

Elementary Operations

There are three types of elementary operations on matrices.

1) Interchange of two rows/column

for ex:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow[e]{R_1 \leftrightarrow R_3} \begin{bmatrix} 7 & 8 & 9 \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{bmatrix} = e(A)$$

2) Multiplying a row/column by non-zero constant ($k \neq 0$)

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow[e]{R_3 \rightarrow 2R_3} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 14 & 16 & 18 \end{bmatrix}$$

↳ elementary row operation

3) Adding constant times of a row/column to another row/column

$$\begin{bmatrix} 1 & 0 & 1 \\ 2 & 3 & 5 \end{bmatrix} \xrightarrow[e]{C_2 \rightarrow C_2 + 2C_1} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 7 & 5 \end{bmatrix}$$

↳ elementary column operation

Does elementary operation change the determinant of matrix?

$$A \xrightarrow{e} e(A)$$

✓ e $R_i \leftrightarrow R_j$ $\det(e(A)) = -\det(A)$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \xrightarrow[e]{R_1 \leftrightarrow R_2} \begin{bmatrix} 3 & 4 \\ 1 & 2 \end{bmatrix} = e(A)$$

↳ $\det(e(A)) = 2$

$$\det(A) = -2$$

$\det(e(A)) =$

II) $R_i \rightarrow kR_i$ ($k \neq 0$)

$$\det(e(A)) = k \det(A)$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \xrightarrow[e]{R_1 \rightarrow 3R_1} \begin{bmatrix} 3 & 6 \\ 3 & 4 \end{bmatrix} = e(A)$$

↳ $\det(A) = -2$

↳ $\det(e(A)) = -6$

$$\text{III)} \quad \underline{R_i} \rightarrow \underline{R_i} + c \underline{R_j} \quad \checkmark$$

$$\det(e(A)) = \det(A)$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \xrightarrow[e]{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 1 & 2 \\ 2 & 2 \end{bmatrix} = e(A)$$

$$(_) \det(A) = -2$$

$$(_) \det(A) = -2$$

| e | Effect on determinant |
|-------------------------------------------|-----------------------------------------|
| $R_i \leftrightarrow R_j$ | $\det(e(A)) = -\det(A)$ |
| $R_i \rightarrow k R_j$ ($k \neq 0$) | $\det(e(A)) = k \det(A)$ ($k \neq 0$) |
| $R_i \rightarrow R_i + c R_j$ | $\det(e(A)) = \det(A)$ (No change) |

Suppose that

$$\det(A) \neq 0, \quad \det(e(A)) \neq 0$$

1. A is invertible then $e(A)$ is also invertible.

2.

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \xrightarrow[e]{R_1 \rightarrow R_1 + R_2} \begin{bmatrix} 4 & 6 \\ 3 & 4 \end{bmatrix} = e(A)$$

$$\xleftarrow[e']{R_1 \rightarrow R_1 - R_2}$$

$$e(A) = \begin{bmatrix} 4 & 6 \\ 3 & 4 \end{bmatrix} \xrightarrow[e']{R_1 \rightarrow R_1 - R_2} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = A$$

Thm.: Let e be any elementary row operation, then there exists

an elementary operation (e') {same type} such that

$$\underline{e}(e'(A)) = e'(e(A)) = A \quad \text{for any matrix } A$$

Further, e' is called inverse elementary row operation of e .

Proof. Case-I) Suppose e is the elementary row operation that interchange row i by row j

$$e: (R_i \leftrightarrow R_j)$$

e' can be considered same as e . ($e' = e$)

$$\text{So that, } ee'(A) = e'e(A)$$

$$e'(e(A)) = A$$

e' can be considered same as e . ($e = e'$)

So that, $ee'(A) = e'e(A)$

$$e'(e(A)) = A$$

$e' = e$ { self invertible row elementary inverse }

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \xrightarrow[e]{R_1 \leftrightarrow R_2} \begin{bmatrix} 4 & 5 & 6 \\ 1 & 2 & 3 \end{bmatrix} = e(A)$$

$$\xrightarrow[e]{e} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

Case II) Suppose e is the elementary row operation which multiplies i th row by a non-zero constant ($k \neq 0$)

$$e := (R_i \rightarrow kR_i)$$

So, e' can be considered as row operation which multiplies

i th row by $\frac{1}{k}$ ($k \neq 0$)

$$e' := (R_i \rightarrow \frac{1}{k} \cdot R_i)$$

Thus, $ee'(A) = e'e(A) = A$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow[e]{R_3 \rightarrow 2R_3} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 14 & 16 & 18 \end{bmatrix} = e(A)$$

$$\xrightarrow[e]{R_3 \rightarrow \frac{1}{2} \cdot R_3} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

Case-III, let e be elementary row operation which adds c times row j to row i .
 $e := (R_i \rightarrow R_i + cR_j)$

so, e' can be considered as elementary operation which subtract c times row j from i

$$e' := (R_i \rightarrow R_i - cR_j)$$

So, that $ee'(A) = e'e(A) = A$

| e | $e^{-1} = e'$ |
|------------------------------------------|-----------------------------------------|
| $R_i \leftrightarrow R_j$ | $R_i \leftrightarrow R_j$ |
| $R_i \rightarrow kR_j$ ($k \neq 0$) | $R_i \rightarrow \frac{1}{k} \cdot R_j$ |
| $R_i \rightarrow R_i + cR_j$ | $R_i \rightarrow R_i - cR_j$ |

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \xrightarrow[e]{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 1 & 2 & 3 \\ 3 & 3 & 3 \end{bmatrix} = e(A)$$

$$\xrightarrow[e]{R_2 \rightarrow R_2 + R_1} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

Defⁿ: Row equivalence

A matrix A is said to be row equivalent to matrix B if matrix B can be obtained by a finite number of elementary row operations on A.

$$A \xrightarrow{e_1} e_1(A) \xrightarrow{e_2} e_2(e_1(A)) \longrightarrow \dots \xrightarrow{e_n} e_n(e_{n-1}(\dots e_3(e_2(e_1(A)))) = B$$

In other words,

B can be written as

$$B = \underbrace{e_n e_{n-1} e_{n-2} \dots e_3 e_2 e_1(A)}_{\downarrow \text{ n times elementary operation}}$$

$$\boxed{A \sim B}$$

Prop Is \sim (row equivalence) an equivalence relation?

