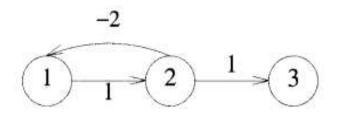
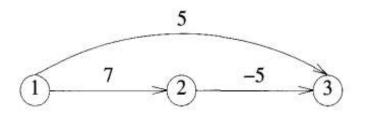
# Bellman-Ford algorithm - Single-source shortest paths

### Bellman-Ford algorithm

- Single-source shortest paths
- Handling negative-weight cycles and negative edges





Graph with negative cycle

Directed graph with a negative-length edge

#### Bellman & Ford



Richard E. Bellman (1920-1984) IEEE Medal of Honor, 1979

http://www.amazon.com/Bellman-Continuum-Collection-Works-Richard/dp/9971500906



Lester R. Ford, Jr. (1927-) president of MAA, 1947-48

http://www.maa.org/aboutmaa/maaapresidents.html

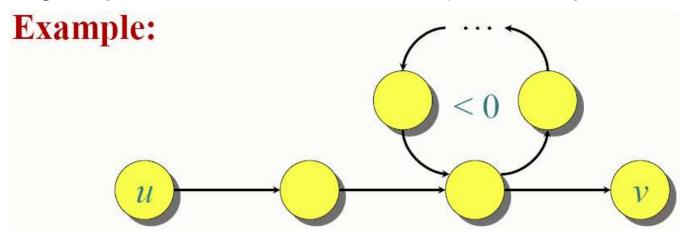
#### **Bellman-Ford in Practice**

- Distance-vector routing protocol
  - Repeatedly relaxedges until convergence
  - Relaxation is local!
- On the Internet:
  - Routing InformationProtocol (RIP)
  - Interior Gateway Routing Protocol (IGRP)



#### **Negative-weight cycles**

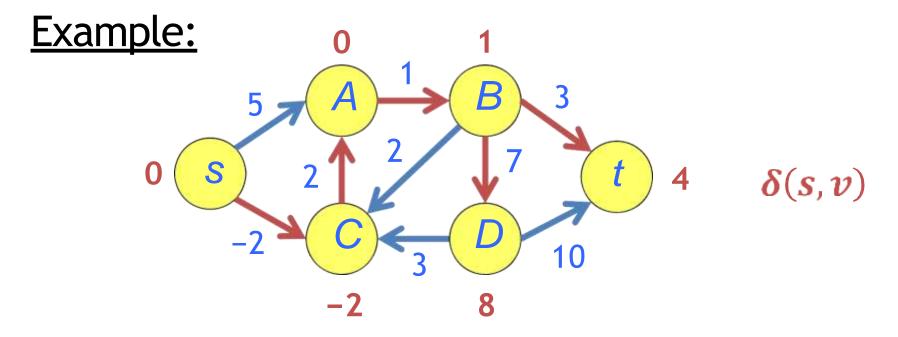
**Recall:** If a graph G = (V, E) contains a negative-weight cycle, then some shortest paths may not exist.

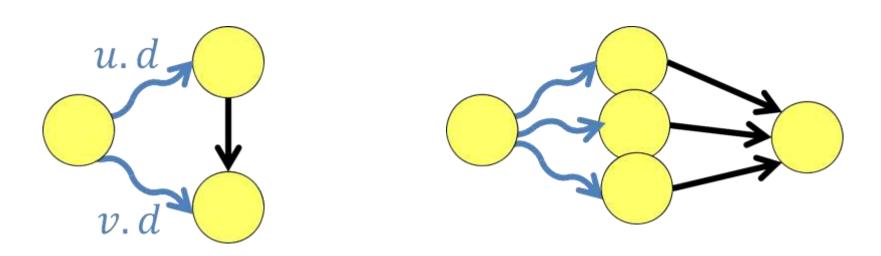


**Bellman-Ford algorithm:** Finds all shortest-path lengths from a **source**  $s \in V$  to all  $v \in V$  or determines that a negative-weight cycle exists.

## Recall: Single-Source Shortest Paths

- Problem: Given a directed graph G = (V, E) with edge-weight function  $w : E \to \mathbb{R}$ , and a source vertex s, compute  $\delta(s, v)$  for all  $v \in V$ 
  - Also want shortest-path tree represented by v.  $\pi$





When there are no cycles of negative length, there is a shortest path between any two vertices of an n-vertex graph that has at most n -1 edges on it

a path that has more than n-1 edges must repeat at least one vertex and hence must contain a cycle.

