## **Data Science Fundamentals**

Part I: Probability theory

ISEP 2<sup>nd</sup> year 2023-2024

Based on the course given by Nathalie Colin & Jean-Claude Guillerot

# Probability theory

- > 5th session (October 27th 2023):
- Chapter 7: EXPECTED VALUE, CHARACTERISTIC FUNCTION AND MOMENTS FOR TWO-DIMENSIONAL RANDOM VARIABLES
- Chapter 6 (continuation): GAUSSIAN RANDOM VARIABLES

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## **Expected value of a function (1/3)**

Reminder: Expected value of a function of a random variable

$$Y = g(X)$$

$$E(Y) = E(g(X)) = \int g(x) f_X(x) dx$$

**Definition**: Expected value of a function of 2 variables

$$Z = g(X, Y)$$

**Continuous case** 

$$E(Z) = E(g(X,Y)) = \iint g(x,y) f_{X,Y}(x,y) dx dy$$

Discrete case

$$E(Z) = E(g(X,Y)) = \sum_{i,j} g(x_i, y_j) P_{i,j}$$

P<sub>i,i</sub>: two-dimensional distribution

## Expected value of a function (2/3)

**Remark:** linearity of the expected value

$$g(x,y) = \sum_{k} \lambda_{k} g_{k}(x,y)$$

$$E(\sum_{k} \lambda_{k} g_{k}(x, y)) = \sum_{k} \lambda_{k} E(g_{k}(x, y))$$
Expected value of a sum = sum of expected values

Example: 
$$E(Z) = E(aX + bY) = aE(X) + bE(Y)$$

#### <u>Two-dimension conditional expected value:</u>

So far, we have seen : 
$$f_{\mathbf{Y}}(\mathbf{y}|\mathbf{X}=\mathbf{x}) = \frac{f_{X,Y}(\mathbf{x},\mathbf{y})}{f_{X}(\mathbf{x})}$$

So: 
$$E(Y|X = x) = \int y f_Y(y|X = x) dy = \frac{\int y f_{x,y}(x,y) dy}{f_Y(x)}$$

## **Expected value of a function (3/3)**

<u>Two-dimension conditional expected value (continuation)</u>:

#### In general:

$$E(g(X,Y)|X = x) = \int g(x,y)f_Y(y|X = x)dy = \frac{\int g(x,y)f_{x,y}(x,y)dy}{f_X(x)}$$

#### Similarly:

$$E(g(X,Y)|Y=y) = \int g(x,y)f_X(x|Y=y)dx = \frac{\int g(x,y)f_{x,y}(x,y)dx}{f_Y(y)}$$

## **Characteristic function (1/2)**

$$\varphi_{X,Y}(t_1,t_2) = E(e^{jt_1x+jt_2y})$$

$$\varphi_{X,Y}(t_1,t_2) = \iint e^{jt_1x+jt_2y} f_{X,Y}(x,y) dxdy$$

with t<sub>1</sub> and t<sub>2</sub>: deterministic real variables

$$\varphi_X(t_1) = \varphi_{X,Y}(t_1,0)$$
  $\varphi_Y(t_2) = \varphi_{X,Y}(0,t_2)$   $\varphi_{X,Y}(0,0) = 1$ 

Theorem: Inversion formulae:  $f_{X,Y} \Leftrightarrow \varphi_{X,Y}$ 

$$f_{X,Y} \Leftrightarrow \varphi_{X,Y}$$

$$f_{X,Y}(x,y) = \frac{1}{(2\pi)^2} \iint e^{-(jt_1x+jt_2y)} \varphi_{X,Y}(t_1,t_2) dt_1 dt_2$$

## **Characteristic function (2/2)**

## **Moment-generating function:**

$$\left. \frac{\partial^{k+l} \varphi_{X,Y}(t_1,t_2)}{\partial t_1^k \partial t_2^l} \right|_{t_1=t_2=0} = j^{k+l} E(X^k Y^l)$$

The proof is similar to that of one-dimensional case: Taylor series of the characteristic function (around the point (0,0)).

$$\varphi_{X,Y}(t_1,t_2) = 1 + jE(X)t_1 + jE(Y)t_2 - \frac{1}{2}E(X^2)t_1^2 - \frac{1}{2}E(Y^2)t_2^2 - E(XY)t_1t_2 + \dots$$

