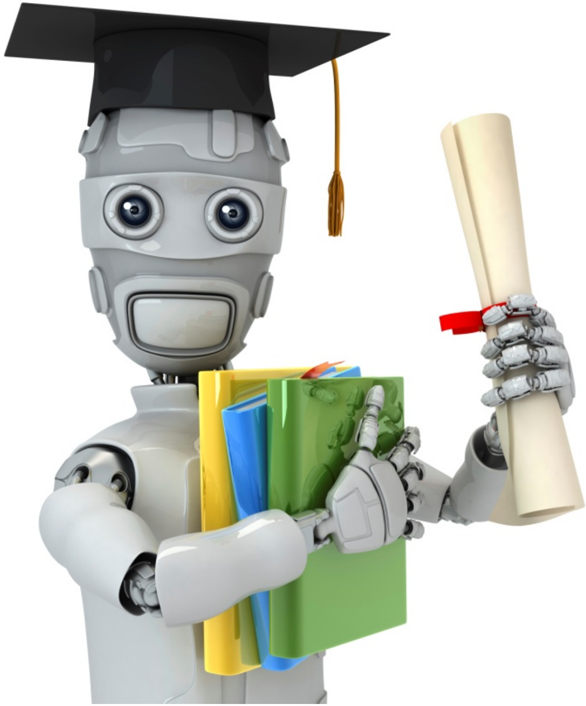


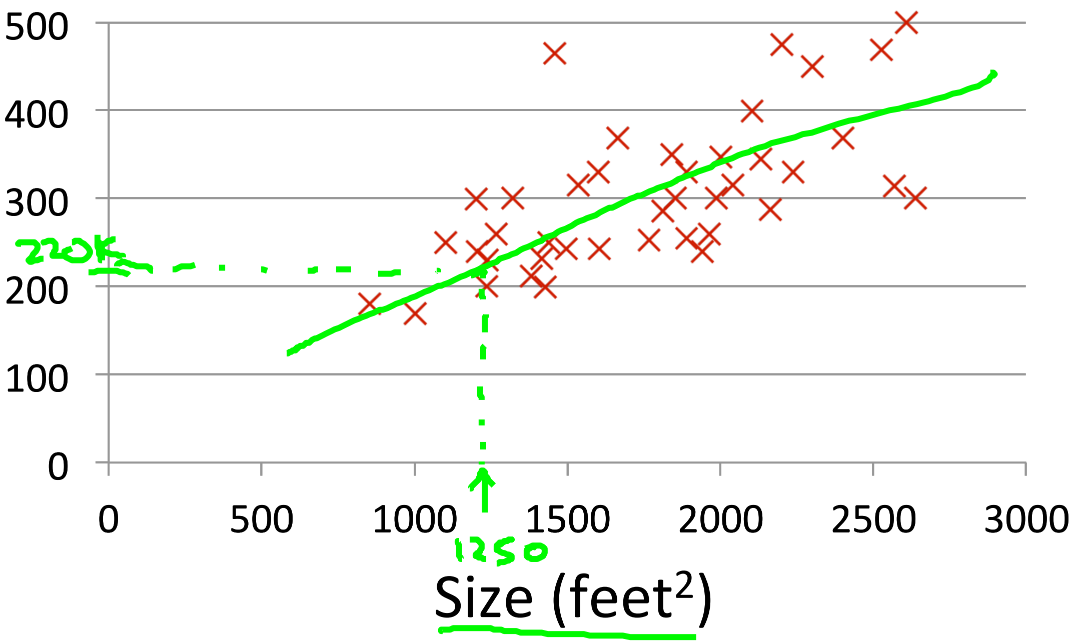
Machine Learning

Linear regression with one variable

Model representation

Housing Prices (Portland, OR)

Price
(in 1000s
of dollars)



<u>Supervised Learning</u>

Given the "right answer" for each example in the data.

<u>Regression</u> Problem

contious

Predict real-valued output

Classification: Discrete-valued output

Training set of housing prices (Portland, OR)

Size in feet^2 (x)	Price ($) in 1000's (y)
2104	460
1416	232
1534	315
852	178
...	...

m = 47

Notation:

- **m** = Number of training examples
- **x**'s = "input" variable / features
- **y**'s = "output" variable / "target" variable

(x, y) - one training example

$(x^{(i)}, y^{(i)})$ - i^{th} training example

$x^{(1)} = 2104$

$x^{(2)} = 1416$

$y^{(1)} = 460$

Andrew Ng

Training Set

↓

Learning Algorithm

↓

Size of house → h → Estimated price

x

hypothesis

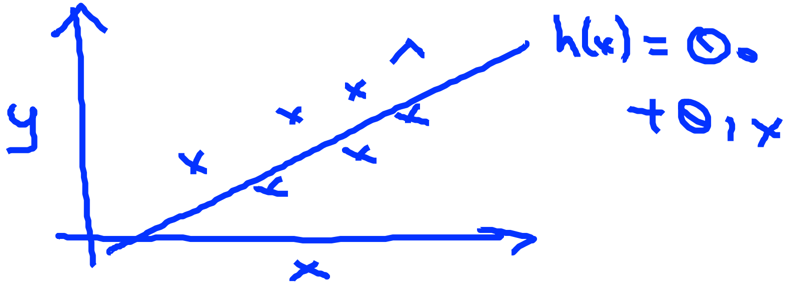
(estimated value of y)

h maps from x's to y's.

How do we represent h ?

$$h_\theta(x) = \theta_0 + \theta_1 x$$

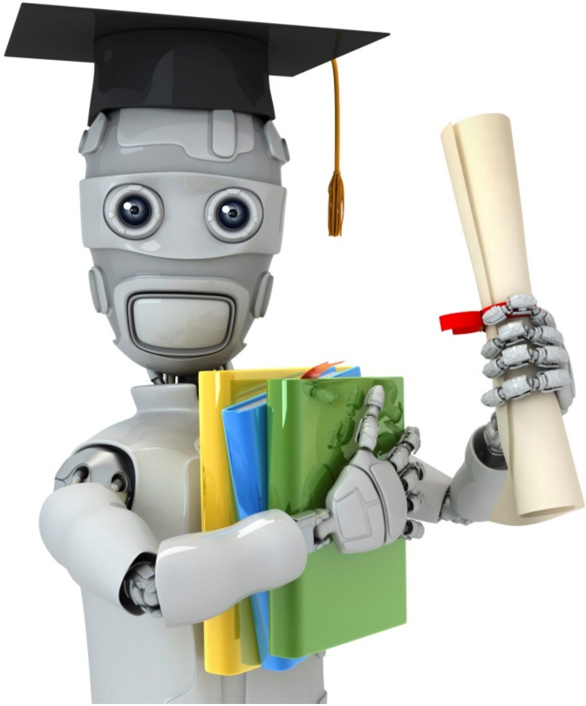
Shorthand: $h(x)$



Linear regression with one variable. (x)

Univariate linear regression.

└ one variable



Machine Learning

Linear regression with one variable

Cost function

Training Set

Size in feet² (x)	Price ($) in 1000's (y)
2104	460
1416	232
1534	315
852	178
…	…

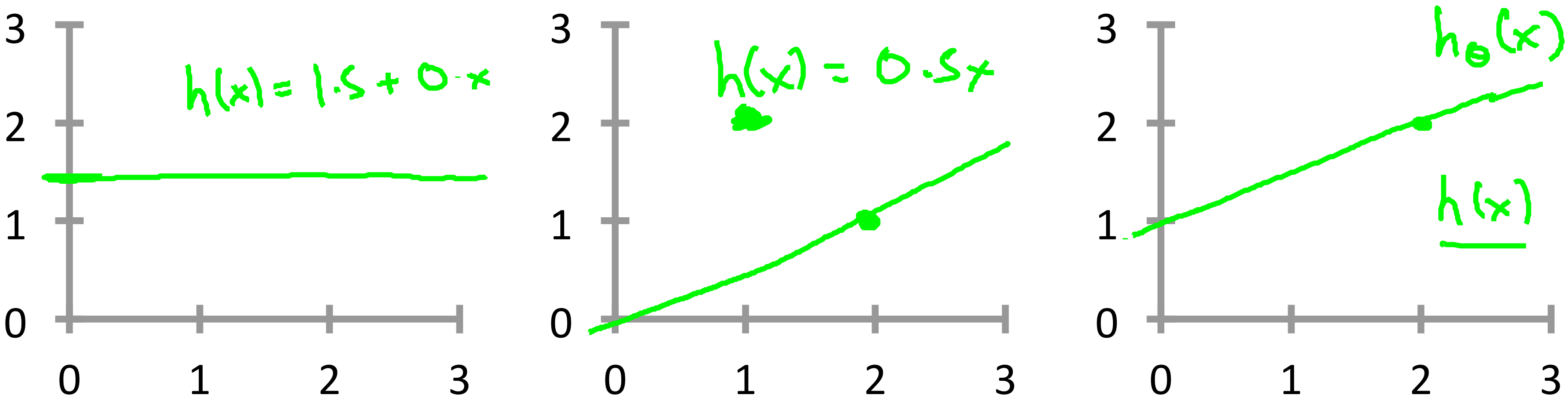
m = 47

Hypothesis: $h_\theta(x) = \theta_0 + \theta_1 x$

θ_i's: Parameters

How to choose θ_i's ?

$$\underline{h_\theta(x)} = \theta_0 + \theta_1 x$$

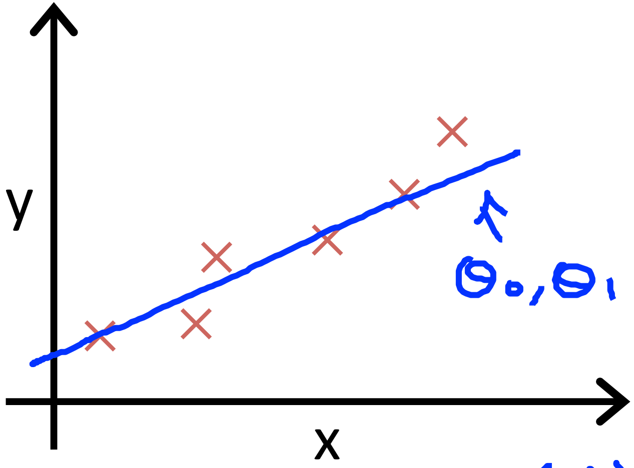


$\theta_0 = 1.5$
$\theta_1 = 0$

$\theta_0 = 0$
$\theta_1 = 0.5$

$\theta_0 = 1$
$\theta_1 = 0.5$

square takes account for both positive bias and negative bias
1/2 makes the function look nicer.



$(x^{(i)}, y^{(i)})$

training examples

$$\underset{\theta_0,\theta_1}{\text{minimize}} \frac{1}{2m}\sum_{i=1}^{m}\left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

$$h_\theta(x^{(i)}) = \theta_0 + \theta_1 x^{(i)}$$

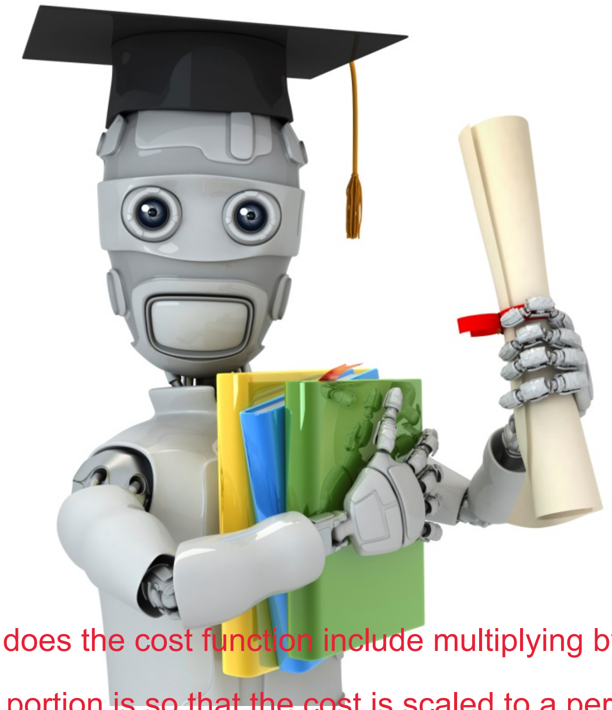
$$J(\theta_0,\theta_1) = \frac{1}{2m}\sum_{i=1}^{m}\left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

$$\underset{\theta_0,\theta_1}{\text{minimize}} \underbrace{J(\theta_0,\theta_1)}_{\text{Cost function}}$$

Squared error function

Idea: Choose θ_0, θ_1 so that $h_\theta(x)$ is close to y for our training examples (x, y)

x, y



Linear regression with one variable

Cost function intuition I

Q4) Why does the cost function include multiplying by 1/(2m)?

The '1/m' portion is so that the cost is scaled to a per-example basis.
Later in the course we will be comparing the cost value J for different sizes of training sets.

Machine Learning

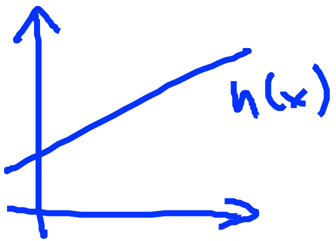
The '1/2' portion is a calculus trick, so that it will cancel with the '2' which appears
in the numerator when we compute the partial derivatives. This saves us a computation in the cost function.

