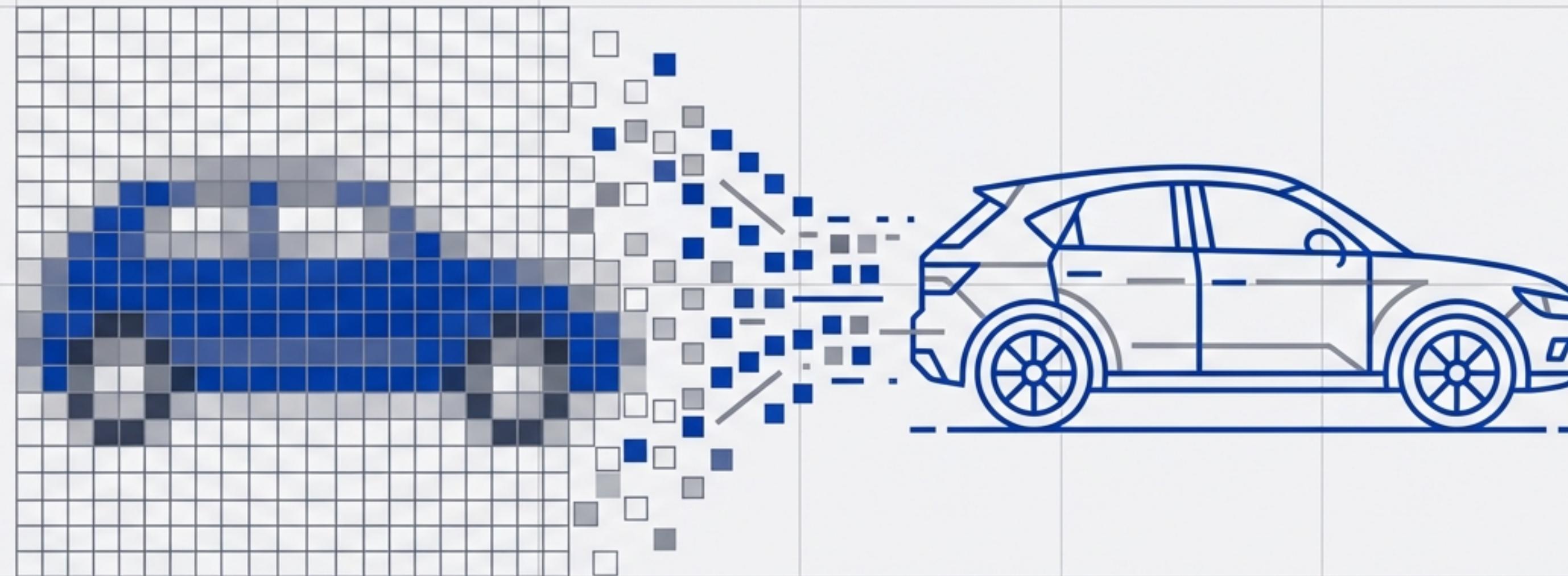


# Mastering Low-Resolution Vision: CIFAR-10 Classification via ResNet50



A Transfer Learning Case Study in Optimization and Feature Extraction

# Project Dashboard: Achieving 92% Accuracy on Low-Fidelity Inputs

## THE GOAL

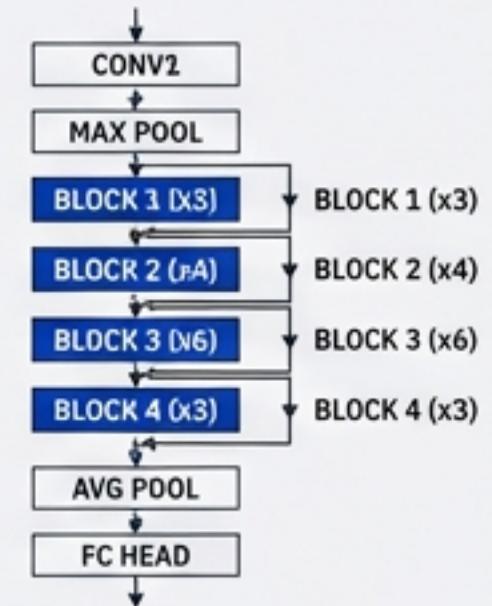
Classify 10 distinct object classes in 32x32 RGB images using the CIFAR-10 dataset. The objective is to extract semantic meaning from low-pixel density inputs.

