**Language Models** 

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Noam Chomsky, 1969

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- "useless": To everyone? To linguists?
- "known interpretation": What are possible interpretations?

#### Intuitive interpretation

- "Probability of a sentence" = how likely is it to occur in natural language
  - Consider only a specific language (English)
  - Not including meta-language (e.g. linguistic discussion)

P(She studies morphosyntax) > P(She studies more faux syntax)

#### **Automatic speech recognition**

Sentence probabilities (language model) help decide between similar-sounding options.

speech input

↓ (Acoustic model)

She studies morphosyntax
She studies more faux syntax
She's studies morph or syntax
...

↓ (Language model)

best-guess output She studies morphosyntax

#### Machine translation

Sentence probabilities help decide word choice and word order.

#### non-English input

↓ (Translation model)

She is going home
She is going house
She is traveling to home
To home she is going

(Language model)

best-guess output

She is going home

# But, what about zero probability sentences?

the Archaeopteryx winged jaggedly amidst foliage vs jaggedly trees the on flew

- Neither has ever occurred before.
  - ⇒ both have zero probability.
- But one is grammatical (and meaningful), the other not.
  - $\Rightarrow$  "Sentence probability" is useless as a measure of grammaticality.

#### The logical flaw

- "Probability of a sentence" = how likely is it to occur in natural language.
- Is the following statement true?

Sentence has never occurred  $\Rightarrow$  sentence has zero probability

• More generally, is this one?

Event has never occurred  $\Rightarrow$  event has zero probability

#### **Events that have never occurred**

• Each of these events has never occurred:

My hair turns blue I injure myself in a skiing accident I travel to Finland

• Yet, they clearly have different (and non-zero!) probabilities.

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- Yet, they clearly have differing (and non-zero!) probabilities.
- Most sentences (and events) have never occurred.
  - This doesn't make their probabilities zero (or meaningless), but
  - it does make estimating their probabilities trickier.

#### Probability theory vs estimation

- Probability theory can solve problems like:
  - I have a jar with 6 blue marbles and 4 red ones.
  - If I choose a marble uniformly at random, what's the probability it's red?
- But what about:
  - I have a jar of marbles.
  - I repeatedly choose a marble uniformly at random and then replace it before choosing again.
  - In ten draws, I get 6 blue marbles and 4 red ones.
  - On the next draw, what's the probability I get a red marble?
- The latter also requires estimation theory.

# **Example: weather forecasting**

#### What is the probability that it will rain tomorrow?

- To answer this question, we need
  - data: measurements of relevant info (e.g., humidity, wind speed/direction, temperature).
  - model: equations/procedures to estimate the probability using the data.
- In fact, to build the model, we will need data (including *outcomes*) from previous situations as well.

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- In fact, to build the model, we will need data (including *outcomes*) from previous situations as well.
- ullet Note that we will never know the "true" probability of rain  $P({\rm rain})$ , only our estimated probability  $\hat{P}({\rm rain})$ .

#### **Example: language model**

What is the probability of sentence  $\vec{w} = w_1 \dots w_n$ ?

- To answer this question, we need
  - data: words  $w_1 \dots w_n$ , plus a large corpus of sentences ("previous situations", or **training data**).
  - model: equations to estimate the probability using the data.
- Different models will yield different estimates, even with the same data.
- Deep question: what model/estimation method do humans use?

#### How to get better probability estimates

Better estimates definitely help in language technology. How to improve them?

- More training data. Limited by time, money. (Varies a lot!)
- **Better model.** Limited by scientific and mathematical knowledge, computational resources
- **Better estimation method.** Limited by mathematical knowledge, computational resources

We will return to the question of how to know if estimates are "better".

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Each is a **generative model**: a probabilistic process that describes how the data were generated.

#### **Defining a model**

Usually, two choices in defining a model:

- **Structure** (or **form**) of the model: the form of the equations, usually determined by knowledge about the problem.
- Parameters of the model: specific values in the equations that are usually determined using the training data.

#### **Example: M&M colors**

#### What is the proportion of each color of M&M?

- Assume a **discrete distribution** with parameters  $\theta$ .
  - $\theta$  is a vector! That is,  $\theta = (\theta_R, \theta_O, \theta_Y, \theta_G, \theta_{BL}, \theta_{BR})$ .
  - For discrete distribution, the parameters ARE the probabilities, e.g.,  $P(\text{red}) = \theta_{\mathrm{R}}.$

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  - For discrete distribution, params ARE the probabilities, e.g.,  $P({\rm red}) = \theta_{\rm R}.$
- In 48 packages, I find 2620 M&Ms, as follows:

• How to estimate  $\theta$  from this data?

<sup>&</sup>lt;sup>1</sup>Actually, data from: https://joshmadison.com/2007/12/02/mms-color-distribution-analysis/

## Relative frequency estimation

Intuitive way to estimate discrete probabilities:

$$P_{\rm RF}(x) = \frac{C(x)}{N}$$

where C(x) is the count of x in a large dataset, and  $N = \sum_{x'} C(x')$  is the total number of items in the dataset.

- $\bullet$  M&M example:  $P_{\rm RF}({\rm red})=\hat{\theta}_{\rm R}=\frac{372}{2620}=.142$
- ullet Or, could estimate probability of word w from a large corpus.
- Can we justify this mathematically?

