# MATH 327 Assignment 2

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### Question 1

The given matrices are in fact Hermitian. We will use Sylvester's criterion to verify positive definiteness.

**a**)

$$A := \begin{pmatrix} 4 & 2 & 6 \\ 2 & 2 & 5 \\ 6 & 5 & 29 \end{pmatrix} \qquad \begin{aligned} \det(A_{11}) &= 4 > 0 \\ \det(A_{22}) &= 4 > 0 \\ \det(A_{33}) &= 64 > 0 \end{aligned}$$

A as defined is positive definite. Then we can apply the algorithm given

$$A = \begin{pmatrix} r_{11} & 0 & 0 \\ r_{12} & r_{22} & 0 \\ r_{13} & r_{23} & r_{33} \end{pmatrix} \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{pmatrix} \longrightarrow \begin{cases} 4 = r_{11}^2 & \Longrightarrow r_{11} = 2 \\ 2 = r_{11}r_{12} & \Longrightarrow r_{12} = 1 \\ 6 = r_{12}r_{13} & \Longrightarrow r_{13} = 3 \\ 2 = r_{12}^2 + r_{22}^2 & \Longrightarrow r_{22} = 1 \\ 5 = r_{12}r_{13} + r_{22}r_{23} & \Longrightarrow r_{23} = 2 \\ 29 = r_{13}^2 + r_{23}^2 + r_{33}^2 \Longrightarrow r_{33} = 4 \end{cases}$$

$$\therefore R = \begin{pmatrix} 2 & 1 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{pmatrix},$$

R is upper triangular the algorithm is successful.

b)

$$A := \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 1 \end{pmatrix} \qquad \frac{\det(A_{11}) = 1 > 0}{\det(A_{22}) = 1 > 0}$$
$$\det(A_{33}) = -1 < 0$$

A as defined is not positive definite. We expect the algorithm to fail.

$$A = \begin{pmatrix} r_{11} & 0 & 0 \\ r_{12} & r_{22} & 0 \\ r_{13} & r_{23} & r_{33} \end{pmatrix} \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{pmatrix} \longrightarrow \begin{cases} 1 = r_{11}^{2} & \Longrightarrow r_{11} = 1 \\ 1 = r_{11}r_{12} & \Longrightarrow r_{12} = 1 \\ 1 = r_{12}r_{13} & \Longrightarrow r_{13} = 1 \\ 2 = r_{12}^{2} + r_{22}^{2} & \Longrightarrow r_{22} = 1 \\ 2 = r_{12}r_{13} + r_{22}r_{23} & \Longrightarrow r_{23} = 1 \\ 1 = r_{13}^{2} + r_{23}^{2} + r_{33}^{2} \Longrightarrow r_{33} = \sqrt{-1} \\ \not > 0 \end{cases}$$

the algorithm fails, a contradiction arises in the last step.

### Question 2

 $\mathbf{a})$ 

We show that  $A^{-1} = I + \alpha u v^T$  is the inverse of A if their product is the identity. That is,

$$AA^{-1} = I \implies (I + uv^{T})(I + \alpha uv^{T}) = I$$
$$\implies I^{2} + \alpha uv^{T} + uv^{T} + uv^{T} \alpha uv^{T} = I$$
$$\implies \alpha uv^{T} + uv^{T} + uv^{T} \alpha uv^{T} = 0$$

We use the fact that by matrix associativity,  $uv^T\alpha uv^T = \alpha(uv^Tuv^T) = \alpha u(v^Tu)v^T$ . Then following from matrix commutative proerty, since  $v^Tu$  is a scalar, this reduces to  $\alpha(v^Tu)uv^T$ . So we write,

$$\implies (\alpha + 1 + \alpha v^T u) u v^T = 0$$

If  $uv^T = O$  then A = I which doesn't hold. So it must be that  $(\alpha + 1 + \alpha v^T u) = 0$  such that

$$\alpha(1 + v^T u) + 1 = 0 \implies -\frac{1}{1 + v^T u} = \alpha,$$

which  $\exists$  for  $v^T u \neq -1$ .

