

华南理工大学

《深度学习与神经网络》课程实验报告

实验题目： 第二次作业

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班级： 计科 2 组别：

合作者：

指导教师： 马千里

实验概述

【实验目的及要求】

- 一、 变分自编码器生成 MNIST 手写数字卷积神经网络用于 MNIST 手写数字数据集分类（提交实现步骤描述以及下面要求提交的结果）
- 二、 循环神经网络用于多变量时间序列预测任务（结合代码 描述实现步骤以及 交下面要求 交的结果）

【实验环境】

操作系统： Windows win 10 Google Colab

实验内容

【实验过程】

小结

本次作业第一问依旧使用 **tensorflow** 来构造神经网络进行预测，第一问使用 **MINIST** 手写数据集，构建了任务要求的编码器和解码器，最后通过随机生成祭祖均值和标准差，通过解码器实现图像的生成，并画出了损失随着迭代的变化图。

第二问要求实现时间序列的预测，经过模板给出的预处理，我使用了 **keras** 构建了 **SimpleRNN** 神经网络，使用了 **Adam** 的优化器，损失函数为 **MAE**，经过训练之后，画出了训练集和测试集的损失随迭代次数的变化图，并挑选了两个预测进行展示、画出了测试机的预测图像，可见模型在预测整体变化趋势上有较好的表现。加分项：使用了不同 优化器。

第一问分别使用了 **GPU** 环境和无 **GPU** 环境，有 **GPU** 运行速度明显提升。

指导教师评语及成绩

评语：

成绩： 指导教师签名：
批阅日期：

```
In [10]: %tensorflow_version 1.x
```

Q1

```
In [11]: import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import norm
import tensorflow as tf
```

```
In [12]: # Import MNIST data
from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets("/tmp/data/", one_hot=True)
```

Extracting /tmp/data/train-images-idx3-ubyte.gz
 Extracting /tmp/data/train-labels-idx1-ubyte.gz
 Extracting /tmp/data/t10k-images-idx3-ubyte.gz
 Extracting /tmp/data/t10k-labels-idx1-ubyte.gz

```
In [13]: # Parameters
learning_rate = 0.0001
num_steps = 10000
batch_size = 100

# Network Parameters
image_dim = 784 # 输入图片维度 784
hiddenReLU_dim = 256 # 隐藏层 (ReLU) 256
hiddenTanh_dim = 512 # 输出层维度 (Tanh) 512
hidden_dim = 512
latent_dim = 2

# A custom initialization (see Xavier Glorot init)
def glorot_init(shape):
    return tf.random_normal(shape=shape, stddev=1. / tf.sqrt(shape[0] / 2.))
```

```
In [14]: # Variables
weights = {
    # 编码器 (全连接层)
    # 隐藏层 (ReLU) 256
    'encoder_ReLU': tf.Variable(glorot_init([image_dim, hiddenReLU_dim])),
    # 输出层维度 (Tanh) 512
    'encoder_Tanh': tf.Variable(glorot_init([hiddenReLU_dim, hiddenTanh_dim])),
    # 生成均值 (全连接层)
    # 输入层维度 512 输出层维度 2
    'z_mean': tf.Variable(glorot_init([hiddenTanh_dim, latent_dim])),
    # 生成标准差
    # 输入层维度 512 输出层维度 2
    'z_std': tf.Variable(glorot_init([hiddenTanh_dim, latent_dim])),
    # 解码器
    # 输入维度 2 隐藏层维度ReLU 512
    'decoder_h1': tf.Variable(glorot_init([latent_dim, hidden_dim])),
    # 输出层维度 784
    'decoder_out': tf.Variable(glorot_init([hidden_dim, image_dim]))
}
biases = {
    # 编码器 (全连接层)
    # 隐藏层 (ReLU) 256
    'encoder_ReLU_b': tf.Variable(glorot_init([hiddenReLU_dim])),
    # 输出层维度 (Tanh) 512
    'encoder_Tanh_b': tf.Variable(glorot_init([hiddenTanh_dim])),
    # 生成均值 (全连接层)
    # 输出层维度 2
    'z_mean_b': tf.Variable(glorot_init([latent_dim])),
    'z_std_b': tf.Variable(glorot_init([latent_dim])),
    # 解码器
    # 输入维度 2 隐藏层维度ReLU 512
    'decoder_h1_b': tf.Variable(glorot_init([latent_dim])),
    # 输出层维度 784
    'decoder_out_b': tf.Variable(glorot_init([hidden_dim]))
}
```

```

'z_mean': tf.Variable(glorot_init([latent_dim])),
#生成标准差
#输出层维度 2
'z_std': tf.Variable(glorot_init([latent_dim])),
#解码器
#隐藏层维度ReLU 512
'decoder_b1': tf.Variable(glorot_init([hidden_dim])),
#输出层维度 784
'decoder_out': tf.Variable(glorot_init([image_dim]))
}