## Moments for a pair of random variables (1/5)

## **Definition**

For 1 random variable, moment of order n:

$$m_n = E(X^n) = \int x^n f_X(x) dx$$

For 2 random variables, moment of order n such that n = l + k:

$$m_{l,k} = E(X^l Y^k) = \iint x^l y^k f_{X,Y}(x, y) dx dy$$

For 2 discrete random variables:

$$m_{l,k} = E(X^{l}Y^{k}) = \sum_{i} \sum_{j} x_{i}^{k} y_{j}^{l} P_{i,j}$$

#### Remarks:

- There are two 1st order moments: E (X) and E (Y)
- > There are three 2nd order moments:  $E(X^2)$ ,  $E(Y^2)$ , E(XY)
- In general, there are (n + 1) moments of  $n^{th}$  order

## Moments for a pair of random variables (2/5)

## **Definition (continuation):**

Central moments with  $m_{10} = E(X)$  and  $m_{01} = E(Y)$ :

$$\begin{split} & \mu_{l,k} = E((X - m_{1,0})^l (Y - m_{0,1})^k) \\ & \mu_{l,k} == \iint (x - m_{1,0})^l (y - m_{0,1})^k \, f_{X,Y}(x,y) dx dy \\ & \mu_{0,0} = 1 \\ & \mu_{1,0} = \mu_{0,1} = 0 \\ & \mu_{2,0} = \sigma_X^2 \quad \mu_{0,2} = \sigma_Y^2 \text{ and } \mu_{l,l} = \sigma_{X,Y} \text{ the covariance of } (X,Y) \end{split}$$

The covariance is also denoted cov (X, Y)

## Moments for a pair of random variables (3/5)

## **Covariance:**

$$\mu_{1,1} = E((X - m_{1,0})(Y - m_{0,1})) = \sigma_{X,Y}$$

$$\mu_{1,1} = \sigma_{X,Y} = E(XY) - E(X)E(Y) = m_{1,1} - m_{1,0}m_{0,1}$$

with  $m_{10} = E(X)$  and  $m_{01} = E(Y)$ 

Remark :  $\sigma_{X,Y}$  it can be positive or negative.

**Schwartz inequality**: relation between the 2<sup>nd</sup> order moments

$$E^2(XY) \leq E(X^2)E(Y^2)$$

$$m_{1,1}^2 \leq m_{2,0} m_{0,2}$$

For zero-mean random variables:

$$\mu_{1,1}^2 \le \mu_{2,0} \mu_{0,2}$$

In general:

$$\sigma_{XY}^2 \leq \sigma_X^2 \sigma_Y^2$$

## Moments for a pair of random variables (4/5)

#### **Correlation coefficient:**

$$r = \frac{E((X - m_{1,0})(Y - m_{0,1}))}{\sqrt{E((X - m_{1,0})^2)E((X - m_{0,1})^2)}} = \frac{\mu_{1,1}}{\mu_{2,0}\mu_{0,2}} = \frac{\sigma_{X,Y}}{\sigma_X\sigma_Y}$$

#### **Properties:**

- The correlation coefficient measures the linear dependence between X and Y
- $-1 \le r \le 1$  (using the Cauchy-Schwartz inequality)
- Special values :
  - $r = \pm 1$ : there is a perfect linear dependency between X and Y: Y = aX + b
  - r = 0 : X and Y are non-correlated E(XY) = E(X)E(Y)

## Moments for 2 random variables (5/5)

### **Independance and correlation:**

Independence: 
$$f_{XY}(x,y) = f_X(x)f_Y(y)$$

$$m_{l,k} = E(X^l Y^k) = E(X^l) E(Y^k)$$
  

$$m_{l,k} = m_{l,0} m_{0,k} \quad \forall l \text{ and } k$$

For I = k = 1 : 
$$m_{1,1} = m_{1,0}m_{0,1} > r = 0$$
 so X and Y decorrelated

Independance => (implies) decorrelation

Decorrelation | Independence unless (X, Y) is gaussian

Orthogonality: E(XY) = 0

## **Application: linear regression (1/2)**

Objective: Given a pair of random variables (X,Y), given X fixed, we want to approach Y by a linear function of X, denoted g(X):

$$g(X) = aX + b$$

such that the mean square error between Y and g(X) is minimal.

We denote Z = Y - (aX + b) and we look for a and b such that  $E(Z^2) = E((Y-g(X))^2) = E((Y - (aX + b))^2)$  (mean square error) is minimal.