b)

If A is singular det(A) = 0. So let us verify,

$$\det(A) = \det(I + uv^T)$$

we use the property  $\det(A + B) = \det(A) + \det(B) + \det(A) \operatorname{tr}(A^{-1}B)$ , giving

$$= \det(I) + \det(uv^T) + \det(I)\operatorname{tr}(I^{-1}uv^T)$$
  
= 1 + \det(uv^T) + \text{tr}(uv^T)

The inner product is the trace of the outer product [source : Optimal Control and Estimation , p.26].

$$= 1 + \det(uv^T) + v^T u$$

For  $\det(uv^T)$ , every row of b is scalar multiple of a, such that the determinant of  $uv^T$  is automatically 0. Finally,

$$= 1 + v^T u = 0 \implies v^T u = -1,$$

A is singular whenever  $v^T u = -1$ . We now look for the Null space. That is Ay = 0 for  $y \neq 0$ .

$$Ay = (I + uv^T)y = y + uv^Ty = 0 \implies -y = uv^Ty$$

Since A is singular for  $v^T u = -1$ , let y = ku for  $k \in \mathbb{R}$ , then

$$-ku = uv^T ku$$
$$-ku = kuv^T u$$
$$-ku = -ku$$

So the choice y = ku is correct. k is arbitrary so we conclude that Null(A) = Span(A).

## Question 3

 $\mathbf{a})$ 

The system Ax = b that determines the LSP is

$$\begin{pmatrix} f_1(y_1) & f_2(y_1) \\ f_1(y_2) & f_2(y_2) \\ \vdots & \vdots \\ f_1(y_5) & f_2(y_5) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_5 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & y_1 \\ 1 & y_2 \\ \vdots & \vdots \\ 1 & y_5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_5 \end{pmatrix}$$

b)

The system Ax = b that determines the LSP is

$$\begin{pmatrix} f_{1}(y_{1}) & f_{2}(y_{1}) & f_{3}(y_{1}) \\ f_{1}(y_{2}) & f_{2}(y_{2}) & f_{3}(y_{2}) \\ \vdots & \vdots & \vdots \\ f_{1}(y_{5}) & f_{2}(y_{5}) & f_{3}(y_{5}) \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} = \begin{pmatrix} z_{1} \\ z_{2} \\ \vdots \\ z_{5} \end{pmatrix} \longrightarrow \underbrace{\begin{pmatrix} 1 & y_{1} & y_{1}^{2} \\ 1 & y_{2} & y_{2}^{2} \\ \vdots & \vdots & \vdots \\ 1 & y_{5} & y_{5}^{2} \end{pmatrix}}_{A} \begin{pmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{3} \end{pmatrix} = \underbrace{\begin{pmatrix} z_{1} \\ z_{2} \\ \vdots \\ z_{5} \end{pmatrix}}_{h}$$

### Question 4

**a**)

Let us consider the following system, and deduce the algorithmic formula

$$\begin{pmatrix} r_{11} & 0 & \dots & 0 \\ r_{21} & r_{22} & \dots & 0 \\ \vdots & \dots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}.$$

Given the system above, the corresponding equations are

$$x_{1} = \frac{b_{1}}{r_{11}}$$

$$x_{2} = \frac{(b_{2} - r_{21}x_{1})}{r_{22}}$$

$$x_{3} = \frac{(b_{3} - r_{31}x_{1} - r_{32}x_{2})}{r_{33}} \implies x_{i} = \frac{1}{r_{ii}} \left(b_{i} - \sum_{j=1}^{i-1} r_{ij}x_{j}\right), \text{for } i = 1, \dots, n$$

$$\vdots$$

$$x_{n} = \frac{(b_{n} - r_{n1}x_{1} - r_{n2}x_{2} - \dots - r_{n,n-1}x_{n-1})}{r_{nn}}$$