Hypothesis:

$$h_\theta(x) = \theta_0 + \theta_1 x$$

Parameters:

$$\theta_0, \theta_1$$



Cost Function:

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

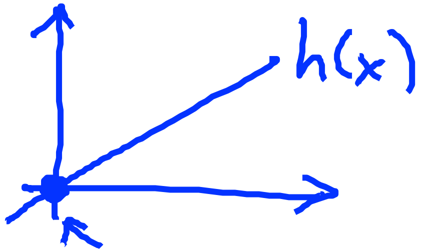
Goal: $\underset{\theta_0, \theta_1}{\text{minimize}}\ J(\theta_0, \theta_1)$

Simplified

$$h_\theta(x) = \theta_1 x$$

$\theta_0 = 0$

$$\theta_1$$



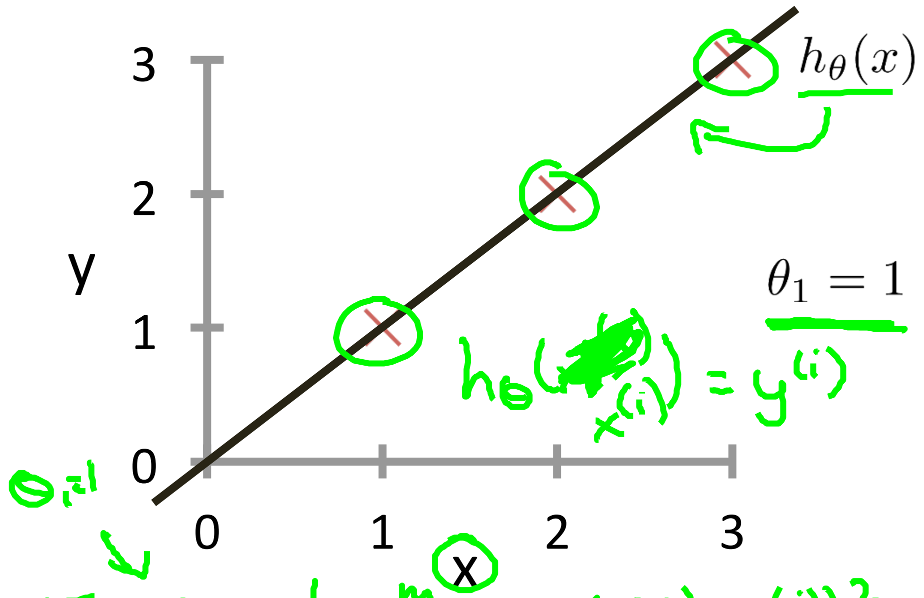
$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

$\theta, x^{(i)}$

$\underset{\theta_1}{\text{minimize}}\ J(\theta_1)$

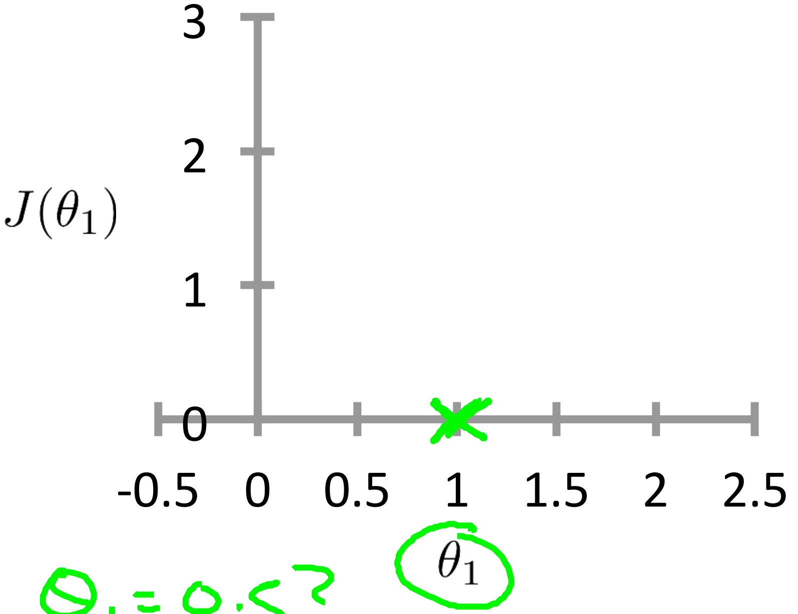
$h_\theta(x)$

(for fixed θ_1, this is a function of x)



$J(\theta_1)$

(function of the parameter θ_1)



$$J(\theta_1) = \frac{1}{2m}\sum_{i=1}^{m}\left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

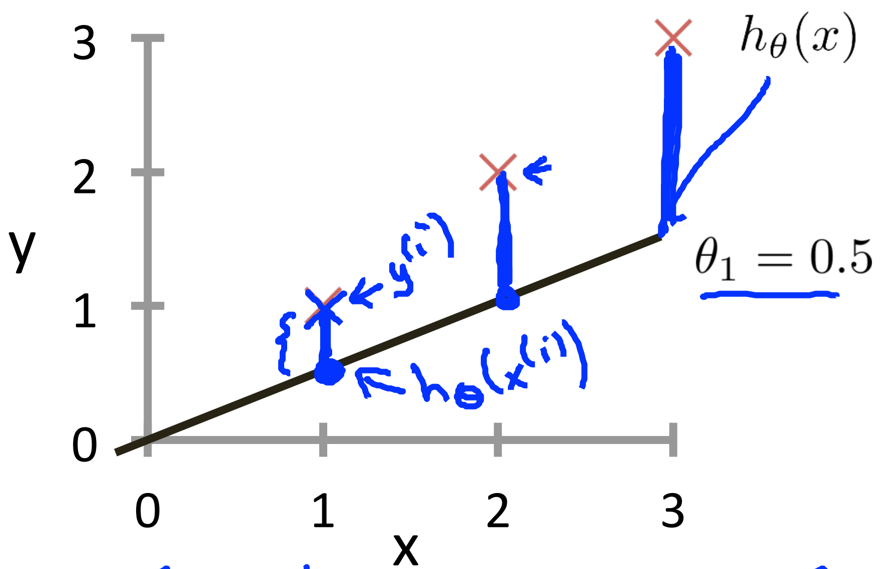
$$= \frac{1}{2m}\sum_{i=1}^{m}\left(\theta_1 x^{(i)} - y^{(i)}\right)^2 = \frac{1}{2m}(0^2+0^2+0^2) = 0^2$$

$\theta_1 = 0.5?$

$J(1) = 0$

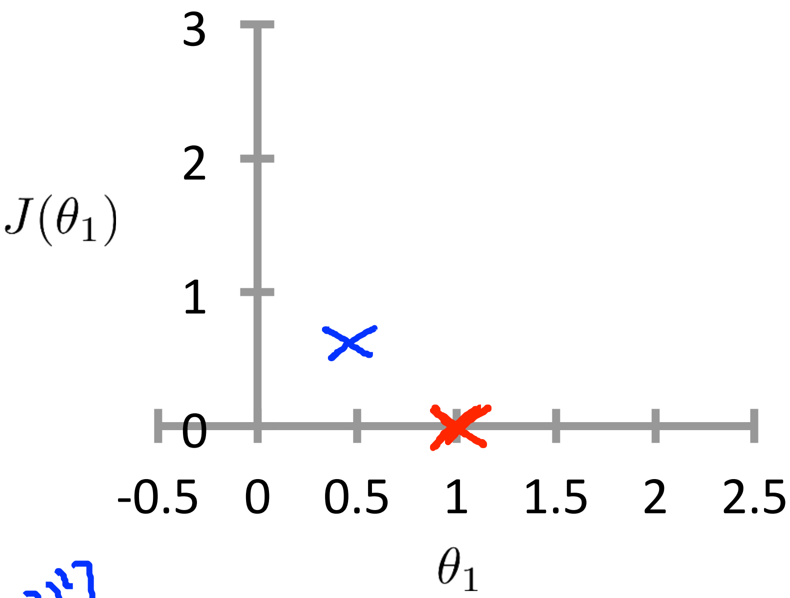
$h_\theta(x)$

(for fixed θ_1, this is a function of x)



$J(\theta_1)$

(function of the parameter θ_1)



$$J(0.5) = \frac{1}{2m}\left[(0.5-1)^2 + (1-2)^2 + (1.5-3)^2\right]$$

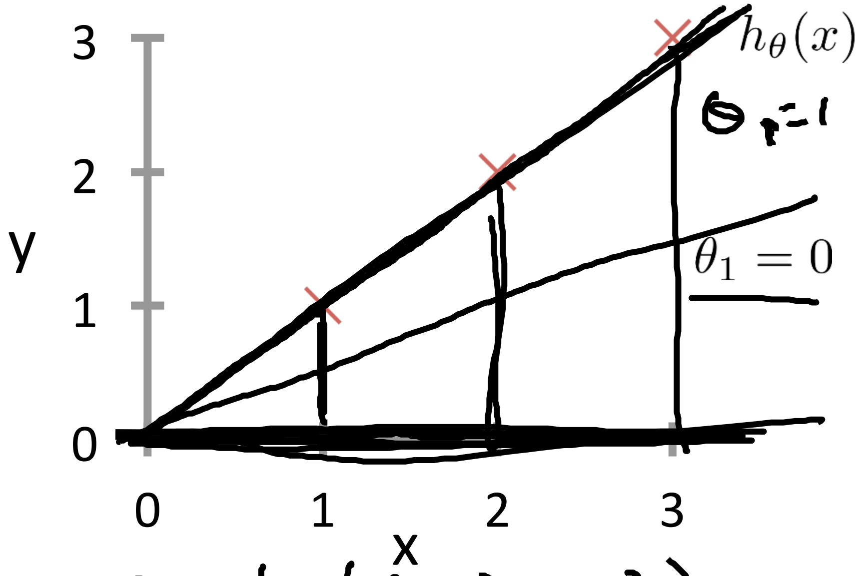
$$= \frac{1}{2\times 3}(3.5) = \frac{3.5}{6} \approx 0.58$$

$\theta_1 = 0?$

$J(0) = ?$

$h_\theta(x)$

(for fixed θ_1, this is a function of x)

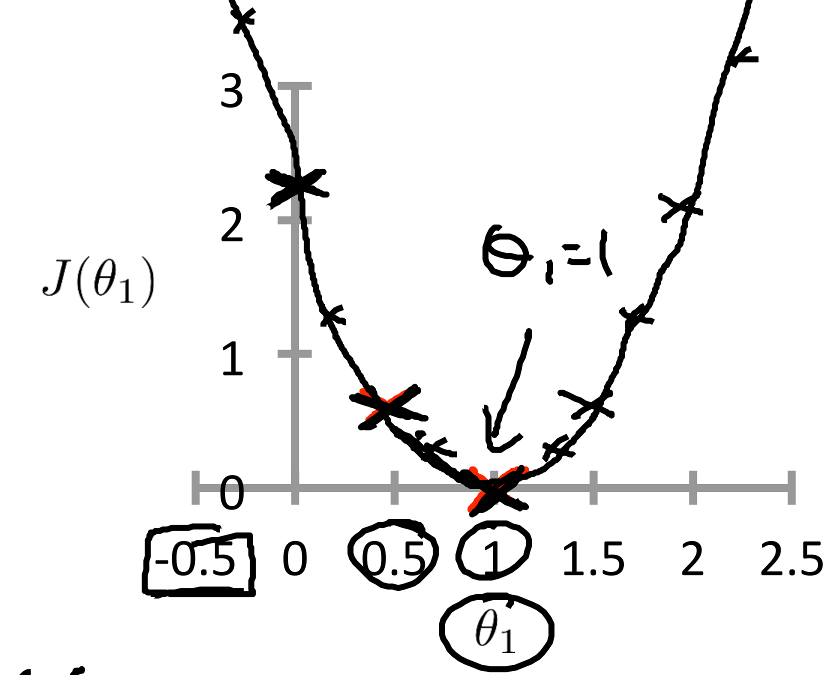


$J(0) = \frac{1}{2m}(1^2 + 2^2 + 3^2)$

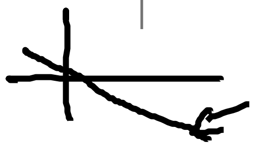
$= \frac{1}{6} \cdot 14 \approx 2.3$

$J(\theta_1)$

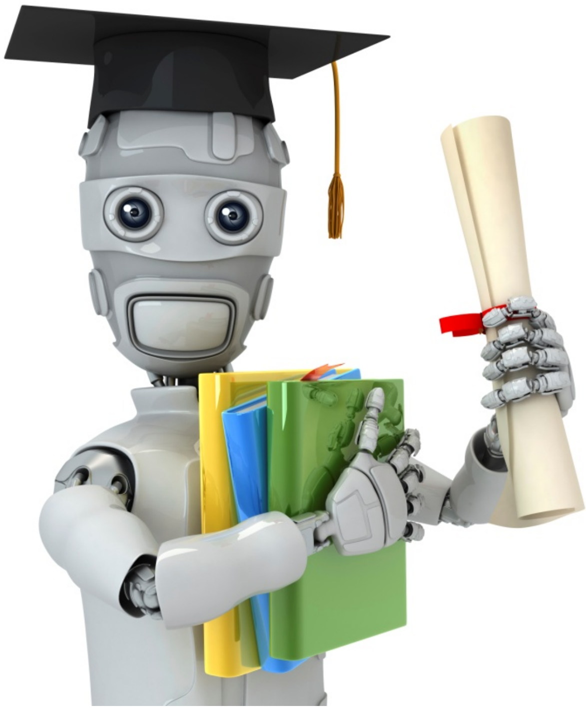
(function of the parameter θ_1)



$h(x) = -0.5x$



$\underset{\theta_1}{\text{minimize}}\ J(\theta_1)$



Machine Learning

Linear regression with one variable

Cost function intuition II

Hypothesis: $h_\theta(x) = \theta_0 + \theta_1 x$

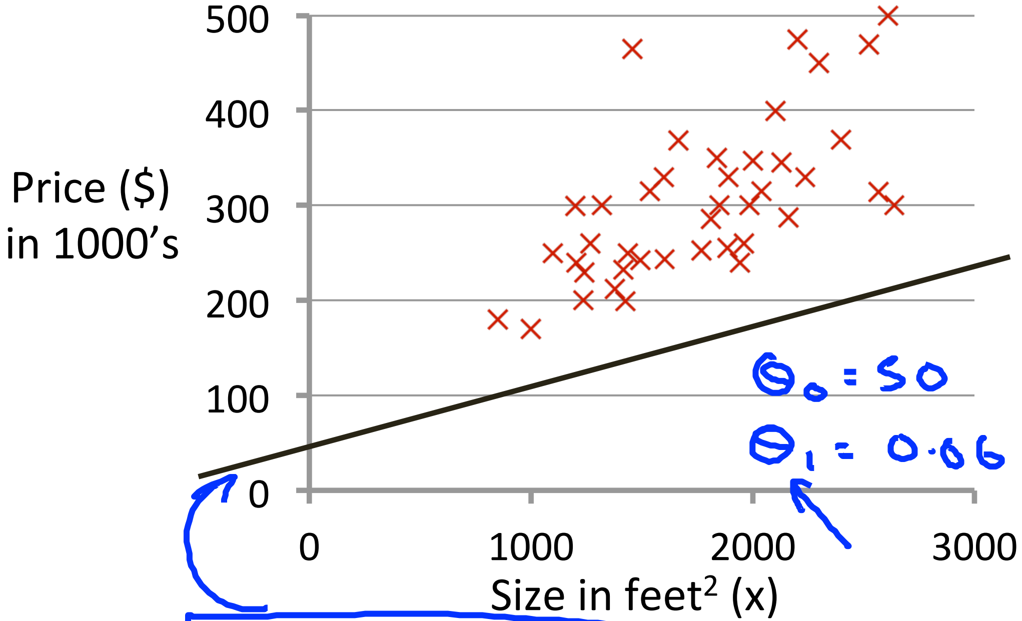
Parameters: θ_0, θ_1

Cost Function: $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$

Goal: $\underset{\theta_0, \theta_1}{\text{minimize}}\ J(\theta_0, \theta_1)$

$h_\theta(x)$

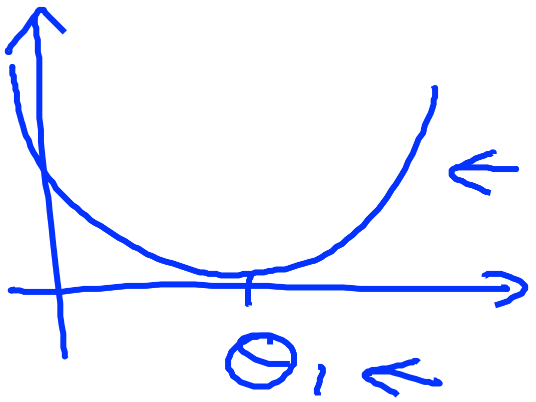
(for fixed θ_0, θ_1, this is a function of x)



