

INF-SUP COMPATIBLE SPACES

Let V_h, Q_h not be inf-sup compatible, then $\exists p_h^* \in Q_h$ s.t. $b(u_h, p_h^*) = 0 \quad \forall u_h \in V_{h,0} \Leftrightarrow \exists \hat{p}^* \in \mathbb{R}^{N_p}$ s.t. $\hat{u}^T B^T \hat{p}^* = 0 \quad \forall \hat{u} \in \mathbb{R}^{N_u} \Leftrightarrow \hat{p}^* \in \text{Ker } B^T$

Remark:

If inf-sup isn't valid, the spurious pressure mode are in $\text{Ker } B^T$

If V_h, Q_h are inf-sup compatible then:

$$\begin{aligned} \text{Ker } B^T &= \{\vec{0}\} \Leftrightarrow \text{Im } B = \mathbb{R}^{N_p} \Leftrightarrow \forall \hat{u} \in \mathbb{R}^{N_u} \exists \hat{p} \in \mathbb{R}^{N_p} \text{ s.t. } B\hat{u} = \hat{p} \\ &\Leftrightarrow \text{rank } B = \text{rank } B^T = N_p, \quad B \in \mathbb{R}^{N_p \times N_u}, \quad B: \mathbb{R}^{N_u} \rightarrow \mathbb{R}^{N_p} \\ &\Rightarrow \dim \text{Ker } B = N_u - N_p > 0 \end{aligned}$$

Remark:

- 1) If inf-sup holds, there $\exists N_u - N_p$ solenoidal velocities
- 2) When V_h, Q_h are inf-sup compatible, $\dim V_h > \dim Q_h$!!!

CONVERGENCE ANALYSIS

If V_h, Q_h are inf-sup comp., then the following holds:

$$\|\nabla(u - u_h)\|_{L^2} \leq 2 \left(1 + \frac{\sqrt{d}}{\beta_h}\right) \inf_{w_h \in V_h} \|\nabla(u - w_h)\|_{L^2} + \frac{\sqrt{d}}{\nu} \inf_{\pi_h \in Q_h} \|p - \pi_h\|_{L^2}$$

$$\|p - p_h\|_{L^2} \leq \frac{2\nu}{\beta_h} \left(1 + \frac{\sqrt{d}}{\beta_h}\right) \inf_{w_h \in V_h} \|\nabla(u - w_h)\|_{L^2} + \left(1 + \frac{2\sqrt{d}}{\beta_h}\right) \inf_{\pi_h \in Q_h} \|p - \pi_h\|_{L^2}$$

Remark:

If $\beta_h \xrightarrow{h \rightarrow 0} 0$, convergence is not granted !!!

Inf-Sup Compatible FE:

- 1) $V_h = [X_h]^d, Q_h = X_h^r \Rightarrow V_h, Q_h$ are NOT inf-sup compatible
- 2) $V_h = \mathbb{P}_1, Q_h = \mathbb{P}_0 \Rightarrow V_h, Q_h$ are NOT inf-sup compatible
- 3) $V_h = \mathbb{P}_{k+1}, Q_h = \mathbb{P}_k, k \geq 1 \Rightarrow V_h, Q_h$ are inf-sup compatible with order of convergence $k+1$
- 4) $V_h = \mathbb{P}_1$ iso $\mathbb{P}_2, Q_h = \mathbb{P}_1 \Rightarrow V_h, Q_h$ are inf-sup compatible with order of convergence 1
- 5) $V_h = \mathbb{P}_1$ bubble, $Q_h = \mathbb{P}_1 \Rightarrow V_h, Q_h$ are inf-sup compatible with order of convergence 1

where

$\mathbb{P}_\kappa :=$ polynomials of $\deg = \kappa$,

$\mathbb{P}_1 \text{ bubble} := \{0 \text{ at } \partial\Omega_i, \text{ polynomials of } \deg = 3 \text{ in } \Omega_i\}$

STABILIZATION METHODS

Let $s: Q_h \times Q_h \rightarrow \mathbb{R}$ pos. def. We find $(u_h, p_h) \in V_h \times Q_h$ s.t. $u_h = g_h$ on T_D and:

$$\begin{cases} a(u_h, v_h) + b(v_h, p_h) = F(v_h) & \forall v_h \in V_h \\ b(u_h, q_h) - s(p_h, q_h) = 0 & \forall q_h \in Q_h \end{cases}$$

