



## UNIT 15

### Reduction of State Tables State Assignment

***This chapter includes:***

- 15.1 Elimination of Redundant States
- 15.2 Equivalent States
- 15.3 Determination of State Equivalence  
Using an Implication Table
- 15.4 Equivalent Sequential Circuits
- 15.5 Reducing Incompletely Specified State  
Tables
- 15.6 Derivation of Flip-Flop Input Equations
- 15.7 Equivalent State Assignments
- 15.8 Guidelines for State Assignment
- 15.9 Using a One-Hot State Assignment

# Learning Objectives

1. Define equivalent states, state several ways of testing for state equivalence, and determine if two states are equivalent.
2. Define equivalent sequential circuits and determine if two circuits are equivalent.
3. Reduce a state table to a minimum number of rows.
4. Specify a suitable set of state assignments for a state table, eliminating those assignments which are equivalent with respect to the cost of realizing the circuit.

# Learning Objectives

5. State three guidelines which are useful in making state assignments, and apply these to making a good state assignment for a given state table.
6. Given a state table and assignment, form the transition table and derive flip-flop input equations.
7. Make a one-hot state assignment for a state graph and write the next-state and output equations by inspection.

# Elimination of Redundant States

TABLE 15-1

State Table for  
Sequence Detector

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Input Sequence	Present State	Next State		Present Output	
		$X = 0$	$X = 1$	$X = 0$	$X = 1$
reset	<i>A</i>	<i>B</i>	<i>C</i>	0	0
0	<i>B</i>	<i>D</i>	<i>E</i>	0	0
1	<i>C</i>	<i>F</i>	<i>G</i>	0	0
00	<i>D</i>	<i>H</i>	<i>I</i>	0	0
01	<i>E</i>	<i>J</i>	<i>K</i>	0	0
10	<i>F</i>	<i>L</i>	<i>M</i>	0	0
11	<i>G</i>	<i>N</i>	<i>P</i>	0	0
000	<i>H</i>	<i>A</i>	<i>A</i>	0	0
001	<i>I</i>	<i>A</i>	<i>A</i>	0	0
010	<i>J</i>	<i>A</i>	<i>A</i>	0	1
011	<i>K</i>	<i>A</i>	<i>A</i>	0	0
100	<i>L</i>	<i>A</i>	<i>A</i>	0	1
101	<i>M</i>	<i>A</i>	<i>A</i>	0	0
110	<i>N</i>	<i>A</i>	<i>A</i>	0	0
111	<i>P</i>	<i>A</i>	<i>A</i>	0	0

# Elimination of Redundant States

## Eliminating Redundant States from Table 15-1:

- ❖ Looking at the table, we see that there is no way of telling states H and I apart. That is, if we start in state H, the next state is A and the output is 0; similarly, if we start in state I, the next state is A and the output is 0. We say that H is equivalent to I ( $H \equiv I$ ).
- ❖ Similarly, rows K, M, N, and P have the same next state and output as H, so K, M, N, and P can be replaced by H, and these rows can be deleted.
- ❖ Also, the next states and outputs are the same for rows J and L, so  $J \equiv L$ . Thus, L can be replaced with J and eliminated from the table. The result is shown in Table 15-2.
- ❖ Having made these changes in the table, rows D and G are identical and so are rows E and F. Therefore,  $D \equiv G$ , and  $E \equiv F$ , so states F and G can be eliminated.

# Elimination of Redundant States

**TABLE 15-2**  
State Table for  
Sequence Detector

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Present State	Next State		Present Output	
	X = 0	X = 1	X = 0	X = 1
A	B	C	0	0
B	D	E	0	0
C	<del>E</del>	<del>D</del>	0	0
D	H	<del>I</del> H	0	0
E	J	KH	0	0
<del>F</del>	<del>L</del> J	<del>M</del> H	0	0
<del>G</del>	<del>N</del> H	<del>R</del> H	0	0
H	A	A	0	0
<del>I</del>	A	A	0	0
J	A	A	0	1
<del>K</del>	A	A	0	0
<del>L</del>	A	A	0	1
<del>M</del>	A	A	0	0
<del>N</del>	A	A	0	0
<del>P</del>	A	A	0	0