# Formalizing the estimation problem

- What is the best choice of  $\theta$  given the data d that we saw?
- Formalize using Bayes' Rule, try to maximize  $P(\theta|d)$ .

$$P(\theta|d) = \frac{P(d|\theta)P(\theta)}{P(d)}$$

- $-P(\theta)$ : **prior** probability of  $\theta$
- $-P(d|\theta)$ : likelihood
- $P(\theta|d)$ : **posterior** probability of  $\theta$  given d

# Formalizing the estimation problem

• Notation: choose  $\hat{\theta}$  to be the  $\theta$  that maximizes  $P(\theta|d)$ :

$$\hat{\theta} = \operatorname*{argmax}_{\theta} P(\theta|d)$$

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$$\hat{\theta} = \operatorname*{argmax}_{\theta} P(\theta|d)$$

• Rewrite with Bayes' Rule, and P(d) doesn't depend on  $\theta$ , so:

$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \frac{P(d|\theta)P(\theta)}{P(d)}$$
$$= \underset{\theta}{\operatorname{argmax}} P(d|\theta)P(\theta)$$

#### Maximum-likelihood estimation

Not obvious how to choose prior... so maybe don't use one?

$$\underset{\theta}{\operatorname{argmax}} P(d|\theta)P(\theta) = \underset{\theta}{\operatorname{argmax}} P(d|\theta)$$

- Just choose  $\theta$  to maximize the likelihood.
  - the parameters that make the observed data most probable
- This turns out to be just the relative frequency estimator, i.e.,

$$P_{\mathrm{ML}}(x) = P_{\mathrm{RF}}(x) = \frac{C(x)}{N}$$

#### Likelihood example

- For a fixed dataset, the likelihood depends on the model we use.
- Our coin example:  $\theta = (\theta_H, \theta_T)$ . Suppose  $d = \mathsf{HTTTHTHTTTT}$ .
- **Model 1:** Assume coin is fair, so  $\hat{\theta} = (0.5, 0.5)$ .
  - Likelihood of this model:

$$P(\mathsf{HTTTHTHTTT}|\hat{\theta}) = (0.5)^3 \cdot (0.5)^7 = 0.00097$$

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  - Likelihood of this model:  $P(\mathsf{HTTTHTHTTT}|\hat{\theta}) = (0.5)^3 \cdot (0.5)^7 = 0.00097$
- **Model 2:** Use ML estimation, so  $\hat{\theta} = (0.3, 0.7)$ .
  - Likelihood of this model:  $(0.3)^3 \cdot (0.7)^7 = 0.00222$
- Maximum-likelihood estimate does have higher likelihood!

#### **Recap: Language models**

• Language models tell us  $P(\vec{w}) = P(w_1 ... w_n)$ : How likely to occur is this sequence of words?

Roughly: Is this sequence of words a "good" one in my language?

## **Example uses of language models**

• Machine translation: reordering, word choice.

```
P_{\text{LM}} (the house is small) > P_{\text{LM}} (small the is house) 

P_{\text{LM}} (I am going home) > P_{\text{LM}} (I am going house) 

P_{\text{LM}} (We'll start eating) > P_{\text{LM}} (We shall commence consuming)
```

• Speech recognition: word choice:

```
P_{\text{LM}}(\text{morphosyntactic analyses}) > P_{\text{LM}}(\text{more faux syntactic analyses})
P_{\text{LM}}(\text{I put it on today}) > P_{\text{LM}}(\text{I putted onto day})
```

But: How do systems use this information?

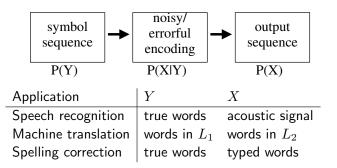
#### Noisy channel model

- Concept from Information Theory, used widely in NLP
- We imagine that the observed data (output sequence) was generated as:



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#### **Example: spelling correction**

- P(Y): Distribution over the words the user intended to type. A language model!
- P(X|Y): Distribution describing what user is likely to type, given what they meant. Could incorporate information about common spelling errors, key positions, etc. Call it a noise model.
- P(X): Resulting distribution over what we actually see.
- Given some particular observation x (say, effert), we want to recover the most probable y that was intended.

#### Noisy channel as probabilistic inference

- Mathematically, what we want is  $\operatorname{argmax}_{y} P(y|x)$ .
  - Read as "the y that maximizes P(y|x)"
- Rewrite using Bayes' Rule:

$$\underset{y}{\operatorname{argmax}} P(y|x) = \underset{y}{\operatorname{argmax}} \frac{P(x|y)P(y)}{P(x)}$$
$$= \underset{x}{\operatorname{argmax}} P(x|y)P(y)$$

# Noisy channel as probabilistic inference

So to recover the best y, we will need

- a **language model** P(Y): relatively task-independent.
- a **noise model** P(X|Y), which depends on the task.
  - acoustic model, translation model, misspelling model, etc.

Both are normally trained on corpus data.

## **Estimating a language model**

- Y is really a sequence of words  $\vec{w} = w_1 \dots w_n$ .
- So we want to know  $P(w_1 \dots w_n)$  for big n (e.g., sentence).
- What will not work: try to directly estimate probability of each full sentence.
  - Say, using MLE (relative frequencies):  $C(\vec{w})/(\text{tot } \# \text{ sentences})$ .
  - For nearly all  $\vec{w}$  (grammatical or not),  $C(\vec{w}) = 0$ .
  - A sparse data problem: not enough observations to estimate probabilities well.

## A first attempt to solve the problem

Perhaps the simplest model of sentence probabilities: a **unigram** model.

- Generative process: choose each word in sentence independently.
- Resulting model:  $\hat{P}(\vec{w}) = \prod_{i=1}^{n} P(w_i)$

## A first attempt to solve the problem

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- Generative process: choose each word in sentence independently.
- Resulting model:  $\hat{P}(\vec{w}) = \prod_{i=1}^{n} P(w_i)$
- So, P(the cat slept quietly) = P(the quietly cat slept)
  - Not a good model, but still a model.
- Of course,  $P(w_i)$  also needs to be estimated!

