Question 3

February 10, 2020

1 COL744: Machine Learning (Assignment 1)

1.1 Question 3

1.1.1 Part (a): Implementing logistic regression using newton's method

In this part I have implemented logistic regression using newton't update method to find optimal theta.

```
[1]: import numpy as np
import numpy as np
import matplotlib as mp
import matplotlib.pyplot as plt

from tqdm import tqdm
import math
```

```
[3]: def g(x):
    '''Logistic function'''
    return 1/(1+((math.e)**(-1*x)))

def newton(X,Y):
    '''
    Newton's update method to find theta

---Parameters
    * X,Y - Training examples
```

```
---Returns
theta
111
theta_lst=[]
theta = np.zeros(X.shape[1])
for i in range(100):
    g_thetaX = g(X.dot(theta))
    grad = (X.T).dot(Y)-(X.T).dot(g thetaX)
    diag = np.diagflat((g_thetaX.T)*(np.ones(g_thetaX.shape)-g_thetaX))
    H = -(((X.T).dot(diag))).dot(X)
    theta_next = theta - (np.linalg.inv(H)).dot(grad)
    theta lst.append(theta)
    theta=theta_next
    if(i>2 and np.sum(np.abs(theta_lst[-1]-theta_lst[-2]))<1e-10):</pre>
        print('converged in %d iterations'%(i))
        break
return theta_lst[-1]
```

```
[4]: theta=newton(X,Y)
print(theta)
```

```
converged in 9 iterations
[ 0.40125316  2.5885477  -2.72558849]
```

1.1.2 Part (b): Ploting decision surface

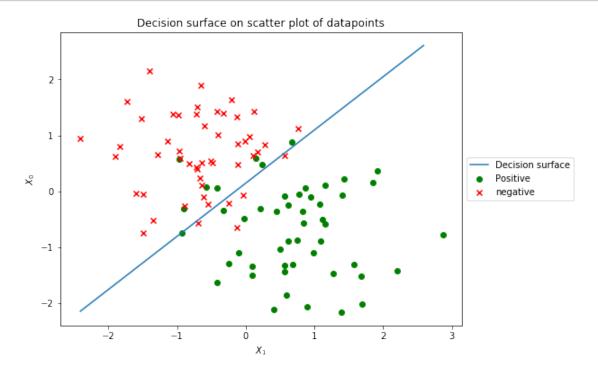
```
[5]: plt.figure(figsize=(8,6))

##### Plotting datapoints
pos_X = X[np.where(Y==1)] #Getting datapoints with positive label
neg_X = X[np.where(Y==0)] #Getting datapoints with negative label
plt.scatter(pos_X[:,1], pos_X[:,2], marker='o', c='green', label='Positive')
plt.scatter(neg_X[:,1], neg_X[:,2], marker='x', c='red', label='negative')

##### Plotting decision surface
X_line = np.arange(X[:,1].min(), X[:,1].max())
Y_line = -1*(1/theta[2])*((theta[1]*X_line)+theta[0])
plt.plot(X_line, Y_line, label='Decision surface')

plt.legend(loc='center left', bbox_to_anchor=(1, 0.5))
plt.xlabel('$X_1$')
plt.ylabel('$X_0$')
plt.title('Decision surface on scatter plot of datapoints')
```





1.1.3 Observations:

• Here we can see that decision boundary found by our algorithm nicely separates positive and negative points.