By applying some properties of the expected value we get:

$$E(Z^{2}) = E((Y - aX)^{2}) + b^{2} - 2bE(Y - aX)$$

## **Application: linear regression (2/2)**

Let us denote  $\varepsilon = E(Z^2) = E(Y - g(X))^2$  the mean square error

We calculate the derivatives to get the values of a and b that minimize  $\varepsilon$ 

$$E(Z^{2}) = \varepsilon = E(Y^{2}) + a^{2}E(X^{2}) + b^{2} - 2aE(XY) - 2bE(Y) + 2abE(X)$$

The derivatives : 
$$\frac{\partial \varepsilon}{\partial a} = aE(X^2) - E(XY) + bE(X) = 0$$

$$\frac{\partial \varepsilon}{\partial b} = b - E(Y) + aE(X) = 0$$

which gives:

$$a = \frac{E(XY) - E(X)E(Y)}{E(X^2) - E^2(X)} = \frac{\sigma_{XY}}{\sigma_X^2} \qquad b = E(Y) - aE(X) \quad et \ r = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}$$

$$a = \frac{r\sigma_Y}{\sigma_X}$$
  $b = E(Y) - \frac{r\sigma_Y}{\sigma_X} E(X) \rightarrow \varepsilon \min = \sigma_Y^2 (1 - r^2) \rightarrow case r^2 = 1$ 

### Regression line

$$y = \frac{r\sigma_Y}{\sigma_X}(x - E(X)) + E(Y)$$

Likewise : if Y=aX+b we find without difficulty that, r=+-1. Conclusion, a necessary and sufficient condition for 2 random variables to be linearly related, is that |r|=1.

## What happens if the correlation coefficient is zero?

If  $r^2 = 0$  the variables are uncorrelated, so E(XY)=E(X)E(Y)

Application : calculation of the variance of a sum when the variables are decorrelated.

$$Var(aX + bY) = a^2Var(X) + b^2Var(Y) = a^2\sigma_X^2 + b^2\sigma_Y^2$$

Remark: the correlation is a measure of the linear dependence between two variables.

The correlation between two variables may be weak even if the variables are very closely related. This means that, if a relation exists, it is not linear, for instance, it can be polynomial, exponential, etc.

## **In summary**

<u>Conditions</u> <u>Then,</u>

If The variables X and Y are:

 $f_{XY}(x,y) = f_X(x) f_Y(y)$  Independent and, then, non-correlated.

E(XY) = E(X)E(Y) non-correlated

E(XY) = 0 orthogonal

 $r = \pm 1$  Linearly dependent

## Formula for the variance

- Cov(X, Y) = E(XY) E(X)E(Y)
- $Var(aX + bY) = a^2Var(X) + b^2Var(Y) + 2abCov(X, Y)$
- Cov(X,X) = Var(X)
- Cov(aX + bY, cU + dV) = ac.Cov(X, U) + ad.Cov(X, V) + bc.Cov(Y, U) + bd.Cov(Y, V)
- Cov(aX + bY, cX + dY) = ac.Var(X) + (ad + bc)Cov(X,Y) + bd.Var(Y)

#### Covariance matrix of a random vector or 2d-variable (X,Y)

$$V(X,Y) = \begin{pmatrix} Var(X) & Cov(X,Y) \\ Cov(X,Y) & Var(Y) \end{pmatrix}$$

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#### **GAUSSIAN RANDOM VARIABLES**

### **Definition:**

The pair of random variables or 2d-vector (X, Y) is Gaussian if its density is of the form:  $f_{X,Y}(x,y)=e^{-\varphi(x,y)}$ 

with

$$\varphi(x,y) = ax^2 + bxy + cy^2 + dx + ey + k$$

Remark: it depends on only 5 parameters

$$k$$
 is fixed by: 
$$\int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{X,Y}(x,y) dx dy = 1$$

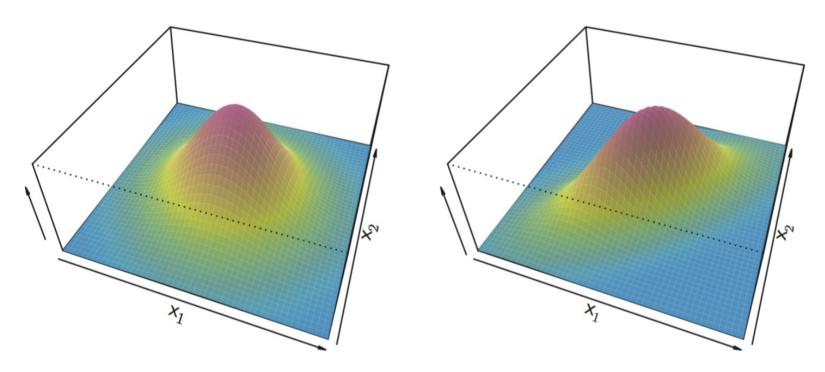
Usual presentation:

