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①

Q.3.2.

Proof: suppose $0 \leq s \leq t$,

to show $W^2(t) - t$ is a martingale, is to prove

$$E[W^2(t) - t | \mathcal{F}_s] = W^2(s) - s$$

then, we begin to prove.

$$E[W^2(t) - t | \mathcal{F}_s] = E[(W(t) - W(s))^2 - t | \mathcal{F}_s]$$

$$= E[(W(t) - W(s))^2 - 2W(s) \cdot (W(t) - W(s)) + \underbrace{W(s)^2}_{\text{is } s\text{-measurable}} - t | \mathcal{F}_s]$$

$$\begin{aligned} E[(W(t) - W(s))^2] &= E[W(t) - W(s)]^2 = E^2(W(t) - W(s)) \\ &= D[W(t) - W(s)] \\ &= t - s. \end{aligned}$$

$\therefore W(s)$ and $W(t) - W(s)$ are independent.

$$\begin{aligned} \therefore E[W(s) \cdot (W(t) - W(s)) | \mathcal{F}_s] &= W(s) \cdot E[W(t) - W(s)] \\ &= W(s) \cdot 0 = 0 \end{aligned}$$

$$\begin{aligned} &\downarrow W(s) \text{ is } s\text{-measurable} \\ E[W(s) | \mathcal{F}_s] &= W(s), \end{aligned}$$

and $W(t) - W(s)$ are independent of $W(s)$

$$\begin{aligned} E[(W(t) - W(s))^2 | \mathcal{F}_s] &= E[W(t) - W(s)]^2 \\ &= t - s \end{aligned}$$

in a sum,

$$E[W^2(t) - t | \mathcal{F}_s] = t - s - 0 + W^2(s) - s = W^2(s) - s.$$

3.3. let $X \sim N(\mu, \sigma^2)$
 to prove $\frac{E[(X-\mu)^4]}{\sigma^4} = 3$

(2)

$$\phi(k) = E[e^{Xk}] = e^{\mu k + \frac{1}{2}k^2\sigma^2}, \quad X-\mu \sim N(0, \sigma^2)$$

$$\phi_{X-\mu}(k) = E[e^{(X-\mu)k}] = e^{\frac{1}{2}k^2\sigma^2}$$

$$\phi'_{X-\mu}(k) = E[(X-\mu)e^{(X-\mu)k}] = k\sigma^2 \cdot e^{\frac{1}{2}k^2\sigma^2}$$

$$\phi''_{X-\mu}(k) = E[(X-\mu)^2 e^{(X-\mu)k}] = (\sigma^2 + k^2\sigma^4) \cdot e^{\frac{1}{2}k^2\sigma^2}$$

$$\phi'''_{X-\mu}(k) = E[(X-\mu)^3 e^{(X-\mu)k}] = (2k\sigma^4 + k^3\sigma^6) e^{\frac{1}{2}k^2\sigma^2} = (3k\sigma^4 + k^3\sigma^6) e^{\frac{1}{2}k^2\sigma^2}$$

$$\begin{aligned} \phi''''_{X-\mu}(k) &= E[(X-\mu)^4 e^{(X-\mu)k}] = (3\sigma^4 + 3k^2\sigma^6 + 3k^2\sigma^6 + k^4\sigma^8) \cdot e^{\frac{1}{2}k^2\sigma^2} \\ &= (3\sigma^4 + 6k^2\sigma^6 + k^4\sigma^8) \cdot e^{\frac{1}{2}k^2\sigma^2} \end{aligned}$$

let $k=0$,

$$E[(X-\mu)^4] = 3 \cdot \sigma^4$$

Q3.4. 布朗运动的其他变差

(i) proved by theorem 3.4.3.

$[W, W](T) = T$ is almost surely true

~~QII~~ suppose. there exists a path whose QI ~~isn't~~ isn't infinite, suppose it's T'

$$\text{for } \sum_{j=0}^{n-1} (W(t_{j+1}) - W(t_j))^2 \leq \max_{0 \leq k \leq n-1} |W(t_{k+1}) - W(t_k)| \cdot \sum_{j=0}^{n-1} |W(t_{j+1}) - W(t_j)|$$

$$\lim_{\|T\| \rightarrow 0} QII \leq \lim_{\|T\| \rightarrow 0} \max_{0 \leq k \leq n-1} |W(t_{k+1}) - W(t_k)| \cdot QI$$

Because W is continuous, so $\max_{0 \leq k \leq n-1} |W(t_{k+1}) - W(t_k)|$ has the limit 0 as $\|T\|$

$T \leq 0 \cdot T'$, that's false. we cannot prove the ~~step~~ hypothesis.

So QI approaches ∞ .