Let  $dist^{\ell}[u]$  be the length of a shortest path from the source vertex v to vertex u under the constraint that the shortest path contains at most  $\ell$  edges. Then,  $dist^{1}[u] = cost[v, u], 1 \le u \le n$ . As noted earlier, when there are no cycles of negative length, we can limit our search for shortest paths to paths with at most n-1 edges. Hence,  $dist^{n-1}[u]$  is the length of an unrestricted shortest path from v to u.

Our goal then is to compute  $dist^{n-1}[u]$  for all u. This can be done using the dynamic programming methodology. First, we make the following observations:

- 1. If the shortest path from v to u with at most k, k > 1, edges has no more than k-1 edges, then  $dist^k[u] = dist^{k-1}[u]$ .
- 2. If the shortest path from v to u with at most k, k > 1, edges has exactly k edges, then it is made up of a shortest path from v to some vertex j followed by the edge  $\langle j, u \rangle$ . The path from v to j has k-1 edges, and its length is  $dist^{k-1}[j]$ . All vertices i such that the edge  $\langle i, u \rangle$  is in the graph are candidates for j. Since we are interested in a shortest path, the i that minimizes  $dist^{k-1}[i] + cost[i, u]$  is the correct value for j.

These observations result in the following recurrence for dist:

$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\}$$

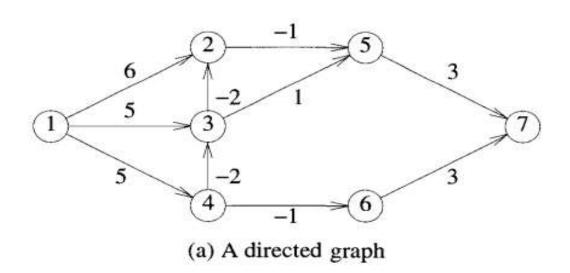
This recurrence can be used to compute  $dist^k$  from  $dist^{k-1}$ , for  $k=2,3,\ldots, n-1$ .

```
Algorithm BellmanFord(v, cost, dist, n)

    \begin{array}{r}
      23456789
    \end{array}

     // Single-source/all-destinations shortest
     // paths with negative edge costs
          for i := 1 to n do // Initialize dist.
               dist[i] := cost[v, i];
          for k := 2 to n-1 do
                for each u such that u \neq v and u has
                          at least one incoming edge do
                     for each \langle i, u \rangle in the graph do
10
                          if dist[u] > dist[i] + cost[i, u] then
11
                               dist[u] := dist[i] + cost[i, u];
12
13
```

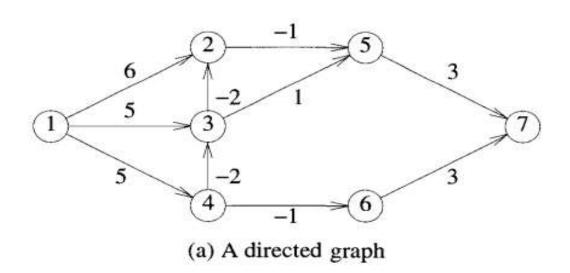
Bellman and Ford algorithm to compute shortest paths



			dis	$t^k[1$	7]		
k	1	2	3	4	5	6	7
1	0	6	5	5	∞	∞	∞
2	0	3	3	5	5	4	∞
3	0	1	3	5	2	4	7
4	0	1	3	5	0	4	5
5	0	1	3	5	0	4	3
6	0	1	3	5	0	4	3

(b) distk

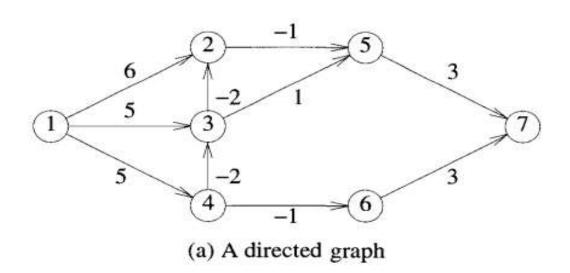
$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$$



			dis	$t^k[1$	7]		
k	1	2	3	4	5	6	7
1	0	6	5	5	∞	∞	∞
2	0	3	3	5	5	4	∞
3	0	1	3	5	2	4	7
4	0	1	3	5	0	4	5
5	0	1	3	5	0	4	3
6	0	1	3	5	0	4	3

(b) distk

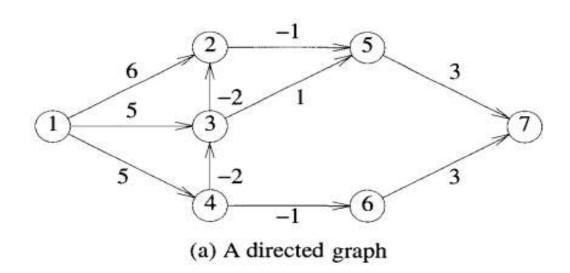
$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$$



			dis	$t^k[1$	7]		
k	1	2	3	4	5	6	7
1	0	6	5	5	∞	∞	∞
2	0	3	3	5	5	4	∞
3	0	1	3	5	2	4	7
4	0	1	3	5	0	4	5
5	0	1	3	5	0	4	3
6	0	1	3	5	0	4	3