\Rightarrow Introduce $S \in \mathbb{R}^{N_p \times N_p}$, $S_{ke} = s(t_k, t_e)$, then we have:

$$\begin{pmatrix} A & B^T \\ B & -S \end{pmatrix} \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \begin{pmatrix} F \\ \vec{0} \end{pmatrix}$$

Remarks:

1) Well posedness holds for general inf-sup condition:

$$\sup_{v_h \in V_{h,0}} \frac{b(v_h, q_h)}{\|\nabla v_h\|_{L^2}} + s(q_h, q_h) \geq \beta_h > 0 \quad \forall p_h \in Q_h$$

2) Compatibility:

$$s(q_h, q_h) \xrightarrow{h \rightarrow 0} 0$$

Optimal convergence holds if $s \xrightarrow{h \rightarrow 0} 0$ at least at the same order as the method. Generally this is true if strong continuum compatibility holds:

$$s(p, p) = 0$$

STABILIZERS:

1) Brezzi - Pitkeraosta:

$$s(p_h, q_h) = \delta \sum_{\Omega_i \in \mathcal{T}_h} h_i^3 |_{\Omega_i} \nabla p_h \cdot \nabla q_h \, d\Omega$$

\Rightarrow uniformly stable if $\dim Q_h = \dim V_h$ with convergence rate 1 independently from the convergence order of the method.

2) Interior - Penalty (IP):

$$s(p_h, q_h) = \delta \sum_{\Omega_i \in \mathcal{T}_h} h_i^3 |_{\partial\Omega_i \cap \partial\Omega} [\nabla p_h] \cdot [\nabla q_h] \, d\Gamma$$

where $[f] = f^+ - f^-$

$$\Rightarrow s(p, p) = 0 \quad \forall p \in H^2(\Omega)$$

\Rightarrow Optimal convergence $\forall K, |P_K|/|P_K|$

RESOLUTION OF THE GALERKIN PROBLEM

1) PRESSURE METHOD:

$$\begin{cases} A\hat{u} + B^T \hat{p} = F \\ B\hat{u} - S\hat{p} = \vec{0} \end{cases} \Rightarrow \hat{u} = A^{-1}(F - B^T \hat{p})$$

$$\Rightarrow BA^{-1}(F - B^T \hat{p}) - S\hat{p} = \vec{0} \Rightarrow \underbrace{(BA^{-1}B^T + S)}_{\Sigma = \text{Schur Component}} \hat{p} = BA^{-1}F$$

$$\Rightarrow \Sigma \hat{p} = BA^{-1}F$$

$$1) S = \vec{0} :$$

$$\Rightarrow \Sigma = BA^{-1}B^T \Rightarrow \text{we have:}$$

$$\frac{C_1}{\sqrt{d}} h_{\min}^d \|\hat{p}\| \leq \hat{p}^T M_p \hat{p} \leq \frac{C_2}{\sqrt{d}} h_{\max}^d \|\hat{p}\|$$

$$\frac{C_1}{\sqrt{d}} h_{\min}^d \beta_h^2 \leq \lambda(BA^{-1}B^T) \leq \frac{C_2}{\sqrt{d}} h_{\max}^d d$$

$$\kappa(BA^{-1}B^T) \leq \frac{C_2}{C_1} \frac{\beta_h^2}{d} \left(\frac{h_{\max}}{h_{\min}} \right)^d$$

$$\Rightarrow \text{take } P = \frac{M_p}{\sqrt{d}}, \text{ then:}$$

$$P^{-1}BA^{-1}B^T v = \lambda v \Rightarrow (\sqrt{d} M_p^{-1}) BA^{-1}B^T v = \lambda v$$

$$\Rightarrow BA^{-1}B^T = \lambda \frac{M_p}{\sqrt{d}} v \wedge \beta_h^2 \leq \lambda \leq d$$

and the same holds for $P = \frac{\text{diag } M_p}{\sqrt{d}}$

2) MONOLITHIC APPROACH:

$$\begin{cases} A\hat{u} + B^T \hat{p} = F \\ \mp B\hat{u} \pm S\hat{p} = \vec{0} \end{cases} \Rightarrow \text{we have:}$$

$$\underbrace{\begin{pmatrix} A & B^T \\ B & -S \end{pmatrix}}_{=\Sigma_1} \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \begin{pmatrix} F \\ \vec{0} \end{pmatrix} \vee \underbrace{\begin{pmatrix} A & B^T \\ -B & S \end{pmatrix}}_{=\Sigma_2} \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \begin{pmatrix} F \\ \vec{0} \end{pmatrix}$$

