

Support Vector Machines

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Three different concepts

- Maximal Margin Classifier
- Support Vector Classifier
- Support Vector Machine

Hyperplanes

Our training data consists of N pairs

$(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$, with $x_i \in \mathbb{R}^p$ and $y_i \in \{-1, 1\}$.

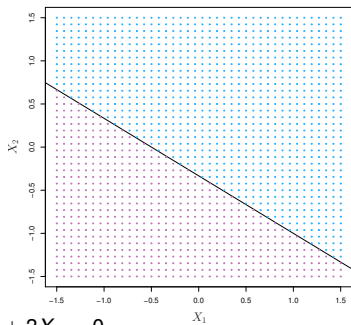
Define a hyperplane by

$$\{x : f(x) = x^T \beta + \beta_0 = 0\}$$

where β is a unit vector.

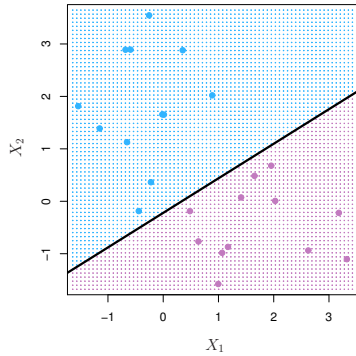
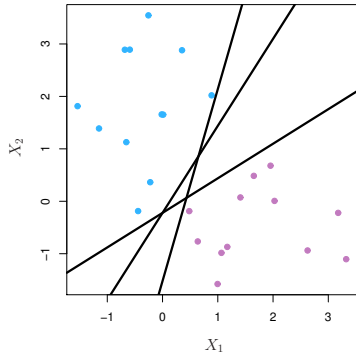
If $\beta_0 \neq 0$, we call this **affine**

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hyperplane for $1 + 2X_1 + 3X_2 = 0$

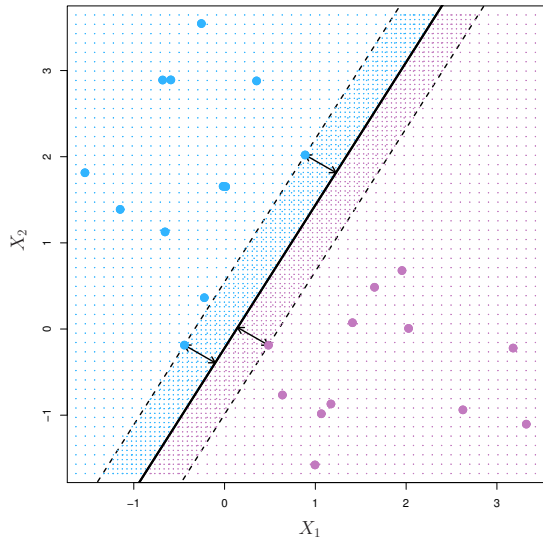
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Maximum Margin Optimization

$$\begin{aligned} & \max_{\beta_0, \beta_1, \dots, \beta_p} M \\ \text{subject to} \quad & \|\beta\| = 1 \\ & y_i(x_i^T \beta + \beta_0) \geq M, \\ & i = 1, \dots, N \end{aligned}$$

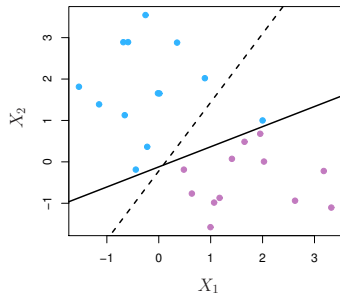
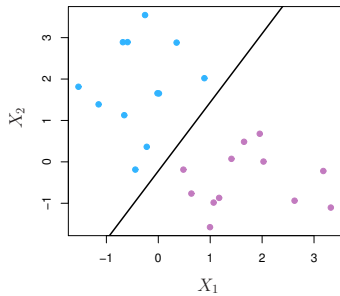
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The main issue with the Maximal Margin Classifier, is overfitting

