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1. When building a ConvNet, typically you start with some POOL layers followed by some CONV layers. True/False?

1 / 1 point

☒ False

☐ True

 **Expand**

✔ **Correct**

Correct. It is typical for ConvNets to use a POOL layer after some Conv layers; sometimes even one POOL layer after each CONV layer; but is not common to start with POOL layers.

2. In LeNet - 5 we can see that as we get into deeper networks the number of channels increases while the height and width of the volume decreases. True/False?

1 / 1 point

☒ True

☐ False

 **Expand**

✔ **Correct**

Correct, since in its implementation only valid convolutions were used, without padding, the height and width of the volume were reduced at each convolution. These were also reduced by the POOL layers, whereas the number of channels was increased from 6 to 16.

3. Training a deeper network (for example, adding additional layers to the network) allows the network to fit more complex functions and thus almost always results in lower training error. For this question, assume we're referring to "plain" networks.

1 / 1 point

☒ False

☐ True

 **Expand**

✔ **Correct**

Correct, Resnets are here to help us train very deep neural networks.

4. The computation of a ResNet block is expressed in the equation:

1 / 1 point

$$a^{[l+2]} = g \left(\underbrace{W^{[l+2]}}_{\text{C}} g \left(\underbrace{W^{[l+1]} a^{[l]} + b^{[l+1]}}_{\text{A}} \right) + b^{[l+2]} + \underbrace{a^{[l]}}_{\text{B}} \right)$$

Which part corresponds to the skip connection?

- ☐ The equation of ResNet.
- ☒ The term in the orange box, marked as B .
- ☐ The term in the red box, marked as C .

C

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✓ Correct

Yes, this term is the result of the skip connection or shortcut.

5. Which ones of the following statements on Residual Networks are true? (Check all that apply.)

1 / 1 point

- ☒ The skip-connection makes it easy for the network to learn an identity mapping between the input and the output within the ResNet block.

✓ Correct
This is true.

- ☐ The skip-connections compute a complex non-linear function of the input to pass to a deeper layer in the network.

- ☒ Using a skip-connection helps the gradient to backpropagate and thus helps you to train deeper networks

✓ Correct
This is true.

- ☐ A ResNet with L layers would have on the order of L^2 skip connections in total.

[Expand](#)

✓ Correct

Great, you got all the right answers.

6. 1×1 convolutions are the same as multiplying by a single number. True/False?

1 / 1 point

- ☐ True
- ☒ False

[Expand](#)

✓ Correct

Yes, a 1×1 layer doesn't act as a single number because it makes a sum over the depth of the volume.

7. Which ones of the following statements on Inception Networks are true? (Check all that apply.)

0 / 1 point

☒ A single inception block allows the network to use a combination of 1×1 , 3×3 , 5×5 convolutions and pooling.

✓ Correct

☐ Inception networks incorporate a variety of network architectures (similar to dropout, which randomly chooses a network architecture on each step) and thus has a similar regularizing effect as dropout.

☒ Inception blocks usually use 1×1 convolutions to reduce the input data volume's size before applying 3×3 and 5×5 convolutions.

✓ Correct

☐ Making an inception network deeper (by stacking more inception blocks together) can improve performance, but can also lead to overfitting and increase in computational cost.

↗ Expand

✗ Incorrect

You didn't select all the correct answers

8. When having a small training set to construct a classification model, which of the following is a strategy of transfer learning that you would use to build the model?

1 / 1 point

- ☒ Use an open-source network trained in a larger dataset freezing the layers and re-train the softmax layer.
- ☐ Use an open-source network trained in a larger dataset. Use these weights as an initial point for the training of the whole network.
- ☐ Use an open-source network trained in a larger dataset, freeze the softmax layer, and re-train the rest of the layers.
- ☐ It is always better to train a network from a random initialization to prevent bias in our model.

↗ Expand

✓ Correct

Yes, this is a strategy that can provide a good result with small data.

9. Which of the following are true about Depth wise-separable convolutions? (Choose all that apply)

1 / 1 point

☐ The result has always the same number of channels n_c as the input.

☒ They combine depthwise convolutions with pointwise convolutions.

✓ Correct

Correct, this combination is what we call depth wise separable convolutions.

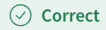
☒ They have a lower computational cost than normal convolutions.

✓ Correct

Yes, as seen in the lectures the use of the depthwise and pointwise convolution reduces the computational cost significantly.

☐ They are just a combination of a normal convolution and a bottleneck layer.

↩ Expand



Correct

Great, you got all the right answers.

10. Suppose that in a MobileNet v2 Bottleneck block we have an $n \times n \times 5$ input volume, we use 30 filters for the expansion, in the depthwise convolutions we use 3×3 filters, and 20 filters for the projection. How many parameters are used in the complete block, suppose we don't use bias?

1 / 1 point

- ☐ 80
- ☐ 1101
- ☒ 1020
- ☐ 8250

↩ Expand



Correct

Yes, the expansion filters use $5 \times 30 = 150$ parameters, the depthwise convolutions need $3 \times 3 \times 30 = 270$ parameters, and the projection part $30 \times 20 = 600$ parameters.