$$\boxed{h_\theta(x) = 50 + 0.06x}$$

$J(\theta_0, \theta_1)$

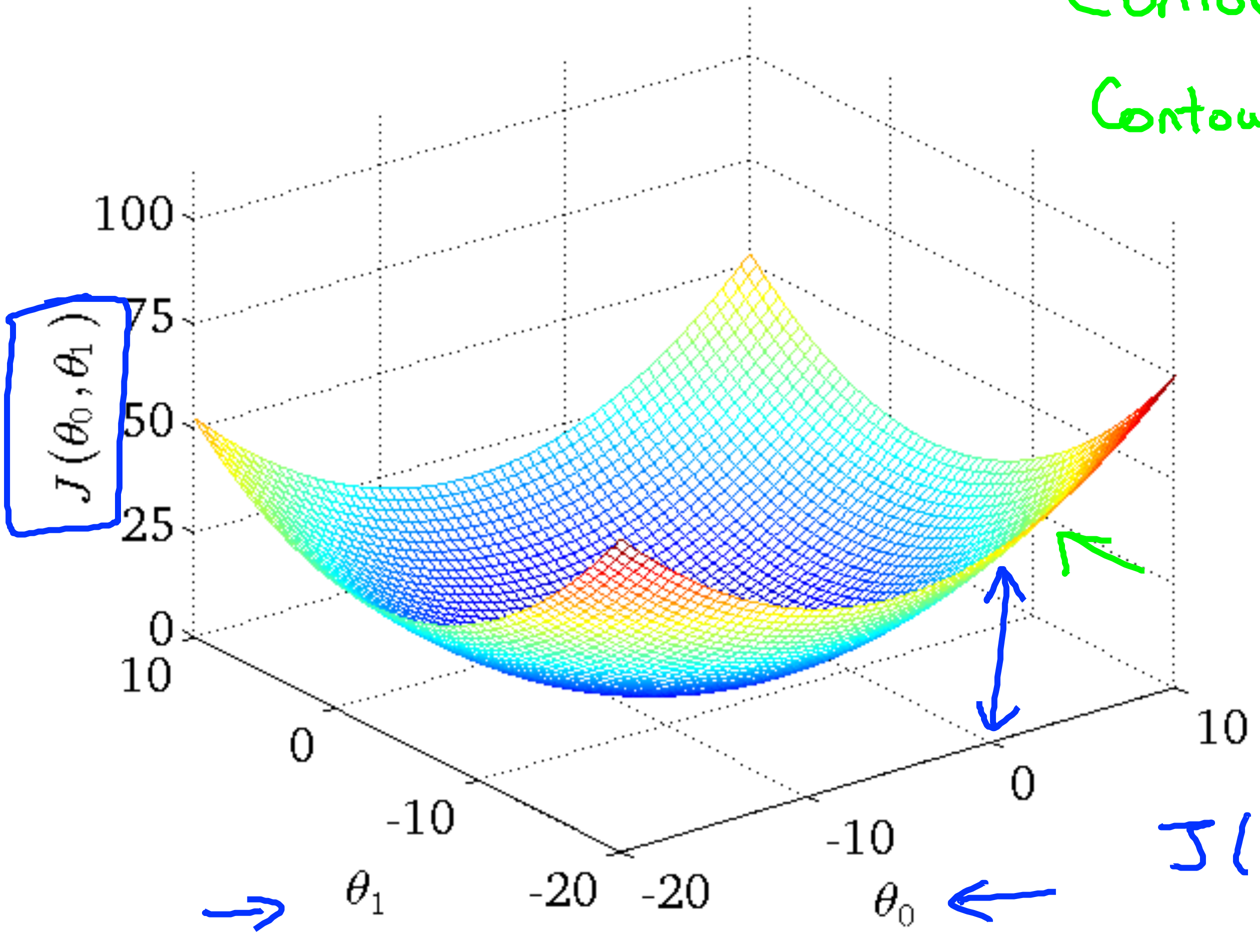
(function of the parameters θ_0, θ_1)



$$\boxed{\theta_0, \theta_1}$$

Contour plots

Contour figures.

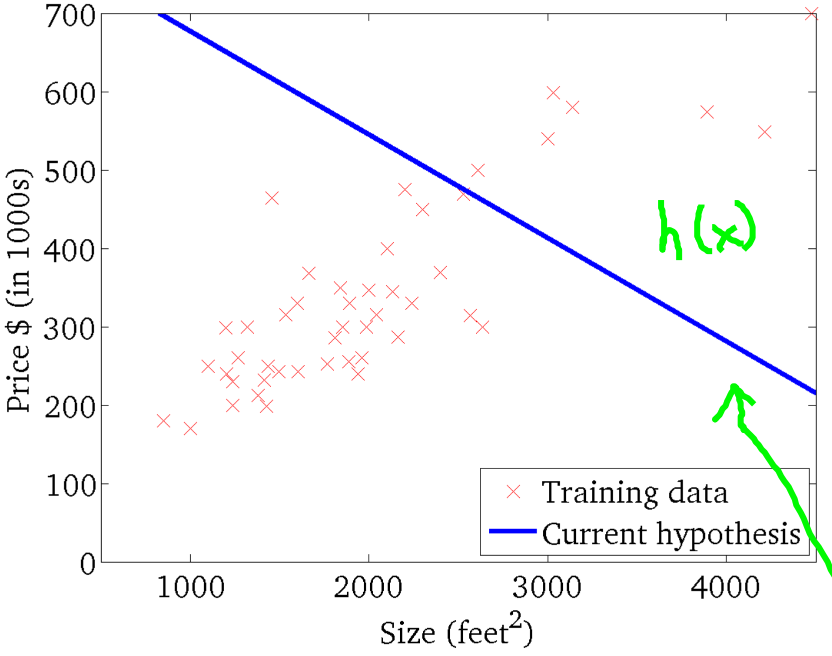


$J(\theta_0, \theta_1)$

Andrew Ng

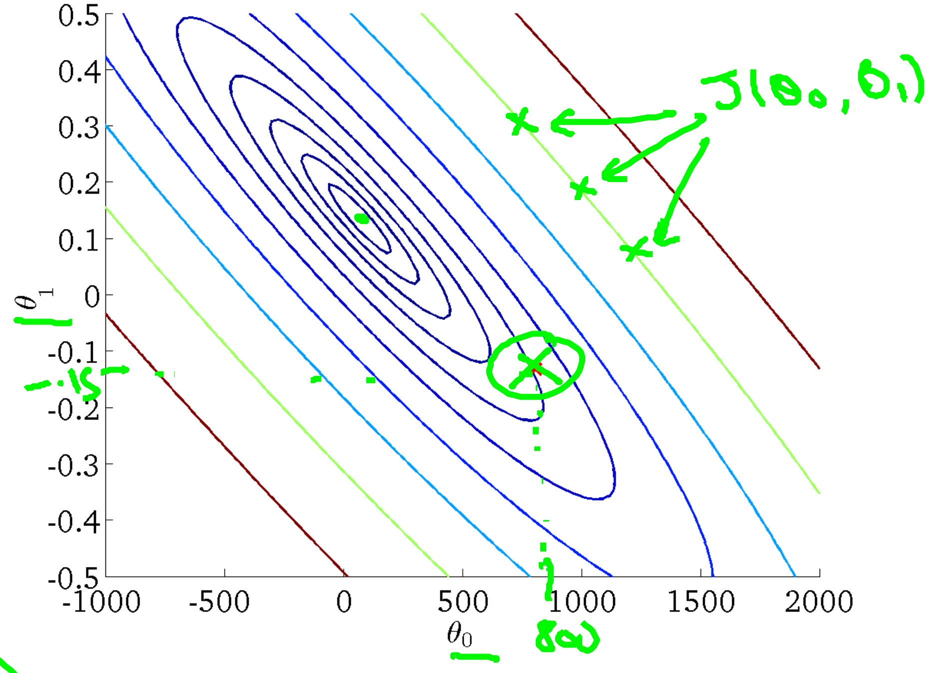
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

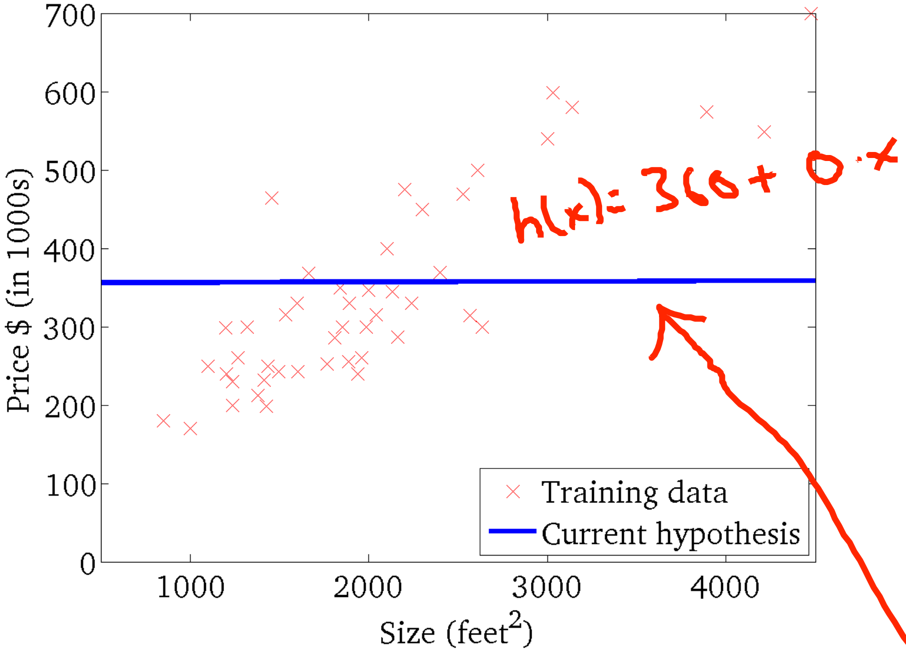
(function of the parameters θ_0, θ_1)



θ_0, θ_1

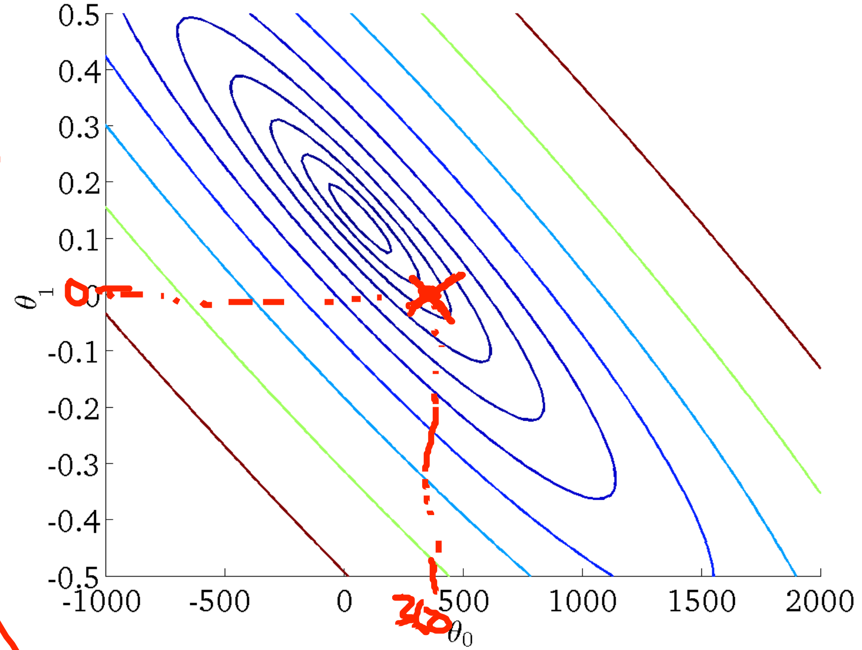
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)

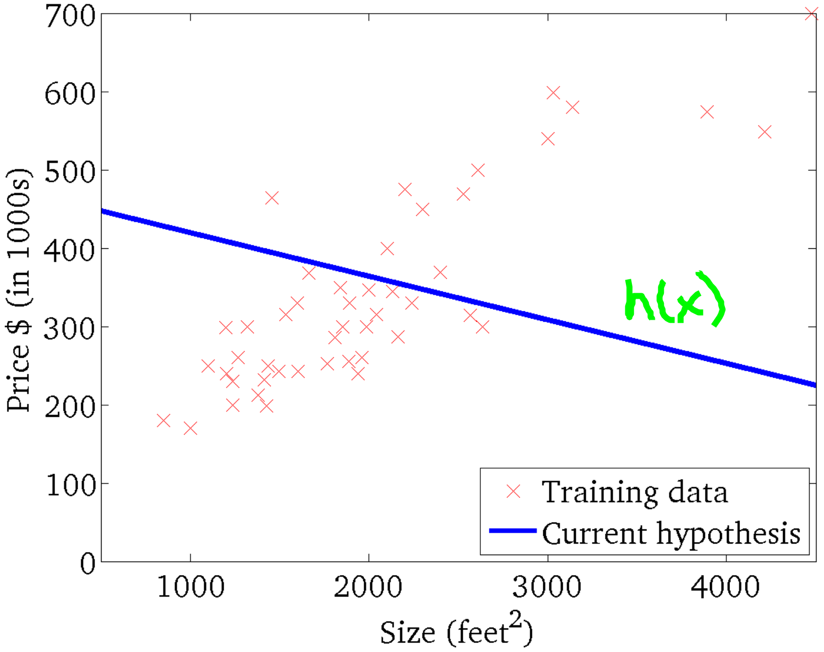


$\theta_0 = 360$

$\theta_1 = 0$

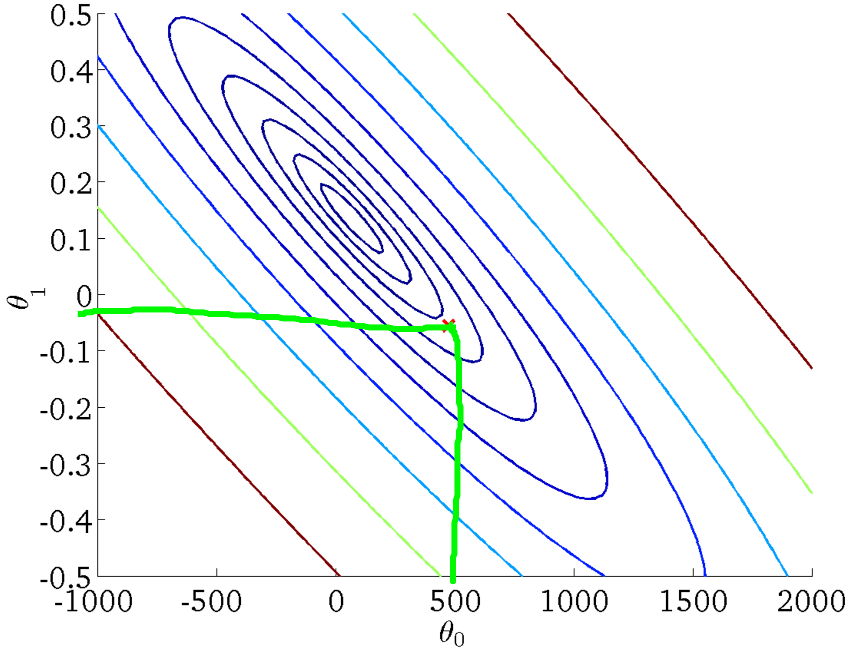
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

