University of Gävle

# Title of the Thesis

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Program Name

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# Foreword

# Abstract

**Keywords: Keyword1, Keyword2, Keyword3, Keyword4, Keyword5**

# List of Abbreviations

**ROS** Robot Operating System

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## References

[1] E. Erős, M. Dahl, K. Bengtsson, A. Hanna, and P. Falkman, "A ros2 based communication architecture for control in collaborative and intelligent automation systems," *Procedia Manufacturing*, vol. 38, pp. 349–357, 2019, 29th International Conference on Flexible Automation and Intelligent Manufacturing ( FAIM 2019), June 24-28, 2019, Limerick, Ireland, Beyond Industry 4.0: Industrial Advances, Engineering Education and Intelligent Manufacturing. [Online]. Available: https://www.sciencedirect.com/science/article/pii/S2351978920300469

# Appendix A

# Appendix B