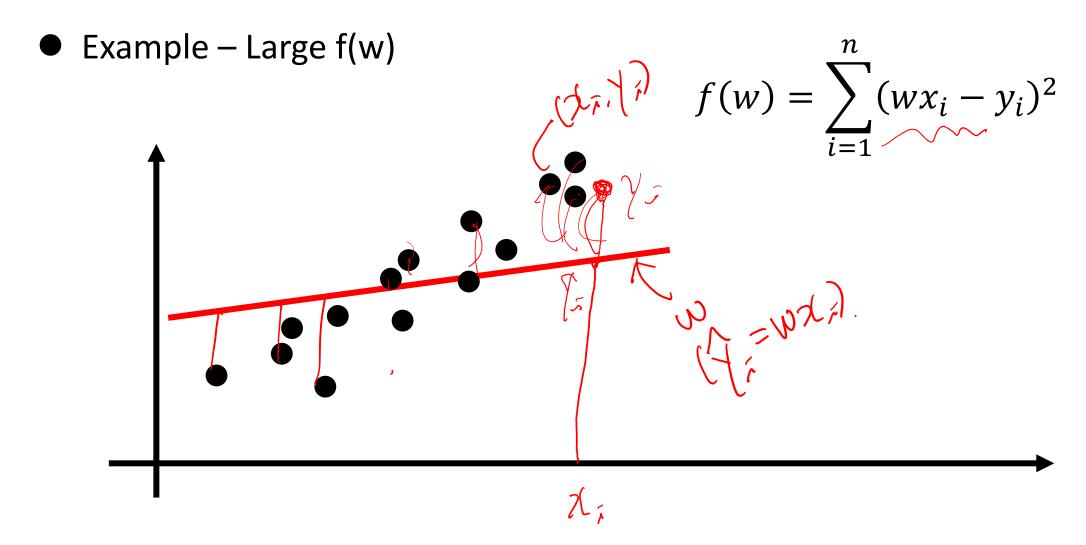
Least Squres Objective

- Instead of "exact y_i ", we evaluate the size of error in prediction
- Classic way is setting slope 'w' to minimize the sum of squared errors:

$$f(w) = \sum_{i=1}^{n} (wx_i - y_i)^2$$

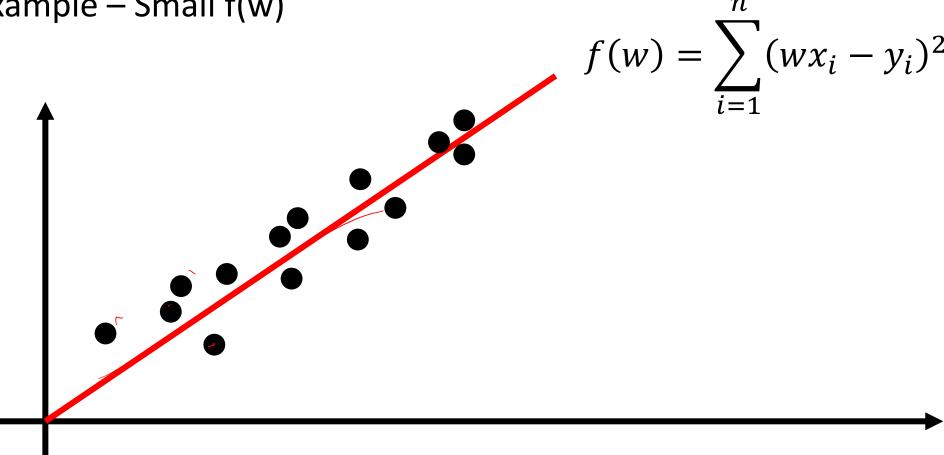
- A probabilistic interpretation is coming later in this course!
- But usually, it is done because it is easy to minimize.

Least Squres Objective



Least Squres Objective

■ Example – Small f(w)



Finding Least Squares Solution

- Not change the solution!
 - Multiply 'f' by any positive constant
 - Add some constants to 'f'

$$f'(w) = C_1 \sum_{i=1}^{n} (wx_i - y_i)^2 + C_2$$

Finding 'w' that minimizes sum of squared errors:

$$f(w) = \frac{1}{2} \sum_{i=1}^{n} (wx_i - y_i)^2 = \frac{1}{2} \sum_{i=1}^{n} [w^2 x_i^2 - 2wx_i y_i + y_i^2]$$

$$= \frac{w^2}{2} \sum_{i=1}^{n} x_i^2 - w \sum_{i=1}^{n} x_i y_i + \frac{1}{2} \sum_{i=1}^{n} y_i^2 = \frac{w^2}{2} a - wb + c$$

$$f'(w) = wa - b = 0$$

$$w = \frac{\sum_{i=1}^{n} x_i y_i}{\sum_{i=1}^{n} x_i^2}$$

Multiple Dimension Linear Function

- A simple way is with a d-dimensional linear model
 - $\widehat{y}_i = \widehat{w}_1 x_{i1} + \widehat{w}_2 x_{i2} + \widehat{w}_3 x_{i3} + \dots + \widehat{x}_d x_{id}$
 - In words, our model is that the output is a weighted sum of the inputs
- We can re-write this in summation notation:
 - $\bullet \ \widehat{y_i} = \sum_{j=1}^d w_j x_{ij}$
- We can also re-write this in vector notation: (inner product)
 - $\bullet \ \widehat{y}_i = \mathbf{w}^{\mathsf{T}} \mathbf{x}_i$
 - In this course, a vector is a column vector