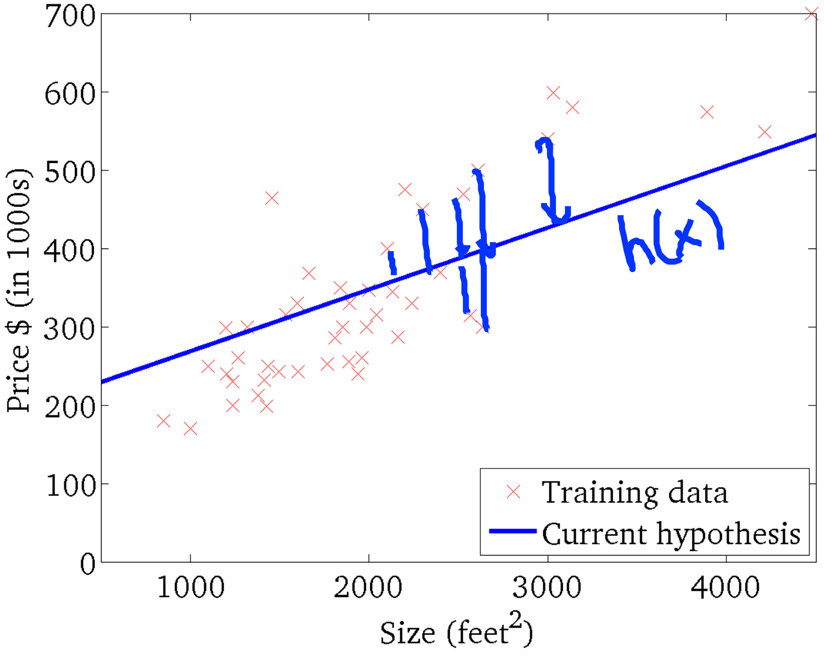
(function of the parameters θ_0, θ_1)



Andrew Ng

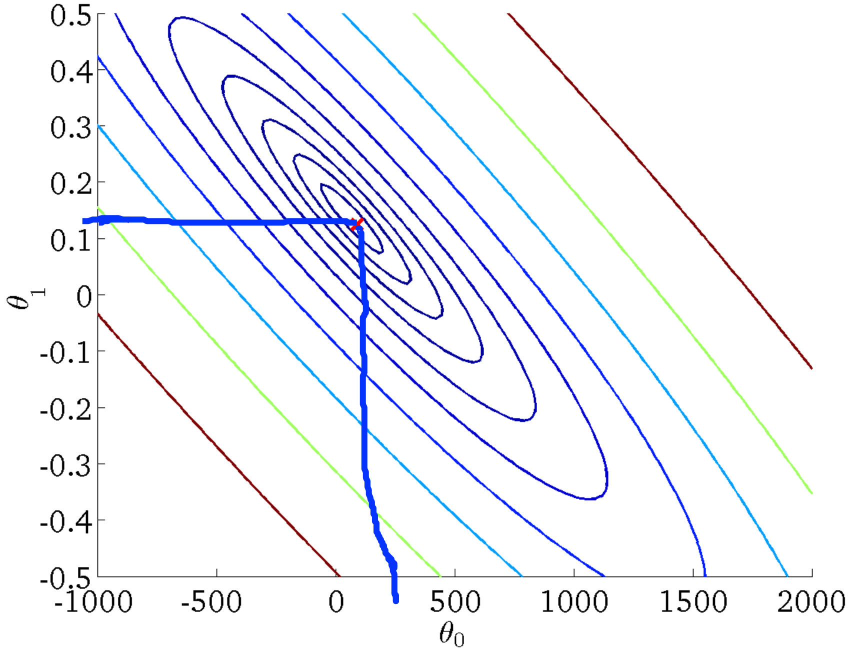
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)

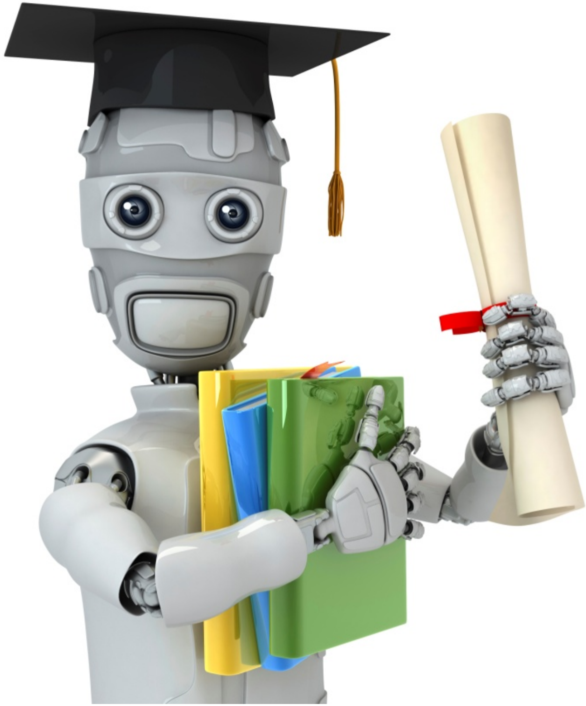


$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



Andrew Ng



Machine Learning

Linear regression with one variable

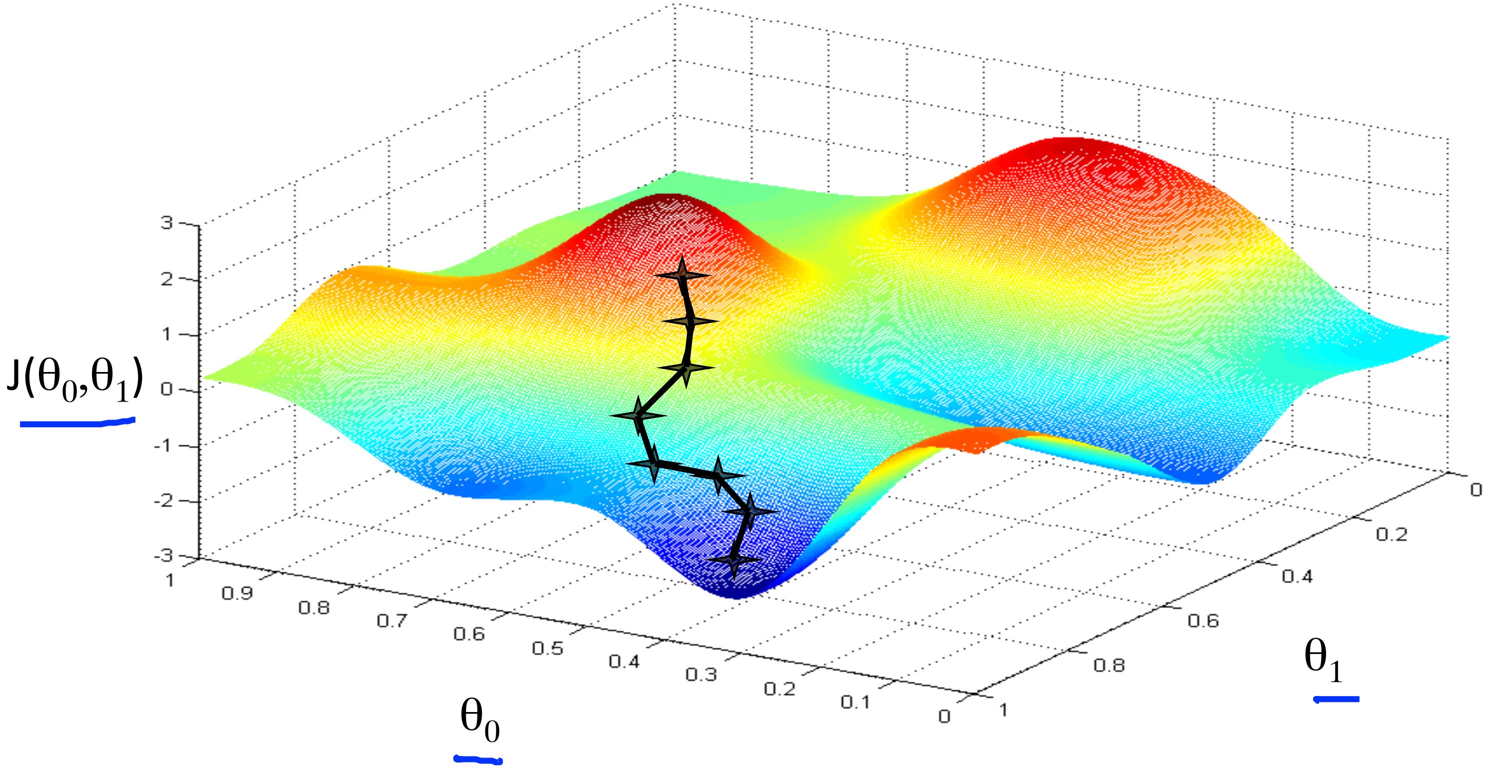
Gradient descent

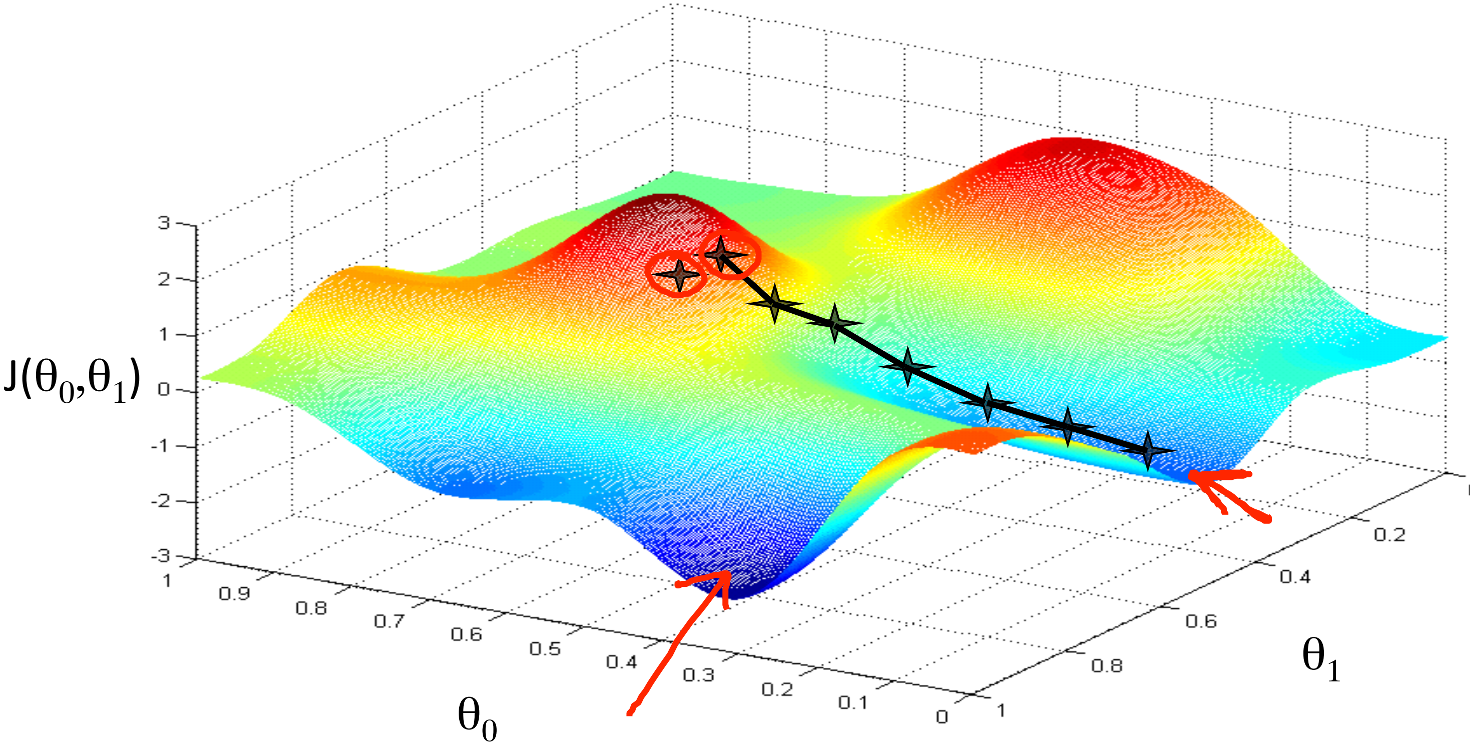
Have some function $J(\theta_0, \theta_1)$ $J(\theta_0, \theta_1, \theta_2, \dots, \theta_n)$

Want $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$ $\min_{\theta_0, \dots, \theta_n} J(\theta_0, \dots, \theta_n)$

Outline:

- Start with some θ_0, θ_1 (say $\theta_0 = 0, \theta_1 = 0$)
- Keep changing θ_0, θ_1 to reduce $J(\theta_0, \theta_1)$ until we hopefully end up at a minimum


J(θ0,θ1)
3
2
1
0
-1
-2
-3
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ0
0
0.2
0.4
0.6
0.8
1
θ1