(b) distk

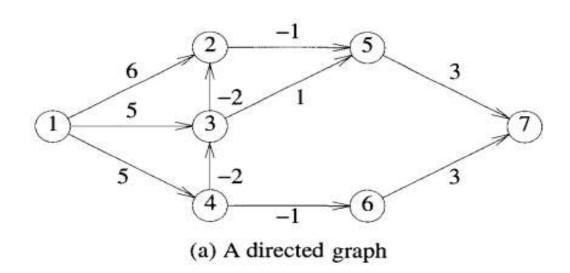
$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$$



			dis	$t^k[1$	7]		
k	1	2	3	4	5	6	7
1	0	6	5	5	∞	∞	∞
2	0	3	3	5	5	4	∞
3	0	1	3	5	2	4	7
4	0	1	3	5	0	4	5
5	0	1	3	5	0	4	3
6	0	1	3	5	0	4	3

(b) distk

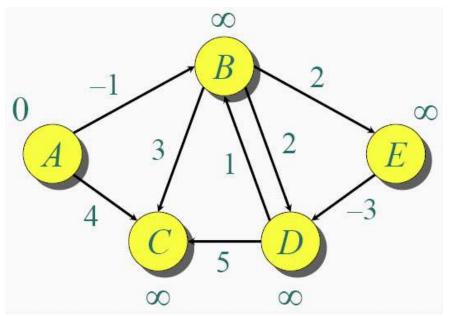
$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$$

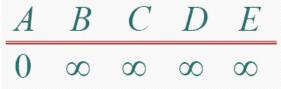


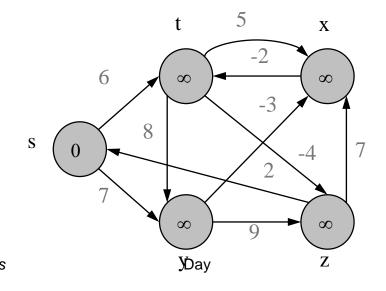
			dis	$t^k[1$	7]		
k	1	2	3	4	5	6	7
1	0	6	5	5	∞	∞	∞
2	0	3	3	5	5	4	∞
3	0	1	3	5	2	4	7
4	0	1	3	5	0	4	5
5	0	1	3	5	0	4	3
6	0	1	3	5	0	4	3

(b) distk

$$dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$$







© 2001 by Charles E. Leiserson 31 L18.

Introduction to Algorithms

 $dist^k[u] \ = \ \min \ \{dist^{k-1}[u], \ \min_i \ \{dist^{k-1}[i] \ + \ cost[i,u]\}\} \ \ k = 2,3,\ldots, \ n-1.$ 

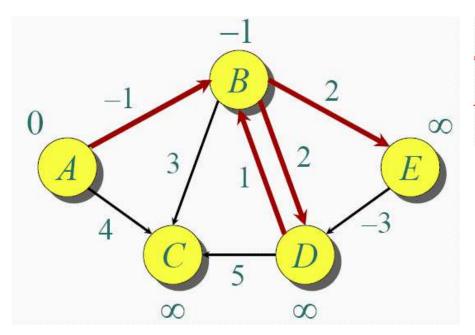
	Α	В	С	D	E
Α	0	-1	4	8	8
В	∞	0	3	2	2
С	8	8	0	8	8
D	∞	1	5	0	~
E	∞	8	∞	-3	0

	Α	В	С	D	E
Α	0	-1	4	8	8
В	8	0	3	2	2
С	8	8	0	8	8
D	8	1	5	0	8
E	8	∞	∞	-3	0

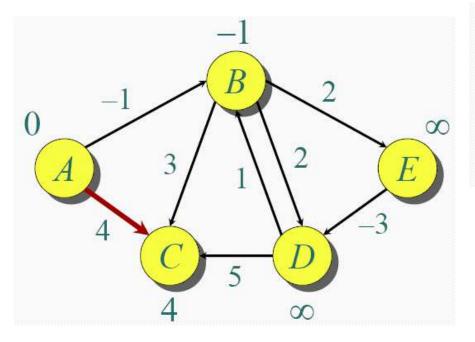
	Α	В	С	D	E
Α	0	-1	4	8	8
В	8	0	3	2	2
С	8	8	0	8	8
D	8	1	5	0	8
E	8	8	8	-3	0

