



[A4-004] 딥러닝 코딩 실습

Lecture 03: Implicit Neural Representations

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Topic

- Implicit Neural Representations
 - Occupancy Networks
 - INRs with Periodic Activation Functions

Explicit Representation of Signals

- Traditionally, **discrete** representations for signals are used

1D Signal: Audio



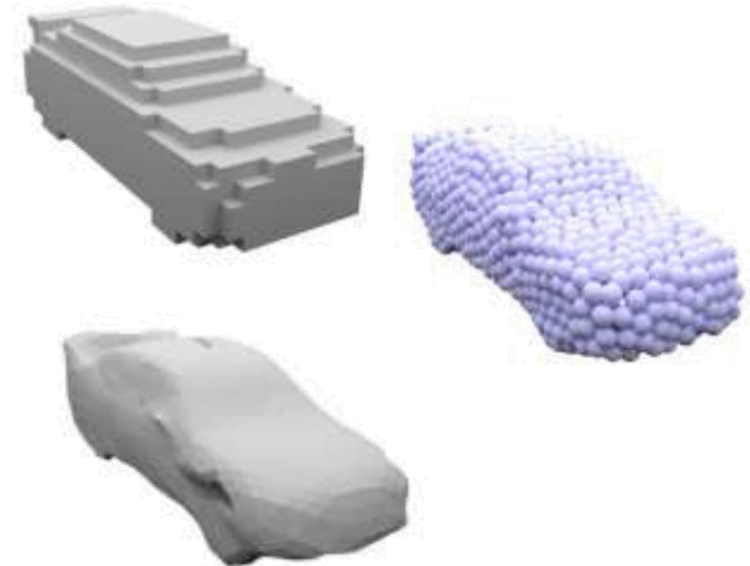
Samples of
sound wave

2D Signal: Images



Pixels

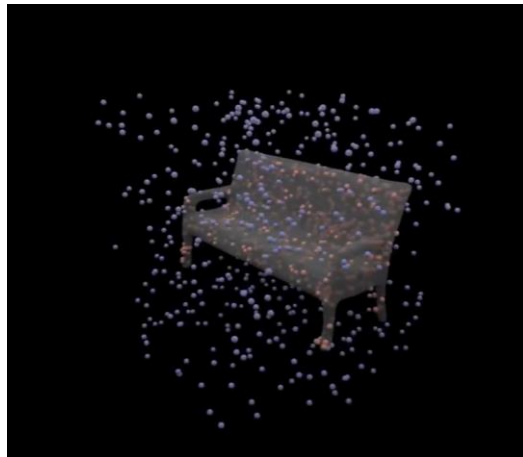
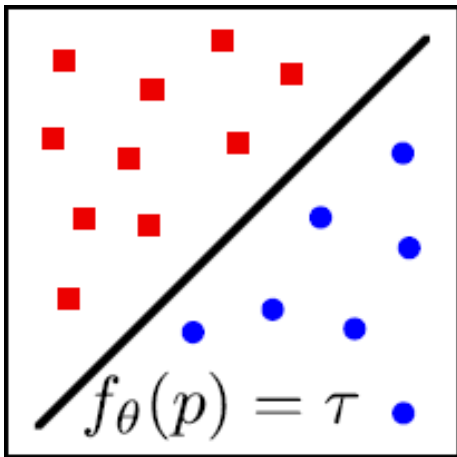
3D Signal: Shapes



Voxels / Mesh /
Point clouds

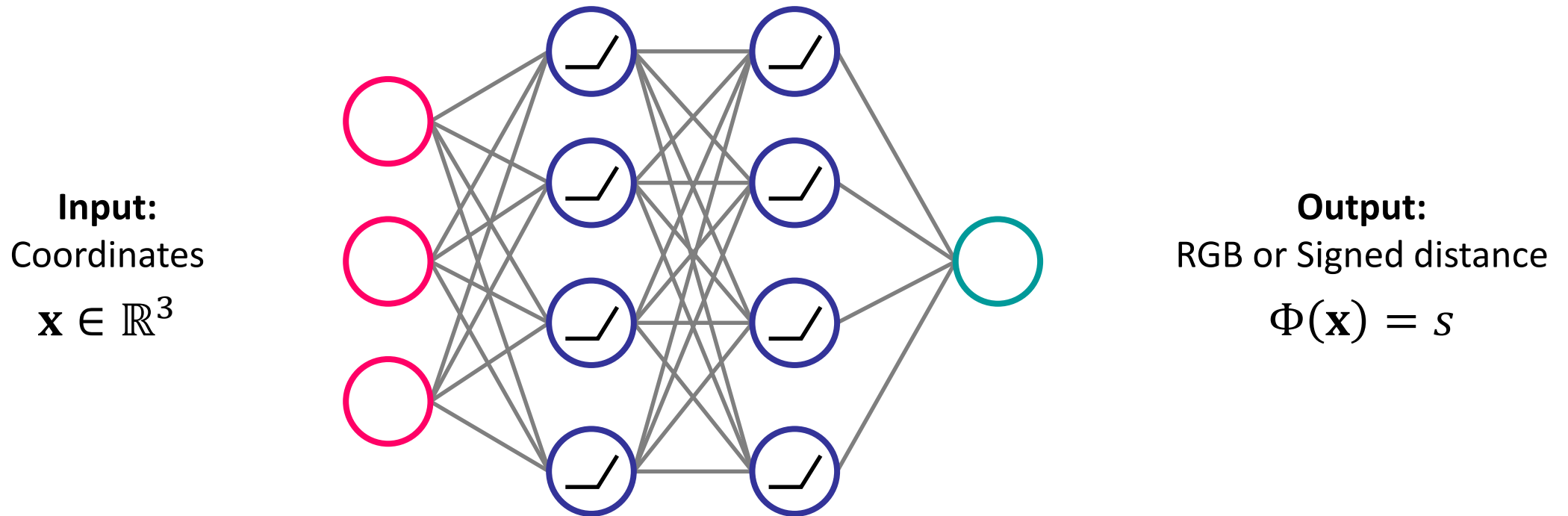
Implicit Representation of Signals

- In implicit neural representations (INRs), signals are parameterized by neural networks
- Example of implicit neural representations for 3D shapes
 - Do not represent 3D shape explicitly
 - Consider surface **implicitly** as **decision boundary**