To calculate the total number of steps, we consider the algorithm for the upper triangular case. Given the range i = n, n - 1, ..., 2, 1, we have for each value an fixed number of operations;

$$i = n$$
:  $\frac{1}{r_{nn}}(b_n)$  ; 1 operation  $i = n - 1$ :  $\frac{1}{r_{n-1,n-1}}(b_{n-1} - r_{11}x_1)$  ; 3 operations

$$i=n-2$$
: 
$$\frac{1}{r_{n-2,n-2}}(b_{n-2}-(r_{11}x_1+r_{22}x_2)) ; 5 \text{ operations}$$

$$\vdots$$

$$i=n-(n-1)=1: \frac{1}{r_{11}}(b_1-(r_{11}x_1+\cdots+r_{n-1,n-1}x_{n-1})) ; 2n-1 \text{ operations}$$

Thus,

$$1+3+5+\cdots+(2n-1)=n^2$$
,

is the number of operations.

b)

The algorithm was stated in class;

$$r_{ii} = \sqrt{a_{ii} - \sum_{j=1}^{i-1} r_{ji}^2}$$
 for  $i = 1, ..., n$  where  $r_{ij} = \frac{1}{r_{ii}} \left( a_{ij} - \sum_{k=1}^{i-1} r_{ki} r_{kj} \right)$  for  $j = i + 1, ..., n$ .

We look for the number of operations.

(Outer k loop:)

$$\sum_{i=1}^{n} \sum_{k=1}^{i-1} 2 = 2 \sum_{i=1}^{n} (i-1) = n(n-1) = n^2 - n.$$

(Inner k loop)

$$\sum_{i=1}^{n} \sum_{j=i+1}^{n} \sum_{k=1}^{i-1} 2 = 2 \sum_{i=1}^{n} \sum_{j=i+1}^{n} (i-1)$$

$$= 2 \sum_{i=1}^{n} (n-i)(i-1)$$

$$= 2n \sum_{i=1}^{n} (i-1) - 2 \sum_{i=1}^{n} i^2 + 2 \sum_{i=1}^{n} i$$

$$= n^2(n-1) - \frac{n(n+1)(2n+1)}{3} + n(n+1) = \frac{n^3 - 3n^2 + 2n}{3}.$$

(Divisions:)

$$\sum_{i=1}^{n} \sum_{j=i+1}^{n} 1 = \sum_{i=1}^{n} (n-i) = \frac{n(n-1)}{2}.$$

(Square root:)

$$\sum_{i=1}^{n} 1 = n.$$

Thus, the total amounts to

$$n^{2} - n + \frac{n^{3} - 3n^{2} + 2n}{3} + \frac{n^{2} - n}{2} + n = \frac{n}{6}(2n^{2} + 3n + 1).$$

**c**)

By Property, given that A is non-singular then  $A^TA$  is positive definite. Then, following the Cholesky decomposition theorem, there exists a unique decomposition  $A^TA = R^TR$  where R is upper triangular. We use the Cholesky decomposition algorithm to find R and thereby  $R^T$ . Then we solve  $R^Ty = A^Tb$  with backwards substitution. And then, we finally solve Rx = y for x, through forward substitution. The operations required for each steep are

1. 
$$\frac{n}{6}(2n^2 + 3n + 1)$$
  
2.  $n^2$   
3.  $n^2$   $\longrightarrow$  most expensive : 1.  $\frac{n}{6}(2n^2 + 3n + 1)$ ,

ordered respectively.

d)

