

MATH 475 Weekly Work 2

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Question 1

a)

$M(T)$ is a non-decreasing function of T . Indeed let the maximum up until $t = T$ occur at the base of the space time cylinder, then if $u(x, t') < M(t)$ for $t' > T$, then $M(t)$ will not change. But if $u(x, t') > M(t) \implies M(t)$ increases. In other words, the maximum can increase if we extend the further the time domain over T , but it can not decrease if we extend the time domain backwards.

b)

By the Weak max principle,

$$\min_{\partial_P \Omega_T} u \leq u(x, t) \leq \max_{\partial_P \Omega_T} u,$$

therefore, since $\partial_P \Omega_T = \Omega \times \{t = 0\} \cup \partial\Omega \times (0, T]$,

$$\max_{\partial_P \Omega_T} u = \max \left(\max_{\Omega \times \{t=0\}}, \max_{\partial\Omega \times (0, T]} \right)$$

We set the Dirichlet boundary constant $\equiv k$,

$$= \max \left(\max_{\Omega \times \{t=0\}}, k \right) \tag{1}$$

Notice (1) is time-independent as requested.

Question 2

a)

Inserting the $(u - r)$ and $p - u$ in the given PDE we have

$$\begin{aligned} (u - r)_t - k\Delta(u - r) &= f - A = f - \max_{\Omega_{t_0}} |f| \\ (p - u)_t - k\Delta(p - r) &= -f - A = -f - \max_{\Omega_{t_0}} |f| \end{aligned}$$

Since $|f(x, t)| \leq \max_{\Omega_{t_0}} |f|$, it follows that both $(u - r)$ and $(p - u)$ are subsolutions. We may apply the weak max principle.

$$\begin{aligned}
 u - r &\leq \max_{\partial_P \Omega_T} (u - r) \\
 u &\leq \max_{\partial_P \Omega_T} (u - r) + r \\
 &= \max_{\partial_P \Omega_T} (u - At - B) + r \\
 &= \max_{\partial_P \Omega_T} (u - At - \max_{\partial_P \Omega_{t_0}} |u|) + r
 \end{aligned}$$

Since $u - \max_{\partial_P \Omega_{t_0}} |u| \leq 0$ and $A > 0$, $\implies \max_{\partial_P \Omega_T} (u - At - \max_{\partial_P \Omega_{t_0}} |u|) < 0$

$$\therefore u \leq r$$

Similarly for $(p - u)$,

$$\begin{aligned}
 p - u &\leq \max_{\partial_P \Omega_T} (p - u) \\
 &\leq \max_{\partial_P \Omega_T} (p - u) + u \\
 &= \max_{\partial_P \Omega_T} (-At - B - u) \\
 &= \max_{\partial_P \Omega_T} (-At - \max_{\partial_P \Omega_{t_0}} |u|) + u
 \end{aligned}$$

Since $-\max_{\partial_P \Omega_{t_0}} |u| - u \leq 0$ and $A > 0$, $\implies \max_{\partial_P \Omega_T} (-At - \max_{\partial_P \Omega_{t_0}} |u| - u) < 0$

$$\therefore p \leq u$$

It follows that $p \leq u \leq r$ which in return implies that

$$-t_0 \max_{\overline{\Omega_{t_0}}} |f| - \max_{\partial_P \Omega_{t_0}} |u| \leq u(x_0, t_0) \leq t_0 \max_{\overline{\Omega_{t_0}}} |f| + \max_{\partial_P \Omega_{t_0}} |u|.$$

b)

Let $u = v - w$. Then it follows that

$$u_t - k\Delta u = v_t - w_t - k\Delta v + k\Delta w = (v_t - k\Delta v) - (w_t - k\Delta w) = f_1 - f_2.$$

Following the identity proved in 2b, this is equivalent to

$$\begin{aligned}
 u(x_0, t_0) &\leq t_0 \max_{\overline{\Omega_{t_0}}} |f_1 - f_2| + \max_{\partial_P \Omega_{t_0}} |u| \\
 \implies v(x_0, t_0) - w(x_0, t_0) &\leq t_0 \max_{\overline{\Omega_{t_0}}} |f_1 - f_2| + \max_{\partial_P \Omega_{t_0}} |v - w|.
 \end{aligned} \tag{a}$$