```

```

In [15]: # 构建编码器
input_image = tf.placeholder(tf.float32, shape=[None, image_dim])
#ReLU隐藏层
encoder1 = tf.matmul(input_image, weights['encoder_ReLU']) + biases['encoder_ReLU_b']
encoder2 = tf.nn.relu(encoder1)
#Tanh输出层
encoder3 = tf.matmul(encoder2, weights['encoder_Tanh']) + biases['encoder_Tanh_b']
encoder4 = tf.nn.tanh(encoder3)
#生成均值和标准差
z_mean = tf.matmul(encoder4, weights['z_mean']) + biases['z_mean']
z_std = tf.matmul(encoder4, weights['z_std']) + biases['z_std']

# 抽样: 再参数化技巧
eps = tf.random_normal(tf.shape(z_std), dtype=tf.float32, mean=0., stddev=1.0,
                        name='epsilon')

# 使用均值和标准差生成隐变量
z = z_mean + tf.exp(z_std / 2) * eps

# 构建解码器
decoder = tf.matmul(z, weights['decoder_h1']) + biases['decoder_b1']
decoder = tf.nn.relu(decoder)
decoder = tf.matmul(decoder, weights['decoder_out']) + biases['decoder_out']
decoder = tf.nn.sigmoid(decoder)

```

```

In [16]: #Loss
def vae_loss(x_reconstructed, x_true):
    # x_reconstructed = tf.nn.sigmoid(x_reconstructed)
    # 重构损失 Reconstruction Loss
    encode_decode_loss = tf.reduce_sum(tf.square(x_true - x_reconstructed), reduction)
    # 正则化损失 KL Divergence Loss
    kl_div_loss = 1 + z_std - tf.square(z_mean) - tf.exp(z_std)
    kl_div_loss = -0.5 * tf.reduce_sum(kl_div_loss, 1)
    return tf.reduce_mean(encode_decode_loss + kl_div_loss)

loss_op = vae_loss(decoder, input_image)
optimizer = tf.train.RMSPropOptimizer(learning_rate=learning_rate)
train_op = optimizer.minimize(loss_op)

# 初始化变量
init = tf.global_variables_initializer()

```

```

In [ ]: import time

time_start=time.time()

sess = tf.Session()

sess.run(init)

# Training

```

```

for i in range(1, num_steps+1):
    # 取样本 (only images are needed, not labels)
    batch_x, _ = mnist.train.next_batch(batch_size)

    # 训练
    feed_dict = {input_image: batch_x}
    _, l = sess.run([train_op, loss_op], feed_dict=feed_dict)
    if i % 1000 == 0 or i == 1:
        print('Step %i, Loss: %f' % (i, l))
    time_end=time.time()

print('time cost',time_end-time_start,'s')

```

```

Step 1, Loss: 280.936920
Step 1000, Loss: 47.046036
Step 2000, Loss: 44.097431
Step 3000, Loss: 44.130878
Step 4000, Loss: 41.943974
Step 5000, Loss: 41.999428
Step 6000, Loss: 42.996471
Step 7000, Loss: 41.839912
Step 8000, Loss: 43.359318
Step 9000, Loss: 43.261772
Step 10000, Loss: 39.034519
time cost 121.42035102844238 s