## **MLE** for unigrams

- How to estimate P(w), e.g., P(the)?
- MLE is just relative frequencies:

$$P_{\mathrm{ML}}(w) = \frac{C(w)}{W}$$

- -C(w) is the token count of w in a large corpus
- $W = \sum_{x'} C(x')$  is the total number of word tokens in the corpus.

#### Unigram models in practice

- Seems like a pretty bad model of language: probability of word obviously does depend on context.
- Yet unigram (or bag-of-words) models are surprisingly useful for some applications.
  - Can model "aboutness": topic of a document, semantic usage of a word
  - Applications: lexical semantics (disambiguation), information retrieval, text classification. (See later in this course)
  - But, we will focus on models that capture at least some syntactic information.

# **General N-gram language models**

#### Step 1: rewrite using chain rule:

$$P(\vec{w}) = P(w_1 \dots w_n)$$
  
=  $P(w_n | w_1, w_2, \dots, w_{n-1}) P(w_{n-1} | w_1, w_2, \dots, w_{n-2}) \dots P(w_1)$ 

ullet Example:  $\vec{w}=$  the cat slept quietly yesterday.

```
\begin{split} P(\text{the, cat, slept, quietly, yesterday}) &= \\ P(\text{yesterday}|\text{the, cat, slept, quietly}) \cdot P(\text{quietly}|\text{the, cat, slept}) \cdot \\ P(\text{slept}|\text{the, cat}) \cdot P(\text{cat}|\text{the}) \cdot P(\text{the}) \end{split}
```

 But for long sequences, many of the conditional probs are also too sparse!

# **General N-gram language models**

Step 2: make an independence assumption:

$$P(\vec{w}) = P(w_1 \dots w_n)$$

$$= P(w_n | w_1, w_2, \dots, w_{n-1}) P(w_{n-1} | w_1, w_2, \dots, w_{n-2}) \dots P(w_1)$$

$$\approx P(w_n | w_{n-2}, w_{n-1}) P(w_{n-1} | w_{n-3}, w_{n-2}) \dots P(w_1)$$

- Markov assumption: only a finite history matters.
- Here, two word history (trigram model):  $w_i$  is cond. indep. of  $w_1 \dots w_{i-3}$  given  $w_{i-1}, w_{i-2}$ .  $P(\text{the, cat, slept, quietly, yesterday}) \approx P(\text{yesterday}|\text{slept, quietly}) \cdot P(\text{quietly}|\text{cat, slept}) \cdot P(\text{slept}|\text{the, cat}) \cdot P(\text{cat}|\text{the}) \cdot P(\text{the})$

#### **Trigram independence assumption**

- Put another way, a trigram model assumes these are all equal:
  - -P(slept|the cat)
  - -P(slept|after lunch the cat)
  - -P(slept|the dog chased the cat)
  - -P(slept|except for the cat)

because all are estimated as P(slept|the cat)

• Not always a good assumption! But it does reduce the sparse data problem.

## Another example: bigram model

• Bigram model assumes one word history:

$$P(\vec{w}) = P(w_1) \prod_{i=2}^{n} P(w_i|w_{i-1})$$

But consider these sentences:

	$w_1$	$w_2$	$w_3$	$w_4$
(1)	the	cats	slept	quietly
(2)	feeds	cats	slept	quietly
(3)	the	cats	slept	on

 What's wrong with (2) and (3)? Does the model capture these problems?

#### **Example: bigram model**

 To capture behaviour at beginning/end of sentence, we need to augment the input:

$$w_0$$
  $w_1$   $w_2$   $w_3$   $w_4$   $w_5$   
 $(1)$   $<$ s $>$  the cats slept quietly  $<$ /s $>$   
 $(2)$   $<$ s $>$  feeds cats slept quietly  $<$ /s $>$   
 $(3)$   $<$ s $>$  the cats slept on  $<$ /s $>$ 

• That is, assume  $w_0 = \langle s \rangle$  and  $w_{n+1} = \langle /s \rangle$  so we have:

$$P(\vec{w}) = P(w_0) \prod_{i=1}^{n+1} P(w_i|w_{i-1}) = \prod_{i=1}^{n+1} P(w_i|w_{i-1})$$

# **Estimating N-Gram Probabilities**

- Maximum likelihood (relative frequency) estimation for bigrams:
  - How many times we saw  $w_2$  following  $w_1$ , out of all the times we saw *anything* following  $w_1$ :

$$P_{\text{ML}}(w_2|w_1) = \frac{C(w_1, w_2)}{C(w_1, \cdot)}$$
$$= \frac{C(w_1, w_2)}{C(w_1)}$$

# **Estimating N-Gram Probabilities**

• Similarly for trigrams:

$$P_{\mathrm{ML}}(w_3|w_1, w_2) = \frac{C(w_1, w_2, w_3)}{C(w_1, w_2)}$$

- Collect counts over a large text corpus
  - Millions to billions of words are usually easy to get
  - (trillions of English words available on the web)

#### **Evaluating a language model**

- Intuitively, trigram model captures more context than bigram model, so should be a "better" model.
- That is, more accurately predict the probabilities of sentences.
- But how can we measure this?

