Heston lidel

St = price

dSt = \mu St dt + \mathbb{V}_t St dUt

dVt = \mathbb{K}(\theta - \mathbb{V}_t) det \text{ONL} det

Eldwtdet = g dt

K = opted of hear rewron

or near verieion parameter

or = volotility of von ance

The = odyn for Xt

CIR model (Cox Ingeneral Poss)

dif = K(+-1/4)d++0/N/4 dz+

by

Verset-1/4 = K(+-1/4)d++0/N/4 +0/N/4 +0/N/4

Verset-1/4 = K(+-1/4)d++0/N/4

Verset-1/4 = K(

For CiR model please read lecture notes. AV+ = K(A-U+) d+ + 6 W+ d 2+

colable E(Vt) F(NS) V=-V0 = Str(0-10) do + JOYI d20 =(V+)-E(V.) = F(+(0-1/2)da) + 0 E(4)-E(4) = (E(4-4))

Elver - Me $\mu_{t} - \mu_{s} = \int \dot{k}(\theta - \mu_{s}) ds$ dux = k(t-M+) = first to get 1/2

de tk hade = k+ d+ et dynamics

i... etc

Hint for Vz

$$\frac{E(V_{t}|V_{0}) = 0}{E(S_{1}v_{1}+t) = y_{1}v_{2}} = 0$$

$$\frac{E(V_{t}|V_{0}) = 0}{E(S_{1}v_{1}+t) = y_{1}v_{2}} = 0$$

$$\frac{E(V_{t}|V_{0}) = 0}{E(S_{1}v_{1}+t)} = 0$$

$$\frac{E(V_{t}|V_{0}) = 0}{E(S_{1}v_{1}+t)}$$

- ru + (k(+-4)) 0 m = 0

SABR dSt= of St dlue dot = v of det

I can cont between 1 10

Option pria is given by plugging into the B-S forme a voletility value of some.

Option Seventinities
$$C(s,t,K,r,\sigma)$$

$$\delta = \frac{\partial C}{\partial s} = \frac{C(s,t,K,r,\sigma)}{\Delta s}$$

$$\delta = \frac{\partial C}{\partial s}(s) = \frac{C(s,t,\sigma)}{\Delta s}$$

Duadrature mitheda

Wethodology to opproximate a definite integral $dx_t = \mu(t, x_0) dt + \sigma(t, x_0) du_t$ price of an European type derivation is: $\mp(t, x_0) = \mp \left[e^{-\int_{t}^{T} r(t) dt} + \int_{t}^{T} r(t) dt + \int_{t}^{T} r(t)$

Problem: Comider T(f) = Sfa)dx

Det: A guadrature rule ef order nie au expression:

 $I_{n}(f) = \sum_{i=1}^{n} w_{i}^{n} f(x_{i}^{n})$

win= weight.

2in = guadrature rodes

工(中) _____ [中] 00 n-> 0

Baric rule of contracting a quadrature rule is - approximate of coing some attrobating function of (polynomials) o.t.

p(x;")=f(x;") frall x;"

- Integrate Ph and return I(R) as In year,

Restougle rule (ordro)

Ideo: opposinate f with piecewise content f

Ry = atuber = L

$$h = \frac{b-a}{n}$$
 $T_n(f) = \sum_{i=1}^{n} f(x_{i-i})$

Ifa=00 or b=00 we need or modification

2) there is nothing special about left have point

Midpoint rule

Inaperoid rule

$$\frac{\int_{a}^{b} (f) = \int_{a}^{b} \int_{a}^{b} \left(\frac{f(a) + f(a)}{2} \right) da = \int_{a}^{b} \left(\frac{f(a)}{2} + \frac{f(a)}{2} + \frac{f(a)}{2} \right) + \int_{a}^{b} \left(\frac{f(a)}{2} + \frac{f(a)}{2} + \frac{f(a)}{2} \right) + \int_{a}^{b} \left(\frac{f(a)}{2} + \frac{f(a)}{2} \right) + \int_$$

Use a guadratre polynomial

Construct a zudnoder polynomial So that $f(x_{i-1}) = P(x_{i-1})$ $f(x_{i}) = P(x_{i+1})$

They cause interpolating polynomials.

given (x_1, y_1) (x_2, y_2) - -- (x_k, y_k) $(x_1 \neq x_2 - + x_k)$ $(x_1 \neq x_2 - + x_1)$ $(x_1 \neq x_2 - + x_2)$ $(x_1 = x_1 + x_2)$ $(x_1 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_1 - x_2)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_2 - x_1)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_1 - x_2)$ $(x_2 = x_2 - x_1)$ $(x_1 = x_1 - x_2)$ $(x_1 = x_1 - x_2$