$J(\theta_0,\theta_1)$
3
2
1
0
-1
-2
-3
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ_0
0
0.2
0.4
0.6
0.8
1
θ_1

Andrew Ng

Gradient descent algorithm

Assignment

$a := b$

$a := a+1$

Truth assertion

$a = b$

$\cancel{a = a+1}$

θ_0, θ_1

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad (\text{for } j = 0 \text{ and } j = 1)$$

}

learning rate

Simultaneously update θ_0 and θ_1

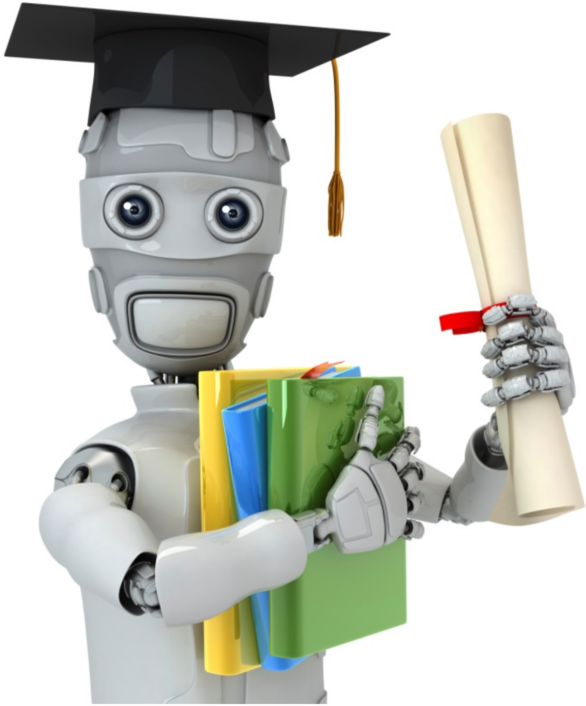
contols how big step we take downhill with creating descent

Correct: Simultaneous update

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$
$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$
$$\theta_0 := \text{temp0}$$
$$\theta_1 := \text{temp1}$$

Incorrect:

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$
$$\theta_0 := \text{temp0}$$
$$\text{temp1} := \theta_1 - \boxed{\alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)}$$
$$\theta_1 := \text{temp1}$$



Machine Learning

Linear regression with one variable

Gradient descent intuition

Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \boxed{\frac{\partial}{\partial\theta_j} J(\theta_0, \theta_1)} \quad \text{(simultaneously update } j = 0 \text{ and } j = 1\text{)}$$

}

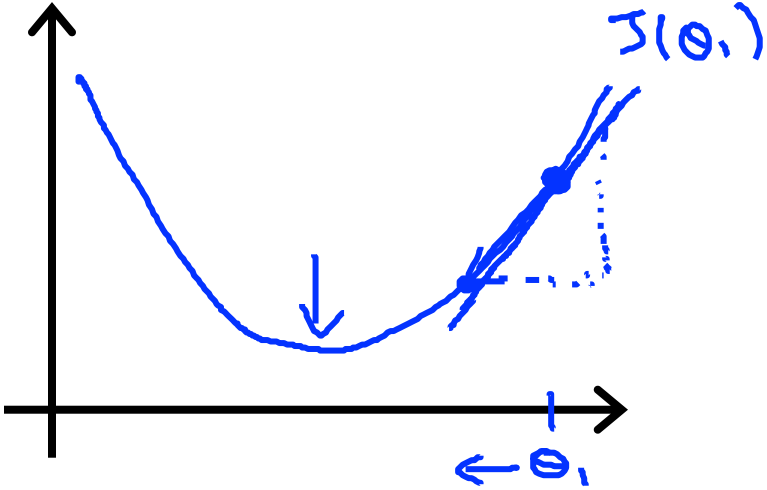
learning rate

derivative

partial derivative of function J respect to variable theta i, keep other variables unchange.

$$\min_{\theta_1} J(\theta_1)$$

$\theta_1 \in \mathbb{R}$.

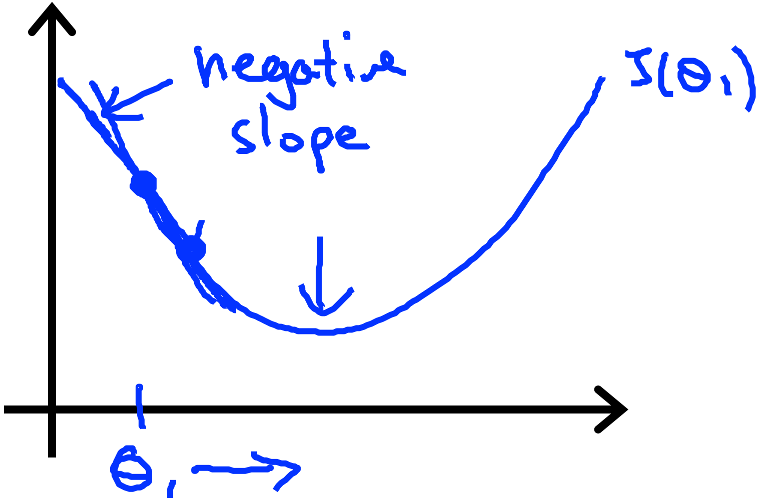


$(\theta_1 \in \mathbb{R})$

$\frac{\partial}{\partial \theta_1}$

$$\theta_1 := \theta_1 - \alpha \underbrace{\boxed{\frac{d}{d\theta_1} J(\theta_1)}}_{\geq 0}$$

$$\theta_1 := \theta_1 - \underline{\alpha} \cdot (\text{positive number})$$

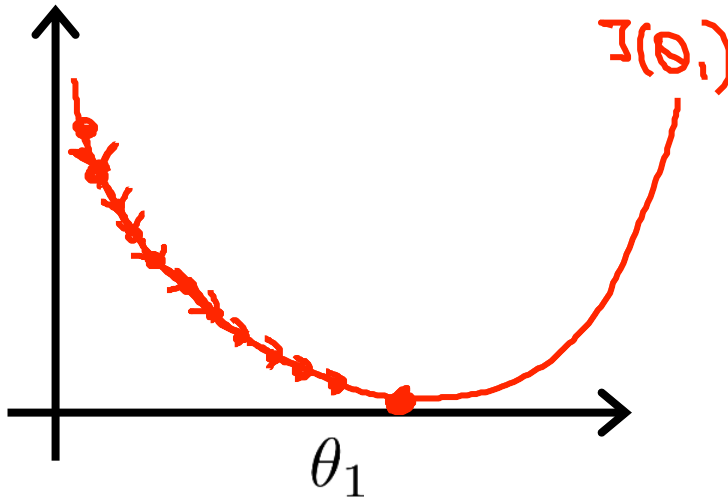


$$\frac{\frac{d}{d\theta_1} J(\theta_1)}{\leq 0}$$

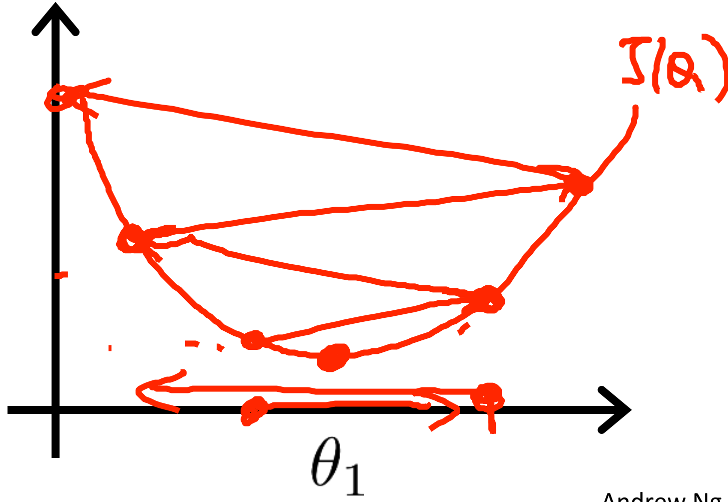
$$\theta_1 := \underline{\theta_1} - \alpha \, (\text{negative number})$$

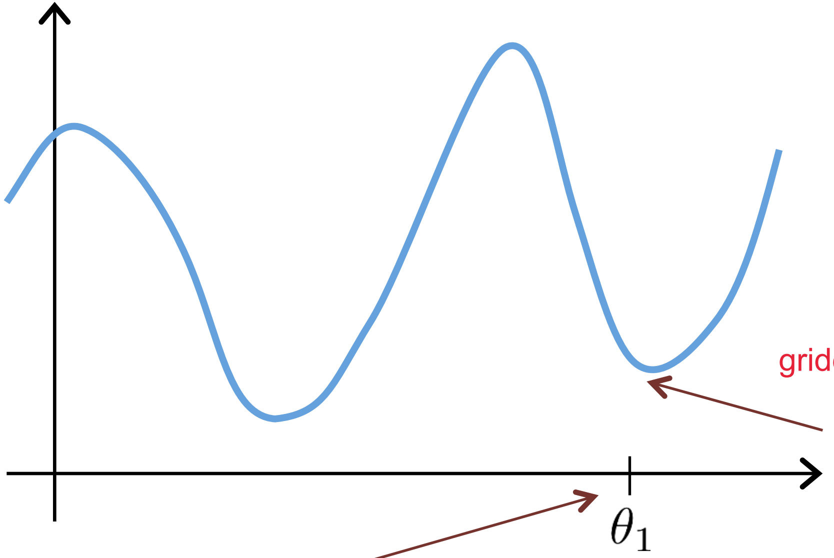
$$\boxed{\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)}$$

If α is too small, gradient descent can be slow.



If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.





gridient will keep unchange

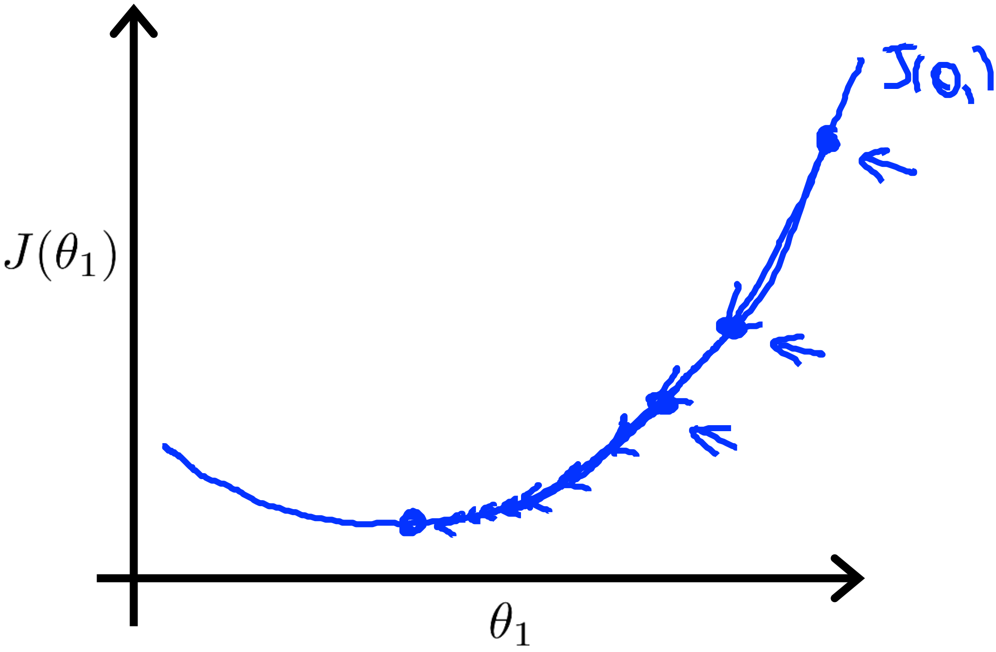
θ_1 at local optima

Current value of θ_1

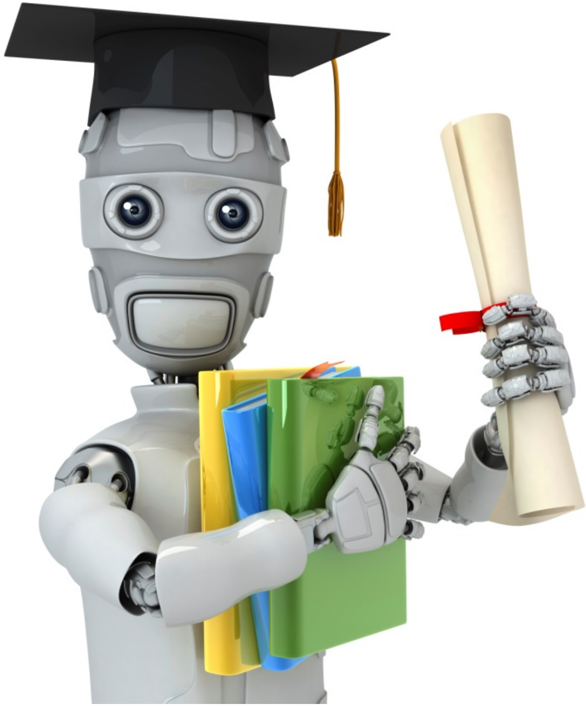
$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

Gradient descent can converge to a local minimum, even with the learning rate α fixed.

$$\theta_1 := \theta_1 - \alpha \boxed{\frac{d}{d\theta_1} J(\theta_1)}$$



As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease α over time.