## **Entropy**

• Definition of the **entropy** of a random variable *X*:

$$H(X) = \sum_{x} -P(x) \log_2 P(x)$$

- Intuitively: a measure of uncertainty/disorder
- ullet Also: the expected value of  $-\log_2 P(X)$

One event (outcome)

$$P(a) = 1$$

$$H(X) = -1 \log_2 1$$

$$= 0$$

2 equally likely events:

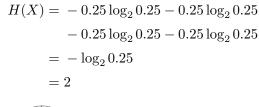
$$P(a) = 0.5$$
$$P(b) = 0.5$$

$$H(X) = -0.5 \log_2 0.5 - 0.5 \log_2 0.5$$
$$= -\log_2 0.5$$
$$= 1$$



4 equally likely events:

$$P(a) = 0.25$$
  $H(X) = 0.25$   $P(b) = 0.25$   $P(c) = 0.25$   $P(d) = 0.25$ 





3 equally likely events and one more likely than the others:

$$P(a) = 0.7$$
$$P(b) = 0.1$$

$$P(c) = 0.1$$

$$P(d) = 0.1$$



$$H(X) = -0.7 \log_2 0.7 - 0.1 \log_2 0.1$$
$$-0.1 \log_2 0.1 - 0.1 \log_2 0.1$$

$$-0.1\log_2 0.1 - 0.1\log_2 0.$$

$$= -0.7\log_2 0.7 - 0.3\log_2 0.1$$

$$= -(0.7)(-0.5146) - (0.3)(-3.3219)$$

$$= 0.36020 + 0.99658$$

$$= 1.35678$$

3 equally likely events and one much more likely than the others:

$$P(a) = 0.97$$
  
 $P(b) = 0.01$   
 $P(c) = 0.01$ 

$$P(d) = 0.01$$

$$H(X) = -0.97 \log_2 0.97 - 0.01 \log_2 0.01$$
$$-0.01 \log_2 0.01 - 0.01 \log_2 0.01$$

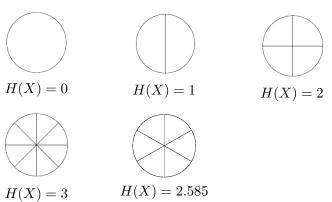
$$= -0.97 \log_2 0.97 - 0.03 \log_2 0.01$$

$$= -(0.97)(-0.04394) - (0.03)(-6.64)$$
$$= 0.04262 + 0.19932$$

$$= 0.24194$$

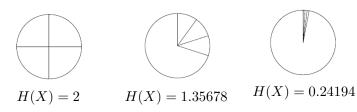
#### **Entropy take-aways**

Entropy of a **uniform distribution** over N outcomes is  $\log_2 N$ :



#### **Entropy take-aways**

Any **non-uniform** distribution over N outcomes has **lower** entropy than the corresponding uniform distribution:



# The Entropy of English

- Given the start of a text, can we guess the next word?
- Humans do pretty well: the entropy is only about 1.3.
- But what about N-gram models?
  - Ideal language model would match the true entropy of English.
  - The closer we get to that, the better the model.
  - Put another way, a good model assigns high prob to real sentences (and low prob to everything else).

#### How good is the LM?

- ullet Cross entropy measures how well model M predicts the data.
- For data  $w_1 \dots w_n$  with large n, well approximated by:

$$H_M(w_1 \dots w_n) = -\frac{1}{n} \log_2 P_M(w_1 \dots w_n)$$

- Avg neg log prob our model assigns to each word we saw
- Or, perplexity:

$$\mathsf{PP}_M(\vec{w}) = 2^{H_M(\vec{w})}$$

# **Example: trigram (Europarl)**

prediction	$P_{ m ML}$	$-\log_2 P_{\mathrm{ML}}$
$P_{\rm ML}(i )$	0.109	3.197
$P_{\rm ML}({\rm would} <{\rm s}>{\rm i})$	0.144	2.791
$P_{\mathrm{ML}}(\mathrm{like} \mathrm{i}\;\mathrm{would})$	0.489	1.031
$P_{\mathrm{ML}}(\mathrm{to} \mathrm{would\ like})$	0.905	0.144
$P_{\mathrm{ML}}(\mathrm{commend} \mathrm{like\ to})$	0.002	8.794
$P_{\mathrm{ML}}(\mathrm{the} \mathrm{to}\;\mathrm{commend})$	0.472	1.084
$P_{\rm ML}$ (rapporteur commend the)	0.147	2.763
$P_{\mathrm{ML}}(\mathrm{on} \mathrm{the\;rapporteur})$	0.056	4.150
$P_{\rm ML}({ m his} { m rapporteur}\ { m on})$	0.194	2.367
$P_{\mathrm{ML}}(\mathrm{work} \mathrm{on\ his})$	0.089	3.498
$P_{\mathrm{ML}}(. \mathrm{his\ work})$	0.290	1.785
$P_{\rm ML}( \rm work .)$	0.99999	0.000014
	average	2.634

# Comparison: 1–4-Gram

word	unigram	bigram	trigram	4-gram
i	6.684	3.197	3.197	3.197
would	8.342	2.884	2.791	2.791
like	9.129	2.026	1.031	1.290
to	5.081	0.402	0.144	0.113
commend	15.487	12.335	8.794	8.633
the	3.885	1.402	1.084	0.880
rapporteur	10.840	7.319	2.763	2.350
on	6.765	4.140	4.150	1.862
his	10.678	7.316	2.367	1.978
work	9.993	4.816	3.498	2.394
	4.896	3.020	1.785	1.510
	4.828	0.005	0.000	0.000
average	8.051	4.072	2.634	2.251
perplexity	265.136	16.817	6.206	4.758

#### **Unseen N-Grams**

- What happens when I try to compute P(consuming|shall commence)?
  - Assume we have seen shall commence in our corpus
  - But we have never seen shall commence consuming in our corpus

#### **Unseen N-Grams**

- What happens when I try to compute P(consuming|shall commence)?
  - Assume we have seen shall commence in our corpus
  - But we have never seen shall commence consuming in our corpus
  - $\rightarrow P(\text{consuming}|\text{shall commence}) = 0$
- Any sentence with shall commence consuming will be assigned probability 0

The guests shall commence consuming supper Green inked shall commence consuming garden the

#### The problem with MLE

- MLE estimates probabilities that make the observed data maximally probable
- by assuming anything unseen cannot happen (and also assigning too *much* probability to low-frequency observed events).
- It over-fits the training data.
- We tried to avoid zero-probability sentences by modelling with smaller chunks (*n*-grams).
- But even these will sometimes have zero prob under MLE.