## THE CONSTRAINT

Downsampled training set limited to 10,000 images to rigorously test efficiency vs. variance constraints.

## THE ARCHITECTURE

ResNet50 (ImageNet Weights)  
+ Custom Classifier Head.



## THE RESULT

# 92% Accuracy

Stable convergence at 0.24 Loss.

**Insight:** Pre-trained [ImageNet](#) weights successfully compensated for low pixel density, ‘inheriting’ edge detection capabilities that would be impossible to train from scratch on this dataset size.

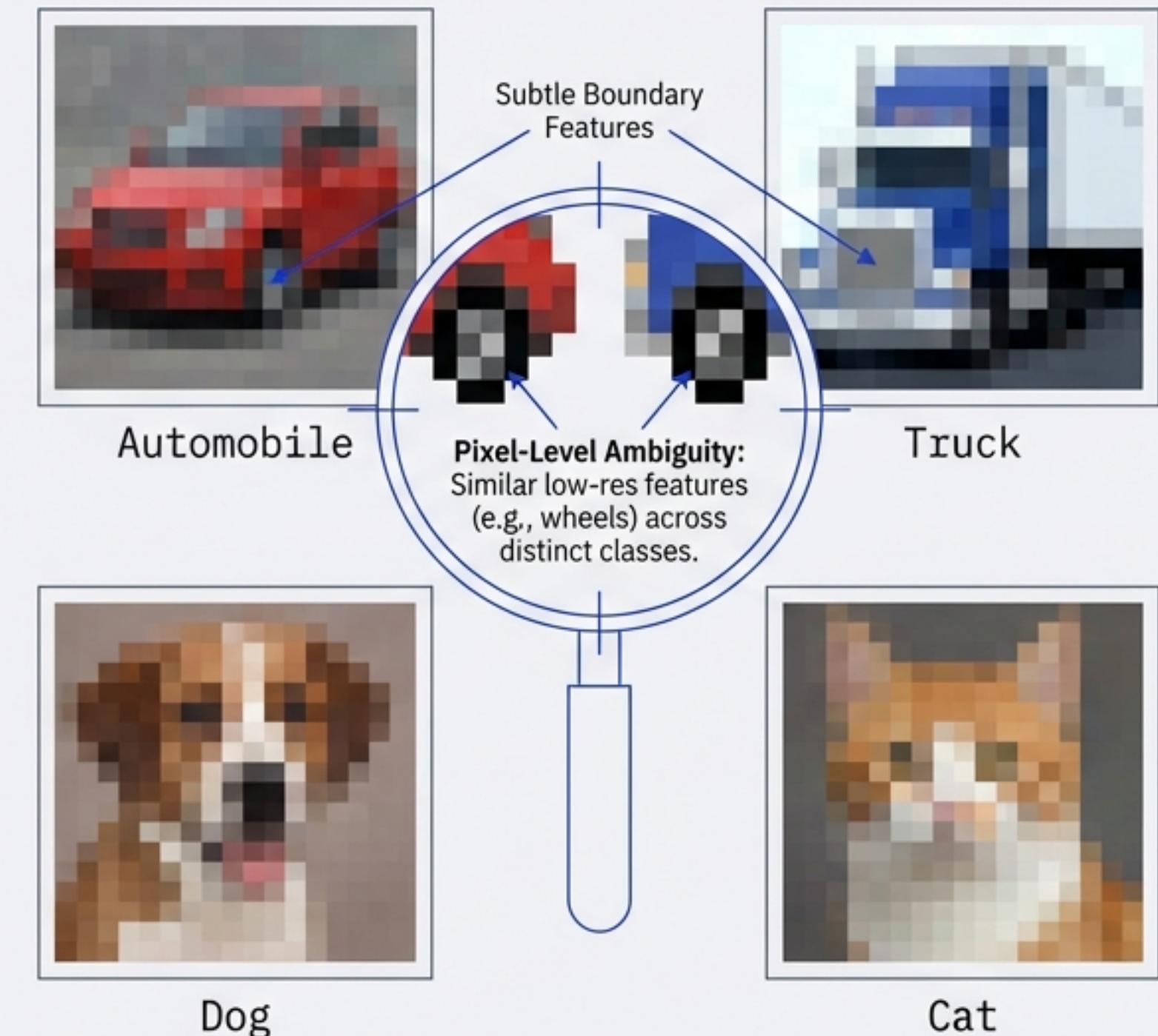
# Complexity Hidden in Low Resolution: The CIFAR-10 Challenge