```

```

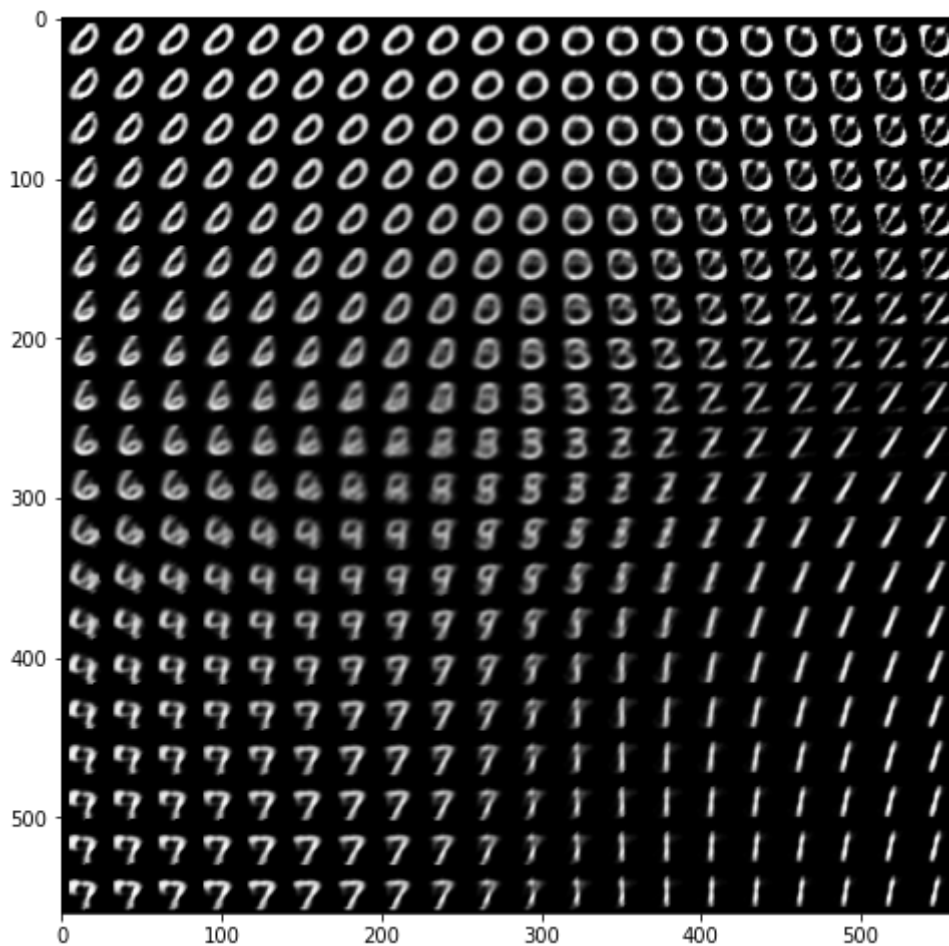
In [ ]: # Testing
# Generator takes noise as input
noise_input = tf.placeholder(tf.float32, shape=[None, latent_dim])
# Rebuild the decoder to create image from noise
decoder = tf.matmul(noise_input, weights['decoder_h1']) + biases['decoder_b1']
decoder = tf.nn.relu(decoder)
decoder = tf.matmul(decoder, weights['decoder_out']) + biases['decoder_out']
decoder = tf.nn.sigmoid(decoder)

# Building a manifold of generated digits
n = 20
x_axis = np.linspace(-3, 3, n)
y_axis = np.linspace(-3, 3, n)

canvas = np.empty((28 * n, 28 * n))
for i, yi in enumerate(x_axis):
    for j, xi in enumerate(y_axis):
        z_mu = np.array([[xi, yi]] * batch_size)
        x_mean = sess.run(decoder, feed_dict={noise_input: z_mu})
        canvas[(n - i - 1) * 28:(n - i) * 28, j * 28:(j + 1) * 28] = \
            x_mean[0].reshape(28, 28)

plt.figure(figsize=(8, 10))
Xi, Yi = np.meshgrid(x_axis, y_axis)
plt.imshow(canvas, origin="upper", cmap="gray")
plt.show()