## Recap: N-gram models

- $\bullet$  We can model sentence probs by conditioning each word on N-1 previous words.
- For example, a bigram model:

$$P(\vec{w}) = \prod_{i=1}^{n} P(w_i | w_{i-1})$$

• Or trigram model:

$$P(\vec{w}) = \prod_{i=1}^{n} P(w_i | w_{i-2}, w_{i-1})$$

# Recap: MLE estimates for N-grams

• To estimate each word prob, we could use MLE...

$$P_{\text{ML}}(w_2|w_1) = \frac{C(w_1, w_2)}{C(w_1)}$$

- ullet But even with a large training corpus, not all N-grams will be observed (we'll still have some zeros).
- Smoothing methods reassign some probability mass from observed to unobserved events.

## **Add-One Smoothing**

• For all possible bigrams, add one more count.

$$P_{\mathrm{ML}}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i)}{C(w_{i-1})}$$

$$P_{+1}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i) + 1}{C(w_{i-1})}$$

?

## **Add-One Smoothing**

For all possible bigrams, add one more count.

$$P_{\text{ML}}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i)}{C(w_{i-1})}$$

$$\Rightarrow P_{+1}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i) + 1}{C(w_{i-1})}$$

• NO! Sum over possible  $w_i$  (in vocabulary V) must equal 1:

$$\sum_{w_i \in V} P(w_i|w_{i-1}) = 1$$

 $\bullet$  True for  $P_{\rm ML}$  but we increased the numerator; must change denominator too.

# **Add-One Smoothing: normalization**

• We want:  $\sum_{w \in V} \frac{C(w_{i-1}, w_i) + 1}{C(w_{i-1}) + x} = 1$ 

• Solve for 
$$x$$
: 
$$\sum_{w_i \in V} (C(w_{i-1}, w_i) + 1) = C(w_{i-1}) + x$$
 
$$\sum_{w_i \in V} C(w_{i-1}, w_i) + \sum_{w_i \in V} 1 = C(w_{i-1}) + x$$
 
$$C(w_{i-1}) + v = C(w_{i-1}) + x$$

• So,  $P_{+1}(w_i|w_{i-1}) = \frac{C(w_{i-1},w_i)+1}{C(w_{i-1})+v}$  where v= vocabulary size.

# **Add-One Smoothing: effects**

• Add-one smoothing:

$$P_{+1}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i) + 1}{C(w_{i-1}) + v}$$

- Large vobulary size means v is often much larger than  $C(w_{i-1})$ , overpowers actual counts.
- Example: in Europarl, v=86,700 word types (30m tokens, max  $C(w_{i-1})=2$ m).

## Add-One Smoothing: effects

$$P_{+1}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i) + 1}{C(w_{i-1}) + v}$$

Using v=86,700 compute some example probabilities:

$C(w_{i-1}) = 10,000$		$C(w_{i-1}) = 100$			
$C(w_{i-1}, w_i)$	$P_{\mathrm{ML}} =$	$P_{+1} \approx$	$C(w_{i-1}, w_i)$	$P_{\mathrm{ML}} =$	$P_{+1} \approx$
100	1/100	1/970	100	1	1/870
10	1/1k	1/10k	10	1/10	1/9k
1	1/10k	1/48k	1	1/100	1/43k
0	0	1/97k	0	0	1/87k

### The problem with Add-One smoothing

- All smoothing methods "steal from the rich to give to the poor"
- Add-one smoothing steals way too much
- ML estimates for frequent events are quite accurate, don't want smoothing to change these much.

# Add- $\alpha$ Smoothing

• Add  $\alpha < 1$  to each count

$$P_{+\alpha}(w_i|w_{i-1}) = \frac{C(w_{i-1}, w_i) + \alpha}{C(w_{i-1}) + \alpha v}$$

ullet Simplifying notation: c is n-gram count, n is history count

$$P_{+\alpha} = \frac{c + \alpha}{n + \alpha v}$$

• What is a good value for  $\alpha$ ?

# Optimizing $\alpha$

- Divide corpus into training set (80-90%), held-out (or development or validation) set (5-10%), and test set (5-10%)
- $\bullet$  Train model (estimate probabilities) on training set with different values of  $\alpha$
- ullet Choose the value of  $\alpha$  that minimizes perplexity on dev set
- Report final results on test set

# A general methodology

- Training/dev/test split is used across machine learning
- ullet Development set used for evaluating different models, debugging, optimizing parameters (like lpha)
- Test set simulates deployment; only used once final model and parameters are chosen. (Ideally: once per paper)
- Avoids overfitting to the training set and even to the test set

## **Adjusted Counts**

• Previously, we estimated probabilities based on actual counts

$$P_{\mathrm{ML}} = \frac{c}{n}$$

• Then, we changed the formula to estimate smoothed probabilities

$$P_{+\alpha} = \frac{c + \alpha}{n + \alpha v}$$

• Another view: we adjusted the counts c

$$P_{+\alpha} = \frac{c^*}{n} \quad \Rightarrow \quad c^* = n \ P_{+\alpha} = (c + \alpha) \frac{n}{n + \alpha v}$$