Now let $u = w - v$. Then it follows that

$$u_t - k\Delta u = w_t - v_t - k\Delta w + k\Delta v = (w_t - k\Delta w) - (v_t - k\Delta v) = f_2 - f_1.$$

Following the identity proved in 2b, this is equivalent to

$$\begin{aligned} u(x_0, t_0) &\leq t_0 \max_{\Omega_{t_0}} |f_2 - f_1| + \max_{\partial_P \Omega_{t_0}} |u| \\ \implies w(x_0, t_0) - v(x_0, t_0) &\leq t_0 \max_{\Omega_{t_0}} |f_2 - f_1| + \max_{\partial_P \Omega_{t_0}} |w - v|. \end{aligned}$$

But we can rewrite this as follows

$$\begin{aligned} -(v(x_0, t_0) - w(x_0, t_0)) &\leq t_0 \max_{\Omega_{t_0}} |-(f_1 - f_2)| + \max_{\partial_P \Omega_{t_0}} |-(v - w)| \\ \implies -(v(x_0, t_0) - w(x_0, t_0)) &\leq t_0 \max_{\Omega_{t_0}} |f_1 - f_2| + \max_{\partial_P \Omega_{t_0}} |v - w| \end{aligned} \quad (b)$$

Given (a) and (b), we conclude that

$$|v(x_0, t_0) - w(x_0, t_0)| \leq t_0 \max_{\Omega_{t_0}} |f_1 - f_2| + \max_{\partial_P \Omega_{t_0}} |v - w|.$$

Question 3

a)

Let $u(x_1, t_1) = c$ for some value $c \in (0, 1) = \Omega_{t_1}$. Then by the strong max principle $u \equiv c$ in Ω_{t_1} . But, from the initial condition, $u(x, 0) = 4x(1 - x)$, we see that u is non-constant therefore we have a contradiction. It follows that $u \neq c$ in Ω_{t_1} . By the weak max principle, the minima and maxima occur on the boundaries. The minimum occurs on the boundary since $u(0, t) = u(1, t) = 0 \implies u > 0$. At the base the maximum occurs internally at $x, t = (\frac{1}{2}, 0) < c \implies u < 1$. We conclude $0 < u < 1$ for the specified time and space domain.

b)

$$\frac{dE}{dt} = \frac{d}{dt} E = \frac{d}{dt} \int_0^1 u^2(x, t) dx = 2k \left[uu_x \Big|_0^1 - \int_0^1 (u_x)^2 dx \right]$$

Since at the boundaries the function is 0, the first term vanishes

$$\begin{aligned} \frac{d}{dt} \int_0^1 u^2(x, t) dx &= \underbrace{-2k \int_0^1 (u_x)^2 dx}_{\text{negative}} \\ \implies E(t) &\text{ is strictly decreasing with respect to } t. \end{aligned}$$

$$u(x, t) = e^{-2\lambda^2 t} (A \cos \lambda x + B \sin \lambda x)$$

$$u_x(x, t) = \lambda e^{-2\lambda^2 t} (B \cos \lambda x - A \sin \lambda x)$$

Boundary conditions to find a summation expression

$$u_x(0, t) = \lambda e^{-2\lambda^2 t} B = 1 \implies B = \frac{1}{\lambda e^{-2\lambda^2 t}}$$

$$u_x(1, t) = \lambda e^{-2\lambda^2 t} (B \cos x - A \sin \lambda x) = 1$$

$$\implies \cos \lambda - \lambda e^{-2\lambda^2 t} A \sin \lambda = 1$$

Implementing $\sin^2(t)$,

$$\implies -\lambda e^{-2\lambda^2 t} A \sin \lambda = 2 \sin^2(\lambda/2)$$

$$\frac{1}{\sqrt{5}} \begin{pmatrix} -i & 2 \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{1}{\sqrt{5}} \begin{pmatrix} i \\ 2 \end{pmatrix} = \frac{(-2i + 2i)\hbar}{10} = 0$$