```



Q1 Using ****GPU****

```
In [20]: import time

time_start=time.time()

loss_list = []

sess = tf.Session()

sess.run(init)

# Training
for i in range(1, num_steps+1):
    # 取样本 (only images are needed, not labels)
    batch_x, _ = mnist.train.next_batch(batch_size)

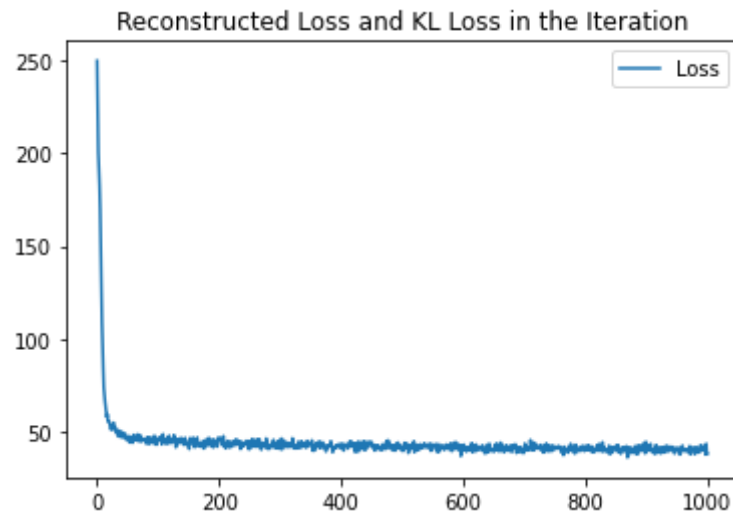
    # 训练
    feed_dict = {input_image: batch_x}
    _, l = sess.run([train_op, loss_op], feed_dict=feed_dict)
    if i % 10 == 0 or i == 1:
        loss_list.append(l)
    if i % 1000 == 0 or i == 1:
        print('Step %i, Loss: %f' % (i, l))
time_end=time.time()
plt.plot(loss_list,label = 'Loss')
plt.title('Reconstructed Loss and KL Loss in the Iteration')
plt.legend()
print('time cost',time_end-time_start,'s')
```

Step 1, Loss: 249.533813
Step 1000, Loss: 46.827553

```

Step 2000, Loss: 45.874405
Step 3000, Loss: 44.098644
Step 4000, Loss: 44.003437
Step 5000, Loss: 42.423561
Step 6000, Loss: 40.928410
Step 7000, Loss: 41.985580
Step 8000, Loss: 42.605621
Step 9000, Loss: 43.384979
Step 10000, Loss: 38.534336
time cost 22.448995351791382 s