This results in great sensitivity to individual data points

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Dealing with Overlap

Define the slack variables $\xi = (\xi_1, \xi_2, \dots, \xi_N)$. We then modify our previous constraints in one of two ways:

$$y_i(x_i^T \beta + \beta_0) \geq M - \xi_i$$

or

$$y_i(x_i^T \beta + \beta_0) \geq M(1 - \xi_i)$$

$$\forall i, \xi_i \geq 0, \sum_{i=1}^N \xi_i \leq \text{constant}$$

With these overlapping datasets, our optimization for the margins becomes:

$$\max_{\beta_0, \beta_1, \dots, \beta_p, \xi_1, \dots, \xi_N} M$$

subject to:

$$\sum_{j=1}^p \beta_j^2 = 1$$

$$y_i(\beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_p x_{ip}) \geq M(1 - \xi_i)$$

$$\xi_i \geq 0$$

$$\sum_{i=1}^N \xi_i \leq \text{a constant, } C$$

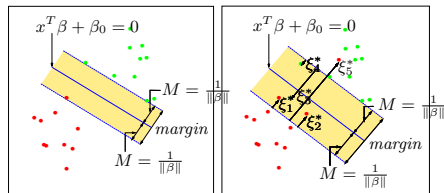


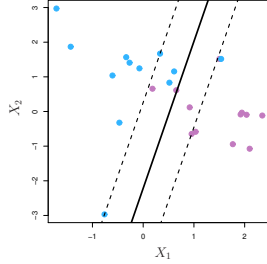
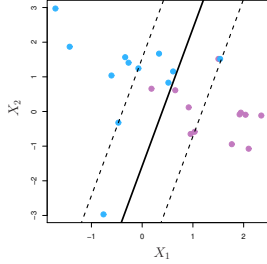
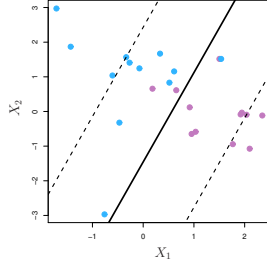
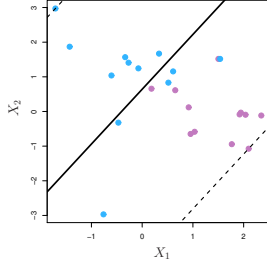
FIGURE 12.1. Support vector classifiers. The left panel shows the separable case. The decision boundary is the solid line, while broken lines bound the shaded maximal margin of width $2M = 2/\|\beta\|$. The right panel shows the nonseparable (overlap) case. The points labeled ξ_j^* are on the wrong side of their margin by an amount $\xi_j^* = M\xi_j$; points on the correct side have $\xi_j^* = 0$. The margin is maximized subject to a total budget $\sum \xi_i \leq \text{constant}$. Hence $\sum \xi_j^*$ is the total distance of points on the wrong side of their margin.

Support Vectors

These points that either lie directly on the margin, or violate the margin are called *Support Vectors*

The number of which will be defined by C

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Example of Non-linear Boundary

$$\max_{\beta_0, \beta_1, \dots, \beta_p, \xi_1, \dots, \xi_N} M$$

subject to:

$$\sum_{j=1}^p \sum_{k=1}^2 \beta_{jk}^2 = 1$$

$$y_i(\beta_0 + \sum_{j=1}^p \beta_{j1} x_{ij} + \sum_{j=1}^p \beta_{j2} x_{ij}^2) \geq M(1 - \xi_i)$$

$$\xi_i \geq 0, \sum_{i=1}^N \xi_i \leq \text{a constant, } C$$

Inner Product

The inner product of two observations, x_i and x_k is given by:

$$\langle x_i, x_k \rangle = \sum_{j=1}^p x_{ij} x_{kj}$$

The linear support vector classifier can be expressed as:

$$f(x) = \beta_0 + \sum_{i=1}^N \alpha_i \langle x, x_i \rangle$$

Kernels

We can represent the relationship between two variables as a *kernel*

Popular choices of K in SVM are

- **Linear:** $K(x, x') = \langle x_i, x_{i'} \rangle$
- **d^{th} -Degree Polynomial:** $K(x, x') = (1 + \langle x, x' \rangle)^d$
- **Radial basis:** $K(x, x') = e^{-\gamma \|x - x'\|^2}$
- **Neural Network:** $K(x, x') = \tanh(\kappa_1 \langle x, x' \rangle + \kappa_2)$