# **Good-Turing Smoothing**

ullet Adjust actual counts c to expected counts  $c^*$  with formula

$$c^* = (c+1)\frac{N_{c+1}}{N_c}$$

- ullet Assuming we are building an N-gram model:
  - $N_c$  number of N-grams that occur exactly c times in corpus (e.g. bigram model:  $N_1$ = how many bigrams occurred once?)
  - $N_0$  total number of unseen N-grams

# **Good-Turing for 2-Grams in Europarl**

Count	Count of counts	Adjusted count	Test count	
c	$N_c$	$c^*$	$t_c$	
0	7,514,941,065	0.00015	0.00016	
1	1,132,844	0.46539	0.46235	
2	263,611	1.40679	1.39946	
3	123,615	2.38767	2.34307	
4	73,788	3.33753	3.35202	
5	49,254	4.36967	4.35234	
6	35,869	5.32928	5.33762	
8	21,693	7.43798	7.15074	
10	14,880	9.31304	9.11927	
20	4,546	19.54487	18.95948	

 $t_c$  are average counts of bigrams in test set that occurred c times in corpus: fairly close to estimate  $c^*$ .

# Good-Turing justification: 0-count items

• Estimate the probability that the next observation is previously unseen (i.e., will have count 1 once we see it)

$$P({\rm unseen}) = \frac{N_1}{n} = \frac{{\rm number\ of\ things\ we\ saw\ once}}{{\rm number\ of\ things\ we\ saw}}$$

This part uses MLE!

ullet Divide that probability equally amongst all unseen events ( $N_0$  of them)

$$P_{\rm GT} = \frac{1}{N_0} \frac{N_1}{n} \quad \Rightarrow \quad c^* = \frac{N_1}{N_0}$$

# Good-Turing justification: 1-count items

• Estimate the probability that the next observation was seen once before (i.e., will have count 2 once we see it)

$$P(\text{once before}) = \frac{2N_2}{n}$$

• Divide that probability equally amongst all 1-count events

$$P_{\rm GT} = \frac{1}{N_1} \frac{2N_2}{n} \quad \Rightarrow \quad c^* = \frac{2N_2}{N_1}$$

Same thing for higher count items

### Remaining problem

- In given corpus, suppose we never observe
  - Scottish beer drinkers
  - Scottish beer eaters
- If we build a trigram model smoothed with Add- $\alpha$  or G-T, which example has higher probability?

# Remaining problem

- Previous smoothing methods assign equal probability to all unseen events.
- ullet Better: use information from lower order N-grams (shorter histories).
  - beer drinkers
  - beer eaters
- Two ways: interpolation and backoff.

### Interpolation

- ullet Higher and lower order N-gram models have different strengths and weaknesses
  - $-\mbox{ high-order }N\mbox{-grams}$  are sensitive to more context, but have sparse counts
  - low-order  $N\mbox{-}{\rm grams}$  consider only very limited context, but have robust counts
- So, combine them:

$$\begin{split} P_I(w_3|w_1,w_2) = & \ \lambda_1 \ P_1(w_3) \\ & + \lambda_2 \ P_2(w_3|w_2) \\ & + \lambda_3 \ P_3(w_3|w_1,w_2) \end{split} \qquad \begin{aligned} & P_1(\text{drinkers}) \\ & P_2(\text{drinkers}|\text{beer}) \\ & + \lambda_3 \ P_3(w_3|w_1,w_2) \end{aligned}$$

### Interpolation

• Note that  $\lambda_i$ s must sum to 1:

$$1 = \sum_{w_3} P_I(w_3|w_1, w_2)$$

$$= \sum_{w_3} [\lambda_1 P_1(w_3) + \lambda_2 P_2(w_3|w_2) + \lambda_3 P_3(w_3|w_1, w_2)]$$

$$= \lambda_1 \sum_{w_3} P_1(w_3) + \lambda_2 \sum_{w_3} P_2(w_3|w_2) + \lambda_3 \sum_{w_3} P_3(w_3|w_1, w_2)$$

$$= \lambda_1 + \lambda_2 + \lambda_3$$

# Fitting the interpolation parameters

- In general, any weighted combination of distributions is called a mixture model.
- So  $\lambda_i$ s are interpolation parameters or mixture weights.
- The values of the  $\lambda_i$ s are chosen to optimize perplexity on a held-out data set.

#### **Back-Off**

ullet Trust the highest order language model that contains N-gram, otherwise "back off" to a lower order model.

#### • Basic idea:

- discount the probabilities slightly in higher order model
- spread the extra mass between lower order N-grams

#### **Discounting**

• Say we've seen the following counts:

x	Count(x)	$P_{ML}(w_i \mid w_{i-1})$		
the	48			
the, dog	15	15/48		
the, woman	11	11/48		
the, man	10	10/48		
the, park	5	5/48		
the, job	2	2/48		
the, telescope	1	1/48		
the, manual	1	1/48		
the, afternoon	1	1/48		
the, country	1	1/48		
the, street	1	1/48		

• The maximum-likelihood estimates are high (particularly for low count items)

### **Discounting**

• Now define 'discounted' counts, for example (a first, simple definition):