```



对比未使用 ****GPU**** 使用了GPU明显速度加快，运行VAE只需要21s

```

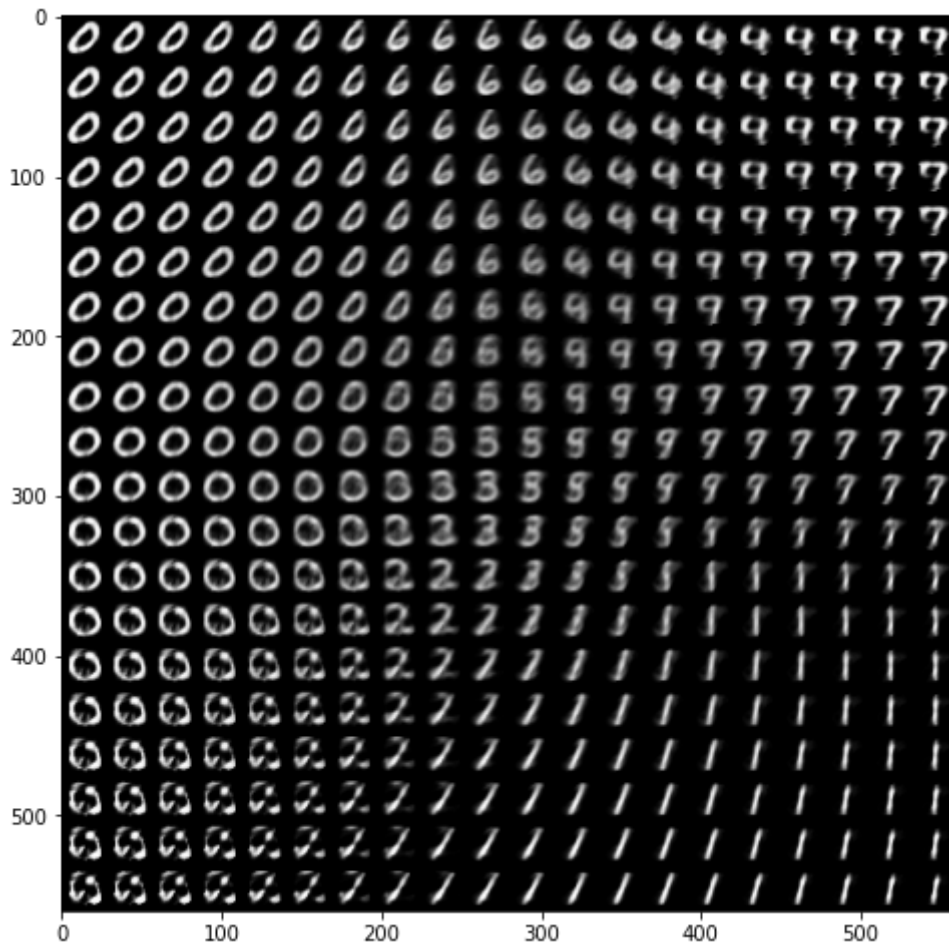
In [ ]: # Testing
# Generator takes noise as input
noise_input = tf.placeholder(tf.float32, shape=[None, latent_dim])
# Rebuild the decoder to create image from noise
decoder = tf.matmul(noise_input, weights['decoder_h1']) + biases['decoder_b1']
decoder = tf.nn.relu(decoder)
decoder = tf.matmul(decoder, weights['decoder_out']) + biases['decoder_out']
decoder = tf.nn.sigmoid(decoder)

# Building a manifold of generated digits
n = 20
x_axis = np.linspace(-3, 3, n)
y_axis = np.linspace(-3, 3, n)

canvas = np.empty((28 * n, 28 * n))
for i, yi in enumerate(x_axis):
    for j, xi in enumerate(y_axis):
        z_mu = np.array([[xi, yi]] * batch_size)
        x_mean = sess.run(decoder, feed_dict={noise_input: z_mu})
        canvas[(n - i - 1) * 28:(n - i) * 28, j * 28:(j + 1) * 28] = \
            x_mean[0].reshape(28, 28)

plt.figure(figsize=(8, 10))
Xi, Yi = np.meshgrid(x_axis, y_axis)
plt.imshow(canvas, origin="upper", cmap="gray")
plt.show()