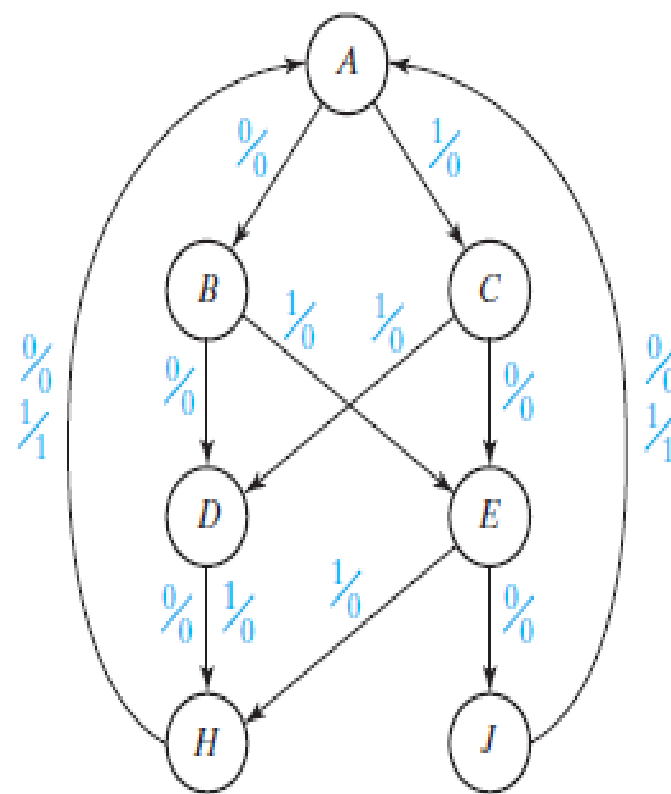
# Elimination of Redundant States

**FIGURE 15-1**  
Reduced State  
Table and Graph  
for Sequence  
Detector

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Present State	Next State		Output	
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
<i>A</i>	<i>B</i>	<i>C</i>	0	0
<i>B</i>	<i>D</i>	<i>E</i>	0	0
<i>C</i>	<i>E</i>	<i>D</i>	0	0
<i>D</i>	<i>H</i>	<i>H</i>	0	0
<i>E</i>	<i>J</i>	<i>H</i>	0	0
<i>H</i>	<i>A</i>	<i>A</i>	0	0
<i>J</i>	<i>A</i>	<i>A</i>	0	1

(a)



(b)



# Equivalent States

## State Equivalence:

❖ Two states are equivalent if there is no way of telling them apart through observation of the circuit inputs and outputs.

We can then state formally the definition of state equivalence as follows:

### Definition 15.1

---

Let  $N_1$  and  $N_2$  be sequential circuits (not necessarily different). Let  $\underline{X}$  represent a sequence of inputs of arbitrary length. Then state  $p$  in  $N_1$  is equivalent to state  $q$  in  $N_2$  iff  $\lambda_1(p, \underline{X}) = \lambda_2(q, \underline{X})$  for every possible input sequence  $\underline{X}$ .

---

# Equivalent States

**Theorem 15.1<sup>1</sup>** Two states  $p$  and  $q$  of a sequential circuit are equivalent iff for every single input  $X$ , the outputs are the same and the next states are equivalent, that is,

$$\lambda(p, X) = \lambda(q, X) \quad \text{and} \quad \delta(p, X) \equiv \delta(q, X)$$

where  $\lambda(p, X)$  is the output given the present state  $p$  and input  $X$ , and  $\delta(p, X)$  is the next state given the present state  $p$  and input  $X$ . Note that the next states do not have to be equal, just equivalent. For example, in Table 15-1,  $D \equiv G$ , but the next states ( $H$  and  $N$  for  $X = 0$ , and  $I$  and  $P$  for  $X = 1$ ) are not equal.

# Determination of State Equivalence Using An Implication Table

## **Implication Table Method Procedure:**

1. Construct a chart which contains a square for each pair of states.
2. Compare each pair of rows in the state table. If the outputs associated with states  $i$  and  $j$  are different, place an  $X$  in square  $i$ - $j$  to indicate that  $i \not\equiv j$ . If the outputs are the same, place the implied pairs in square  $i$ - $j$ . (If the next states of  $i$  and  $j$  are  $m$  and  $n$  for some input  $x$ , then  $m$ - $n$  is an implied pair.) If the outputs and next states are the same (or if  $i$ - $j$  only implies itself), place a check ( $\checkmark$ ) in square  $i$ - $j$  to indicate that  $i \equiv j$ .

# Determination of State Equivalence Using An Implication Table

## **Implication Table Procedure (continued):**

3. Go through the table square-by-square. If square  $i$ - $j$  contains the implied pair  $m$ - $n$ , and square  $m$ - $n$  contains an  $X$ , then  $i \not\equiv j$ , and an  $X$  should be placed in square  $i$ - $j$ .
4. If any  $X$ 's were added in step 3, repeat step 3 until no more  $X$ 's are added.
5. For each square  $i$ - $j$  which does not contain an  $X$ ,  $i \equiv j$ .

# Determination of State Equivalence Using An Implication Table

TABLE 15-3

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Present State	Next State $X = 0 \quad 1$		Present Output
<i>a</i>	<i>d</i>	<i>c</i>	0
<i>b</i>	<i>f</i>	<i>h</i>	0
<i>c</i>	<i>e</i>	<i>d</i>	1
<i>d</i>	<i>a</i>	<i>e</i>	0
<i>e</i>	<i>c</i>	<i>a</i>	1
<i>f</i>	<i>f</i>	<i>b</i>	1
<i>g</i>	<i>b</i>	<i>h</i>	0
<i>h</i>	<i>c</i>	<i>g</i>	1