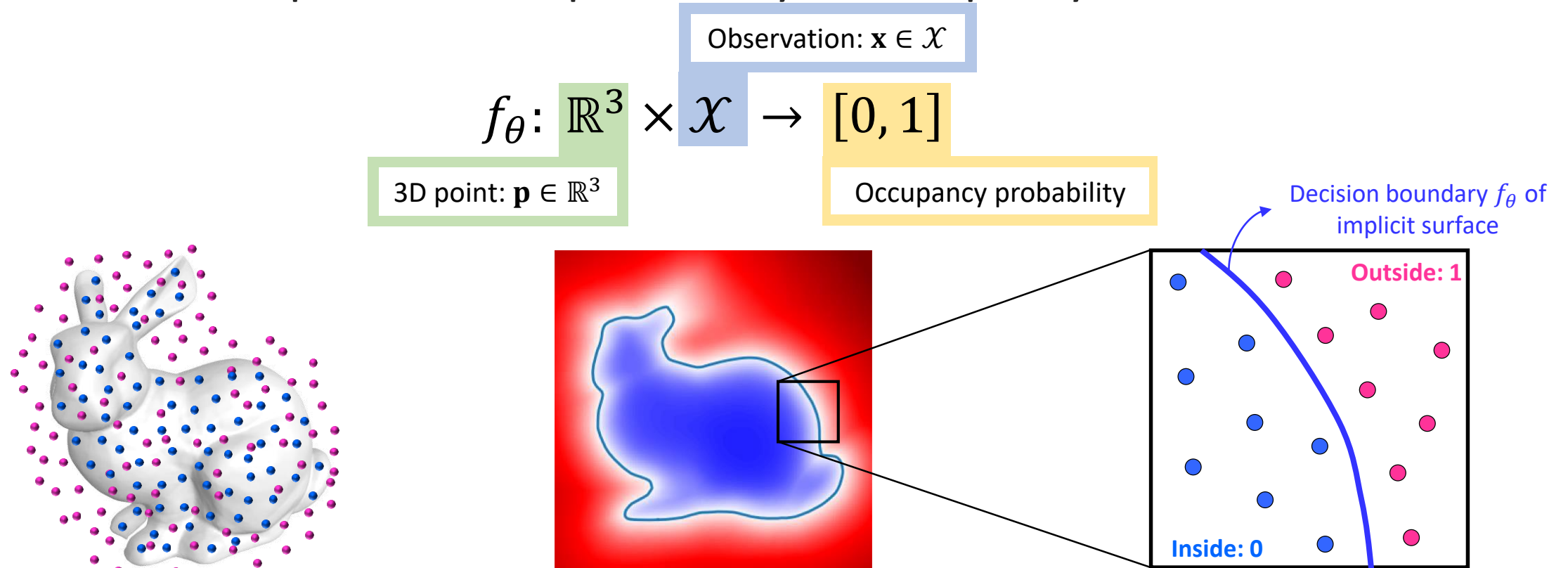
Implicit Representation of Signals

- Benefits of Implicit Neural Representations (INRs)
 - **Agnostic** to grid resolution
 - **Differentiations** computed automatically



Occupancy Network

- Occupancy Network
 - The **occupancy network** f_θ takes a pair (\mathbf{p}, \mathbf{x}) as input and outputs a real number which represents the probability of occupancy:



Occupancy Network: Architecture

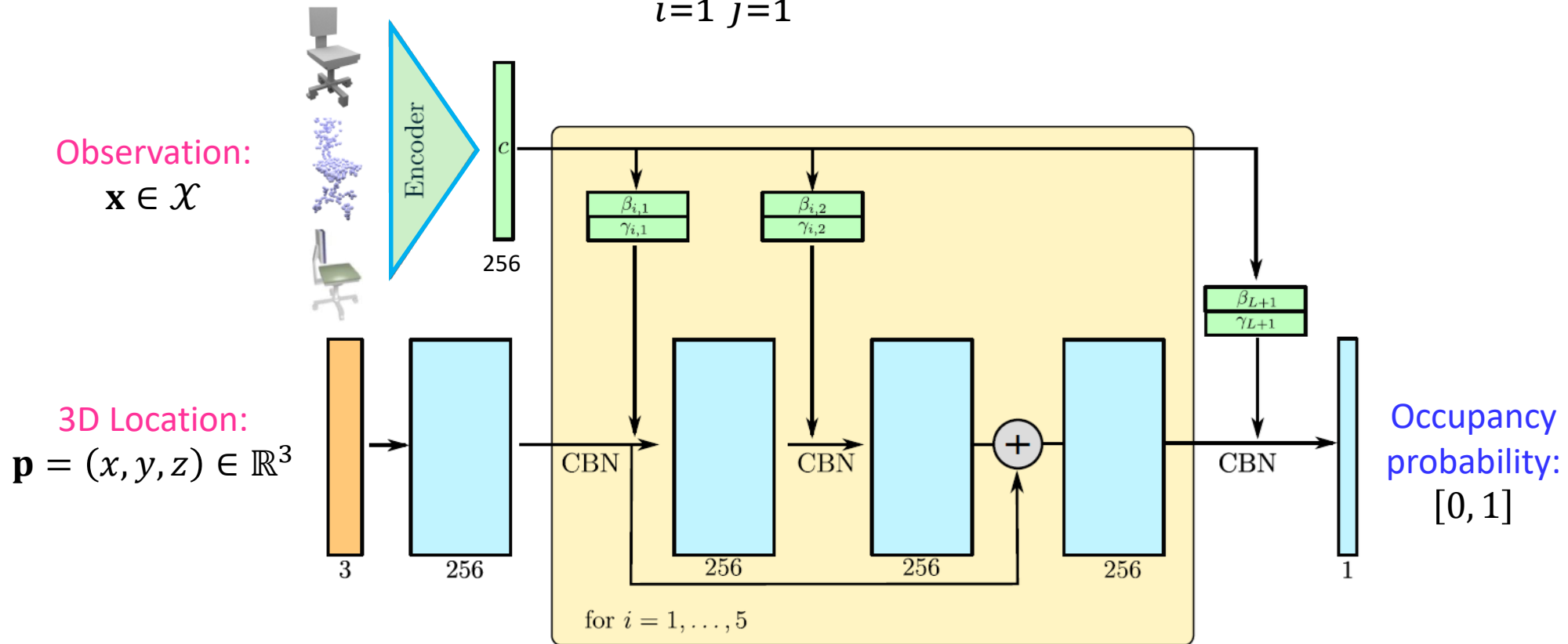
- Model & Loss Function

$$\mathcal{L}(\theta) = \frac{1}{|\mathcal{B}|} \sum_{i=1}^{|\mathcal{B}|} \sum_{j=1}^K BCE(f_{\theta}(\mathbf{p}_{ij}, \mathbf{x}_i), o_{ij})$$