 $\operatorname{Count}^*(x) = \operatorname{Count}(x) - 0.5$ 

#### • New estimates:

x	Count(x)	Count*(x)	$\frac{\operatorname{Count}^*(x)}{\operatorname{Count}(x)}$
the	48		
the, dog	15	14.5	14.5/48
the, woman	11	10.5	10.5/48
the, man	10	9.5	9.5/48
the, park	5	4.5	4.5/48
the, job	2	1.5	1.5/48
the, telescope	1	0.5	0.5/48
the, manual	1	0.5	0.5/48
the, afternoon	1	0.5	0.5/48
the, country	1	0.5	0.5/48
the, street	1	0.5	0.5/48

### **Discounting**

• We now have some "missing probability mass":

$$\alpha(w_{i-1}) = 1 - \sum_{w} \frac{\text{Count}^*(w_{i-1}, w)}{\text{Count}(w_{i-1})}$$

e.g., in our example,  $\alpha(the) = 10 \times 0.5/48 = 5/48$ 

• Divide the remaining probability mass between words w for which  $Count(w_{i-1}, w) = 0$ .

# **Back-Off Equation**

$$\begin{split} P_{BO}(w_i|w_{i-N+1},...,w_{i-1}) &= \\ &= \begin{cases} P^*(w_i|w_{i-N+1},...,w_{i-1}) \\ &\text{if } \operatorname{count}(w_{i-N+1},...,w_i) > 0 \\ \alpha(w_{i-N+1},...,w_{i-1}) \ P_{BO}(w_i|w_{i-N+2},...,w_{i-1}) \\ &\text{else} \end{cases} \end{split}$$

- Requires
  - adjusted prediction model  $P^*(w_i|w_{i-N+1},...,w_{i-1})$
  - backoff weights  $\alpha(w_1,...,w_{N-1})$

## Katz Back-off Models (Bigrams)

• For a bigram model, define two sets

$$\mathcal{A}(w_{i-1}) = \{w : \text{Count}(w_{i-1}, w) > 0\}$$
  
 $\mathcal{B}(w_{i-1}) = \{w : \text{Count}(w_{i-1}, w) = 0\}$ 

• A bigram model

$$P_{KATZ}(w_i \mid w_{i-1}) = \begin{cases} \frac{\operatorname{Count}^*(w_{i-1}, w_i)}{\operatorname{Count}(w_{i-1})} & \text{If } w_i \in \mathcal{A}(w_{i-1}) \\ \\ \alpha(w_{i-1}) \frac{P_{ML}(w_i)}{\sum_{w \in \mathcal{B}(w_{i-1})} P_{ML}(w)} & \text{If } w_i \in \mathcal{B}(w_{i-1}) \end{cases}$$

where

$$\alpha(w_{i-1}) = 1 - \sum_{w \in A(w_{i-1})} \frac{\text{Count}^*(w_{i-1}, w)}{\text{Count}(w_{i-1})}$$

## Katz Back-off Models (Trigrams)

• For a trigram model, first define two sets

$$\mathcal{A}(w_{i-2}, w_{i-1}) = \{ w : \text{Count}(w_{i-2}, w_{i-1}, w) > 0 \}$$

$$\mathcal{B}(w_{i-2}, w_{i-1}) = \{ w : \text{Count}(w_{i-2}, w_{i-1}, w) = 0 \}$$

• A trigram model is defined in terms of the bigram model:

$$P_{KATZ}(w_i \mid w_{i-2}, w_{i-1}) = \begin{cases} \frac{\text{Count}^*(w_{i-2}, w_{i-1}, w_i)}{\text{Count}(w_{i-2}, w_{i-1})} \\ \frac{\alpha(w_{i-2}, w_{i-1}) P_{KATZ}(w_i \mid w_{i-1})}{\sum_{w \in \mathcal{B}(w_{i-2}, w_{i-1})} P_{KATZ}(w_i \mid w_{i-1})} \\ \text{If } w_i \in \mathcal{B}(w_{i-2}, w_{i-1}) \end{cases}$$

where

$$\alpha(w_{i-2}, w_{i-1}) = 1 - \sum_{w \in \mathcal{A}(w_{i-2}, w_{i-1})} \frac{\text{Count}^*(w_{i-2}, w_{i-1}, w)}{\text{Count}(w_{i-2}, w_{i-1})}$$

### Do our smoothing methods work here?

Example from MacKay and Bauman Peto (1994):

Imagine, you see, that the language, you see, has, you see, a frequently occurring couplet, 'you see', you see, in which the second word of the couplet, 'see', follows the first word, 'you', with very high probability, you see. Then the marginal statistics, you see, are going to become hugely dominated, you see, by the words 'you' and 'see', with equal frequency, you see.

- $\bullet$  P(see) and P(you) both high, but see nearly always follows you.
- So P(see|novel) should be much lower than P(you|novel).

# Diversity of histories matters!

- A real example: the word York
  - fairly frequent word in Europarl corpus, occurs 477 times
  - as frequent as foods, indicates and providers
  - → in unigram language model: a respectable probability
- However, it almost always directly follows New (473 times)
- So, in unseen bigram contexts, York should have low probability
  - lower than predicted by unigram model used in interpolation or backoff.

# **Kneser-Ney Smoothing**

- Kneser-Ney smoothing takes diversity of histories into account
- Count of distinct histories for a word:

$$N_{1+}(\bullet w_i) = |\{w_{i-1} : c(w_{i-1}, w_i) > 0\}|$$

• Recall: maximum likelihood est. of unigram language model:

$$P_{ML}(w) = \frac{C(w_i)}{\sum_{w_i} C(w_i)}$$

• In KN smoothing, replace raw counts with count of histories:

$$P_{KN}(w_i) = \frac{N_{1+}(\bullet w)}{\sum_{w_i} N_{1+}(\bullet w_i)}$$

### **Kneser-Ney in practice**

- Original version used backoff, later "modified Kneser-Ney" introduced using interpolation (Chen and Goodman, 1998).
- Fairly complex equations, but until recently the best smoothing method for word n-grams.
- See Chen and Goodman for extensive comparisons of KN and other smoothing methods.
- KN (and other methods) implemented in language modelling toolkits like SRILM (classic), KenLM (good for really big models), OpenGrm Ngram library (uses finite state transducers), etc.