## Dataset Specifications

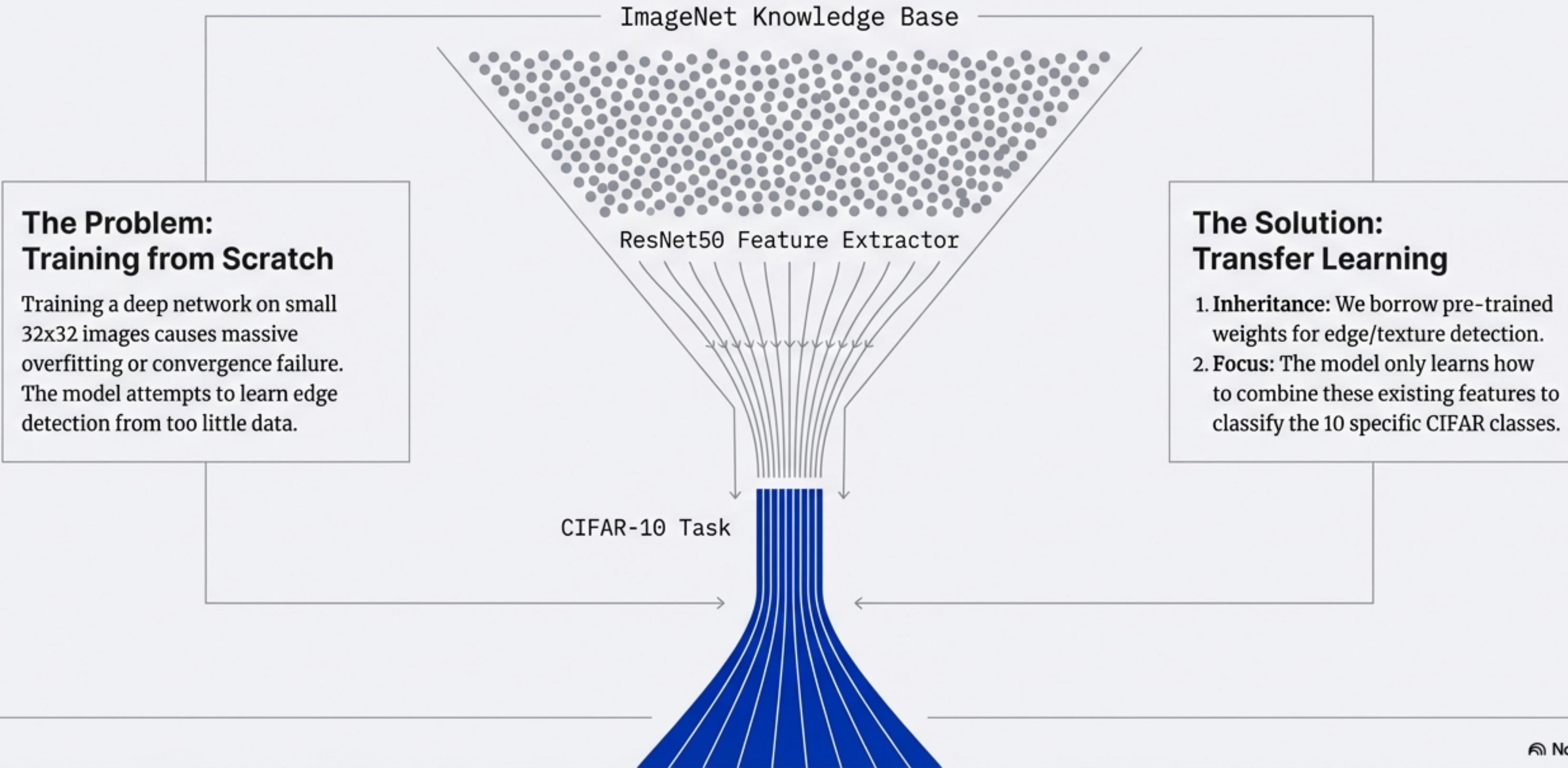
- **Volume:** 60,000 Total Images  
(Downsampled to 10k Training / 10k Testing)
- **Dimensions:** 32x32 pixels, 3 Channels (RGB)
- **Classes:** 10 mutually exclusive categories