$|\mathcal{B}|$: #. of batch

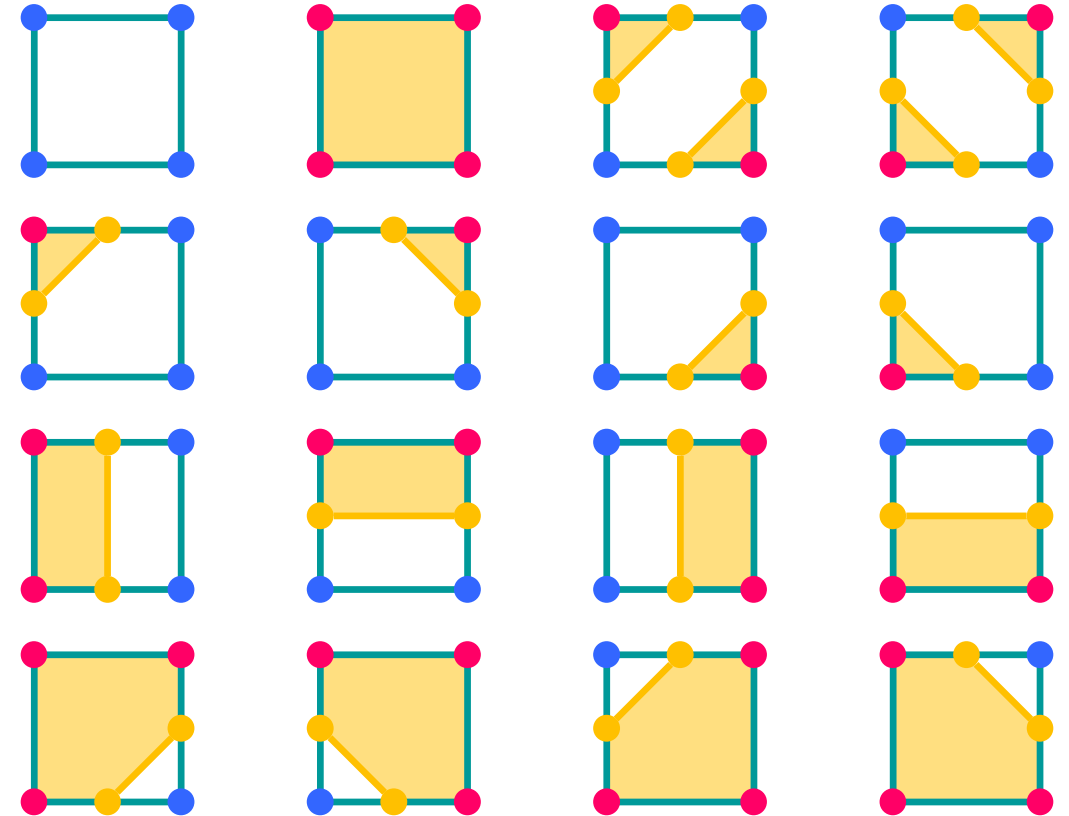
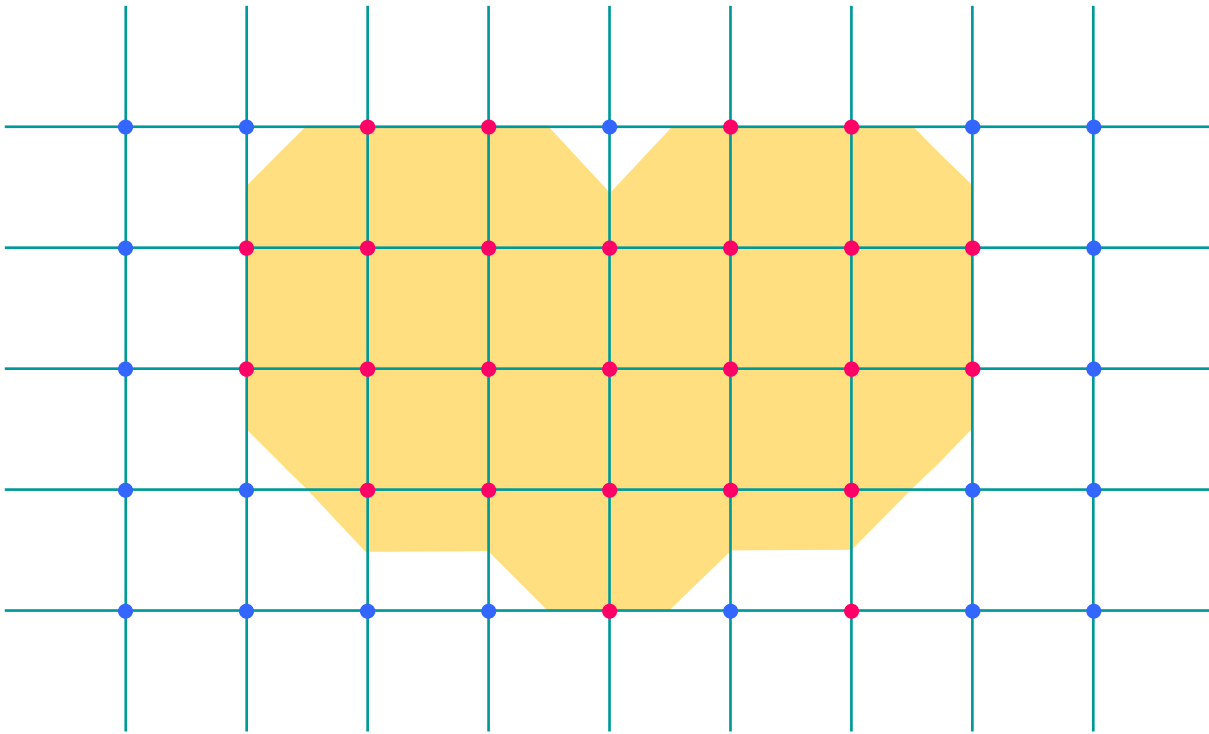
K : #. of randomly sampled points

BCE : Cross-entropy loss

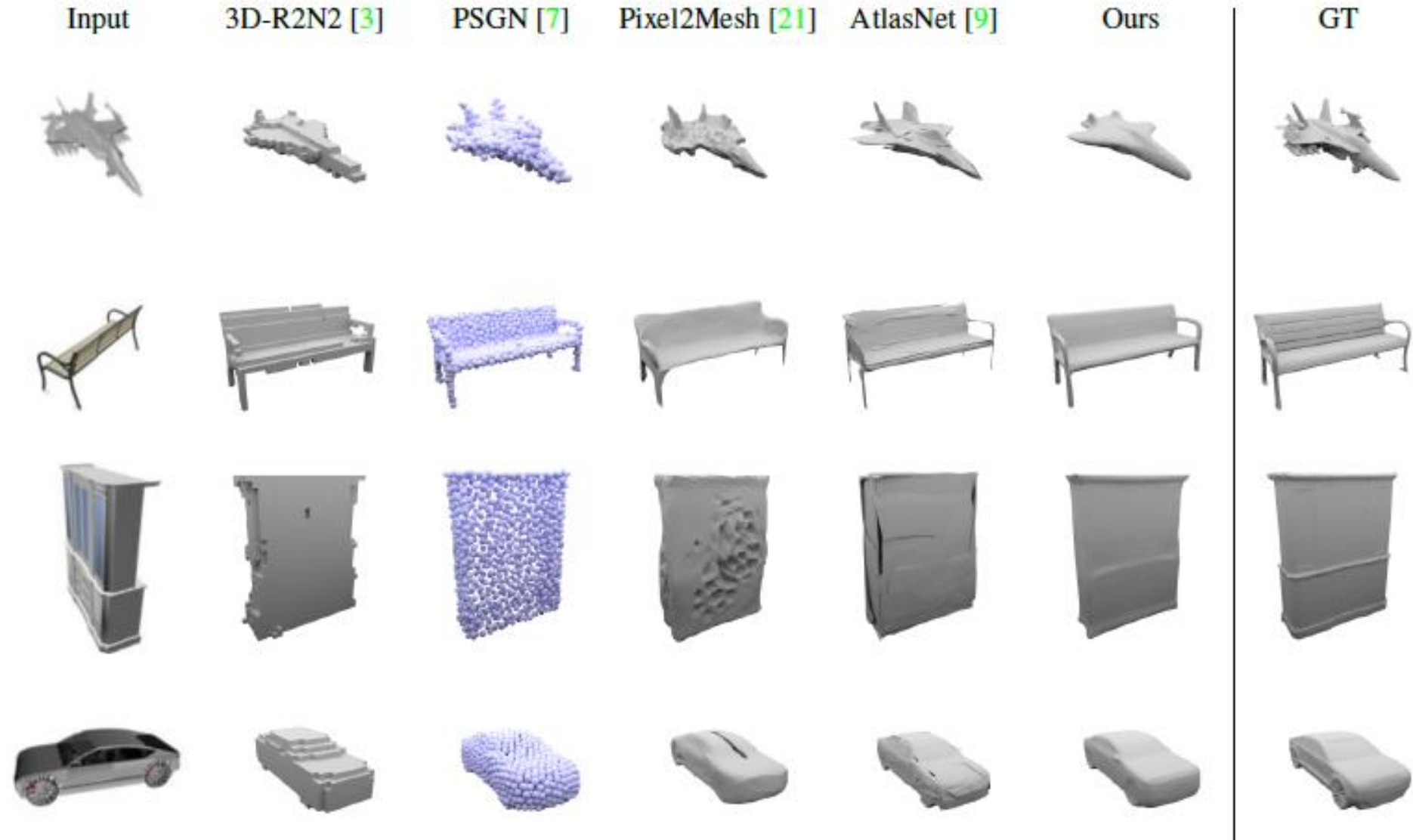


Marching Cube for 3D Visualization

- Marching Cubes
 - A computer graphics algorithm for extracting a polygonal mesh of an isosurface from a three-dimensional discrete scalar field (e.g., point clouds)