As before, we consider

$$\begin{pmatrix} 16 & 4 & 8 & 4 \\ 4 & 10 & 8 & 4 \\ 8 & 8 & 12 & 10 \\ 4 & 4 & 10 & 12 \end{pmatrix} = \begin{pmatrix} r_{11} & 0 & 0 & 0 \\ r_{12} & r_{22} & 0 & 0 \\ r_{13} & r_{23} & r_{33} & 0 \\ r_{14} & r_{24} & r_{34} & r_{44} \end{pmatrix} \begin{pmatrix} r_{11} & r_{12} & r_{13} & r_{14} \\ 0 & r_{22} & r_{23} & r_{24} \\ 0 & 0 & r_{33} & r_{34} \\ 0 & 0 & 0 & r_{44} \end{pmatrix},$$

which gives the equations

$$\begin{array}{lll}
16 = r_{11}^{2} & \Longrightarrow & r_{11} = 4 & , 8 = r_{12}r_{13} + r_{22}r_{23} & \Longrightarrow & r_{23} = 2 \\
4 = r_{11}r_{12} & \Longrightarrow & r_{12} = 1 & , 4 = r_{12}r_{14} + r_{22}r_{24} & \Longrightarrow & r_{24} = 1 \\
8 = r_{11}r_{13} & \Longrightarrow & r_{13} = 2 & , 12 = r_{13}^{2} + r_{23}^{2} + r_{33}^{2} & \Longrightarrow & r_{33} = 2, \\
4 = r_{11}r_{14} & \Longrightarrow & r_{14} = 1 & , 10 = r_{13}r_{14} + r_{23}r_{24} + r_{33}r_{34} & \Longrightarrow & r_{34} = 3 \\
10 = r_{12}^{2} + r_{22}^{2} & \Longrightarrow & r_{22} = 3 & , 12 = r_{14}^{2} + r_{24}^{2} + r_{34}^{2} + r_{44}^{2} & \Longrightarrow & r_{44} = 1
\end{array}$$

which results in

$$R^T = \begin{pmatrix} 4 & 0 & 0 & 0 \\ 1 & 3 & 0 & 0 \\ 2 & 2 & 2 & 0 \\ 1 & 1 & 3 & 1 \end{pmatrix}.$$

Here we solve  $R^T y = A^T b$  through the method outlined in Question 4.

$$y_{1} = \frac{1}{4}(32) = 8$$

$$y_{2} = \frac{1}{3}(26 - (1)y_{1}) = 6$$

$$y_{3} = \frac{1}{2}(38 - (2)y_{1} - (2)y_{2}) = 17$$

$$y_{4} = \frac{1}{1}(30 - (1)y_{1} - (1)y_{2} - (3)y_{3}) = -35$$

$$y = \begin{pmatrix} 8 \\ 6 \\ 17 \\ -35 \end{pmatrix}$$

Now through forward substitution we solve Rx = y;

$$x_{4} = -\frac{35}{1} = -35$$

$$x_{3} = \frac{1}{2}(17 - 3(x_{4})) = 61$$

$$x_{2} = \frac{1}{3}(6 - 2(x_{3}) - 1(x_{4})) = -27$$

$$x_{1} = \frac{1}{4}(8 - 1(x_{2}) - 2(x_{3}) - 1(x_{4})) = -13$$

$$x = \begin{pmatrix} -35 \\ 61 \\ -27 \\ -13 \end{pmatrix}$$

### Question 5

**a**)

$$||x_1 + x_2||_2^2 = \sum_{i=1}^m |(x_1 + x_2)_i|^2$$

$$= \sum_{i=1}^m (x_1 + x_2)_i^2$$

$$= \sum_{i=1}^m x_{1,i}^2 + x_{2,i}^2 - 2\sum_{i=1}^m x_{1,i}x_{2,i}$$

$$= \sum_{i=1}^m x_{1,i}^2 + x_{2,i}^2 - 2x_1^T x_2$$

Given that all vectors are orthogonal we have that  $x_i^T x_j = 0$ , so

$$= \sum_{i=1}^{m} x_{1,i}^{2} + x_{2,i}^{2}$$

$$= \sum_{i=1}^{m} |x_{1,i}|^{2} + |x_{2,i}|^{2} = ||x_{1}||_{2}^{2} + ||x_{2}||_{2}^{2}$$

b)

#### n = 1:

This case is trivial since in both equalities the sum over n = 1 vanishes to 1, therefore the

equality is automatically satisfied.