FIGURE 15-3

Implication Chart  
for Table 15-3

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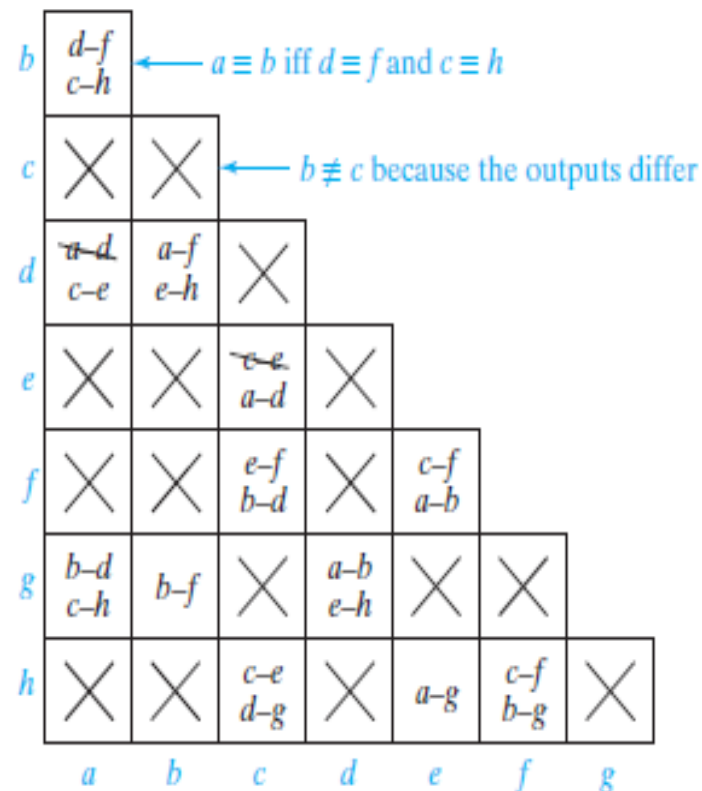


TABLE 15-4

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Present State	Next State $X = 0 \quad 1$		Output
<i>a</i>	<i>a</i>	<i>c</i>	0
<i>b</i>	<i>f</i>	<i>h</i>	0
<i>c</i>	<i>c</i>	<i>a</i>	1
<i>f</i>	<i>f</i>	<i>b</i>	1
<i>g</i>	<i>b</i>	<i>h</i>	0
<i>h</i>	<i>c</i>	<i>g</i>	1

# Determination of State Equivalence Using An Implication Table

**FIGURE 15-4**  
Implication Chart  
After First Pass  
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<i>b</i>	<del><i>d-f</i></del> <del><i>c-h</i></del>						
<i>c</i>	×	×					
<i>d</i>	<i>c-e</i>	<del><i>a-f</i></del> <del><i>e-h</i></del>	×				
<i>e</i>	×	×	<i>a-d</i>	×			
<i>f</i>	×	×	<del><i>e-f</i></del> <del><i>b-d</i></del>	×	<del><i>c-f</i></del> <del><i>a-b</i></del>		
<i>g</i>	<i>b-d</i> <i>c-h</i>	<del><i>b-f</i></del>	×	<del><i>a-b</i></del> <del><i>e-h</i></del>	×	×	
<i>h</i>	×	×	<i>c-e</i> <i>d-g</i>	×	<i>a-g</i>	<del><i>c-f</i></del> <del><i>b-g</i></del>	×
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>

# Determination of State Equivalence Using An Implication Table

**FIGURE 15-5**  
Implication Chart  
After Second Pass  
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<i>b</i>	<del><i>d-f</i> <i>e-h</i></del>						
<i>c</i>	×	×					
<i>d</i>	<i>c-e</i>	<del><i>a-f</i> <i>e-h</i></del>	×				
<i>e</i>	×	×	<i>a-d</i>	×			
<i>f</i>	×	×	<del><i>a-f</i> <i>b-d</i></del>	×	<del><i>c-f</i> <i>d-h</i></del>		
<i>g</i>	<del><i>b-d</i> <i>e-h</i></del>	<del><i>b-f</i></del>	×	<del><i>a-b</i> <i>e-h</i></del>	×	×	
<i>h</i>	×	×	<del><i>c-e</i> <i>d-g</i></del>	×	<del><i>a-g</i> <i>b-g</i></del>	×	
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>

# Equivalent Sequential Circuits

## Equivalent Sequential Circuits Formal Definition:

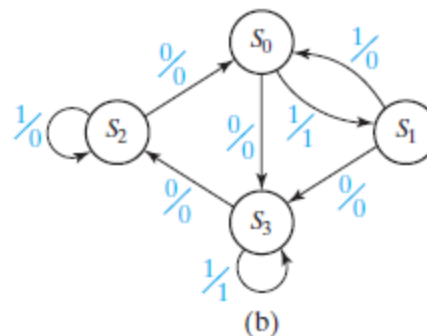
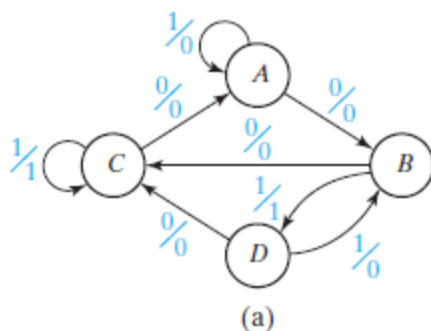
**Definition 15.2** Sequential circuit  $N_1$  is equivalent to sequential circuit  $N_2$  if for each state  $p$  in  $N_1$ , there is a state  $q$  in  $N_2$  such that  $p \equiv q$ , and conversely, for each state  $s$  in  $N_2$ , there is a state  $t$  in  $N_1$  such that  $s \equiv t$ .