	Α	В	С	D	E
Α	0	-1	4	8	8
В	8	0	3	2	2
С	8	8	0	8	∞
D	8	1	5	0	∞
E	8	8	8	-1	0

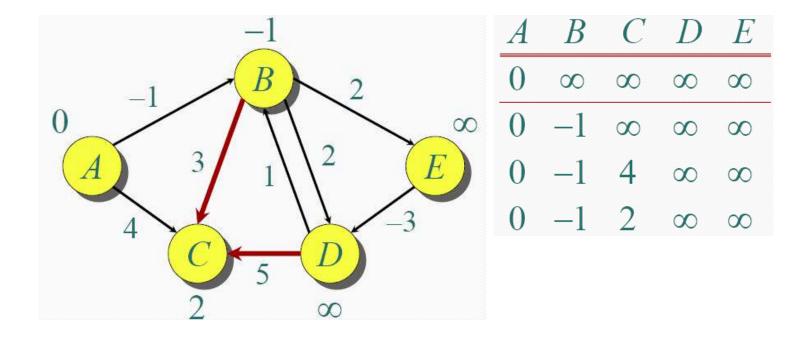
	Α	В	С	D	E
Α	0	-1	4	8	8
В	8	0	3	2	2
С	8	8	0	8	8
D	8	1	5	0	8
E	8	8	8	-3	0

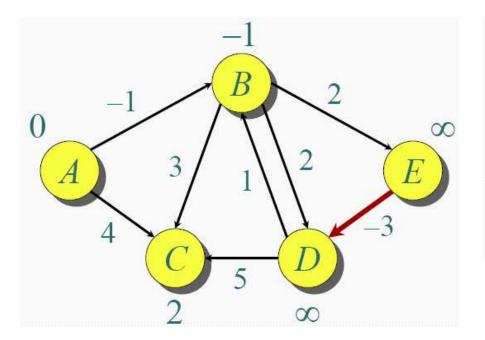


A	В	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$

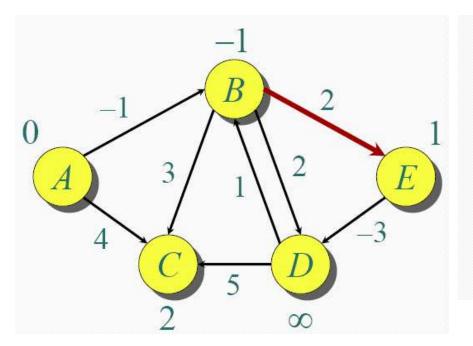


$\boldsymbol{A}$	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$

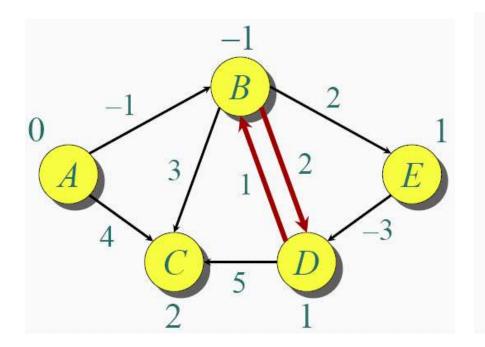




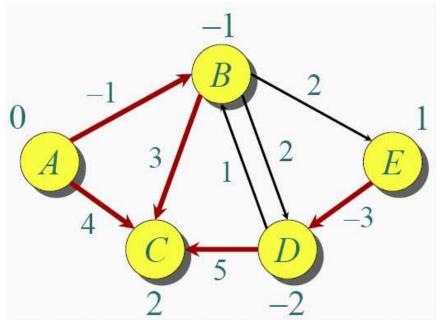
$\boldsymbol{A}$	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$



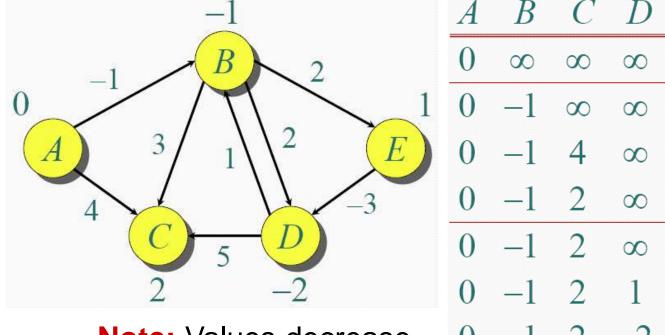
A	В	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1



A	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1
0	-1	2	1	1



$\boldsymbol{A}$	B	C	D	$E_{\perp}$
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1
0	-1	2	1	1
0	-1	2	-2	1



**Note:** Values decrease monotonically.