## The Semantic Challenge

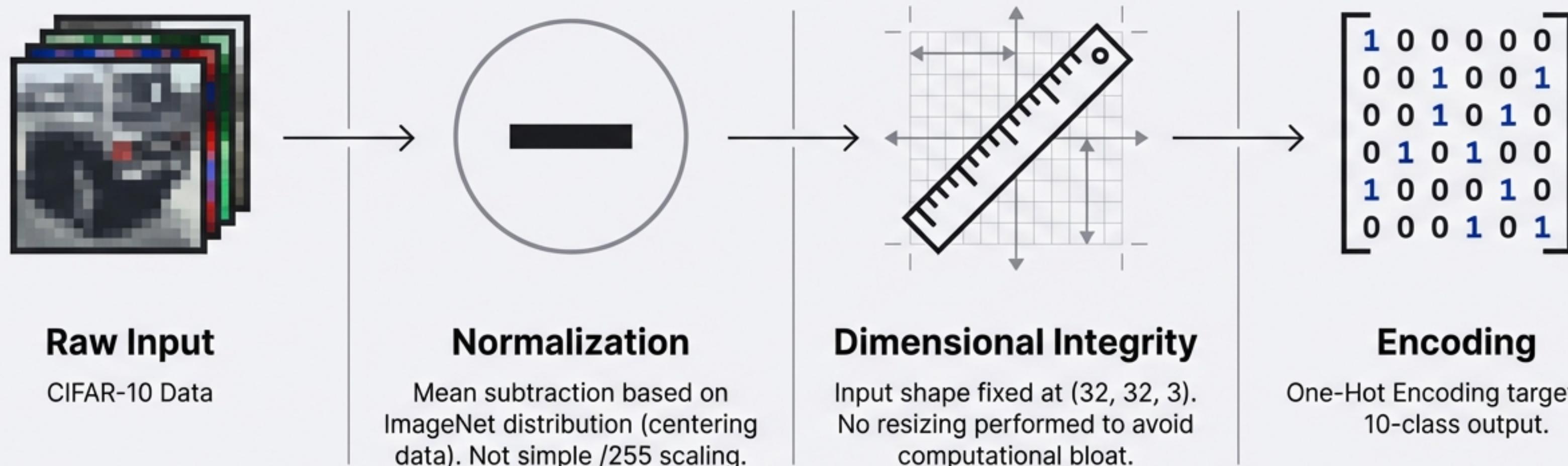
The primary difficulty is nuance within low resolution. “Automobile” includes sedans and SUVs, while “Truck” is strictly heavy-duty vehicles. The model must learn subtle boundary features rather than just size or shape.