**FIGURE 15-6**  
Tables and Graphs  
for Equivalent  
Circuits

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	$N_1$			
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
$A$	$B$	$A$	0	0
$B$	$C$	$D$	0	1
$C$	$A$	$C$	0	1
$D$	$C$	$B$	0	0

	$N_2$			
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
$S_0$	$S_3$	$S_1$	0	1
$S_1$	$S_3$	$S_0$	0	0
$S_2$	$S_0$	$S_2$	0	0
$S_3$	$S_2$	$S_3$	0	1





# Equivalent Sequential Circuits

**FIGURE 15-7**  
Implication Tables  
for Determining  
Circuit Equivalence  
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$S_0$	$\times$	$C-S_3$ $D-S_1$	$A-S_3$ $C-S_1$	$\times$
$S_1$	$B-S_3$ $A-S_0$	$\times$	$\times$	$C-S_3$ $B-S_0$
$S_2$	$B-S_0$ $A-S_2$	$\times$	$\times$	$C-S_0$ $B-S_2$
$S_3$	$\times$	$C-S_2$ $D-S_3$	$A-S_2$ $C-S_3$	$\times$
	$A$	$B$	$C$	$D$

(a)

$S_0$	$\times$	$C-S_3$ $D-S_1$	<del><math>A-S_3</math> <math>C-S_1</math></del>	$\times$
$S_1$	<del><math>B-S_3</math> <math>A-S_0</math></del>	$\times$	$\times$	$C-S_3$ $B-S_0$
$S_2$	$B-S_0$ $A-S_2$	$\times$	$\times$	<del><math>C-S_0</math> <math>B-S_2</math></del>
$S_3$	$\times$	<del><math>C-S_2</math> <math>D-S_3</math></del>	$A-S_2$ $C-S_3$	$\times$
	$A$	$B$	$C$	$D$

(b)

Equivalent State pairs:

$$A \equiv S_2 \quad B \equiv S_0 \quad C \equiv S_3 \quad D \equiv S_1$$

Since each state in  $N_1$  has an equivalent state in  $N_2$  and conversely,  $N_1 \equiv N_2$ .

# Reducing Incompletely Specified State Tables

## Incompletely Specified Examples:

**TABLE 15-5**  
Incompletely  
Specified  
Examples

Present State	Next State		Output	
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
$S_0$	$S_1$	$S_3$	0	$-^2$
$S_1$	$S_2$	$S_3$	$-^1$	0
$S_2$	$S_1$	$S_0$	1	0
$S_3$	$S_2$	$S_3$	0	1

(a)

Present State	Next State		Output	
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
$S_0$	$S_2$	$S_1$	0	1
$S_1$	$S_1$	$S_0$	-	1
$S_2$	$S_2$	$S_1$	1	1

(b)

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# Reducing Incompletely Specified State Tables

FIGURE 15-8

Implication Charts  
for Table 15-5(a)

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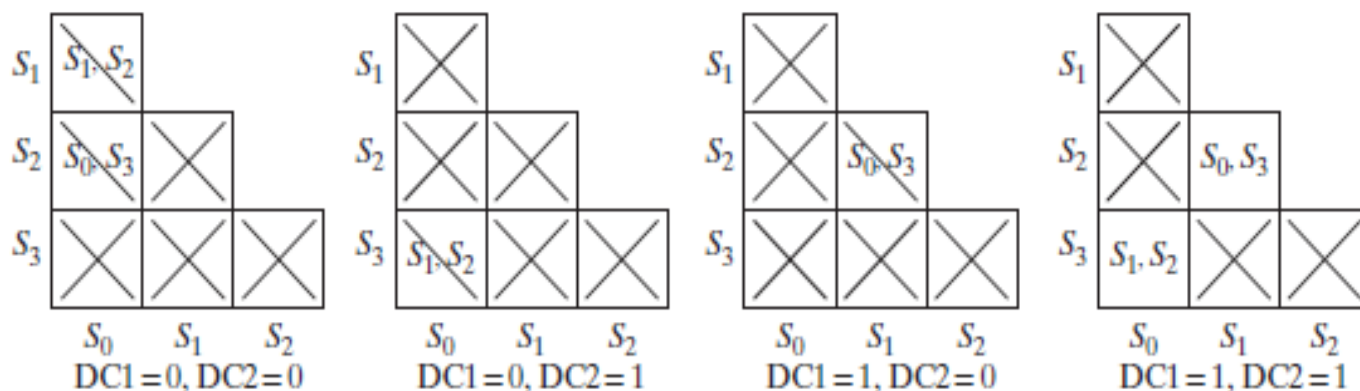