 $(n-1) \Longrightarrow (n)$ : Define  $y := x_1 + \cdots + x_{n-1} \in \mathbb{R}^m$ , which is also orthogonal to  $x_n$  by property of orthogonality. Then,

$$\left\| \sum_{i=1}^{n} x_i \right\|_{2}^{2} = \|x_1 + \dots + x_{n-1} + x_n\|$$
$$= \|y + x_n\|_{2}^{2}$$

The theorem holds for two vector addition as it was shown in part a), thence

$$= \|y\|_{2}^{2} + \|x_{n}\|_{2}^{2}$$

$$= \|x_{1} + \dots + x_{n-1}\|_{2}^{2} + \|x_{n}\|_{2}^{2}$$

Let  $y = x_1 + \cdots + x_{n-2}$ , we repeat the exact same process. After n-1 such processes we are left off with

$$= \|x_1\|_2^2 + \dots + \|x_n\|_2^2$$
$$= \sum_{i=1}^n \|x_i\|_2^2$$

### Question 6

**a**)

Let  $R_1 = (a)_{ij}$  and  $R_2 = (b)_{ij}$  along with  $C = R_1 R_2 = (c)_{ij} = (a)_{ik}(b)_{kj}$ . Then, by definition of upper triangular,  $(a)_{ij} = 0$  for i > j which implies that  $a_{ik} = 0$  for i > k. Similarly,  $(b)_{ij} = 0$  for k > j which then implies  $(b)_{kj} = 0$  for k > j.

So then,  $(c)_{ij} = 0$  if i > k or k > j which in return imply that  $i > k > j \implies i > j$ . So  $(c)_{ij} = R_1 R_2$  is upper triangular as well.

b)

Let the operations associated with the 0s be ignored, then

$$\begin{pmatrix}
1 & 2 & 3 & \dots & n \\
0 & 1 & 2 & \dots & n-1 \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
0 & 0 & 0 & \dots & 1
\end{pmatrix}$$

$$\begin{pmatrix}
0 & 1 & 2 & \dots & n-1 \\
0 & 0 & 1 & \dots & n-2 \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
0 & 0 & 0 & \dots & 0
\end{pmatrix}$$
Multiplications

Additions

So we have the sequence

$$\left(\sum_{k=1}^{n} k + \sum_{k=1}^{n-1} k + \dots + \sum_{k=1}^{1} k\right) + \left(\sum_{k=1}^{n-1} k + \dots + \sum_{k=1}^{1} k\right) = \sum_{j=1}^{n} \sum_{k=1}^{j} k + \sum_{j=1}^{n-1} \sum_{k=1}^{j} k$$

$$= \frac{n(n+1)(n+2)}{6} + \frac{n(n-1)(n+1)}{6}$$

$$= \frac{n(n+1)(2n+1)}{6}$$

**c**)

$$R_{2}x = \begin{pmatrix} \vdots & \vdots & \ddots & \vdots \\ 0 & \vdots & \ddots & \vdots \\ 0 & & \ddots & \end{pmatrix} \begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix} \longrightarrow \begin{cases} n & (n-1) \\ (n-2) & (n-2) \\ (n-2) & (n-3) \\ \vdots & & \vdots \\ 1 & & 0 \end{cases}$$

$$\implies \sum_{i=1}^{n} i + \sum_{i=1}^{n-1} i = \frac{n(n+1)}{2} + \frac{n(n-1)}{2} = n^{2}.$$

d)

Here we consider two possibilities;  $(R_1R_2)x$  or  $R_1(R_2x)$ , both of which hold under matrix associativity but have different operations cost.

$$(R_1R_2)x$$
:  $\frac{n(n+1)(2n+1)}{6} + n^2$ ,  $R_1(R_2x)$ :  $n^2 + n^2$ .

The second option is much more efficient.