# Leveraging ‘Inherited’ Vision to Prevent Overfitting



# Technical Workflow: Preparing Data for Deep Residual Networks



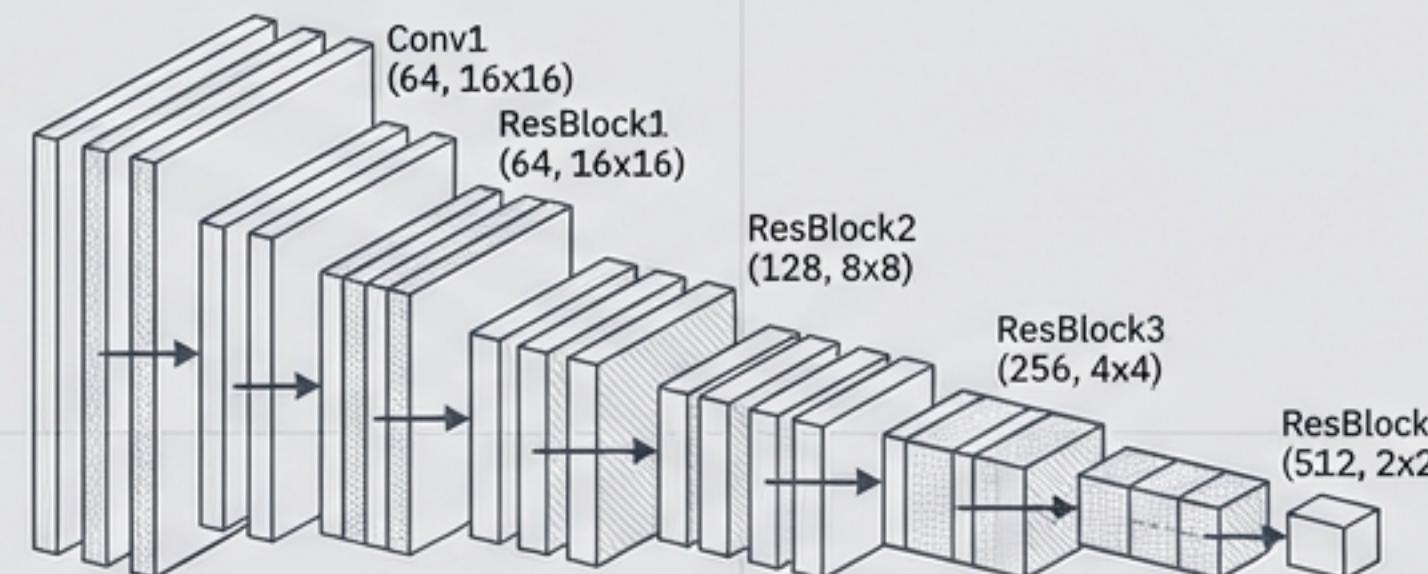
```
> input_shape = (32, 32, 3)
> preprocess_input(x) # Applies Caffe-style mean subtraction
> to_categorical(y, 10)
```

# The Hybrid Design: Frozen Base + Custom Head

## PART A: THE BASE (Feature Extractor)

ResNet50 (include\_top=False)

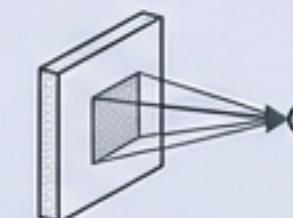
Input: (32, 32, 3) | Weights: ImageNet | Status: Frozen



## PART B: THE HEAD (Classifier)

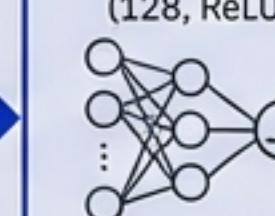
Inter Tight Semibold | IBM Plex Mono

GlobalAveragePooling2D

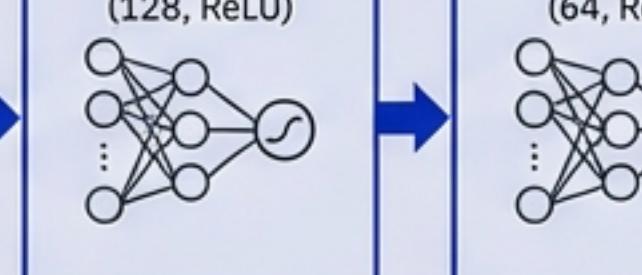


(Reduces dimensionality)

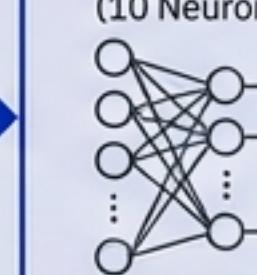
Dense  
(128, ReLU)



Dense  
(64, ReLU)



Softmax  
(10 Neurons)



The Custom Head maps the complex ResNet features to the 10 specific classes of CIFAR-10.

# A Two-Phase Training Strategy for Stability

## Phase 1: Feature Extraction 10 Epochs



Base layers are FROZEN.

We train only the custom head. This prevents large, random gradients from destroying the delicate, pre-trained ImageNet weights.

## Phase 2: Fine-Tuning 10 Epochs



Base layers are UNFROZEN.

We train the entire network with a very low learning rate. This allows the deep ResNet filters to adapt slightly to CIFAR-specific textures.

Total Training Duration: **20 Epochs**. Strategy minimizes "**Catastrophic Forgetting**".