Results of Occupancy Network



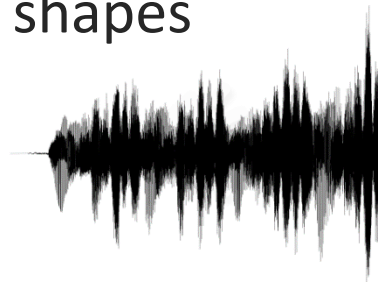
Results of Occupancy Network

Single View 3D Reconstruction
Results

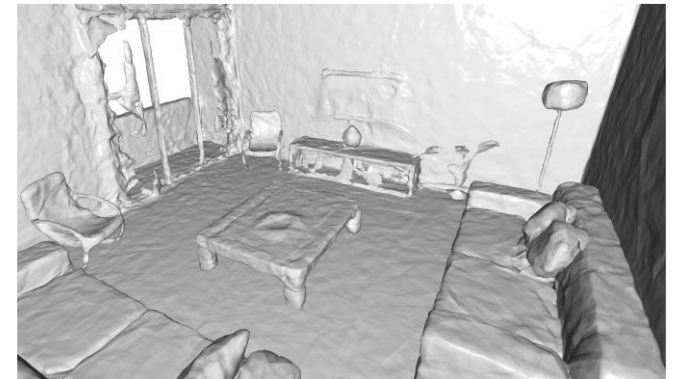
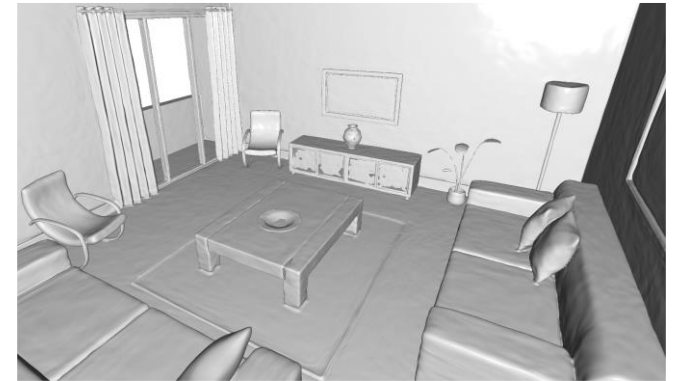
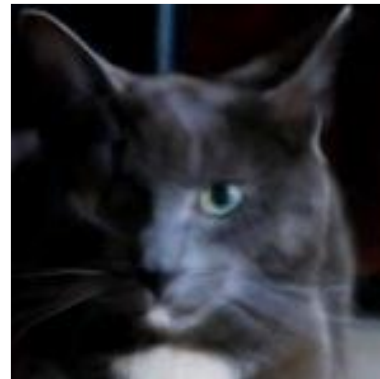
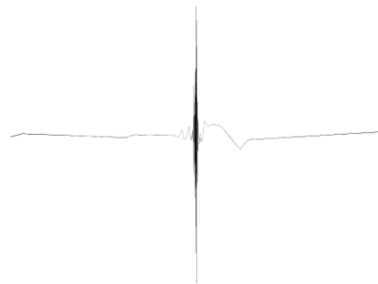
Problems of INRs

- Recent implicit neural representations build on ReLU-based MLPs **lack the capacity to represent fine details** in the underlying signals
 - Missing high frequencies in sound wave
 - Blurry images
 - Distorted 3D shapes

Original
Signals

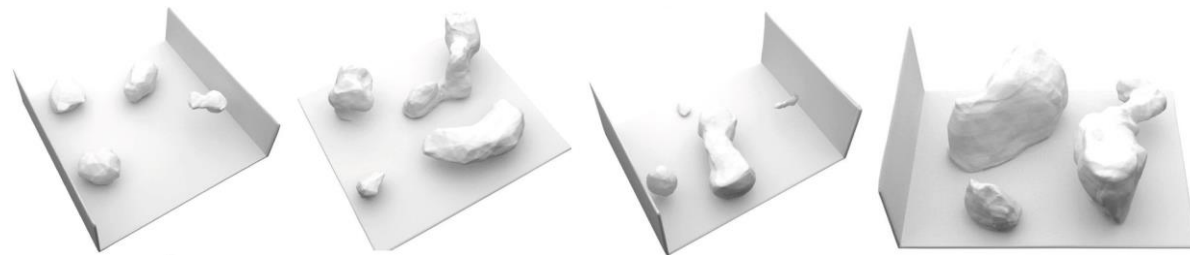


Signals
represented by INRs
(MLP w/ ReLU)

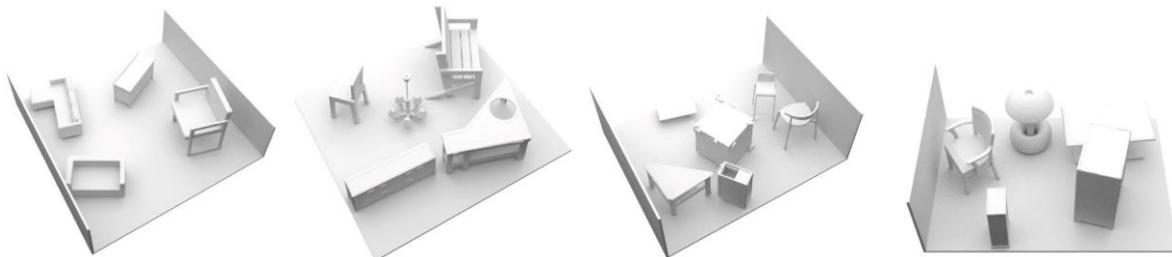


Problems of INRs

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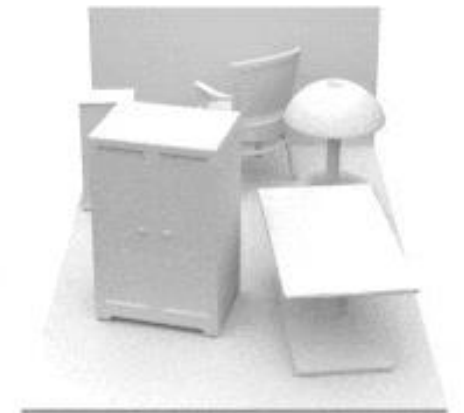
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Ground-Truth Mesh