Machine Learning

Linear regression with one variable

Gradient descent for linear regression

Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

$$(\text{for } j = 1 \text{ and } j = 0)$$

}

Linear Regression Model

$$h_\theta(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

Why apply Gradient descent algorithm to Linear Regression Model?

it's computationally cheaper (faster) to find the solution using the gradient descent in some cases.

$$\frac{\partial}{\partial \theta_j} \underline{J(\theta_0, \theta_1)} = \frac{\partial}{\partial \theta_j} \underline{\frac{1}{2m} \sum_{i=1}^{m} \left(\underline{h_\theta(x^{(i)}} - y^{(i)}\right)^2}$$

$$= \frac{\partial}{\partial \theta_j} \frac{1}{2m} \sum_{i=1}^{m} \left(\underline{\theta_0 + \theta_1 x^{(i)}} - y^{(i)}\right)^2$$

take only theta 0 as variable

$$j = 0 : \underline{\frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)$$

take only theta 1 as variable

$$j = 1 : \underline{\frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right) \cdot x^{(i)}$$

Gradient descent algorithm

$$\frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

repeat until convergence {

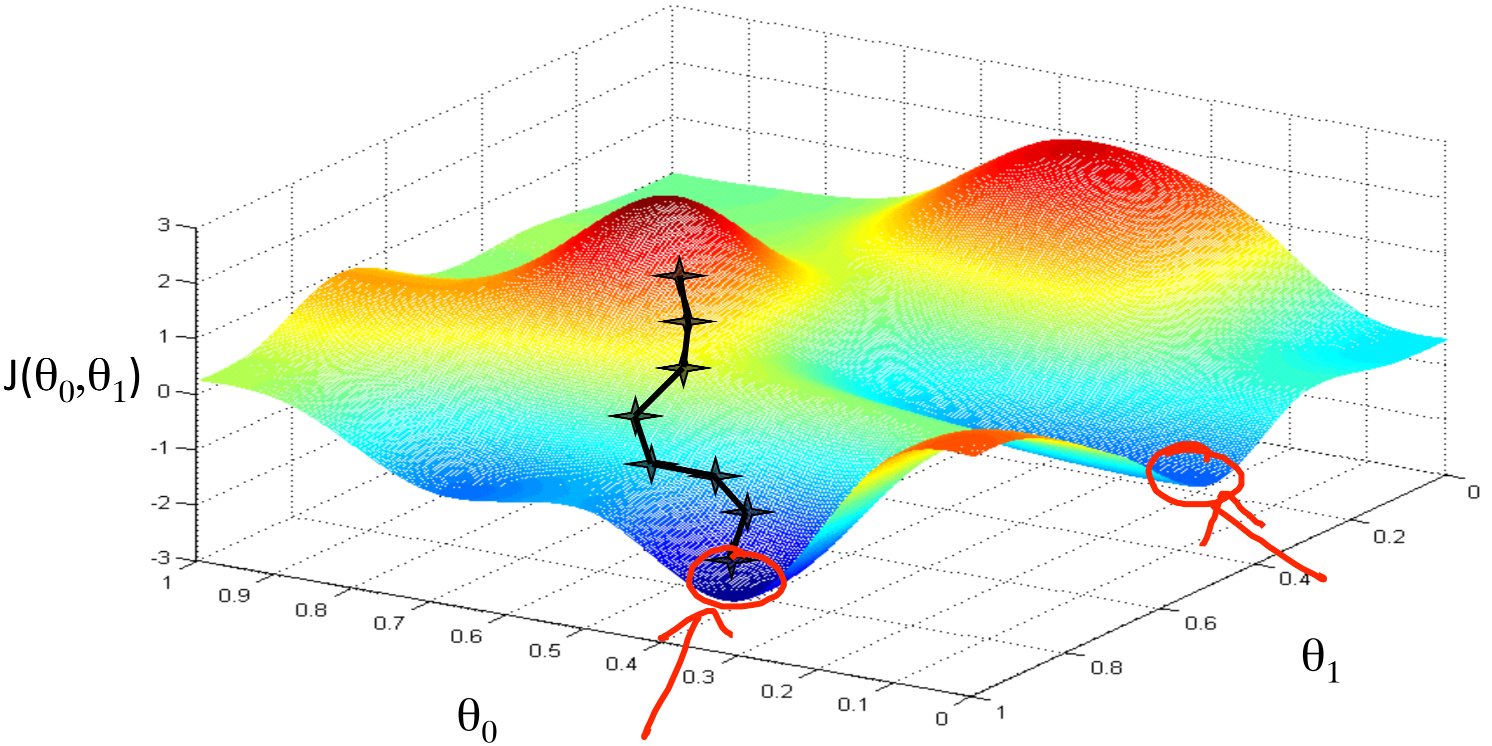
$$\theta_0 := \theta_0 - \alpha \boxed{\frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right)}$$

$$\theta_1 := \theta_1 - \alpha \boxed{\frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}}$$

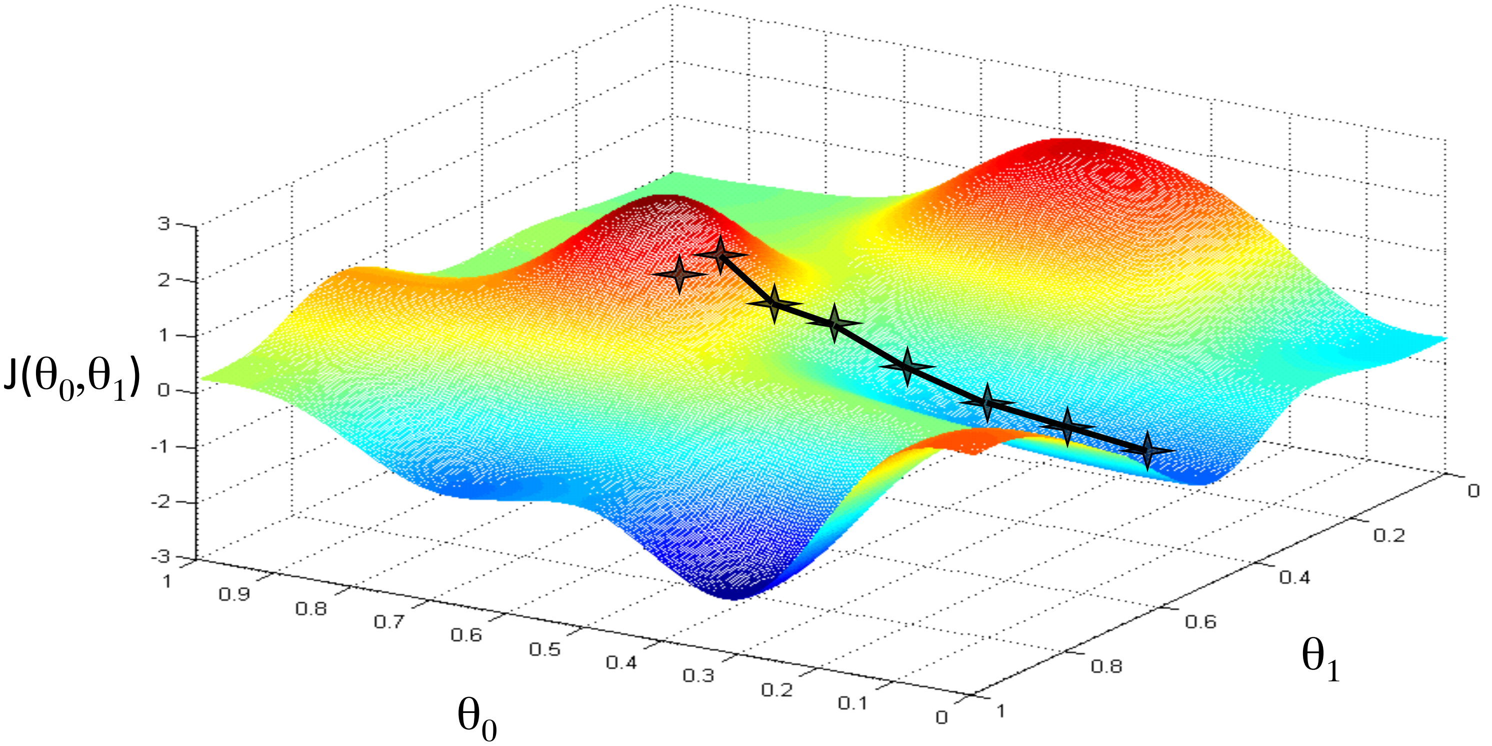
}

$$\frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

update θ_0 and θ_1 simultaneously



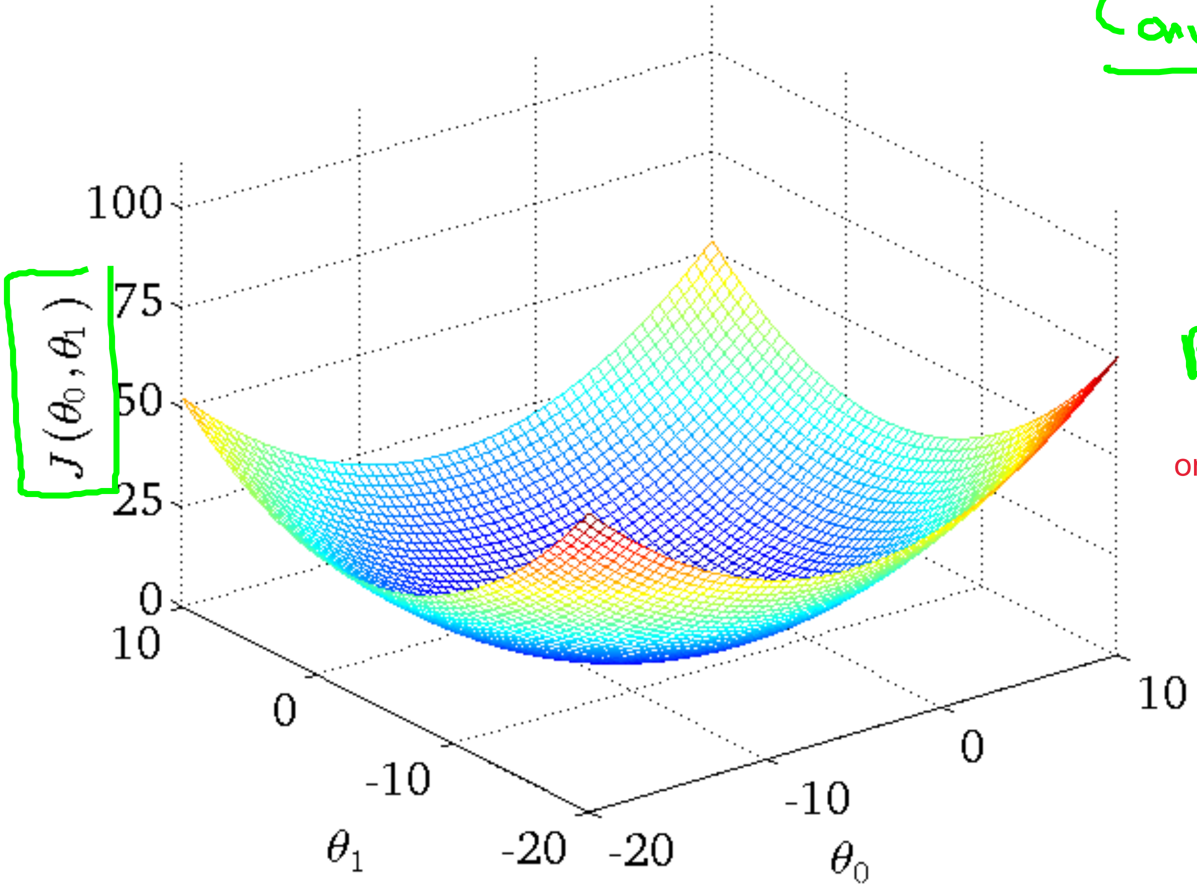
3
2
1
0
-1
-2
-3
$J(\theta_0,\theta_1)$
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ_0
0
0.2
0.4
0.6
0.8
1
θ_1



$J(\theta_0,\theta_1)$
3
2
1
0
-1
-2
-3
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ_0
0
0.2
0.4
0.6
0.8
1
θ_1

Andrew Ng

"Convex function"

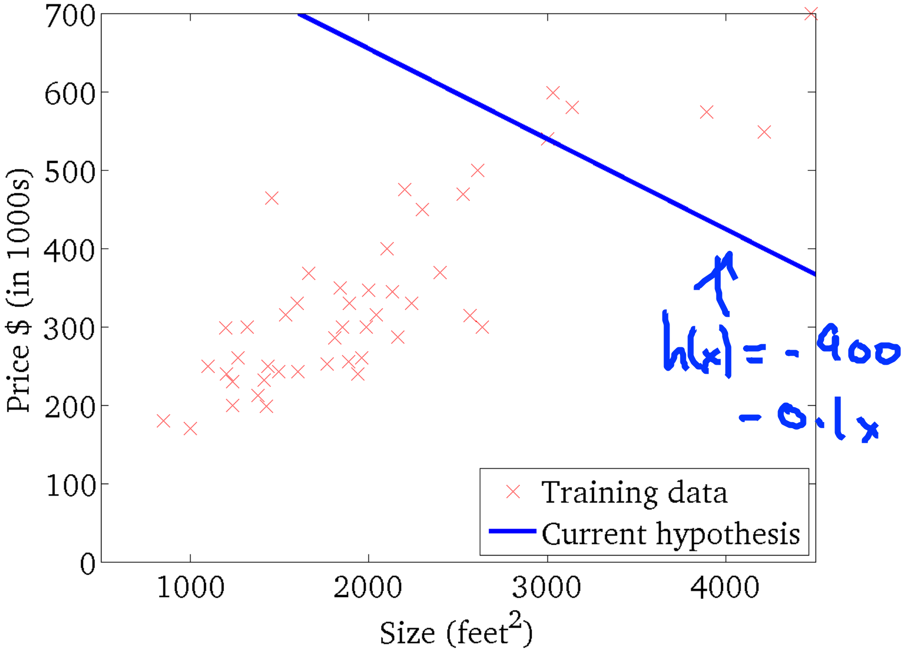


Bowl-shaped

only one global minimum

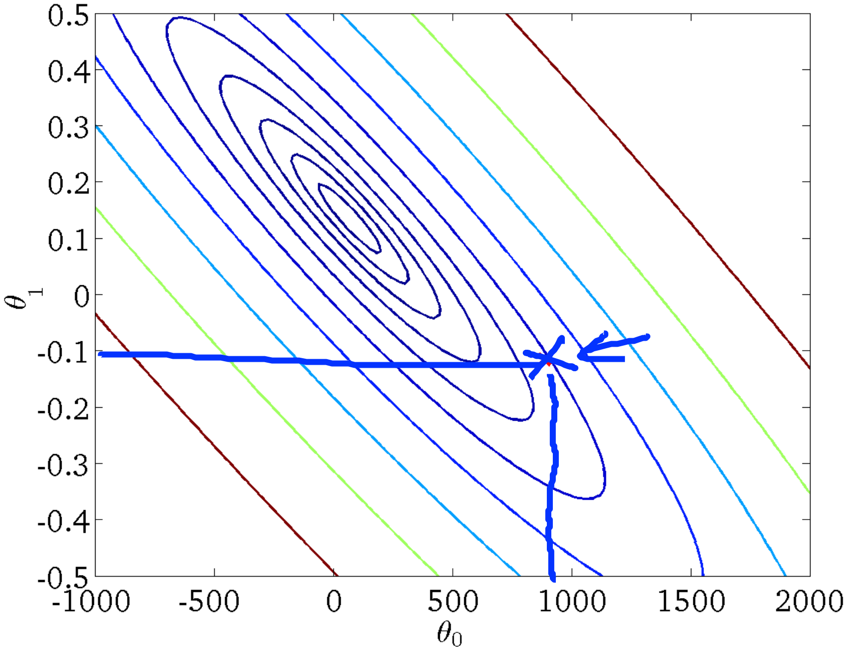
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