Yes,

1) Reflexive

for any matrix A, $A \sim A$.

As $\boxed{e_1: R_1 \rightarrow R_1 + 0R_2}$ $e_2: R_1 \rightarrow \textcircled{1} R_1$ k=1

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow[e_1]{R_1 \rightarrow R_1 + 0R_2} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = e_1(A)$$

↳ elementary row operation

$A \sim A$ so, \sim is reflexive,

2) Symmetric,

Suppose A is row equivalent to B i.e. $A \sim B$

We need to show: $B \sim A$.

So, B can be obtained by finite (n numbers) of elementary row operation on A.

i.e. $\boxed{B = e_n e_{n-1} e_{n-2} \dots e_3 e_2 e_1(A)}$ $\xrightarrow{\textcircled{1}}$

$$\textcircled{A} \xrightarrow{e_1} e_1(A) \xrightarrow{e_2} e_2(e_1(A)) \longrightarrow \dots \xrightarrow{e_n} \textcircled{B}$$

Now, To show: A can be obtained by applying elementary row operation on B.

So, consider e_k^{-1} be the inverse elementary row operation of each e_k for $k=1, 2, 3, \dots, n$.

eg (1) $B = e_n e_{n-1} e_{n-2} \dots e_3 e_2 e_1 (A)$

Applying e_n^{-1}

$$e_n^{-1}(B) = \underbrace{e_n^{-1}(e_n)}_{=I} e_{n-1} e_{n-2} \dots e_3 e_2 e_1 (A)$$

$$e_n^{-1}(B) = e_{n-1} e_{n-2} \dots e_3 e_2 e_1 (A)$$

Again applying e_{n-1}^{-1}

$$e_{n-1}^{-1}(e_n^{-1}B) = \underbrace{e_{n-1}^{-1}(e_{n-1})}_{=I} \dots e_3 e_2 e_1 (A)$$

Similarly,

$$\underbrace{e_1^{-1} e_2^{-1} e_3^{-1} \dots e_{n-1}^{-1} e_n^{-1}}_{\text{finite (n) elementary operations}} (B) = \underbrace{(A)}_{B \sim A}$$

\hookrightarrow finite (n) elementary operations

So, A can be obtained by finite number of elementary operations on B.

$$\text{So, } B \sim A$$

This mean, \sim is symmetric relation.

3) Transitivity

Suppose A, B and C are three matrices such that

$$A \sim B, B \sim C$$

To show: $A \sim C$

$$B = \underbrace{e_n e_{n-1} e_{n-2} \dots e_3 e_2 e_1}_{\text{finite number of elementary operations on A}} (A) \quad \text{--- (1)}$$

\hookrightarrow n (finite) number of elementary operations on A

$$C = \underbrace{f_m f_{m-1} f_{m-2} \dots f_3 f_2 f_1}_{\text{finite number of elementary operations on B}} (B) \quad \text{--- (2)}$$

\hookrightarrow m (finite) number of elementary operations on B.

Substitute value of B from eq (1) to eq (2).

$$C = \underbrace{f_m f_{m-1} f_{m-2} \dots f_3 f_2 f_1 (e_n e_{n-1} e_{n-2} \dots e_3 e_2 e_1 (A))}_{\text{(m+n) finite number of elementary operations on A}}$$

\hookrightarrow (m+n) finite number of elementary operations on A

$$\boxed{A \sim C}$$

\sim is a transitive relation.

$$\boxed{A \sim C}$$

\sim is a transitive relation.

As, \sim is reflexive, symmetric and transitive

Thus, \sim is an equivalence relation.

Defⁿ

An Elementary Matrix is a square matrix obtained by applying a single elementary row operation on identity matrix.

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow[e]{R_2 \rightarrow 2 \cdot R_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} = e(I_3)$$

\hookrightarrow elementary row operation \hookrightarrow Elementary Matrix corresponding to elementary operation e

$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow[e]{R_2 \rightarrow R_2 + 2R_1} \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} = e(I_2)$$

\hookrightarrow elementary row operation \hookrightarrow Elementary matrix

Notation: $e(I) \rightarrow$ where e denotes elementary operation &
 I is the identity matrix.

Properties . .

1) Elementary matrix is invertible.

$$I_n = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} \xrightarrow[e]{} \begin{bmatrix} \quad \quad \quad \end{bmatrix} e(I)$$

$\hookrightarrow \det(I_n) = 1$ $\hookrightarrow \det(e(I))$

$$\text{Either } \det(e(I)) = -\det(I_n) = -1$$

$$\text{or } \det(e(I)) = k \cdot \det(I_n) = k \neq 0$$

In each of the case, $\det(e(I)) \neq 0$

$\det(e(I)) \neq 0 \Rightarrow e(I)$ Elementary matrix is invertible.

*Thm: Inverse of the elementary matrix is an elementary matrix.

Proof-