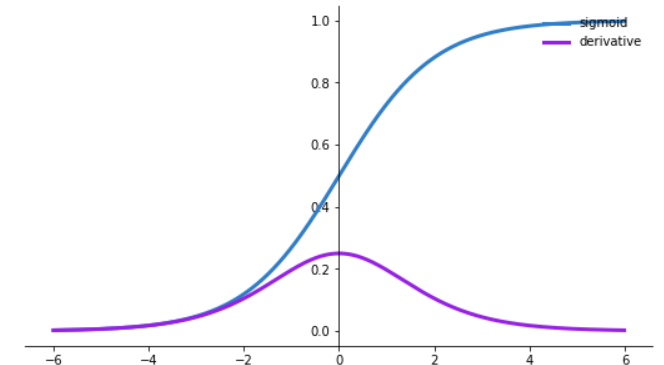
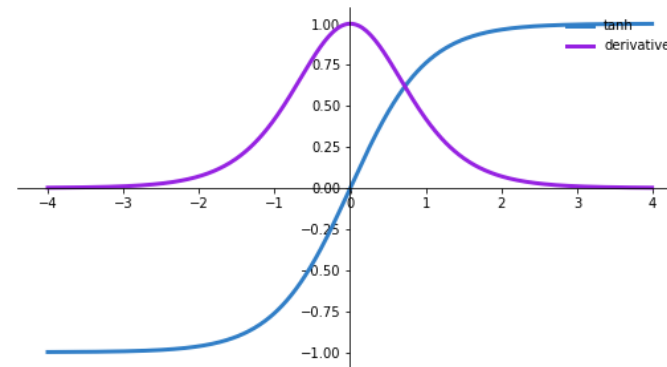
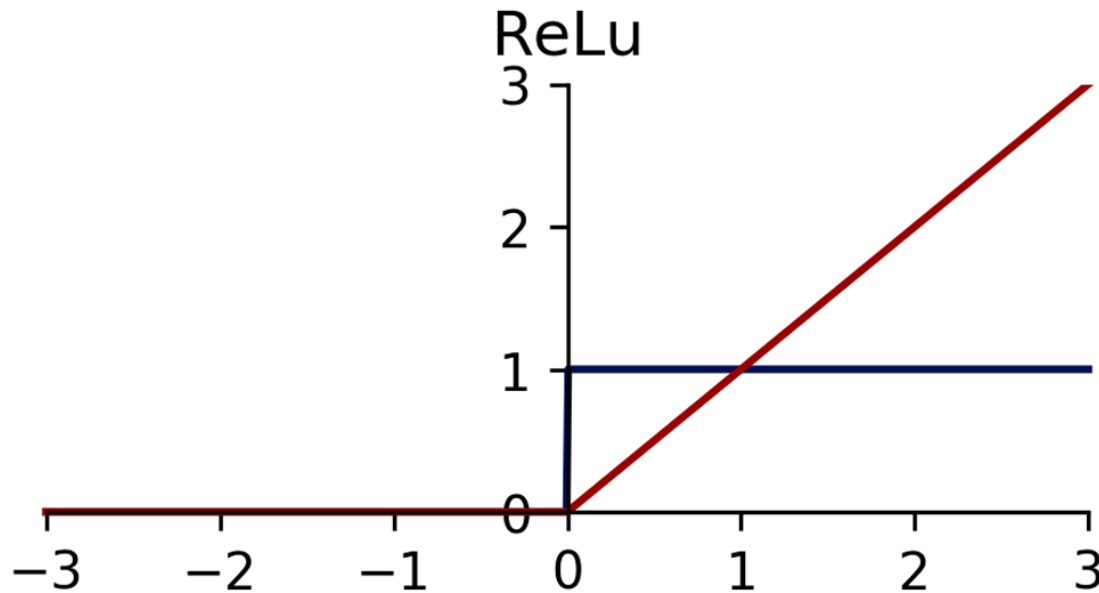
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Ground-Truth Mesh

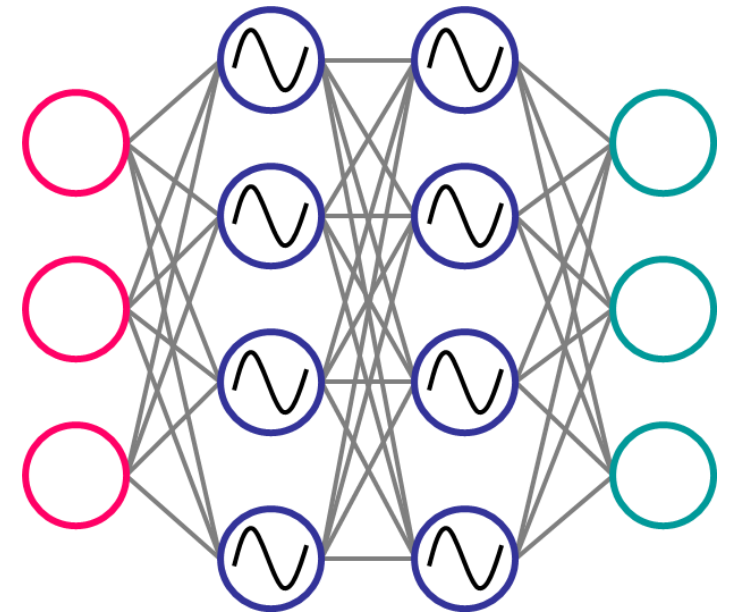
Limitations of ReLU

- Characteristics of ReLU
 - Being piecewise linear \rightarrow The second derivative is zero
 - Incapable of modeling information contained in higher-order derivatives of natural signals



Sinusoidal Representation Networks (SIREN)

- Contributions of SIREN
 - A continuous INR using periodic activation functions (sine) that fits complicated signals as well as their derivatives robustly
 - An initialization scheme for training and validation that distributions of these representations can be learned using hypernetworks
 - Demonstration of a wide range of applications:
 - image, video, and audio representation
 - 3D shape reconstruction
 - solving first/second-order differential equations



Problem Formulation

- Implicit problem formulation takes as input the spatial coordinates $\mathbf{x} \in \mathbb{R}^m$ and, optionally, derivatives of Φ with respect to these coordinates

$$F(\mathbf{x}, \Phi, \nabla_{\mathbf{x}}\Phi, \nabla_{\mathbf{x}}^2\Phi, \dots) = 0, \quad \Phi : \mathbf{x} \mapsto \Phi(\mathbf{x})$$

- Our goal is to find a class of functions $\Phi(\mathbf{x})$ that satisfies the relation F

Find $\Phi(\mathbf{x})$

subject to $\mathcal{C}_m(a(\mathbf{x}), \Phi(\mathbf{x}), \nabla_{\mathbf{x}}\Phi(\mathbf{x}), \dots) = 0, \quad \forall \mathbf{x} \in \Omega_m, \quad m = 1, \dots, M$

SIREN: Model Architecture

- Periodic Activations for INRs
 - MLPs with Sine activations

$$\Phi(\mathbf{x}) = \mathbf{W}_n(\phi_{n-1} \circ \phi_{n-2} \circ \cdots \circ \phi_0)(\mathbf{x}) + \mathbf{b}_n$$

$$\mathbf{x}_i \mapsto \phi_i(\mathbf{x}_i) = \sin(\mathbf{W}_i \mathbf{x}_i + \mathbf{b}_i)$$