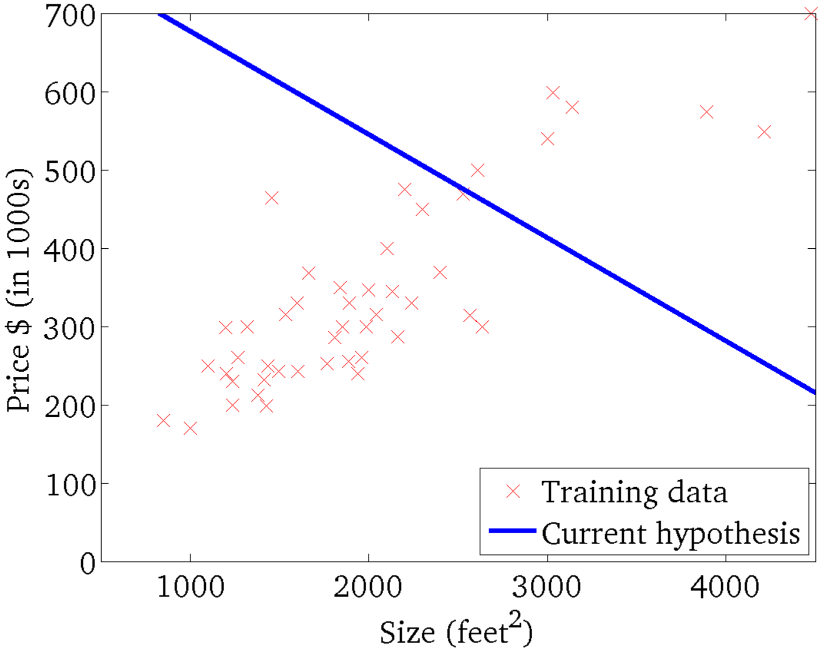
(function of the parameters θ_0, θ_1)



Andrew Ng

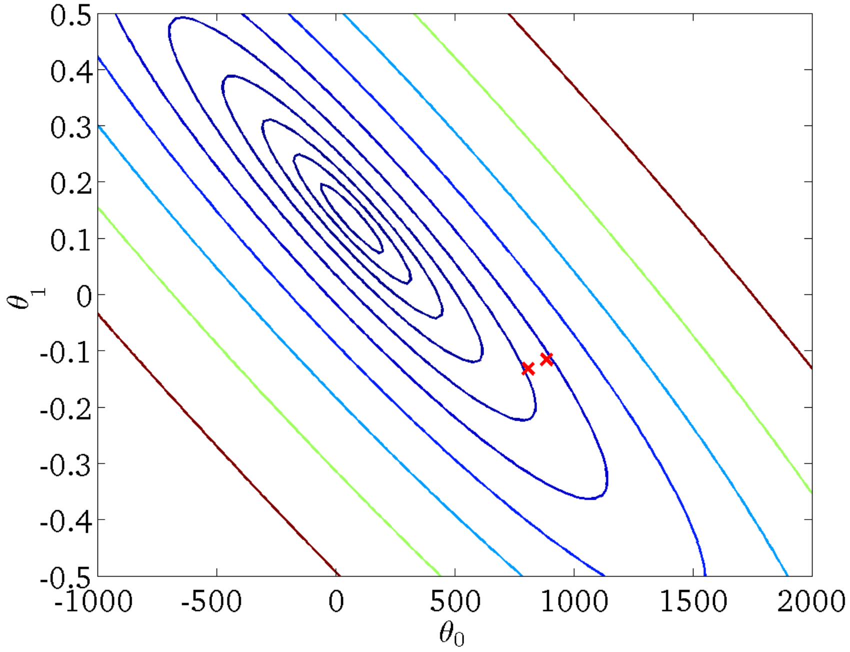
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



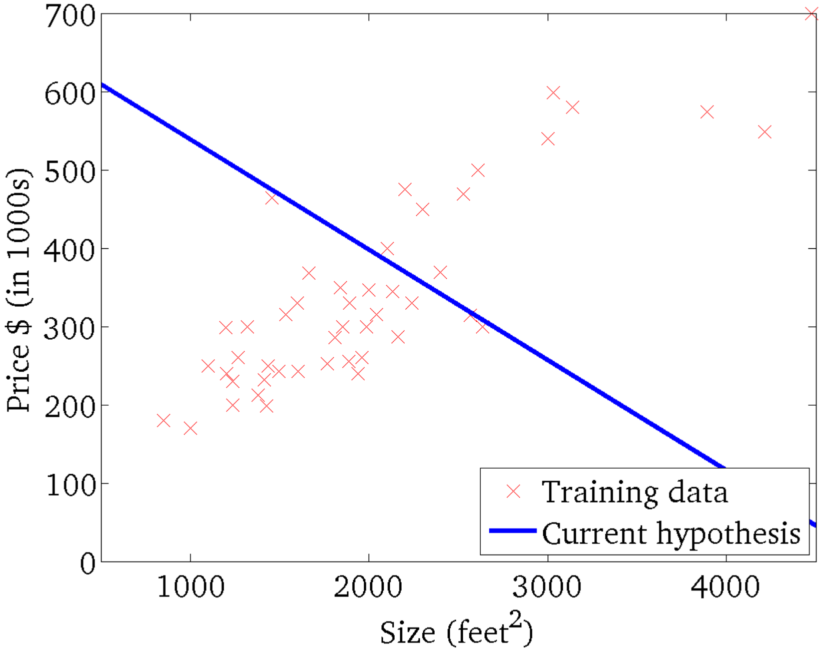
$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



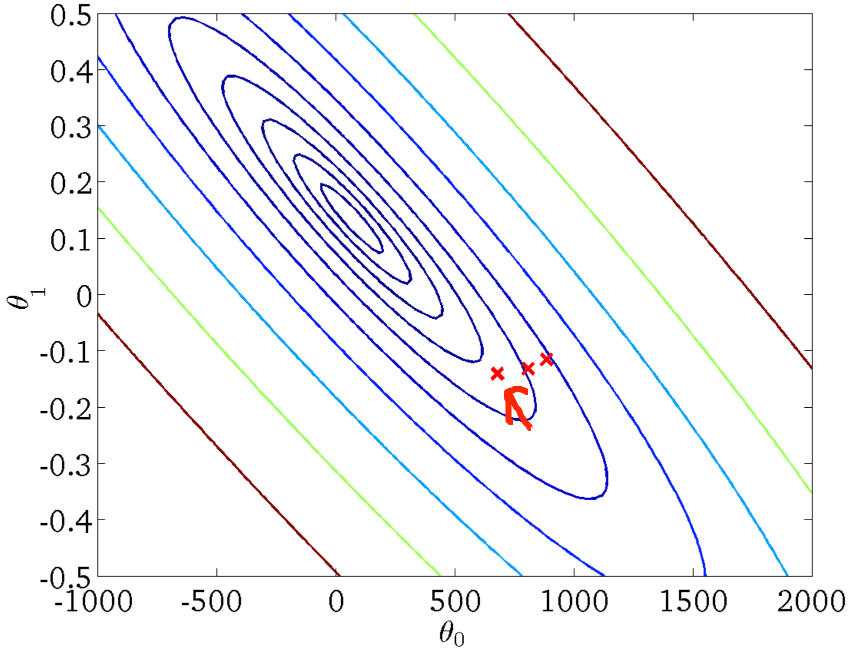
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



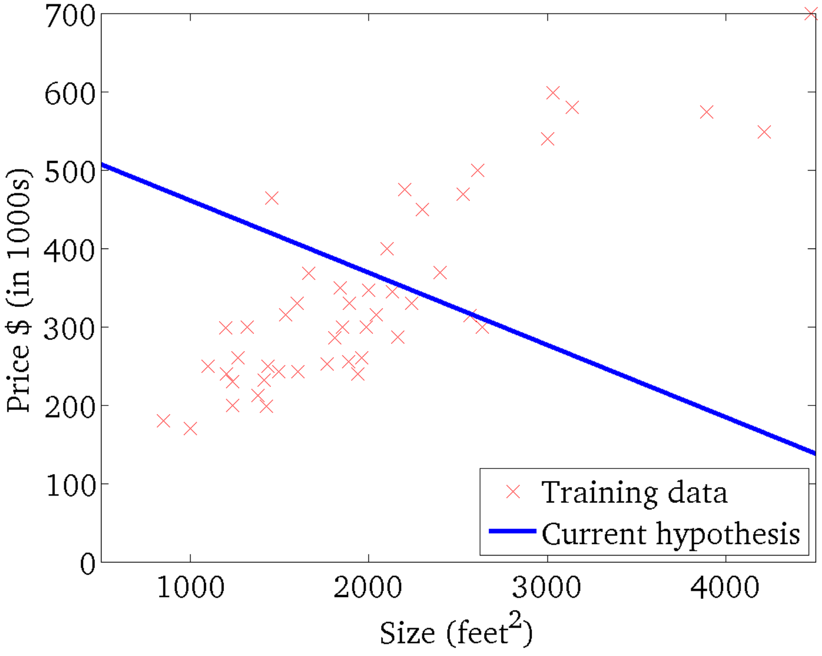
$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



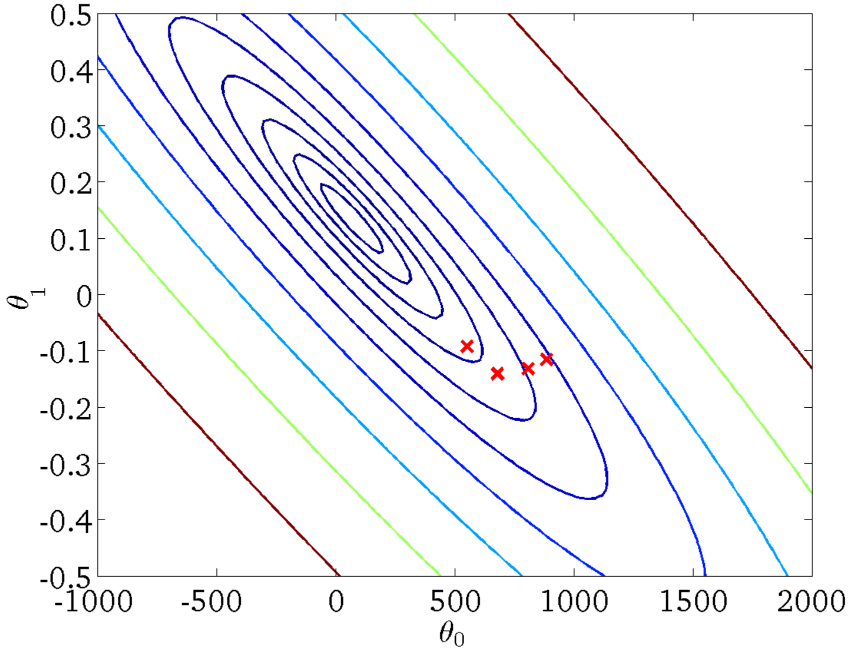
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

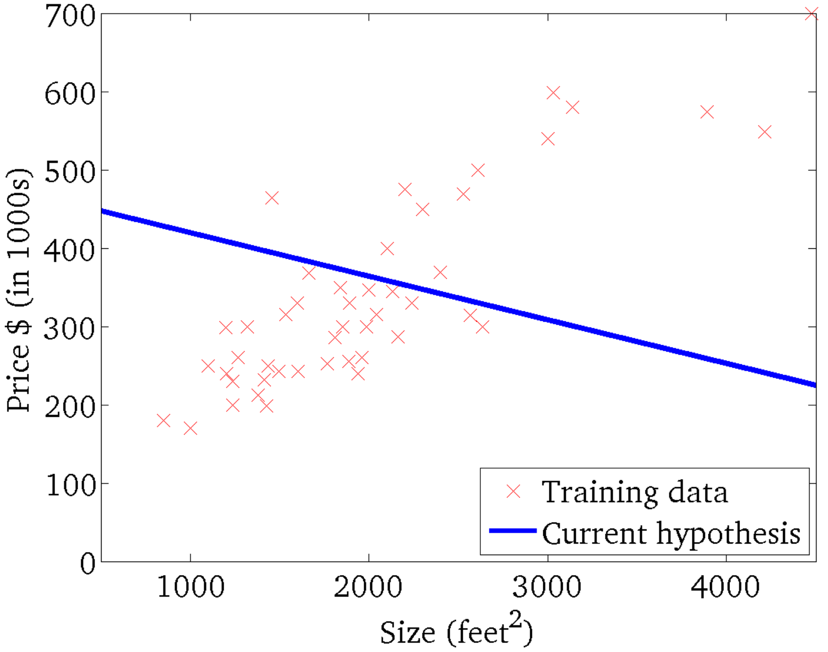
(function of the parameters θ_0, θ_1)



Andrew Ng

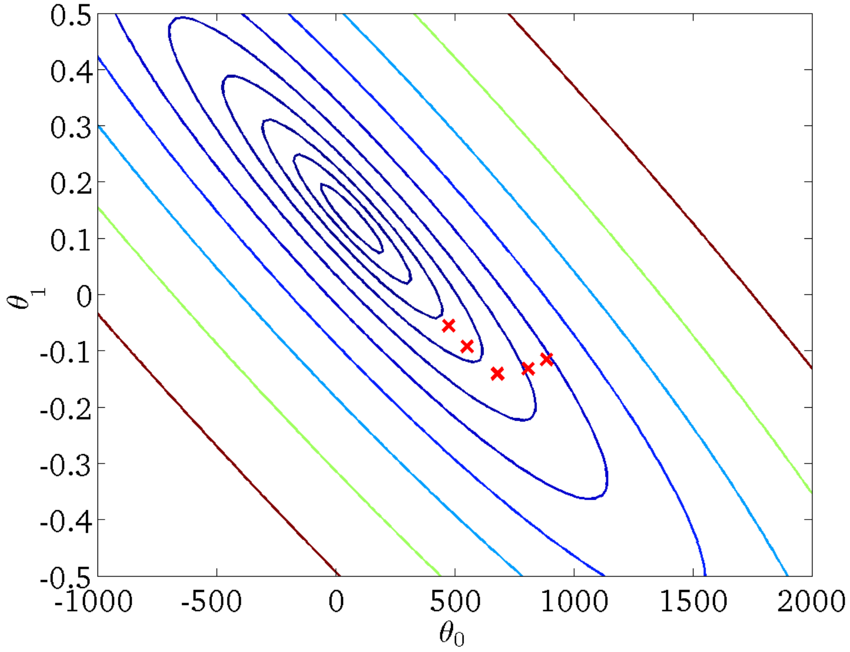
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

