Michal Staniaszek

Born 7 December 1990 British national www.michalstaniaszek.com m.staniaszek@gmail.com

Work Experience

| Остовек 2016 to Мау 2017 | STRANDS Project Research Associate at University of Birmingham, Birmingham, UK Assisted project partners with system integration, improving software tools and monitoring to support robot deployment in an office. Transferred knowledge and integrated system at commercial partner facility. | |
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| March 2016 to | Marie Skłodowska-Curie Early Stage Researcher at Fraunhofer IPA, Stuttgart, Germany | |
| July 2016 | PhD candidate in environment modelling and motion prediction in dynamic environments as part of the Horizon 2020 SECURE project. Left the post due to supervision issues. | |
| July 2015 to | Innovation Team Intern at YUJIN ROBOT CO., LTD, Seoul, Republic of Korea | |
| January 2016 | Python and C++ development in ROS for the GoCart logistics robot. Worked on behaviour trees and behaviour design, diagnostics, simulation layer implementation and module interfacing. Made contributions to several ROS packages. | |
| July 2013 | Systems and Software Assistant at KAON LTD, Guildford, UK | |
| | Developed a GUI prototype for a portable device in Java, to demonstrate functionality to the customer. Set up and tested filesystems on linux for optimal operation on a large RAID device. | |

Education and Qualifications

| August 2013 to June 2015 | MSc Systems, Control and Robotics, Robotics and Autonomous Systems track KTH Royal Institute of Technology, Stockholm, Sweden |
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| September 2009 to June 2013 | BSc Computer Science with Study Abroad, First Class Honours Top of graduating class (final year: 92%, weighted average: 89%) University of Birmingham, Birmingham, UK |
| SEPTEMBER 2011 to July 2012 | Japanese Language Programme, Advanced Level Japanese Language Proficiency Test level N1 (90%) KEIO UNIVERSITY, Tokyo, Japan |

ACADEMIC AND RESEARCH ACTIVITY

| January to June 2015 | Master's Thesis — Feature-Feature Matching for Object Retrieval in Point Clouds Developed a system using PCL and ROS to extract features from point clouds, and find query objects in the resulting feature set. Performed an experimental evaluation to find good descriptors and interest point methods. Supervised by John Folkesson. | |
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| July to August 2014 | Participant in Tohoku University Engineering Summer Programme (TESP) Attended lectures on several different areas related to robotics, and worked on a short project on obstacle avoidance for a tracked mobile robot. Participants were robotics students from across the world. | |
| SEPTEMBER 2012 to April 2013 | Bachelor's Thesis — Time Delay Estimation in Gravitationally Lensed Photon Streams Developed a system to estimate characteristic functions of streams with weighted least squares techniques and compare them with probabilistic techniques to estimate the time delay. Supervised by Peter Tiňo. | |
| January to July 2011 | | |
| October 2010 to July 2013 | Founding member of Birmingham Autonomous Robotics Club Co-founded the club due to interest from computer science faculty and undergraduate students in solving robotics problems and increasing the profile of the field in the school. | |

TEACHING

| January 2013 to April 2013 | Robot Programming Demonstrator at University of Birmingham Answered questions from students about the implementation of various algorithms and the application of artificial intelligence techniques for use on LEGO NXT robots. | |
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| September 2012 to December 2012 | Foundation Year Computer Science Demonstrator at University of Birmingham Helped foundation year students understand basic programming concepts, and evaluated their performance in assignments. | |
| September 2010 to April 2011 | Software Workshop (Java) Demonstrator at UNIVERSITY OF BIRMINGHAM One of five second year students selected to demonstrate for the First Year Workshop Java module. Provided advice on assignments, programming concepts, and the Java API. | |

Bursaries, Scholarships and Awards

| July 2013 | Computer Science Prize Awarded to the highest scoring final year student in the University of Birmingham School of Computer Science | |
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| July 2013 | Research Committee Project Prize Awarded for the best research related dissertation by the University of Birmingham School of Computer Science | |
| January to | Japan Student Services Organisation Scholarship | |
| April 2012 | Short-term scholarship to support study in Japan. | |
| July to | Nuffield Undergraduate Research Bursary | |

Programming and Software

Languages

Basic: Java, C, Matlab, OpenCV, PCL, CMake, English: Native

Emacs, ETEX Japanese: Fluent
Linux, ROS, bash Polish: Fluent
C++, Python, Git German: Basic

Public repositories at github.com/heuristicus

INTERESTS

Intermediate:

Advanced:

Cycling, Japanese language and culture, languages, music, photography, reading

Referees

| Nick Hawes | John Folkesson | Daniel Stonier |
|---|-------------------------------|---------------------------------|
| Reader in Autonomous Intelligent Robotics | Assistant Professor | Chief Algorithms Architect |
| n.a.hawes@cs.bham.ac.uk | johnf@kth.se | stonier@yujinrobot.com |
| School of Computer Science | Centre for Autonomous Systems | Yujin Robot Co., Ltd |
| University of Birmingham | Kungliga Tekniska Högskolan | 601 Namsung Plaza, 130 |
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