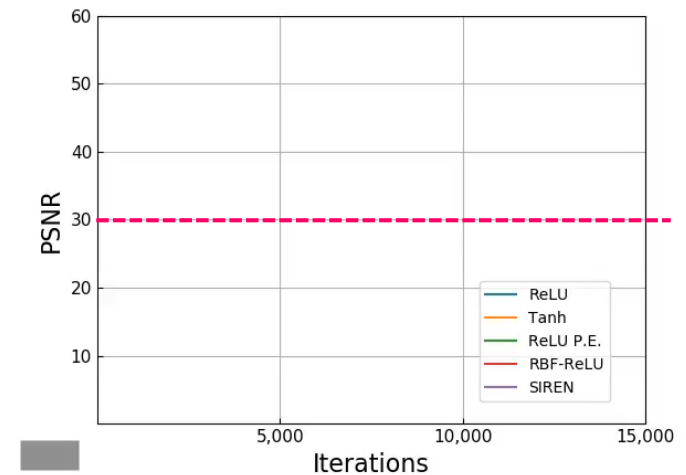
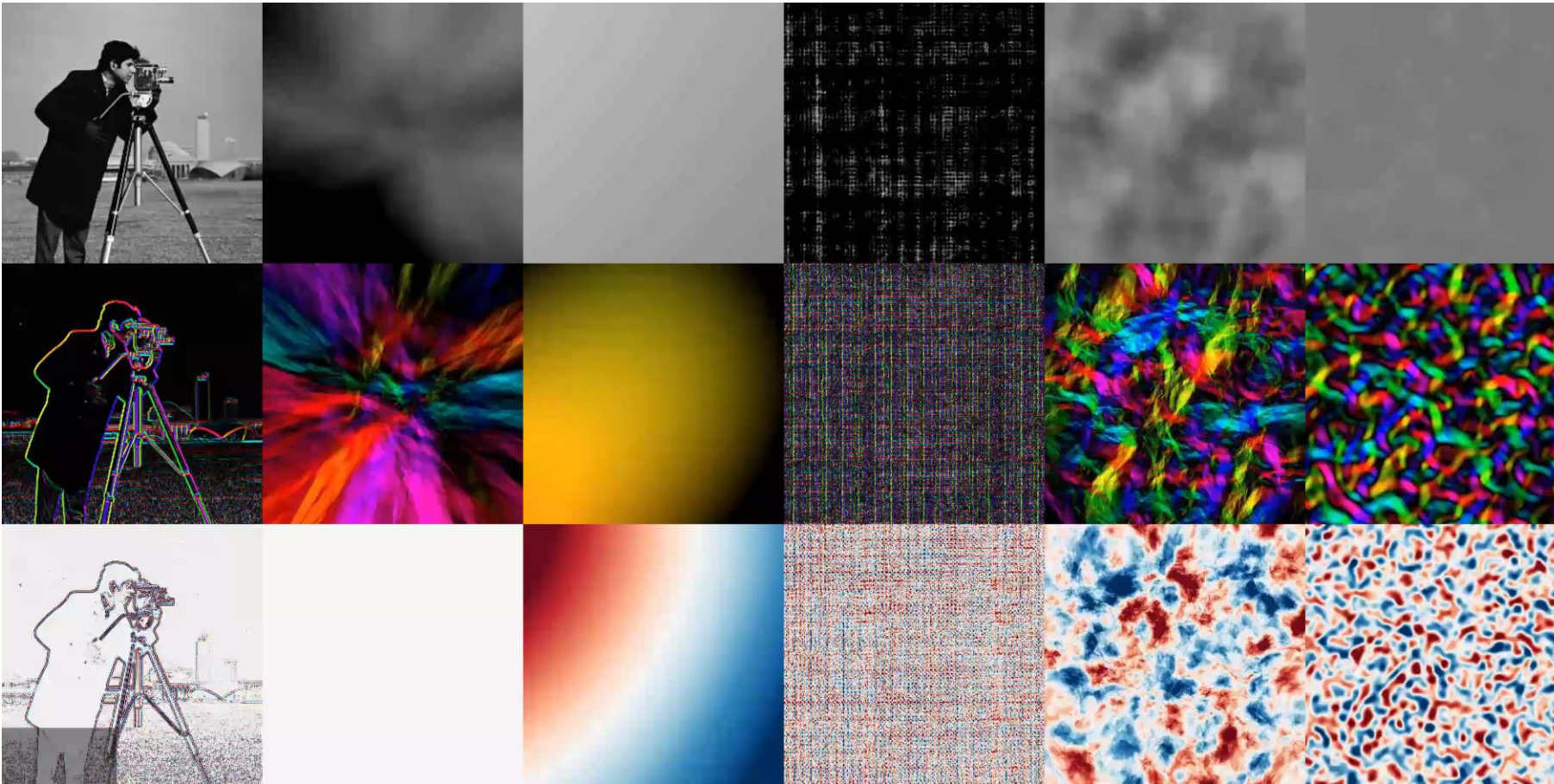
- $\phi_i : \mathbb{R}^{M_i} \mapsto \mathbb{R}^{N_i}$ is the i -th layer of the networks
- $\mathbf{W}_i : \mathbb{R}^{M_i \times N_i}$ is the i -th weight matrix
- $\mathbf{b}_i : \mathbb{R}^{N_i}$ is the i -th bias vector
- $\mathbf{x}_i : \mathbb{R}^{M_i}$ is the i -th input vector

SIREN: Initialization Scheme

- Key idea of Initialization in SIREN
 - It is to **preserve the distribution of activations** through the network so that the final output at initialization does not depend on the number of layers
 - Without carefully chose uniformly distributed weights, SIREN doesn't perform well
- Assuming that $\mathbf{x} \sim \mathcal{U}(-1, 1)$
- For the 1st layer: Initialize the weights \mathbf{W} of the 1st layer such that $\sin(\omega_0 \cdot \mathbf{W}\mathbf{x} + \mathbf{b})$ spans multiple periods over $[-1, 1]$
- For other layers: Initialize the weights \mathbf{W} according to $\mathcal{U}\left(-\sqrt{6/n}, \sqrt{6/n}\right)$

Experiments: Image Representation

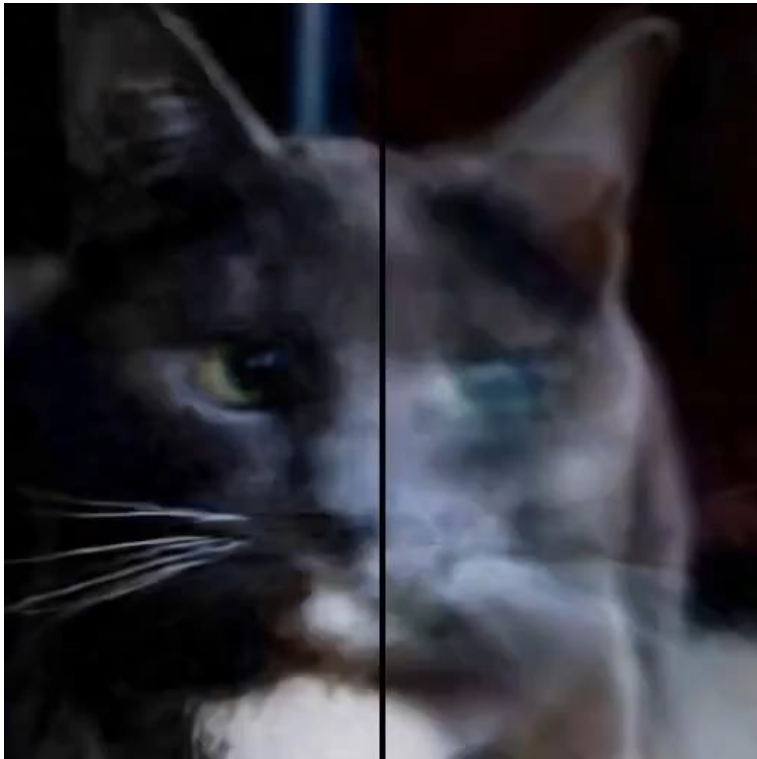
- Mapping 2D Pixel Coordinates to a Color