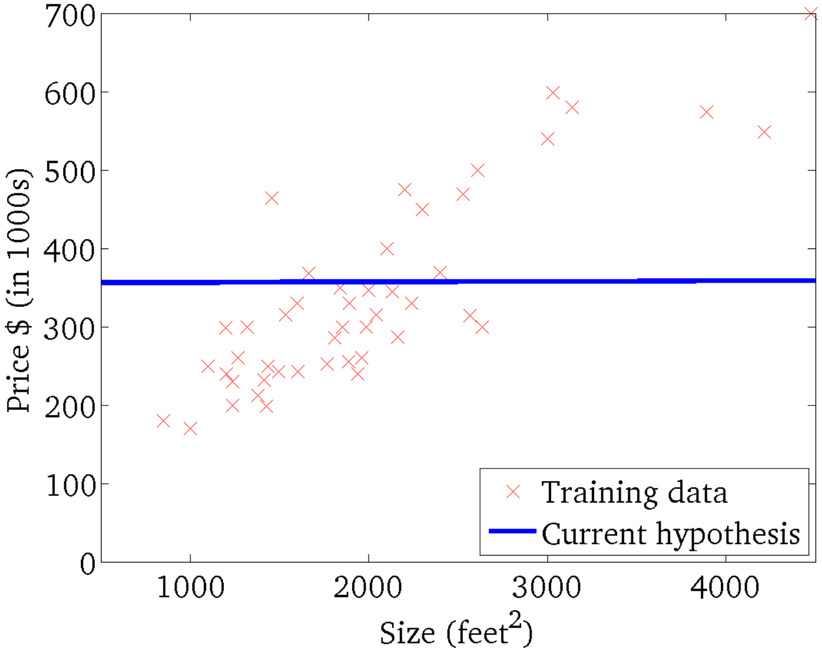
(function of the parameters θ_0, θ_1)



Andrew Ng

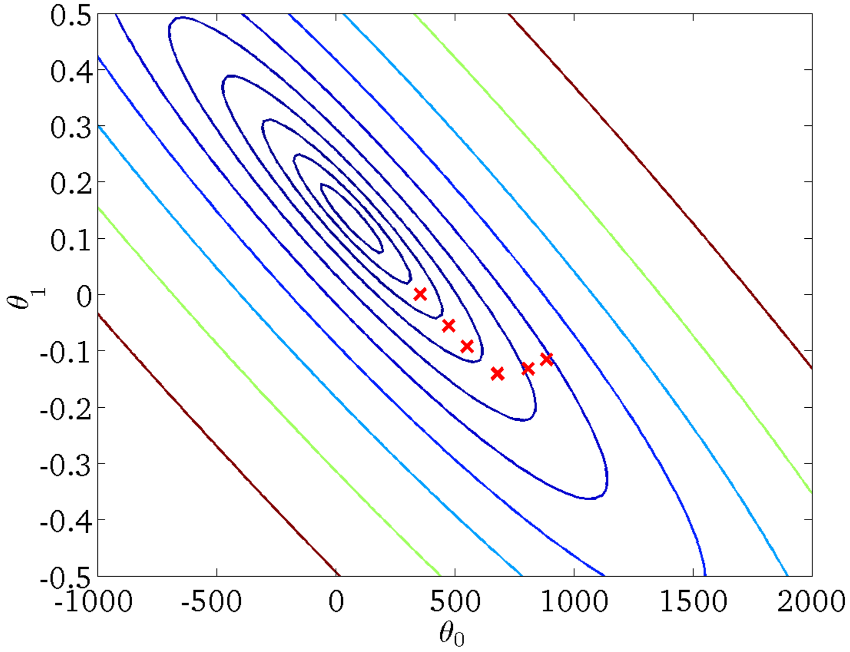
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



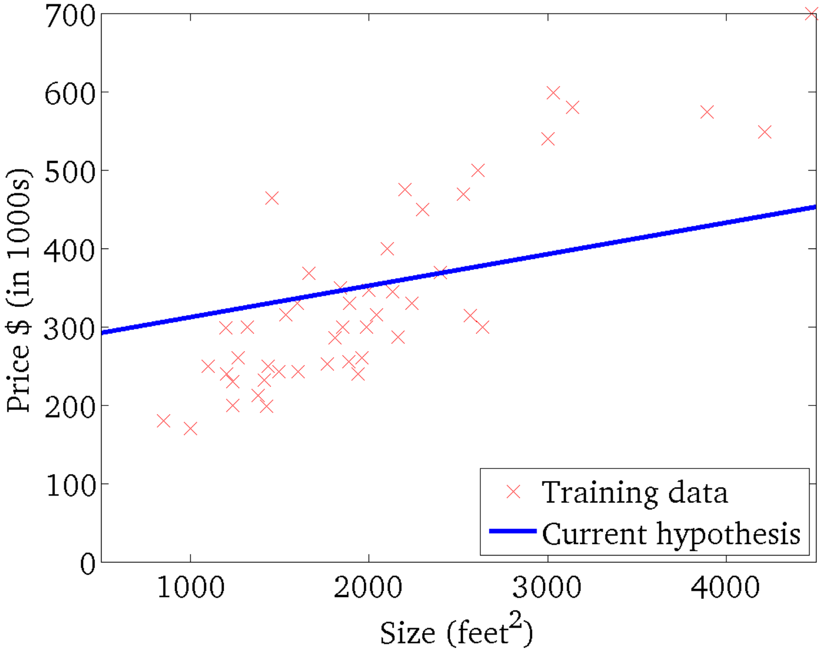
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



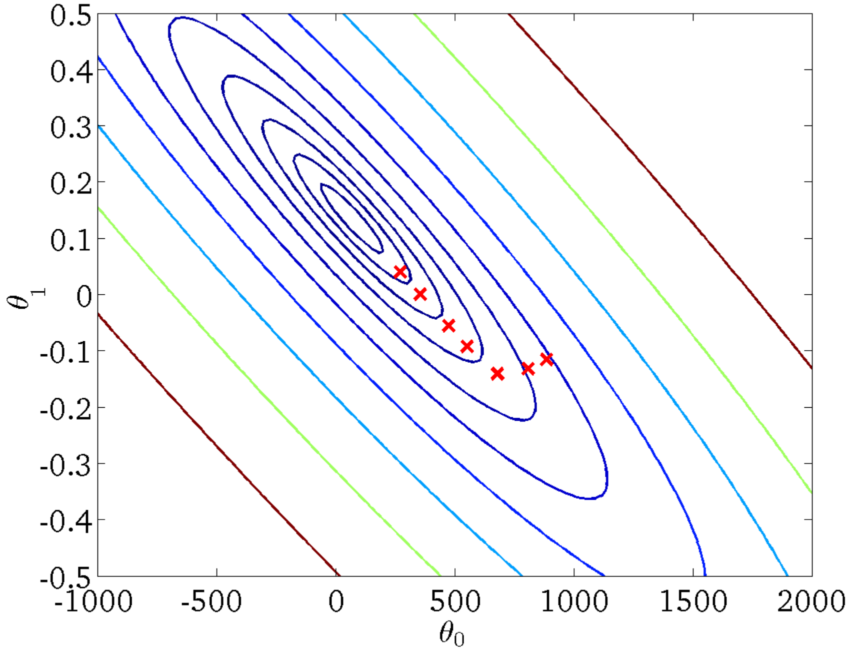
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)

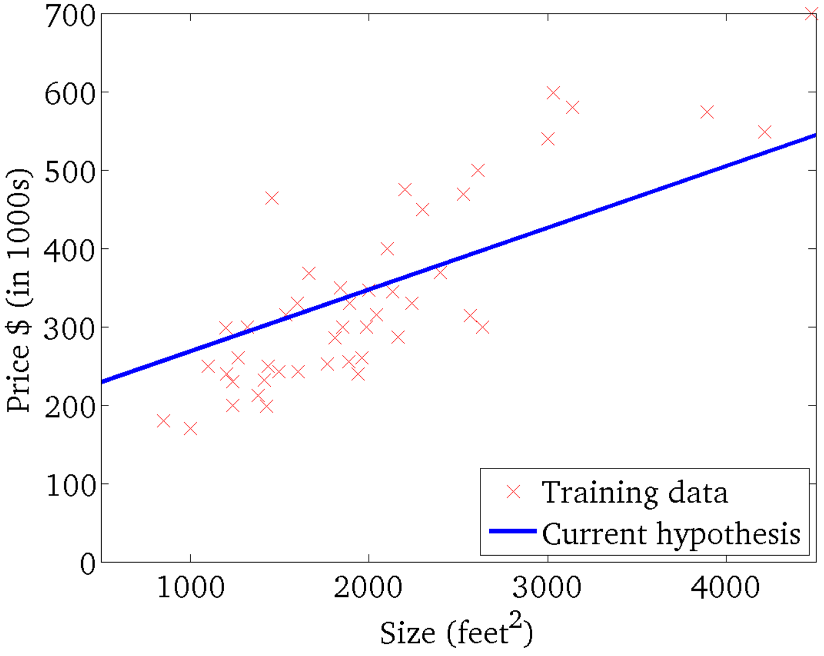


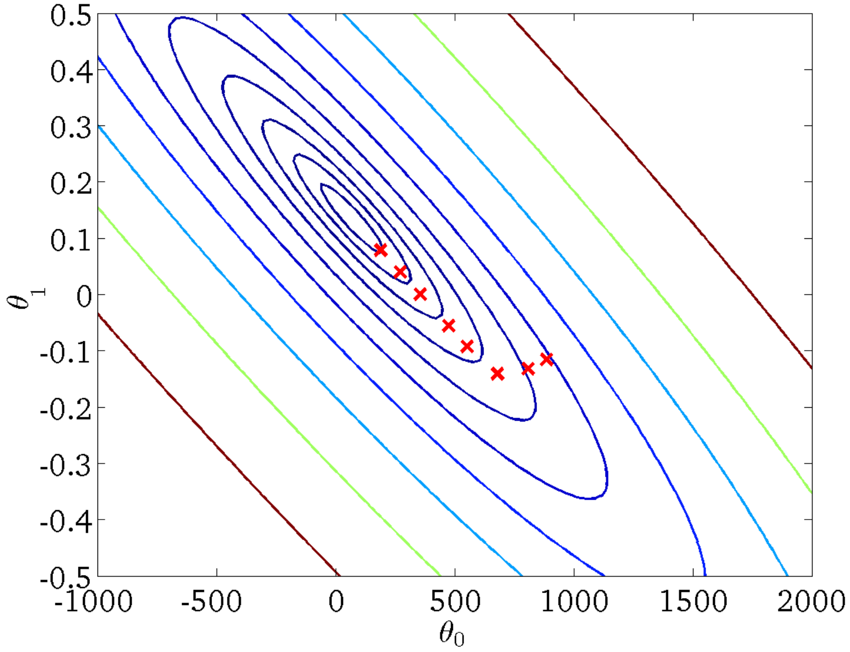
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)

$J(\theta_0, \theta_1)$

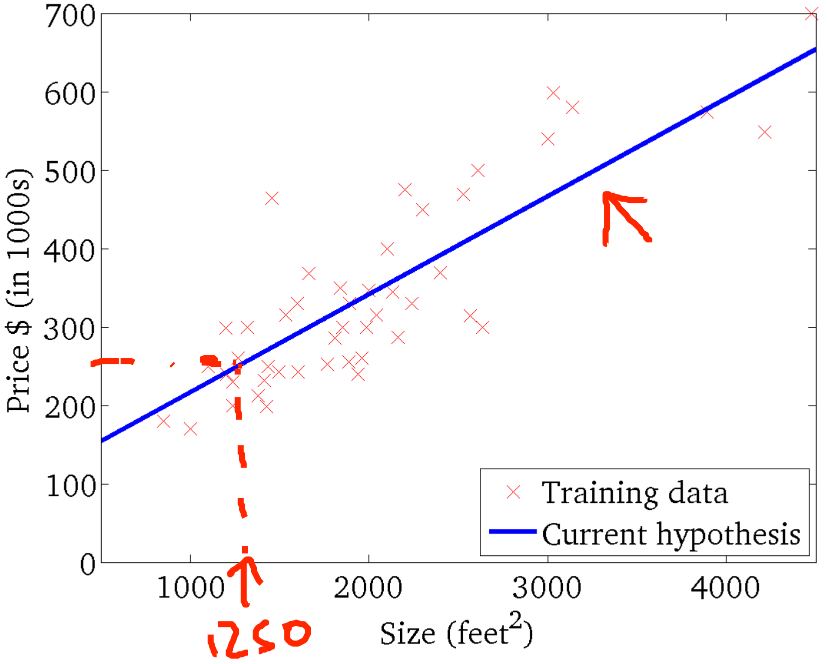
(function of the parameters θ_0, θ_1)





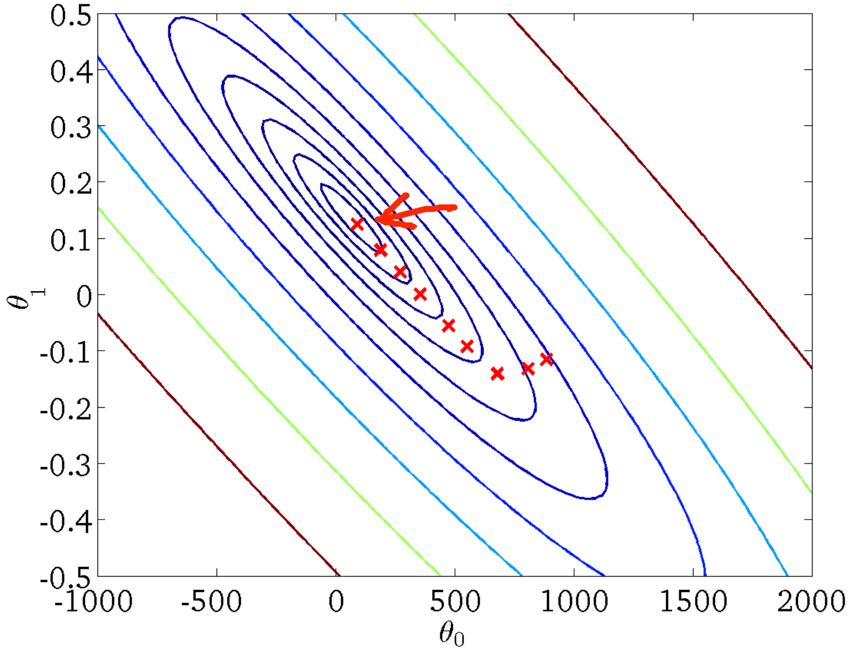
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



Andrew Ng

一堆

"Batch" Gradient Descent

"Batch": Each step of gradient descent uses all the training examples.

$$\sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right)$$