```



Q2

```
In [ ]: import pandas as pd
import tensorflow as tf
from pandas import read_csv
from datetime import datetime
from sklearn.preprocessing import LabelEncoder, MinMaxScaler
import numpy as np
import matplotlib.pyplot as plt
from math import sqrt
from sklearn.metrics import mean_squared_error
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import LSTM
from keras.layers import SimpleRNN

def parse(x):
    return datetime.strptime(x, '%Y %m %d %H')

...
异常值处理
...

dataset = read_csv('PRSA_data_2010.1.1-2014.12.31.csv', parse_dates = [['year', 'mo
dataset.drop('No', axis=1, inplace=True)
dataset.columns = ['pollution', 'dew', 'temp', 'press', 'wnd_dir', 'wnd_spd', 'snow'
dataset.index.name = 'date'
dataset['pollution'].fillna(0, inplace=True)
dataset = dataset[24:]

...
从数据到数据集构建
```

```

'''
def series_to_supervised(data, n_in=1, n_out=1, dropnan=True):
    n_vars = 1 if type(data) is list else data.shape[1]
    df = pd.DataFrame(data)
    cols, names = list(), list()
    # 输入序列构建
    for i in range(n_in, 0, -1):
        cols.append(df.shift(i))
        names += [('value%d(t-%d)' % (j+1, i)) for j in range(n_vars)]
    # 输出序列构建
    for i in range(0, n_out):
        cols.append(df.shift(-i))
        if i == 0:
            names += [('value%d(t)' % (j+1)) for j in range(n_vars)]
        else:
            names += [('value%d(t+%d)' % (j+1, i)) for j in range(n_vars)]
    # 数据拼接
    agg = pd.concat(cols, axis=1)
    agg.columns = names
    # 异常值处理
    if dropnan:
        agg.dropna(inplace=True)
    return agg

values = dataset.values
# 标签one hot化
encoder = LabelEncoder()
values[:,4] = encoder.fit_transform(values[:,4])
values = values.astype('float32')
# 归一化特征
scaler = MinMaxScaler(feature_range=(0, 1))
scaled = scaler.fit_transform(values)
# 数据集构建
reframed = series_to_supervised(scaled, 2, 1)
# 去除当前时刻的天气数据
reframed.drop(reframed.columns[[17,18,19,20,21,22,23]], axis=1, inplace=True)
reframed.to_csv('dataset.csv')
print(reframed.head())

'''
数据集划分, 使用前三年的数据训练, 其他的数据测试
'''
values = reframed.values
n_train_hours = 365 * 24 * 3
train = values[:n_train_hours, :]
test = values[n_train_hours:, :]
train_X, train_y = train[:, :-1], train[:, -1]
test_X, test_y = test[:, :-1], test[:, -1]
# 数据格式 [samples, timesteps, features]
train_X = train_X.reshape((train_X.shape[0], 1, train_X.shape[1]))
test_X = test_X.reshape((test_X.shape[0], 1, test_X.shape[1]))
print(train_X.shape, train_y.shape, test_X.shape, test_y.shape)

```

	value1(t-2)	value2(t-2)	value3(t-2)	...	value7(t-1)	value8(t-1)	value1(t)
2	0.129779	0.352941	0.245902	...	0.000000	0.0	0.159960
3	0.148893	0.367647	0.245902	...	0.000000	0.0	0.182093
4	0.159960	0.426471	0.229508	...	0.037037	0.0	0.138833
5	0.182093	0.485294	0.229508	...	0.074074	0.0	0.109658
6	0.138833	0.485294	0.229508	...	0.111111	0.0	0.105634

```

[5 rows x 17 columns]
(26280, 1, 16) (26280,) (17518, 1, 16) (17518,)

```

In []:

```

'''
模型构建
'''

```



```

model = Sequential()
model.add(SimpleRNN(units=100, activation='softmax', return_sequences=True, input_shape=(1, 100)))
model.add(Dense(1))
model.compile(loss='mae', optimizer='adam', metrics=['accuracy'])
print(model.summary())
# 训练模型

history = model.fit(train_X, train_y, epochs=50, batch_size=72, validation_data=(test_X, test_y))
# 对损失进行可视化
plt.plot(history.history['loss'], label='train')
plt.plot(history.history['val_loss'], label='test')
plt.legend()
plt.show()

```

Model: "sequential_1"

Layer (type)	Output Shape	Param #
=====		
simple_rnn_1 (SimpleRNN)	(None, 1, 100)	11700
dense_1 (Dense)	(None, 1, 1)	101
=====		

Total params: 11,801
 Trainable params: 11,801
 Non-trainable params: 0

None

Epoch 1/50

365/365 [=====] - 1s 2ms/step - loss: 0.0576 - accuracy: 0.0709 - val_loss: 0.0524 - val_accuracy: 0.0103

