

1. Prior-Aligned Meta-RL: Thompson Sampling with Learned Priors and Guarantees in Finite-Horizon MDPs

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Abstract: We study meta-reinforcement learning in finite-horizon MDPs where related tasks share similar structures in their optimal action-value functions. Specifically, we posit a linear representation $Q^{\#h}(s, a) = \Phi^h(s, a) \theta^h(k)$ and place a Gaussian meta-prior $N(\theta^{\#h}, \Sigma^{\#h})$ over the task-specific parameters $\theta^h(k)$. Building on randomized value functions, we propose two Thompson-style algorithms: (i) MTSRL, which learns only the prior mean and performs posterior sampling with the learned mean and known covariance; and (ii) MTSRL+, which additionally estimates the covariance and employs prior widening to control finite-sample estimation error. Further, we develop a prior-alignment technique that couples the posterior under the learned prior with a meta-oracle that knows the true prior, yielding meta-regret guarantees: we match prior-independent Thompson sampling in the small-task regime and strictly improve with more tasks once the prior is learned. Concretely, for known covariance we obtain $\tilde{O}(H_4 S_3/2 \sqrt{ANK})$ meta-regret, and with learned covariance $\tilde{O}(H_4 S_3/2 \sqrt{AN_3 K})$; both recover a better behavior than prior-independent after $K \tilde{O}(H_2)$ and $K \tilde{O}(N_2 H_2)$, respectively. Simulations on a stateful recommendation environment (with feature and prior misspecification) show that after brief exploration, MTSRL/MTSRL+ track the meta-oracle and substantially outperform prior-independent RL and bandit-only meta-baselines. Our results give the first meta-regret guarantees for Thompson-style RL with learned Q-priors, and provide practical recipes (warm-start via RLSVI, OLS aggregation, covariance widening) for experiment-rich settings. © 2025, CC BY.

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