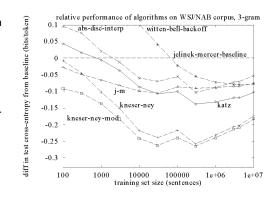
#### What works better in practice?

#### Trigrams and beyond:

- Unigrams, bigrams generally useless
- Trigrams much better (when there's enough data)
- 4-, 5-grams really useful in MT, but not so much for speech

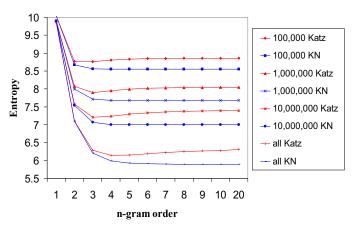
#### Discounting

- Absolute discounting, Good-Turing, held-out estimation, Witten-Bell, etc...
- See [Chen+Goodman] reading for tons of graphs...



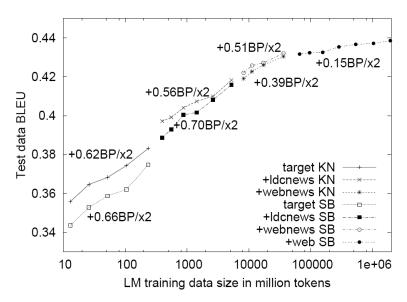
#### Data vs. Method?

Having more data is better…



- ... but so is using a better estimator
- Another issue: N > 3 has huge costs in speech recognizers

#### Data vs. Method?



Tons of data closes gap, for extrinsic MT evaluation

# Bayesian interpretations of smoothing

• We started by asking: What's the best  $\theta$  given the data d that we saw?

$$P(\theta|d) \propto P(d|\theta)P(\theta)$$

- MLE ignored  $P(\theta)$ , and we had to introduce smoothing.
- It turns out that many smoothing methods are mathematically equivalent to forms of Bayesian estimation, i.e., the use of non-uniform priors!
  - Add- $\alpha$  smoothing: Dirichlet prior
  - Kneser-Ney smoothing: Pitman-Yor prior

See MacKay and Bauman Peto (1994); (Goldwater, 2006, pp. 13-17); Goldwater et al. (2006); Teh (2006).

### Are we done with smoothing yet?

We've considered methods that predict rare/unseen words using

- Uniform probabilities (add- $\alpha$ , Good-Turing)
- Probabilities from lower-order n-grams (interpolation, backoff)
- Probability of appearing in new contexts (Kneser-Ney)

What's left?

## Word similarity

- Two words with  $C(w_1) \gg C(w_2)$ 
  - salmon
  - swordfish
- Can P(salmon|caught two) tell us something about P(swordfish|caught two)?
- *n*-gram models: no.

# Word similarity in language modeling

- Early version: class-based language models (J&M 4.9.2)
  - Define classes c of words, by hand or automatically
  - $-P_{CL}(w_i|w_{i-1}) = P(c_i|c_{i-1})P(w_i|c_i)$  (an HMM)
- Recent version: distributed language models
  - Current models have better perplexity than MKN.
  - Ongoing research to make them more efficient.
  - Examples: Log Bilinear LM (Mnih and Hinton, 2007), Recursive Neural Network LM (Mikolov et al., 2010), LSTM LMs, etc.

# **Distributed word representations**

• Each word represented as high-dimensional vector (50-500 dims)

E.g., salmon is 
$$[0.1, 2.3, 0.6, -4.7, \ldots]$$

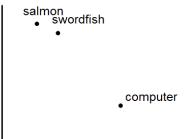
Similar words represented by similar vectors

```
E.g., swordfish is [0.3, 2.2, 1.2, -3.6, ...]
```

#### Training the model

• Goal: learn word representations (embeddings) such that words that behave similarly are close together in high-dimensional space.

2-dimensional example:



### Training the model

- $\bullet$  N-gram LM: collect counts, maybe optimize some parameters
  - (Relatively) quick, especially these days (minutes-hours)
- distributed LM: learn the representation for each word
  - Solved with machine learning methods (e.g., neural networks)
  - Can be extremely time-consuming (hours-days)
  - Learned embeddings seem to encode both semantic and syntactic similarity (using different dimensions) (Mikolov et al., 2013).

# Using the model

Want to compute  $P(w_1 \dots w_n)$  for a new sequence.

- ullet N-gram LM: again, relatively quick
- distributed LM: often prohibitively slow for real applications
- An active area of research for distributed LMs

# Other Topics in Language Modeling

Many active research areas in language modeling:

- Factored/morpheme-based language models: back off to word stems, part-of-speech tags, and/or other morphemes in word
- Syntactic language models: using parse trees
- Domain adaptation: when only a small domain-specific corpus is available
- Time efficiency and space efficiency are both key issues (esp on mobile devices!)

#### What about unknown words?

- **Q.** How to handle words in the test corpus that did not occur in the training data, i.e. **out of vocabulary (OOV)** words?
- **A.** Simple solution : Train a model that includes an explicit symbol for an unknown word (<UNK>).
  - Choose a vocabulary in advance and replace other words in the training corpus with <UNK>.
  - Replace the first occurrence of each word in the training data with <UNK>.