TABLE 15-6  
Modified  
Table 15-5(b)

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Present State	Next State		Output	
	$X = 0$	$X = 1$	$X = 0$	$X = 1$
$S_0$	$S_2$	$S_1^1$	0	1
$S_1^1$	$S_1^2$	$S_0$	0	1
$S_1^2$	$S_1^2$	$S_0$	1	1
$S_2$	$S_2$	$S_1^1$	1	1

# Reducing Incompletely Specified State Tables

## Procedure to Reduce an Incompletely Specified Table:

- ❖ To reduce an incompletely specified table, a minimum of the maximal compatibles are selected, say  $C_1, C_2, \dots, C_k$ , so that
  - (1) each state of the table appears in at least one of the  $C_i$ , and
  - (2) for each input combination  $x$  and each  $C_i$ , the next states of the states in  $C_i$  are contained in some  $C_j$ . (It may be that  $j=i$ .)

# Reducing Incompletely Specified State Tables

## Even Parity Detector for 0 Through 5:

TABLE 15-7

Even Parity  
Detector For 0  
Through 5

	Present State	Next State		Output	
		X = 0	X = 1	X = 0	X = 1
0	$S_0$	$S_1$	$S_2$	-	-
	$S_1$	$S_3$	$S_4$	-	-
1	$S_2$	$S_4$	-	-	-
00	$S_3$	$S_0$	$S_0$	1	0
01, 10	$S_4$	$S_0$	$S_0$	0	1

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FIGURE 15-9

Implication Chart  
for Table 15-7

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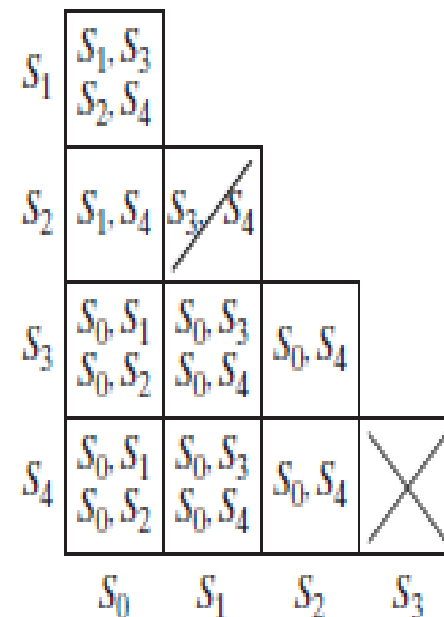


TABLE 15-8

Reduced Table for  
Table 15-7

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	Present State	Next State		Output	
		X = 0	X = 1	X = 0	X = 1
$S_0 S_1 S_3$	A	A	B	1	0
$S_0 S_2 S_4$	B	C	B	0	1
$S_0 S_1 S_4$	C	A	B	0	1

# Derivation of Flip-Flop Input Equations

## **Procedure to Derive Flip-Flop Input Equations:**

1. Assign flip-flop state values to correspond to the states in the reduced table.
  2. Construct a transition table which gives the next states of the flip-flops as a function of the present states and inputs.
  3. Derive the next-state maps from the transition table.
  4. Find flip-flop input maps from the next-state maps using the techniques developed in Unit 12 and find the flip-flop input equations from the maps.
- ❖ See pages 516-520 for applications of this procedure.

# Equivalent State Assignments

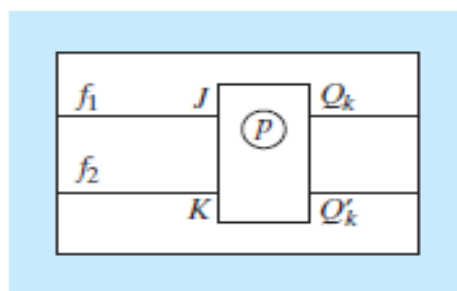
## Equivalent State Assignments:

❖ Now we must assign flip-flop states to correspond to the states in the table.

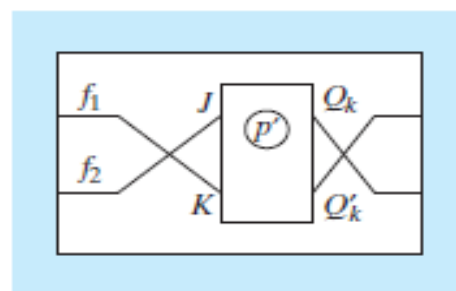
**TABLE 15-11**  
State Assignments  
for 3-Row Tables  
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	1	2	3	4	5	6	7		19	20	21	22	23	24
$S_0$	00	00	00	00	00	00	01	...	11	11	11	11	11	11
$S_1$	01	01	10	10	11	11	00		00	00	01	01	10	10
$S_2$	10	11	01	11	01	10	10		01	10	00	10	00	01

**FIGURE 15-13**  
Equivalent Circuits  
Obtained by  
Complementing  $Q_k$   
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(a) Circuit A