Epoch 2/50

365/365 [=====] - 1s 2ms/step - loss: 0.0372 - accuracy: 0.0709 - val_loss: 0.0247 - val_accuracy: 0.0103

Epoch 3/50

365/365 [=====] - 1s 2ms/step - loss: 0.0186 - accuracy: 0.0709 - val_loss: 0.0172 - val_accuracy: 0.0103

Epoch 4/50

365/365 [=====] - 1s 2ms/step - loss: 0.0163 - accuracy: 0.0709 - val_loss: 0.0162 - val_accuracy: 0.0103

Epoch 5/50

365/365 [=====] - 1s 2ms/step - loss: 0.0158 - accuracy: 0.0709 - val_loss: 0.0159 - val_accuracy: 0.0103

Epoch 6/50

365/365 [=====] - 1s 2ms/step - loss: 0.0154 - accuracy: 0.0709 - val_loss: 0.0156 - val_accuracy: 0.0103

Epoch 7/50

365/365 [=====] - 1s 2ms/step - loss: 0.0152 - accuracy: 0.0709 - val_loss: 0.0153 - val_accuracy: 0.0103

Epoch 8/50

365/365 [=====] - 1s 2ms/step - loss: 0.0149 - accuracy: 0.0709 - val_loss: 0.0151 - val_accuracy: 0.0103

Epoch 9/50

365/365 [=====] - 1s 2ms/step - loss: 0.0147 - accuracy: 0.0709 - val_loss: 0.0147 - val_accuracy: 0.0103

Epoch 10/50

365/365 [=====] - 1s 2ms/step - loss: 0.0145 - accuracy: 0.0709 - val_loss: 0.0149 - val_accuracy: 0.0103

Epoch 11/50

365/365 [=====] - 1s 2ms/step - loss: 0.0143 - accuracy: 0.0709 - val_loss: 0.0143 - val_accuracy: 0.0103

Epoch 12/50

365/365 [=====] - 1s 2ms/step - loss: 0.0142 - accuracy: 0.0709 - val_loss: 0.0141 - val_accuracy: 0.0103

Epoch 13/50

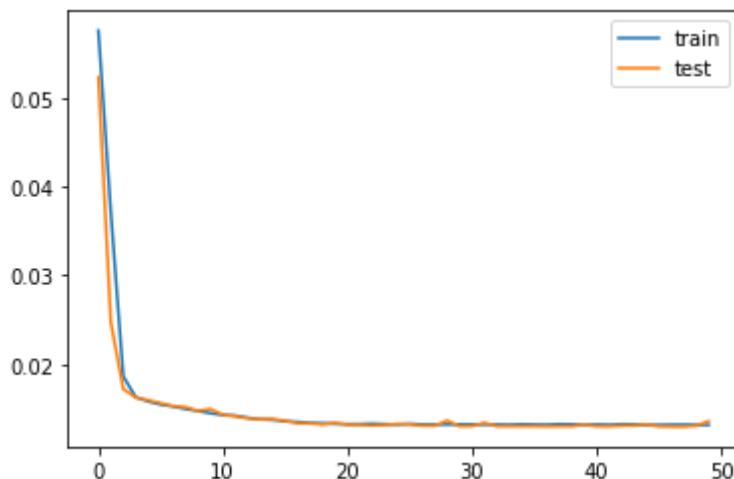
365/365 [=====] - 1s 2ms/step - loss: 0.0139 - accuracy: 0.0709 - val_loss: 0.0139 - val_accuracy: 0.0103

