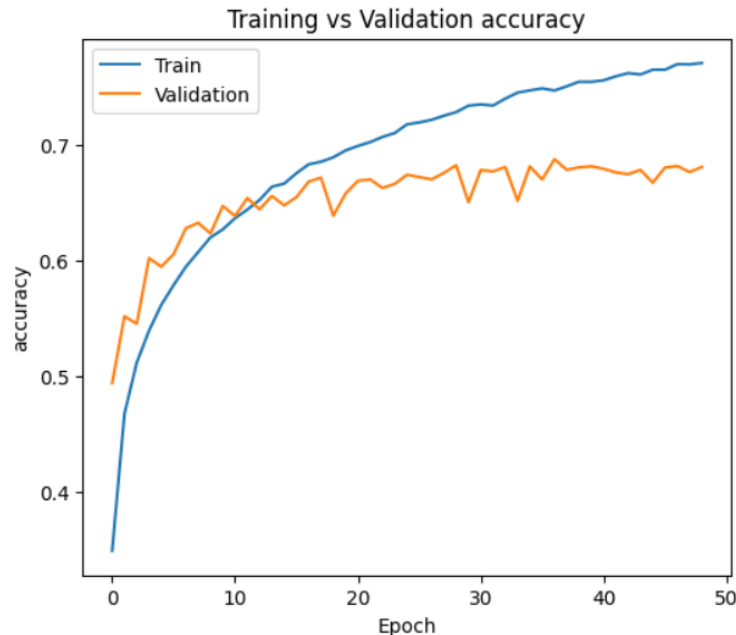
1 Output
Layer

Deep Learning CNN model is created

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 30, 30, 32)	896 = $(3 \times 3 \times 3 + 1) \times 32$
max_pooling2d_1 (MaxPooling 2D)	(None, 15, 15, 32)	0
dropout_2 (Dropout)	(None, 15, 15, 32)	0
flatten_1 (Flatten)	(None, 7200) = $15 \times 15 \times 32$	0
dense_2 (Dense)	(None, 128)	921728 = $(7200 + 1) \times 128$
dropout_3 (Dropout)	(None, 128)	0
dense_3 (Dense)	(None, 10)	1290 = $(128 + 1) \times 10$
=====		
Total params: 923,914		
Trainable params: 923,914		
Non-trainable params: 0		

CNN in Python (cont.)

- We will experiment with various *optimizers* or algorithms searching for the best set of network *weights* and *biases*
- The error function is called *loss* to guide the optimiser
- Other *metrics* can also be used measure the net performance, e.g. accuracy



The training process terminated after 49 epochs.

```
model.compile(loss=categorical_crossentropy,  
              optimizer=RMSprop(learning_rate=0.001,weight_decay=1e-6),  
              metrics='accuracy')
```

← optimizers
← Performance metric

```
hist = model.fit(x_train, y_train,  
                batch_size=128,  
                epochs=100,  
                verbose=2,  
                validation_data=(x_test, y_test),  
                validation_split=0.2,  
                callbacks=keras_callbacks)
```

← Train the model and evaluate against test set.

```
Epoch 1/100  
391/391 - 3s - loss: 2.1041 - accuracy: 0.2456 - val_loss: 1.8539 - val_accuracy: 0.3309  
Epoch 2/100  
391/391 - 2s - loss: 1.8945 - accuracy: 0.3132 - val_loss: 1.7669 - val_accuracy: 0.3608  
Epoch 3/100
```

```
Adadelta(lr=0.001, rho=0.95, epsilon=1e-07)  
Adadelta(lr=0.05, rho=0.99, epsilon=1e-07)  
Adam(lr=0.001, beta_1=0.9, beta_2=0.999, epsilon=1e-07)
```

Other Optimizers

Final Performance measures:

```
Train loss: 0.2722  
Train accuracy: 0.9236  
  
Test loss: 1.098  
Test accuracy: 0.6806
```



CNN in Python (cont.)