(ii). similar as (i)

$$QIII = \lim_{\|T\| \rightarrow 0} \sum_{j=0}^{n-1} |W(t_{j+1}) - W(t_j)|^3 \leq \max_{0 \leq k \leq n-1} |W(t_{k+1}) - W(t_k)| \cdot \sum_{j=0}^{n-1} (W(t_{j+1}) - W(t_j))^2$$

$$= \max_{0 \leq k \leq n-1} |W(t_{k+1}) - W(t_k)| \cdot T$$

$$= 0 \cdot T = 0.$$

\therefore So $QIII$ approaches 0. for almost every path of W .

Q 3.6
(i) to prove the Markov property of X_t

$$E[f(X_t) | \mathcal{F}_s] = E[f(X_t - X_s + X_s) | \mathcal{F}_s]$$

let dummy variable $w = X_s$, let w be a constant

$$\therefore E[f(X_t) | \mathcal{F}_s] = E[f(X_t - X_s + w) | \mathcal{F}_s] \quad \begin{array}{l} (X_t - X_s \text{ is independent of } X_s, \\ X_s \text{ is } \mathcal{F}_s\text{-measurable}) \end{array}$$

$$= E[f(X_t - X_s + w)]$$

$$X_t - X_s = W(t) - W(s) + (t-s)\mu \sim N((t-s)\mu, t-s), \quad \text{let } y = X_t - X_s + w$$

$$= \frac{1}{\sqrt{2\pi(t-s)}} \int_{-\infty}^{\infty} f(X_t - X_s + w) e^{-\frac{(X_t - X_s - \mu(t-s))^2}{2(t-s)}} dy \quad \text{then } X_t - X_s = y - w$$

$$= \frac{1}{\sqrt{2\pi(t-s)}} \int_{-\infty}^{\infty} f(y) e^{-\frac{(y-w-\mu(t-s))^2}{2(t-s)}} dy = g(w), \quad w \text{ is } X_s$$

$$\text{rewrite } T=t-s, \quad p(t, w, y) = \frac{1}{\sqrt{2\pi t}} e^{-\frac{(y-w-\mu t)^2}{2t}}$$

(ii) to prove the Markov property of S_t similar to (i)

$$\begin{aligned} E[f(S_t) | \mathcal{F}_s] &= E[f((S_t - S_s) + S_s) | \mathcal{F}_s] \\ &= E[f((S_t - S_s) + w) | \mathcal{F}_s] \end{aligned} \quad \begin{array}{l} \text{let } \\ w = S_s, \quad w \text{ is a constant} \\ S_t - S_s \text{ and } S_s \text{ are independent} \\ S_s \text{ is } \mathcal{F}_s\text{-measurable} \end{array}$$

(ii) next page.

$$(ii) S(t) = S_0 e^{6W(t) + Vt}$$

$$= S_0 e^{6(Wt + \frac{V}{6}t)}$$

similar to (i). $u = \frac{V}{6}$, $X(t) = Wt + \frac{V}{6}t$.

$$S(t) = S_0 \cdot e^{6 \cdot X(t)}, u = \frac{V}{6}$$

composite function

\therefore in this situation $f(y)$ in (i) is $f(g(y))$ in (ii) where $g(y) = S(t)$.

\therefore we can use the conclusion of (i).

$$\text{let } y = X(t) - X(s) + W$$

$$X(t) - X(s) = y - W.$$

$$E[f(S(t)) | F(s)] = E[f(S_0 e^{6X(t)}) | F(s)].$$

$$= \frac{1}{\sqrt{2\pi(t-s)}} \int_{-\infty}^{S_0 e^{6y}} f(y) e^{-\frac{1}{2(t-s)}(y-W)^2} dy \quad (\text{conclusion of (i)})$$

$$\text{let } z = S_0 e^{6y}$$

$$dz = S_0 \cdot 6 \cdot e^{6y} \quad (1)$$

$$y = \ln \frac{z}{S_0} \cdot \frac{1}{6} \quad (2)$$

$$= \frac{1}{\sqrt{2\pi(t-s)}} \int_{-\infty}^{\infty} f(z) \cdot e^{-\frac{1}{2(t-s)} \left(\ln \frac{z}{S_0} - \frac{1}{6} \ln \frac{S_0}{S_0} - \frac{1}{6} W(t-s) \right)^2} dz \cdot \frac{1}{6 \cdot z} \quad (\text{put (1) in})$$

$$= \frac{1}{6z\sqrt{2\pi}} \int_{-\infty}^{\infty} f(z) e^{-\frac{(\ln \frac{z}{S_0} - \frac{1}{6} W(t-s))^2}{2(t-s)}} dz = g(S_s)$$

rewrite. $\tau = t-s$.

$$p(\tau, x, y) = \frac{1}{6y\sqrt{2\pi}} e^{-\frac{(\ln \frac{y}{x} - \frac{1}{6} W)^2}{2\tau}}$$

Additional Question

a). $\therefore W, B$ are brownian Motion

No.