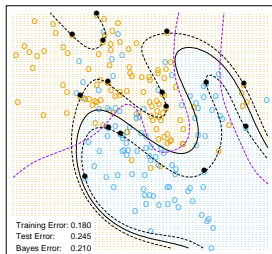
Support Vector Machines

If the kernel is non-linear, the classifier

$$f(x) = \sum_{i=1}^N \alpha_i K(x, x_i) + \beta_0$$

is referred to as a *support vector machine*

SVM - Degree-4 Polynomial in Feature Space



SVM - Radial Kernel in Feature Space

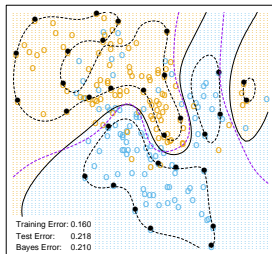


FIGURE 12.3. Two nonlinear SVMs for the mixture data. The upper plot uses a 4th degree polynomial

SVM for Regression

The linear regression model has the form:

$$f(x) = x^T \beta + \beta_0$$

Where β is estimated by minimizing

$$H(\beta, \beta_0) = \sum_{i=1}^N V(y_i - f(x_i)) + \frac{\lambda}{2} \|\beta\|^2$$

where

$$V_{\epsilon}(r) = \begin{cases} 0 & \text{if } |r| < \epsilon \\ |r| - \epsilon & \text{otherwise} \end{cases}$$

We can compare this error measure V_ϵ to more robust measures used in statistics, such as the Huber

$$V_H(r) = \begin{cases} r^2/2 & \text{if } |r| \leq c \\ c|r| - c^2/2 & |r| > c \end{cases}$$

This reduces from quadratic to linear the contributions of observations with absolute value greater than c , which makes fitting less sensitive to outliers.

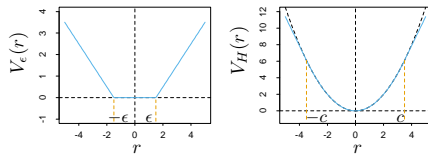


FIGURE 12.8. The left panel shows the ϵ -insensitive error function used by the support vector regression machine. The right panel shows the error function used in Huber's robust regression (blue curve). Beyond $|c|$, the function changes from quadratic to linear.

If $\hat{\beta}, \hat{\beta}_0$ are the minimizer of H , we have the solution

$$\hat{\beta} = \sum_{i=1}^N (\hat{\alpha}_i^* - \hat{\alpha}_i) x_i$$

$$\hat{f}(x) = \sum_{i=1}^N (\hat{\alpha}_i^* - \hat{\alpha}_i) \langle x, x_i \rangle + \beta_0$$

where $\hat{\alpha}_i^*, \hat{\alpha}_i$ are positive and solve the quadratic programming problem

$$\min_{\alpha, \alpha_i^*} \epsilon \sum_{i=1}^N (\alpha_i^* + \alpha_i) - \sum_{i=1}^N y_i (\alpha_i^* - \alpha_i) + \frac{1}{2} \sum_{i, i'=1}^N (\alpha_i^* - \alpha_i) (\alpha_{i'}^* - \alpha_{i'}) \langle x_i, x_{i'} \rangle$$

subject to constraints

$$0 \leq \alpha_i, \alpha_i^* \leq 1/\lambda$$

$$\sum_{i=1}^N (\alpha_i^* - \alpha_i) = 0$$

$$\alpha_i \alpha_{i'} = 0$$

Regression and Kernels

For a set of basis functions $\{h_m(x)\}$, $m = 1, 2, \dots, M$

$$f(x) = \sum_{m=1}^M \beta_m h_m(x) + \beta_0$$

To estimate β and β_0 we minimize

$$H(\beta, \beta_0) = \sum_{i=1}^N V(y_i - f(x_i)) + \frac{\lambda}{2} \sum \beta_m^2$$

The solution has the form:

$$\hat{f}(x) = \sum_{i=1}^N \hat{a}_i K(x, x_i)$$

with $K(x, y) = \sum_{m=1}^M h_m(x) h_m(y)$

- [1] Trevor Hastie Gareth James, Daniela Witten and Robert Tibshirani. *An Introduction to Statistical Learning with Applications in R*. Number v. 6. Springer, 2013.