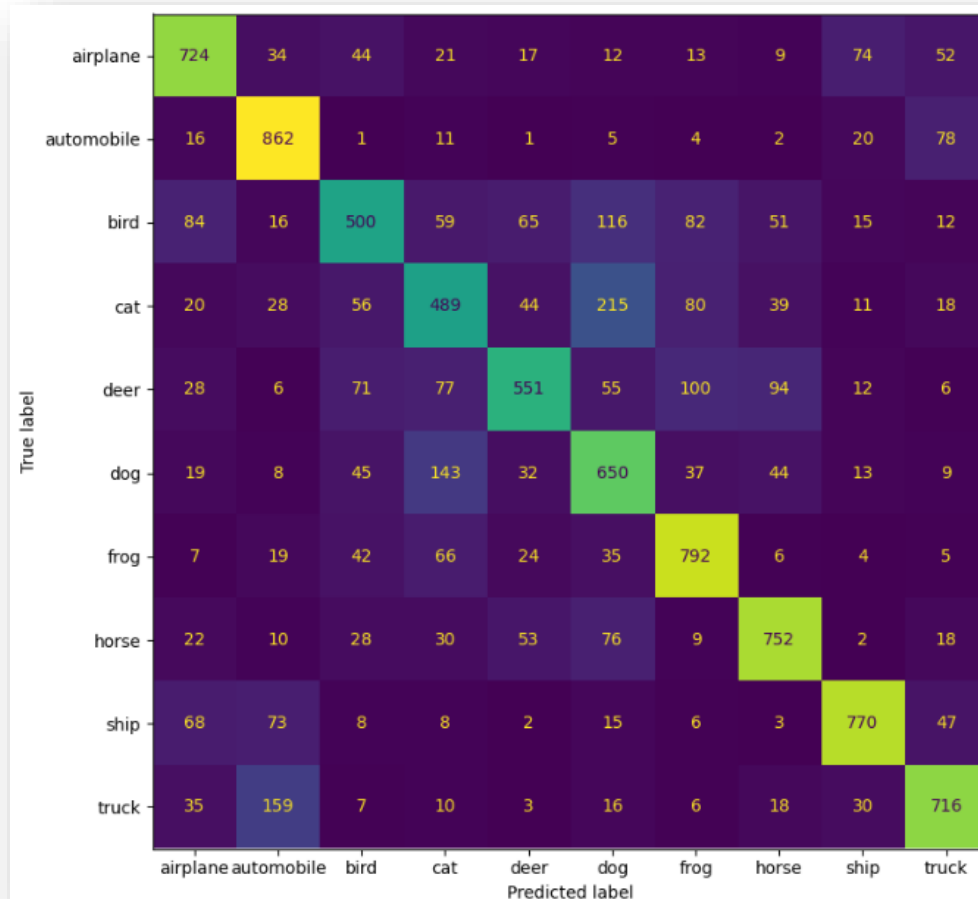
Evaluation Metrics

The result of Kappa is : 0.645

The result of the classification report is:

	precision	recall	f1-score	support
airplane	0.71	0.72	0.72	1000
automobile	0.71	0.86	0.78	1000
bird	0.62	0.50	0.55	1000
cat	0.54	0.49	0.51	1000
deer	0.70	0.55	0.61	1000
dog	0.54	0.65	0.59	1000
frog	0.70	0.79	0.74	1000
horse	0.74	0.75	0.75	1000
ship	0.81	0.77	0.79	1000
truck	0.75	0.72	0.73	1000
accuracy			0.68	10000
macro avg	0.68	0.68	0.68	10000
weighted avg	0.68	0.68	0.68	10000

Confusion Matrix



Discussion

```
def model_1():
    model = Sequential()
    model.add(Flatten(input_shape=(img_rows, img_cols, channels)))
    model.add(Dense(128, activation='relu'))
    model.add(Dropout(0.2))
    model.add(Dense(10, activation='softmax'))
    model.summary()
    return model
```

Is this a CNN model?

```
def model_2():
    model = Sequential()
    model.add(Conv2D(32, kernel_size=(3, 3),
                    activation='relu',
                    input_shape=(img_rows, img_cols, channels)))
    model.add(MaxPooling2D(pool_size=(2, 2)))
    model.add(Dropout(0.25))
    model.add(Flatten())
    model.add(Dense(128, activation='relu'))
    model.add(Dropout(0.5))
    model.add(Dense(num_classes, activation='softmax'))
    model.summary()
    return model
```

Which model would perform better? And Why?

The result of Kappa is : 0.387
The result of the classification report is:

	precision	recall	f1-score	support
airplane	0.60	0.36	0.46	1000
automobile	0.55	0.58	0.56	1000
bird	0.37	0.29	0.33	1000
cat	0.30	0.28	0.29	1000
deer	0.47	0.29	0.36	1000
dog	0.42	0.30	0.35	1000
frog	0.40	0.66	0.50	1000
horse	0.53	0.48	0.51	1000
ship	0.59	0.56	0.58	1000
truck	0.38	0.66	0.48	1000
accuracy			0.45	10000
macro avg	0.46	0.45	0.44	10000
weighted avg	0.46	0.45	0.44	10000

The result of Kappa is : 0.645
The result of the classification report is:

	precision	recall	f1-score	support
airplane	0.71	0.72	0.72	1000
automobile	0.71	0.86	0.78	1000
bird	0.62	0.50	0.55	1000
cat	0.54	0.49	0.51	1000
deer	0.70	0.55	0.61	1000
dog	0.54	0.65	0.59	1000
frog	0.70	0.79	0.74	1000
horse	0.74	0.75	0.75	1000
ship	0.81	0.77	0.79	1000
truck	0.75	0.72	0.73	1000
accuracy			0.68	10000
macro avg	0.68	0.68	0.68	10000
weighted avg	0.68	0.68	0.68	10000

How to improve prediction performance?



Working with Real Digital Photos

```
drive.mount('/content/drive')

# Set the paths to the folders containing the image files
city_path = '/content/drive/MyDrive/Colab Notebooks/dataset/city'
country_path = '/content/drive/MyDrive/Colab Notebooks/dataset/country'
```



```
# Iterate through the files in the first folder
for file in os.listdir(city_path):
    # Check if the file is a jpeg or jpg file
    if file.endswith('.jpeg') or file.endswith('.jpg'):
        # Load the image data from the file using TensorFlow
        img = tf.io.read_file(os.path.join(city_path, file))
        img = tf.image.decode_jpeg(img)
        img = tf.image.resize(img, (100, 100))
        # Assign a label to the file
        label = 'City'
        # Add the image data and label to the data list
        data.append((img, label))
```

In this lecture, we have covered:

- The concepts and architectures of CNN.
- Experiments with various model architectures of CNN in Python.
- Discussion on the applications of these deep learning techniques.

Summary