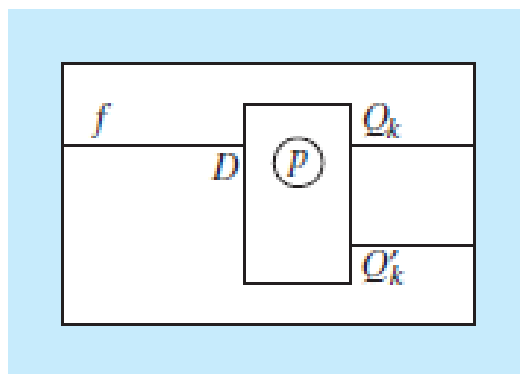
(b) Circuit B  
(identical to A except leads to  
flip-flop  $Q_k$  are crossed)

# Equivalent State Assignments

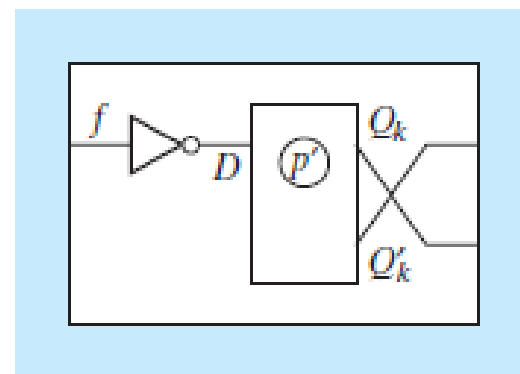
FIGURE 15-14

Equivalent Circuits  
Obtained by  
Complementing  $Q_k$

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(a) Circuit A



(b) Circuit B  
(identical to A except for  
connections to flip-flop  $Q_k$ )

TABLE 15-12

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Assignments			Present State	Next State		Output	
$A_3$	$B_3$	$C_3$		$X = 0$	1	0	1
00	00	11	$S_1$	$S_1$	$S_3$	0	0
01	10	10	$S_2$	$S_2$	$S_1$	0	1
10	01	01	$S_3$	$S_3$	$S_3$	1	0



# Equivalent State Assignments

## J and K Input Equations:

### Assignment A

$$J_1 = XQ_2'$$

$$K_1 = X'$$

$$J_2 = X'Q_1$$

$$K_2 = X$$

$$Z = X'Q_1 + XQ_2$$


---

$$D_1 = XQ_2'$$

$$D_2 = X'(Q_1 + Q_2)$$

### Assignment B

$$J_2 = XQ_1'$$

$$K_2 = X'$$

$$J_1 = X'Q_2$$

$$K_1 = X$$

$$Z = X'Q_2 + XQ_1$$


---

$$D_2 = XQ_1'$$

$$D_1 = X'(Q_2 + Q_1)$$

### Assignment C

$$K_1 = XQ_2$$

$$J_1 = X'$$

$$K_2 = X'Q_1'$$

$$J_2 = X$$

$$Z = X'Q_1' + XQ_2'$$


---

$$D_1 = X' + Q_2'$$

$$D_2 = X + Q_1Q_2$$

# Equivalent State Assignments

## Equivalent and Distinct State Assignments:

- ❖ Two state assignments are equivalent if one can be derived from the other by permuting and complementing columns.
- ❖ Two state assignments which are not equivalent are said to be distinct.

**TABLE 15-13**  
Nonequivalent  
Assignments for  
Three and Four  
States

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States	3-State Assignments			4-State Assignments		
	1	2	3	1	2	3
<i>a</i>	00	00	00	00	00	00
<i>b</i>	01	01	11	01	01	11
<i>c</i>	10	11	01	10	11	01
<i>d</i>	–	–	–	11	10	10

# Equivalent State Assignments

**TABLE 15-14**  
Number of Distinct  
(Nonequivalent)  
State Assignments

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Number of States	Minimum Number of State Variables	Number of Distinct Assignments
2	1	1
3	2	3
4	2	3
5	3	140
6	3	420
7	3	840
8	3	840
9	4	10,810,800
:	:	:
:	:	:
:	:	:
16	4	$\approx 5.5 \times 10^{10}$

# Guidelines for State Assignment

## Guidelines:

Assignments for two states are said to be adjacent if they differ in only one variable. Thus, 010 and 011 are adjacent, but 010 and 001 are not. The following *guidelines* are useful in making assignments which will place 1's together (or 0's together) on the next-state maps:

1. States which have the same next state for a given input should be given adjacent assignments.
2. States which are the next states of the same state should be given adjacent assignments.