Least Squares in d-Dimensions

• The linear least squares model in d-dimensions minimizes:

$$f(\mathbf{w}) = \frac{1}{2} \sum_{i \neq 1}^{n} (\mathbf{w}^{T} \mathbf{x}_{i} - y_{i})^{2}$$

Least Squares Partial Derivatives for 1 sample

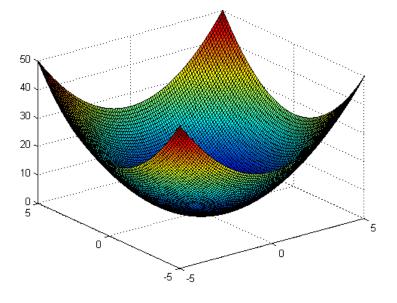
$$f(w_1, w_2, \dots, w_d) = \frac{1}{2} \left(\sum_{j=1}^d w_j x_{ij} \right)^2 - \left(\sum_{j=1}^d w_j x_{ij} \right) y_i + \frac{1}{2} y_i^2$$

$$\frac{\partial}{\partial w_i} f(w_1, w_2, \dots, w_d) = \left(\sum_{j=1}^d w_j x_{ij} \right) x_{ik} - y_i x_{ik} = \left(\mathbf{w}^T \mathbf{x}_i - y_i \right) x_{ik}$$

Least Squares in d-Dimensions

Least Squares Partial Derivatives for all samples

$$\frac{\partial}{\partial w_k} f(w_1, w_2, \dots, w_d) = \sum_{i=1}^n (\mathbf{w}^T \mathbf{x}_i - y_i) x_{ik}$$



- Unfortunately, the partial derivative for w_j depends on all $\{w_1, w_2, ..., w_d\}$
 - Thus, we can't just set equal to 0 and solve for w_j
 - We need to find 'w' where the gradient vector equals the zero vector!

$$\nabla f(w_1, w_2, \dots, w_d) = \left[\frac{\partial f}{\partial w_1}, \frac{\partial f}{\partial w_2}, \frac{\partial f}{\partial w_3}, \dots, \frac{\partial f}{\partial w_d} \right]^T = 0$$

Linear and Quadratic Gradients

$$A = A^T$$

$$f(w) = \underbrace{aw^2}_{\partial w} \int_{\partial w} \frac{\partial}{\partial w} f(w) = \underbrace{2aw}_{\partial w}$$

$$g(w) = bw \quad \downarrow \quad \frac{\partial}{\partial w} g(w) = b$$

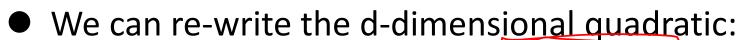
$$h(w) = c \qquad \left| \frac{\partial}{\partial w} h(w) \right| = 0$$

$$f(\mathbf{w}) = \mathbf{w}^{\mathrm{T}} \mathbf{A} \mathbf{w} \quad \forall \quad \nabla f(\mathbf{w}) = \mathbf{A} \mathbf{w}$$
If A is symmetric

$$g(\mathbf{w}) = \mathbf{w}^{\mathsf{T}}\mathbf{b} \quad \left| \right\rangle \quad \nabla g(\mathbf{w}) = \mathbf{b}$$

$$h(\mathbf{w}) = \mathbf{c} \qquad \qquad | \langle \nabla h(\mathbf{w}) \rangle = 0$$

Linear and Quadratic Gradients



$$f(\mathbf{w}) = \frac{1}{2} \mathbf{w}^{T} \mathbf{x}_{i} - y_{i}^{2} = \frac{1}{2} \mathbf{w}^{T} \mathbf{x}_{i} - \mathbf{y}^{T} \mathbf{y} + \frac{1}{2} \mathbf{y}^{T} \mathbf{y}$$

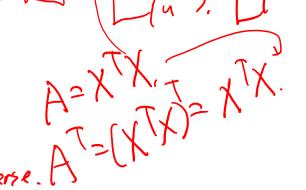
$$f(\mathbf{w}) = \frac{1}{2} \mathbf{w}^{T} \mathbf{A} \mathbf{w} + \mathbf{w}^{T} \mathbf{b} + \mathbf{c}$$

Thus, the gradient is given by:



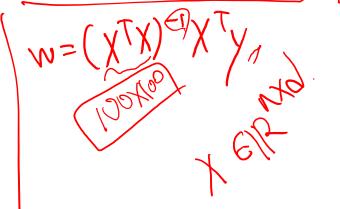
 $\mathbf{X}^{\mathsf{T}}\mathbf{X}\mathbf{w} = \mathbf{X}^{\mathsf{T}}\mathbf{y}$ (in the form of Ax = b)

• When X^TX is invertible, $\mathbf{w} = (X^TX)^T$



Inverse Matrix & Pseudo-inverse Matrix

- For $m \times n$ system A,
 - Ax = b
 - Let's find x that minimizes the energy of $||Ax b||^2$
- The derivative of $||Ax b||^2$ becomes
 - Ax b = 0
 - Ax = b
 - But, we can't estimate the inverse of A because A is not square!



Inverse Matrix & Pseudo-inverse Matrix

- The derivative of $||Ax b||^2$ becomes
 - Ax b = 0
 - Ax = b
 - But, we can't estimate the inverse of A because A is not square!
- Then, let's make it square matrix
 - $A^T A x = A^T b$
 - When the columns of A are linearly independent, A^TA is invertible. Thus,
 - $x = (A^T A)^{-1} A^T b \equiv A^+ b$