Experiments: Video Representation

- SIREN with pixel coordinates together with a time coordinate to parameterize a video

$$\mathcal{L} = \sum_i \|\Phi(\mathbf{x}_i) - f(\mathbf{x}_i)\|^2$$

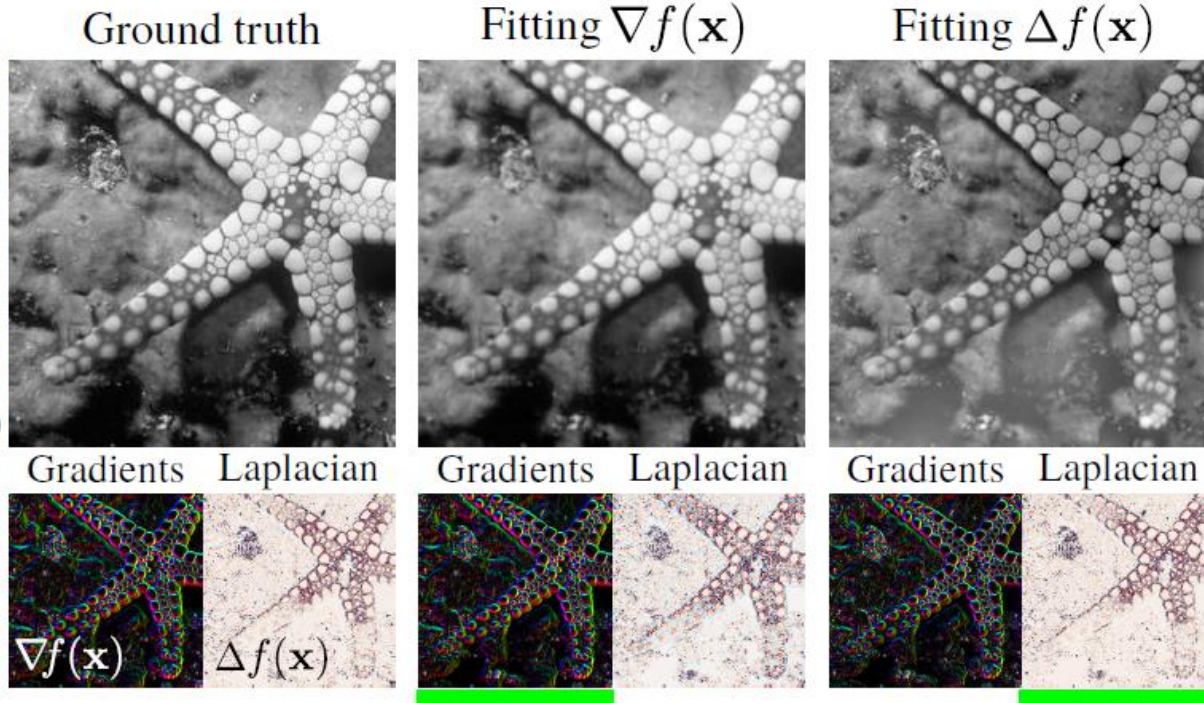


Experiments: Poisson Image Reconstruction

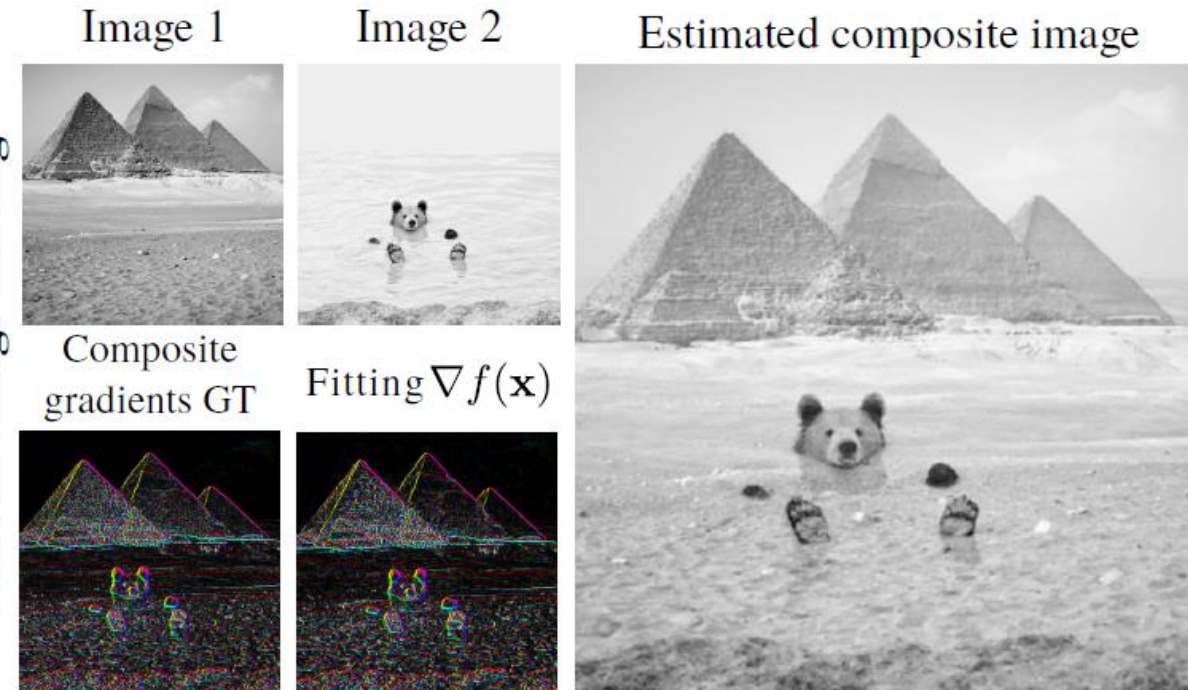
- SIREN for solving Poisson equation to reconstruct images from their derivatives

$$\mathcal{L}_{\text{grad}} = \int_{\Omega} \|\nabla_{\mathbf{x}} \Phi(\mathbf{x}) - \nabla_{\mathbf{x}} f(\mathbf{x})\| d\mathbf{x}$$

Poisson Image Reconstruction



Poisson Image Editing



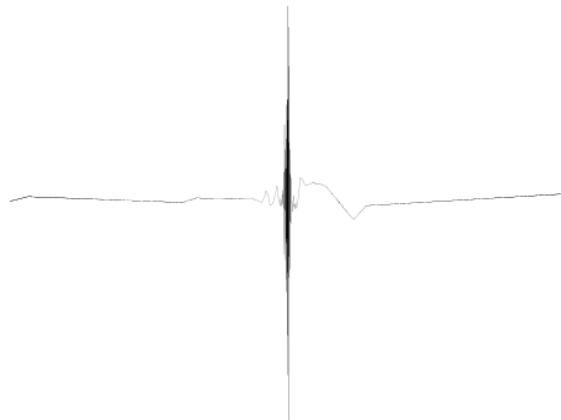
Experiments: Audio Representation

- SIREN with a single, time-coordinate input and scalar output may parameterize audio signals
 - It succeeds in reproducing the audio signal for music

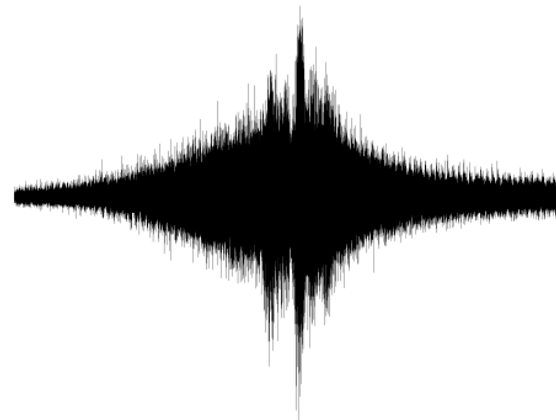
$$\mathcal{L} = \int_{\Omega} \|\Phi(\mathbf{x}) - f(t)\| dt$$



Ground-Truth



MLP + ReLU



MLP + ReLU
w/ Positional Encoding



SIREN

Experiments: 3D Scene Representation

- SIREN for fitting differentiable signed distance functions (SDFs) to represent 3D scene