A third guideline is used for simplification of the output function:

3. States which have the same output for a given input should be given adjacent assignments.

# Guidelines for State Assignment

## Derivation of State Assignment:

FIGURE 15-15

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<i>ABC</i>		<i>X = 0    1</i>		<i>0</i>	<i>1</i>
000	$S_0$	$S_1$	$S_2$	0	0
110	$S_1$	$S_3$	$S_2$	0	0
001	$S_2$	$S_1$	$S_4$	0	0
111	$S_3$	$S_5$	$S_2$	0	0
011	$S_4$	$S_1$	$S_6$	0	0
101	$S_5$	$S_5$	$S_2$	1	0
010	$S_6$	$S_1$	$S_6$	0	1

(a) State table

<i>BC</i> \ <i>A</i>		
	0	1
00	$S_0$	
01	$S_2$	$S_5$
11	$S_4$	$S_3$
10	$S_6$	$S_1$

<i>BC</i> \ <i>A</i>		
	0	1
00	$S_0$	
01	$S_1$	$S_6$
11	$S_3$	$S_4$
10	$S_5$	$S_2$

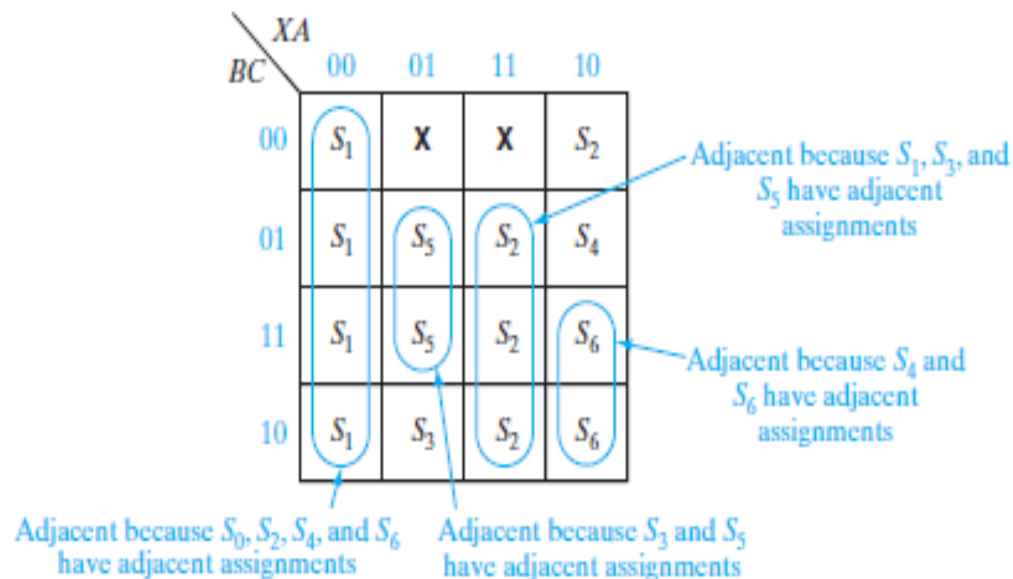
(b) Assignment maps

# Guidelines for State Assignment

**FIGURE 15-16**

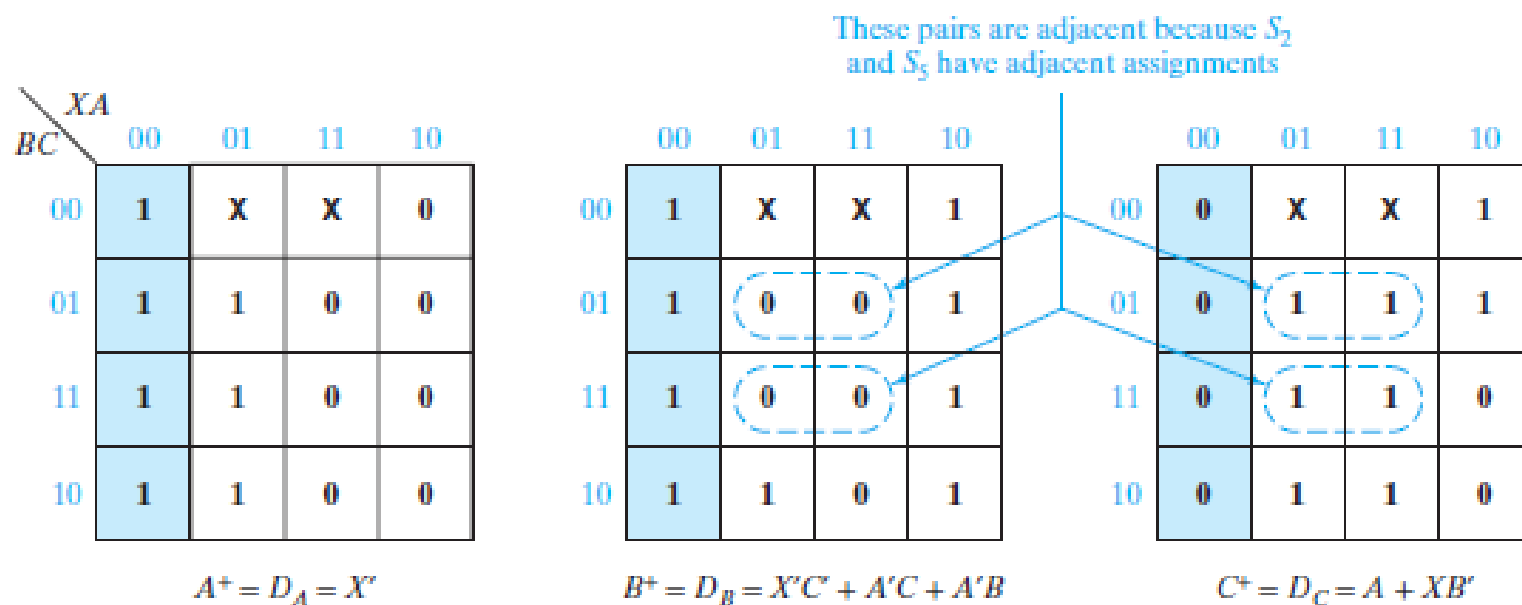
Next-State Maps  
for Figure 15-15

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(a) Next-state maps for Figure 15-15

# Guidelines for State Assignment



(b) Next-state maps for Figure 15-15 (cont.)

