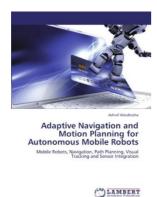
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# ADAPTIVE NAVIGATION AND MOTION PLANNING FOR AUTONOMOUS MOBILE ROBOTS



LAP Lambert Acad. Publ. Okt 2011, 2011. Taschenbuch. Book Condition: Neu. 220x150x16 mm. Neuware - Exploring autonomy in robotics is a meaningful task. The intuitive definition of autonomy is the capability of a robot to make a decision based on its own knowledge, acquired by its distributed sensors, without any human interference. Throughout this framework we discuss some algorithms and techniques underlying the subjects of adaptive navigation, motion planning and sensor integration for autonomous mobile robots. Mobile Robots will play...

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- · Authored by Ashraf Aboshosha
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