Epoch 14/50
365/365 [=====] - 1s 2ms/step - loss: 0.0138 - accuracy: 0.0709 - val_loss: 0.0138 - val_accuracy: 0.0103
Epoch 15/50
365/365 [=====] - 1s 2ms/step - loss: 0.0137 - accuracy: 0.0709 - val_loss: 0.0138 - val_accuracy: 0.0103
Epoch 16/50
365/365 [=====] - 1s 2ms/step - loss: 0.0135 - accuracy: 0.0709 - val_loss: 0.0136 - val_accuracy: 0.0103
Epoch 17/50
365/365 [=====] - 1s 2ms/step - loss: 0.0135 - accuracy: 0.0709 - val_loss: 0.0133 - val_accuracy: 0.0103
Epoch 18/50
365/365 [=====] - 1s 2ms/step - loss: 0.0134 - accuracy: 0.0709 - val_loss: 0.0133 - val_accuracy: 0.0103
Epoch 19/50
365/365 [=====] - 1s 2ms/step - loss: 0.0133 - accuracy: 0.0709 - val_loss: 0.0132 - val_accuracy: 0.0103
Epoch 20/50
365/365 [=====] - 1s 2ms/step - loss: 0.0133 - accuracy: 0.0709 - val_loss: 0.0134 - val_accuracy: 0.0103
Epoch 21/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0132 - val_accuracy: 0.0103
Epoch 22/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0131 - val_accuracy: 0.0103
Epoch 23/50
365/365 [=====] - 1s 2ms/step - loss: 0.0133 - accuracy: 0.0709 - val_loss: 0.0131 - val_accuracy: 0.0103
Epoch 24/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0131 - val_accuracy: 0.0103
Epoch 25/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0133 - val_accuracy: 0.0103
Epoch 26/50
365/365 [=====] - 1s 2ms/step - loss: 0.0133 - accuracy: 0.0709 - val_loss: 0.0132 - val_accuracy: 0.0103
Epoch 27/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 28/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 29/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0136 - val_accuracy: 0.0103
Epoch 30/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 31/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 32/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0134 - val_accuracy: 0.0103
Epoch 33/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 34/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 35/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 36/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103

```

Epoch 37/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 38/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 39/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 40/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0132 - val_accuracy: 0.0103
Epoch 41/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 42/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 43/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0131 - val_accuracy: 0.0103
Epoch 44/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0131 - val_accuracy: 0.0103
Epoch 45/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0132 - val_accuracy: 0.0103
Epoch 46/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 47/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0129 - val_accuracy: 0.0103
Epoch 48/50
365/365 [=====] - 1s 2ms/step - loss: 0.0132 - accuracy: 0.0709 - val_loss: 0.0129 - val_accuracy: 0.0103
Epoch 49/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0130 - val_accuracy: 0.0103
Epoch 50/50
365/365 [=====] - 1s 2ms/step - loss: 0.0131 - accuracy: 0.0709 - val_loss: 0.0136 - val_accuracy: 0.0103

```



```

In [ ]: idx=np.random.randint(0,len(test_X)-1)
# 对测试集进行预测
y_scale = model.predict(test_X[:, :])
y_scale = y_scale.reshape((len(y_scale),1))
test_X_scale = test_X.reshape((test_X.shape[0], test_X.shape[2]))
# 对预测值进行逆标准处理
inv_ypre = np.concatenate((y_scale, test_X_scale[:, 9:]), axis=1)
inv_ypre = scaler.inverse_transform(inv_ypre)[: ,0]
# 对测试集标签进行逆标准化处理

```

```

inv_ytest = test_y[:,].reshape((len(test_y[:,]), 1))
inv_ytest = np.concatenate((inv_ytest, test_X_scale[:, 9:]), axis=1)
inv_ytest = scaler.inverse_transform(inv_ytest)[:,0]
i = np.random.randint(0,len(test_X)-1)
j = np.random.randint(0,len(test_X)-1)
print("pred:",inv_ypre[i]," | real:",inv_ytest[i])
print("pred:",inv_ypre[j]," | real:",inv_ytest[j])
# 计算 RMSE
rmse = sqrt(mean_squared_error(inv_ypre, inv_ytest))
print('Test RMSE: %.3f' % rmse)
plt.plot(inv_ypre,label = 'prediction')
plt.plot(inv_ytest,'--y',label = 'test')
plt.legend()
plt.show()

```

pred: 63.388096 | real: 61.0
 pred: 71.45156 | real: 59.0
 Test RMSE: 26.913