The 5 parameters are  $m_x$ ,  $m_v$ , r,  $\sigma_x$  and  $\sigma_v$ 

$$f_{X,Y}(x,y) = \frac{1}{2\pi \sigma_x \sigma_y \sqrt{1-r^2}} e^{-\frac{1}{2(1-r^2)} \varphi(x,y)}$$

$$\varphi(x,y) = \frac{(x-m_{x1})^2}{\sigma_x^2} - \frac{2r(x-m_{x1})(y-m_{y1})}{\sigma_x \sigma_y} + \frac{(y-m_{y1})^2}{\sigma_y^2}$$

#### **GAUSSIAN RANDOM VARIABLES**



Left: Equal variance and zero correlation, Right: different variances and existing correlation.

For a *p*-dimensional vector, the density is: 
$$f(x) = \frac{1}{(2\pi)^{\frac{1}{2}}|V|^{\frac{1}{2}}}e^{-\frac{1}{2}(x-\mu)^{T}V^{-1}(x-\mu)}$$

Where  $\mu \in \mathbb{R}^p$  is the vector of expected values (mean vector) and  $\mathbf{V}$  is the covariance matrix.

## **Marginal densities**

$$f_{Y}(y) = \int_{-\infty}^{+\infty} f_{X,Y}(x,y) dx$$

Marginal for Y:

Similarly for X:

$$f_Y(y) = rac{1}{\sigma_Y \sqrt{2\pi}} e^{-rac{(y-m_Y^2)^2}{2\sigma_Y^2}}$$

$$f_X(x) = \frac{1}{\sigma_X \sqrt{2\pi}} e^{-\frac{(x-m_X^2)^2}{2\sigma_X^2}}$$

 $m_x$ ,  $\sigma_x$ : expected value and standard deviation of X

 $m_{v}$ ,  $\sigma_{v}$ : expected value and standard deviation of Y

Two dimensional gaussian density ⇒ Gaussian marginal densities

the opposite is not necessarily true

r is the "coefficient of correlation" between X and Y,

## **Independance**:

X and Y gaussian each and  $f_{XY}(x,y) = f_X(x)f_Y(y)$  independent from each other. (X,Y) Gaussian, r=0

Important remark: the non-correlation between 2 random variables (i.e. r = 0) implies the independence only in the case of a gaussian vector.

## Summary table about Gaussian vector properties

#### In general

- X and Y independent ⇒ cov(X,Y)=0
- cov(X,Y)=0 ⇒ X and Y independent

<u>Definition:</u> (X,Y) is a Gaussian vector  $\Leftrightarrow \forall \alpha, \beta \in \mathbb{R}$ ,  $\alpha X + \beta Y$  is a Gaussian random variable.

- If (X,Y) is a Gaussian vector and X and Y are independent ⇔ cov(X,Y)=0.
- (X,Y) Gaussian vector ⇒ X Gaussian and Y Gaussian (particular case if β=0 and α=0 respectively).
- (X Gaussian and Y Gaussian) ⇒ (X,Y) Gaussian vector.
- (X Gaussian, Y Gaussian and (X,Y) independent) ⇒ (X,Y)
   Gaussian vector. (the opposite is true iff cov(X,Y)=0)
- (X Gaussian, Y Gaussian and (X,Y) independent)  $\Rightarrow \forall \alpha, \beta \in \mathbb{R}$ ,  $\alpha X + \beta Y$  is a Gaussian random variable.

## Theorem concerning Gaussian vectors

**Theorem:** Let X be a Gaussian random vector in  $\mathbb{R}^p$  that follows the p-dimensional Gaussian distribution with parameters  $\mu$  (vector of means) and **V** (covariance matrix). If **A** is a deterministic dxp-matrix and a vector  $U \in \mathbb{R}^d$ , then:

$$E(AX + U) = A E(X) + U$$
  
 $Var(AX+U) = AVA^T$