# Guidelines for State Assignment

	$X = 0$	$1$	$X = 0$	$1$
$a$	$a$	$c$	$0$	$0$
$b$	$d$	$f$	$0$	$1$
$c$	$c$	$a$	$0$	$0$
$d$	$d$	$b$	$0$	$1$
$e$	$b$	$f$	$1$	$0$
$f$	$c$	$e$	$1$	$0$

(a)

$Q_1$	$Q_2 Q_3$	$0$	$1$
$00$	$a$	$c$	
$01$		$e$	
$11$	$d$	$b$	
$10$		$f$	

(b)

$a = 000$   
 $b = 111$   
 $c = 100$   
 $d = 011$   
 $e = 101$   
 $f = 110$

$Q_1$	$Q_2 Q_3$	$0$	$1$
$00$	$c$	$a$	
$01$		$e$	
$11$	$d$	$b$	
$10$	$f$		

(c)

$a = 100$   
 $b = 111$   
 $c = 000$   
 $d = 011$   
 $e = 101$   
 $f = 010$

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**TABLE 15-15**  
Transition Table for  
Figure 15-17(a)

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$Q_1 Q_2 Q_3$	$Q_1 + Q_2 + Q_3$	$X = 0$	$1$	$X = 0$	$1$
1 0 0		100	000	0	0
1 1 1		011	010	0	1
0 0 0		000	100	0	0
0 1 1		011	111	0	1
1 0 1		111	010	1	0
0 1 0		000	101	1	0



# Guidelines for State Assignment

(Figure 15-18) from the transition table. The D flip-flop input equations can be read directly from these maps:

$$D_1 = Q_1^+ = X'Q_1Q_2' + XQ_1'$$

$$D_2 = Q_2^+ = Q_3$$

$$D_3 = Q_3^+ = XQ_1'Q_2 + X'Q_3$$

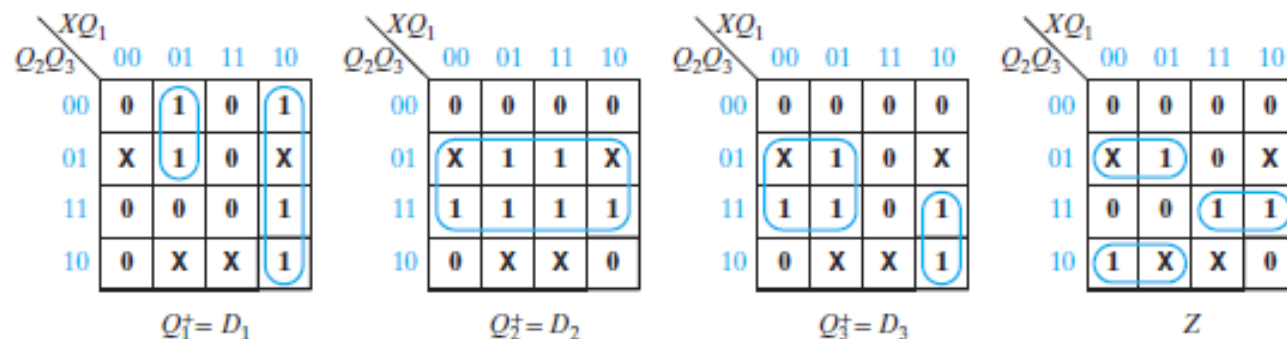
and the output equation is

$$Z = XQ_2Q_3 + X'Q_2'Q_3 + XQ_2Q_3'$$

The cost of realizing these equations is 10 gates and 26 gate inputs.

**FIGURE 15-18**  
Next-State and  
Output Maps for  
Table 15-15

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# Using a One-Hot State Assignment

## One-Hot State Assignment:

❖ The one-hot assignment uses one flip-flop for each state, so a state machine with  $N$  states requires  $N$  flip-flops. Exactly one of the flip-flops is set to one in each state.

❖ For example, a system with four states ( $S_0$ ,  $S_1$ ,  $S_2$ , and  $S_3$ ) could use four flip-flops ( $Q_0$ ,  $Q_1$ ,  $Q_2$ , and  $Q_3$ ) with the following state assignment:

$S_0$ :  $Q_0 Q_1 Q_2 Q_3 = 1000$ ,  $S_1$ :  $0100$ ,  $S_2$ :  $0010$ ,  $S_3$ :  $0001$

The other 12 combinations are not used.

❖ In general, when a one-hot state assignment is used, each term in the next-state equation for each flip-flop contains exactly one state variable, and the reduced equation can be written by inspecting the state graph.