Imperial College London

PLANNING REPORT FOR MSC PROJECT

IMPERIAL COLLEGE LONDON

DEPARTMENT OF BIOENGINEERING

PPO Based Co-Training of Human and Supernumerary Robotic Limbs

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Chapter 1: Project Specification

1.1 Background

Test reference from Peng et al. (2018)

Appendix A: First Appendix

Reference

Peng, X. B., Abbeel, P., Levine, S. and Van de Panne, M. (2018). Deepmimic: Example-guided deep reinforcement learning of physics-based character skills, *ACM Transactions On Graphics (TOG)* **37**(4): 1–14.