When \mathbf{x} is on the surface,
SDF to be 1

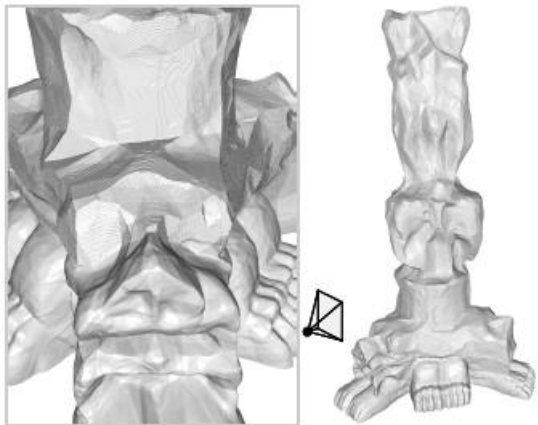
When \mathbf{x} is not on the surface,
penalize it

$$\mathcal{L}_{\text{sdf}} = \int_{\Omega} |||\nabla_{\mathbf{x}}\Phi(\mathbf{x})| - 1||d\mathbf{x} + \int_{\Omega_0} ||\Phi(\mathbf{x})|| + (1 - \langle \nabla_{\mathbf{x}}\Phi(\mathbf{x}), \mathbf{n}(\mathbf{x}) \rangle)d\mathbf{x} + \int_{\Omega \setminus \Omega_0} \psi(\Phi(\mathbf{x}))d\mathbf{x}$$

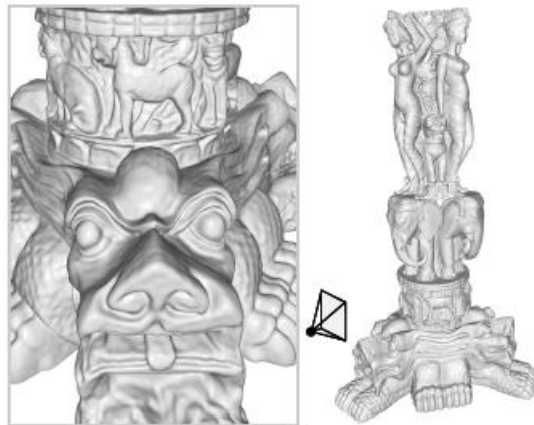
Gradient of SDF to be 1

Gradient of SDF to be
the normal vector of the surface

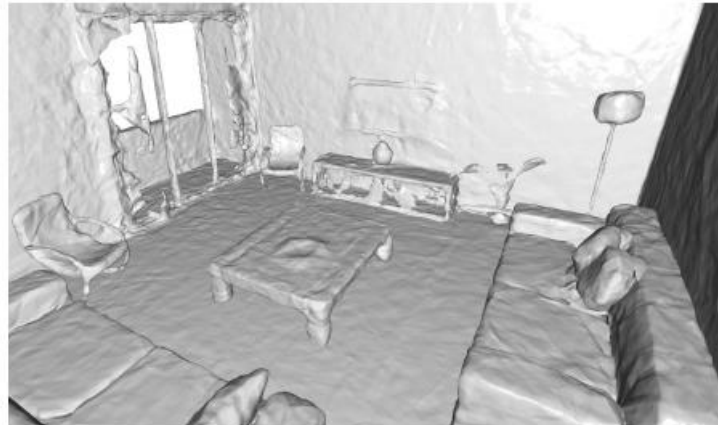
ReLU (baseline)



SIREN (ours)



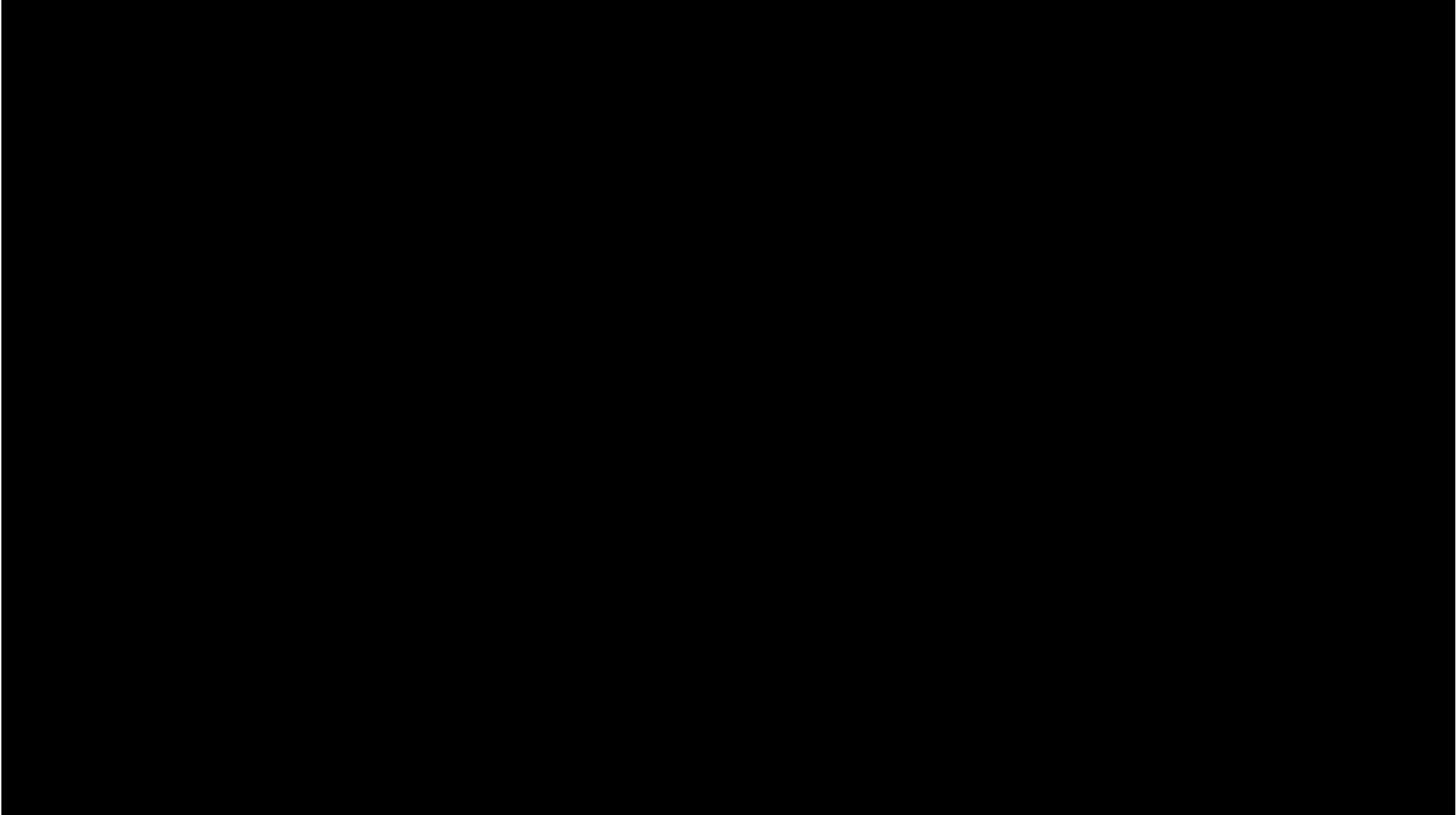
ReLU (baseline)



SIREN (ours)



Experiments: 3D Scene Representation



Practice: INRs

- Practice
 - Implicit Neural Representations with Periodic Activation Functions
 - <https://github.com/vsitzmann/siren>