EMPLOYMENT HISTORY

JUNE 2017 to

Research Assistant at Technische Universität Wien, Vienna, Austria

January 2019

PhD candidate and teaching assistant in the Vision for Robotics group, working on semantic segmentation and mapping for long-term autonomous robot operation.

OCTOBER 2016 to

STRANDS Project Research Associate at University of Birmingham, Birmingham, UK

Assisted project partners with system integration. Facilitated robot deployment on-site and developed software tools for monitoring and running the system. Aggregated and improved project documentation.

March to **July 2016**

May 2017

Marie Skłodowska-Curie Early Stage Researcher at Fraunhofer IPA, Germany

PhD candidate in environment modelling and motion prediction in dynamic environments as part of the Horizon 2020 SECURE project.

July 2015 to January 2016 Innovation Team Intern at YUJIN ROBOT Co., LTD, Seoul, Republic of Korea

Python and C++ development in ROS for the GoCart logistics robot. Worked on behaviour trees and behaviour design, diagnostics, simulation layer implementation and module interfacing. Made contributions to several ROS

packages.

EDUCATION AND QUALIFICATIONS

August 2013 to

MSc Systems, Control and Robotics, Robotics and Autonomous Systems track

JUNE 2015

KTH ROYAL INSTITUTE OF TECHNOLOGY, Stockholm, Sweden

SEPTEMBER 2009 to

BSc Computer Science with Study Abroad, First Class Honours

IUNE 2013

Top of graduating class (final year: 92%, weighted average: 89%)

University of Birmingham, Birmingham, UK

September 2011 to

Japanese Language Programme, Advanced Level

JULY 2012

Japanese Language Proficiency Test level N1 (90%)

Keio University, Tokyo, Japan

ACADEMIC AND RESEARCH ACTIVITY

JANUARY to

Master's Thesis: Feature-Feature Matching for Object Retrieval in Point Clouds

June 2015

Developed a system using PCL and ROS to extract features from point clouds, and find query objects in the resulting feature set. Performed an experimental evaluation to find good descriptors and interest point methods. Supervised

by John Folkesson.

July to

Participant in Tohoku University Engineering Summer Programme (TESP)

August 2014

Attended lectures on several different areas related to robotics, and worked on a short project on obstacle avoidance for a tracked mobile robot. Participants were robotics students from across the world.

September 2012 to

Bachelor's Thesis: Time Delay Estimation in Gravitationally Lensed Photon Streams

APRIL 2013

Developed a system to estimate characteristic functions of streams with weighted least squares techniques and compare them with probabilistic techniques to estimate the time delay. Supervised by Peter Tiňo.

January to

Participant at Student Autonomous Underwater Competition - Europe (SAUC-E)

July 2011

Collaboration between the University of Birmingham and University of Southampton to prepare the Delphin AUV for the competition in July. Converted the control system from Matlab to ROS Python.

OCTOBER 2010 to

Founding member of Birmingham Autonomous Robotics Club

JULY 2013

Co-founded the club due to interest from computer science faculty and undergraduate students in solving robotics problems and increasing the profile of the field in the school.

TEACHING

June 2017 to January 2019	Teaching Assistant at Vision for Robotics Group, Technische Universität Wien Administering the <i>Machine Vision and Cognitive Robotics</i> and <i>Robotics and Computer Vision</i> courses. Updating and maintaining assignment content, managing tutors, grading assignments, and providing assistance to students.
January 2017 to	Robot Programming Demonstrator at University of Birmingham
April 2017	Discussed theoretical and software problems with students to help them complete assignments and understand the AI concepts being taught. Graded student assignments.
January 2013 to	Robot Programming Demonstrator at University of Birmingham
April 2013	Provided assistance to students with the implementation of various algorithms and the application of artificial intelligence techniques for use on LEGO NXT robots.
September 2012 to	Foundation Year Computer Science Demonstrator at University of Birmingham
December 2012	Helped foundation year students understand basic programming concepts, and evaluated their performance in assignments.
September 2010 to	Software Workshop (Java) Demonstrator at University of Birmingham
April 2011	One of five second year students selected to demonstrate for the First Year Workshop Java module. Provided advice on assignments, programming concepts, and the Java API.

Bursaries, Scholarships and Awards

JULY 2013	Computer Science Prize & Research Committee Project Prize Awarded by the University of Birmingham School of Computer Science to the highest scoring final year student, and for the best research-related final dissertation.
	Japan Student Services Organisation Scholarship Short-term scholarship to support study in Japan.
July to September 2011	Nuffield Undergraduate Research Bursary Bursary to support a summer research project to investigate particle filter localisation for AUVs.

Programming and Software	Languages
Python, C++, ROS, git, Linux, ŁTŁX	English (native), Japanese (fluent), Polish (bilingual)

Public repositories at github.com/heuristicus

Referees

Addresses and positions for referees are current. Bold text indicates where the person supervised me.

University of Birmingham	Technische Universität Wien	Yujin Robot
Nick Hawes	Markus Vincze	Daniel Stonier
Associate Professor of Robotics	Associate Professor	${\bf Program\ Manager-Simulation}$
nickh@robots.ox.ac.uk	vincze@acin.tuwien.ac.at	d.stonier@gmail.com
0.6.101.4.7.44.4	10 11	m n. l.r
Oxford Robotics Institute	Automation and Control Institute	Totota Research Institute
Oxford Robotics Institute 23 Banbury Road, Felstead House	Automation and Control Institute Technische Universität Wien	One Kendall Square
23 Banbury Road, Felstead House	Technische Universität Wien	One Kendall Square