(6)

\therefore let $A = \frac{1}{2}(W+B)$.

according to the definition.

(i). $A(0) = \frac{1}{2}(W(0)+B(0)) = 0$, $A(t) = \frac{1}{2}(W(t)+B(t)) > 0$.

(ii) for each increments.

$\Delta A_{tj} = A(t_{j+1}) - A(t_j) = \frac{1}{2}(W_{t_{j+1}} - W_{t_j}) + \frac{1}{2}(B_{t_{j+1}} - B_{t_j})$, $\Delta t_{j+1} = \frac{1}{2}(W_{t_{j+1}} - W_{t_j}) + \frac{1}{2}(B_{t_{j+1}} - B_{t_j})$

\therefore every increments of B and W are independent
 \therefore every increments of A are independent.

(iii) $E[A_{t_{j+1}} - A_{t_j}] = \frac{1}{2}E[W_{t_{j+1}} - W_{t_j}] + \frac{1}{2}E[B_{t_{j+1}} - B_{t_j}] = 0$.

$Var[A_{t_{j+1}} - A_{t_j}] = Var[\frac{1}{2}(W_{t_{j+1}} - W_{t_j})] + Var[\frac{1}{2}(B_{t_{j+1}} - B_{t_j})] = \frac{1}{2}(t_{j+1} - t_j)$, A_t is not Brownian Motion

b). X, Y are martingales.

Yes

suppose $0 \leq s \leq t$ and $A(t) = \frac{1}{2}(X(t) + Y(t))$

$E[X(t) | F_s] = X(s)$, $E[Y(t) | F_s] = Y(s)$

thus, $E[A(t) | F_s] = E[\frac{1}{2}X(t) | F_s] + E[\frac{1}{2}Y(t) | F_s] = \frac{1}{2}(X(s) + Y(s)) = A(s)$

c) suppose, $Q_I = [X, X](T) = A$, $0 < A < \infty$, order.

No

Q_I is the first variation.

$Q_I = \sum_{k=0}^{n-1} |X_{t_{k+1}} - X_{t_k}|^2 \leq \max_{0 \leq k \leq n-1} |X_{t_{k+1}} - X_{t_k}| \cdot \sum_{k=0}^{n-1} |X_{t_{k+1}} - X_{t_k}|$

i). if X is continuous, $\max_{0 \leq k \leq n-1} |X_{t_{k+1}} - X_{t_k}|$ has the limit 0.

thus, $A = 0 \cdot Q_I$, $Q_I = \infty$.

ii). if X isn't continuous, that's false.

the counter example is $f(x) = \begin{cases} 0, & x \in [0, 1] \\ 1, & x \in [1, 2] \end{cases}$

~~that~~

Bonus Question. 3.5.

⑥

$$E[e^{-rT}(S_T - K)^+] = S[e^{-rT} \cdot S_T - K | S_T - K \geq 0]$$

$$\because S_T - K \geq 0 \rightarrow S_0 \cdot e^{(r - \frac{1}{2}\sigma^2)T + \sigma W(T)} - K \geq 0$$

$$W(T) > \frac{K}{S_0 \cdot e^{(r - \frac{1}{2}\sigma^2)T}}$$

$$W(T) > \frac{1}{\sigma} \left(\ln \frac{K}{S_0} - (r - \frac{1}{2}\sigma^2)T \right)$$

$$= d_1$$

$$\therefore E[e^{-rT}(S_T - K)^+] = \int_{d_1}^{\infty} (S_0 e^{(r - \frac{1}{2}\sigma^2)T + \sigma x} - K) \cdot e^{-\frac{x^2}{2}} \cdot \frac{1}{\sqrt{2\pi}} dx$$

$$= \frac{S_0}{\sqrt{2\pi}} \int_{d_1}^{\infty} e^{-\frac{(x - \sigma T)^2}{2}} dx - \frac{K \cdot e^{-rT}}{\sqrt{2\pi}} \int_{d_1}^{\infty} e^{-\frac{x^2}{2}} dx$$

$$\frac{d_1}{\sqrt{T}} - \sigma\sqrt{T} = \frac{1}{\sigma\sqrt{T}} \left[\ln \frac{S_0}{K} + (r + \frac{1}{2}\sigma^2)T \right] = -d_1(T, S_0),$$

$$\frac{-d_1}{\sqrt{T}} = \frac{1}{\sigma\sqrt{T}} \left[\ln \frac{S_0}{K} + (r - \frac{1}{2}\sigma^2)T \right] = d_1(T, S_0)$$

$$\therefore E[e^{-rT}(S_T - K)^+] = S_0 N(d_1(T, S_0)) - K e^{-rT} N(d_1(T, S_0))$$