1) Σ_1 is symmetric BUT it is indefinite:

$$\begin{pmatrix} \hat{u} & \hat{p} \end{pmatrix}^T \Sigma_1 \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \underbrace{\hat{u}^T A \hat{u}}_{\geq 0} + \underbrace{2\hat{p}^T B \hat{u}}_{?} - \underbrace{\hat{p}^T S \hat{p}}_{\leq 0}$$

2) Σ_2 is NOT symmetric BUT it is semi-pos. def.:

$$\begin{pmatrix} \hat{u} & \hat{p} \end{pmatrix}^T \Sigma_2 \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \hat{u}^T A \hat{u} + \hat{p}^T S \hat{p} \geq 0$$

\Rightarrow take $P = \begin{pmatrix} A & \vec{0} \\ \vec{0} & \frac{M_p}{V} \end{pmatrix}$, then we have:

$$P^{-1} \Sigma v = \mu_i v, \quad \Sigma = \begin{pmatrix} A & B^T \\ B & \vec{0} \end{pmatrix}, \quad i = 1, \dots, N_u + N_p$$

$$\Rightarrow \begin{pmatrix} A & B^T \\ B & \vec{0} \end{pmatrix} \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix} = \mu_i \begin{pmatrix} A & \vec{0} \\ \vec{0} & \frac{M_p}{V} \end{pmatrix} \begin{pmatrix} \hat{u} \\ \hat{p} \end{pmatrix}$$

1) $\hat{u} \in \text{Ker } B, \hat{p} = \vec{0} \Rightarrow \dim \text{Ker } B = N_u - N_p$

$$\begin{cases} A\hat{u} = \mu_i A u \\ \vec{0} = \vec{0} \end{cases} \Rightarrow \exists N_u \cdot N_p \text{ eigenvalues } \mu_i, 2N_p \text{ remain !!!}$$

2) $\hat{u} \notin \text{Ker } B, \hat{p} \neq \vec{0}$:

$$\begin{cases} A\hat{u} + B^T \hat{p} = \mu_i A \hat{u} \\ B\hat{u} = \mu_i \frac{M_p}{V} \hat{p} \end{cases} \Rightarrow A(1 - \mu_i) \hat{u} = -B^T \hat{p}$$

$$\Rightarrow A\hat{u} = \frac{1}{\mu_i - 1} B^T \hat{p} \Rightarrow \frac{1}{\mu_i - 1} B A^{-1} B^T \hat{p} = \mu_i \frac{M_p}{V} \hat{p}$$

$$\Rightarrow B A^{-1} B^T \hat{p} = \mu_i (\mu_i - 1) \frac{M_p}{V} \hat{p}$$

$$\Rightarrow \mu_i (\mu_i - 1) = \lambda_i, \quad 0 < \beta_h^2 \leq \lambda_i \leq d$$

$$\Rightarrow \mu_i = \frac{1 \pm \sqrt{1 + 4\lambda_i}}{2}$$

1) N_p are negative, $\mu_i \in \left[\frac{1 - \sqrt{1 + 4d}}{2}, \frac{1 + \sqrt{1 + 4\beta_h^2}}{2} \right]$

2) N_p are positive, $\mu_i \in \left[\frac{1 + \sqrt{1 + 4\beta_h^2}}{2}, \frac{1 + \sqrt{1 + 4d}}{2} \right]$

Remark:

$$\begin{pmatrix} A & \vec{0} \\ \pm B & \frac{M_p}{V} \end{pmatrix} \text{ is also a good preconditioner } (+: \Sigma_1, -: \Sigma_2)$$

\Rightarrow In this approach, we have the following system:

$$\underbrace{\begin{pmatrix} K_v & 0 & B_1^T \\ 0 & K_v & B_2^T \\ B_1 & B_2 & 0 \end{pmatrix}}_{K_v} \begin{pmatrix} \hat{u}_1 \\ \hat{u}_2 \\ \hat{p} \end{pmatrix} = \begin{pmatrix} F_1 \\ F_2 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} K_v \hat{u}_1 + B_1^T \hat{p} = F_1 \\ K_v \hat{u}_2 + B_2^T \hat{p} = F_2 \\ B_1 \hat{u}_1 + B_2 \hat{u}_2 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} \hat{u}_1 = K_v^{-1} (F_1 - B_1^T \hat{p}) \\ \hat{u}_2 = K_v^{-1} (F_2 - B_2^T \hat{p}) \end{cases} \Rightarrow (B_1 K_v^{-1} B_1^T + B_2 K_v^{-1} B_2^T) \hat{p} = 0$$

$$\Rightarrow b = B_1^T \hat{p}, \quad K_v z = b$$