# Reaching Convergence: 92% Accuracy

**92%**

Final Top-1 Accuracy

**0.24**

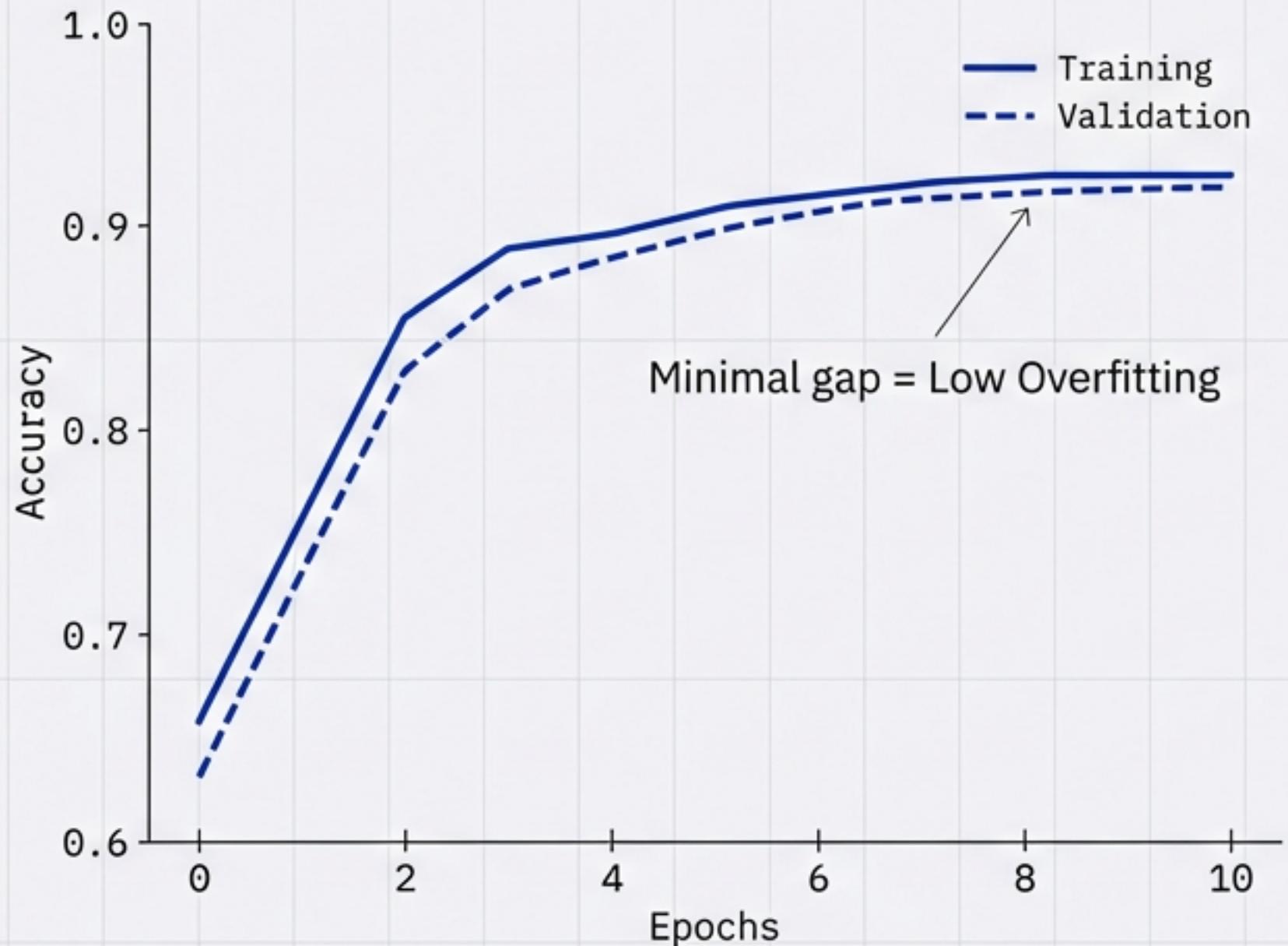
Final Loss

Training Stage	Accuracy	Loss	State
Epoch 1	75%	0.55	Initial Head Training
Epoch 10	92%	0.24	Post Fine-Tuning

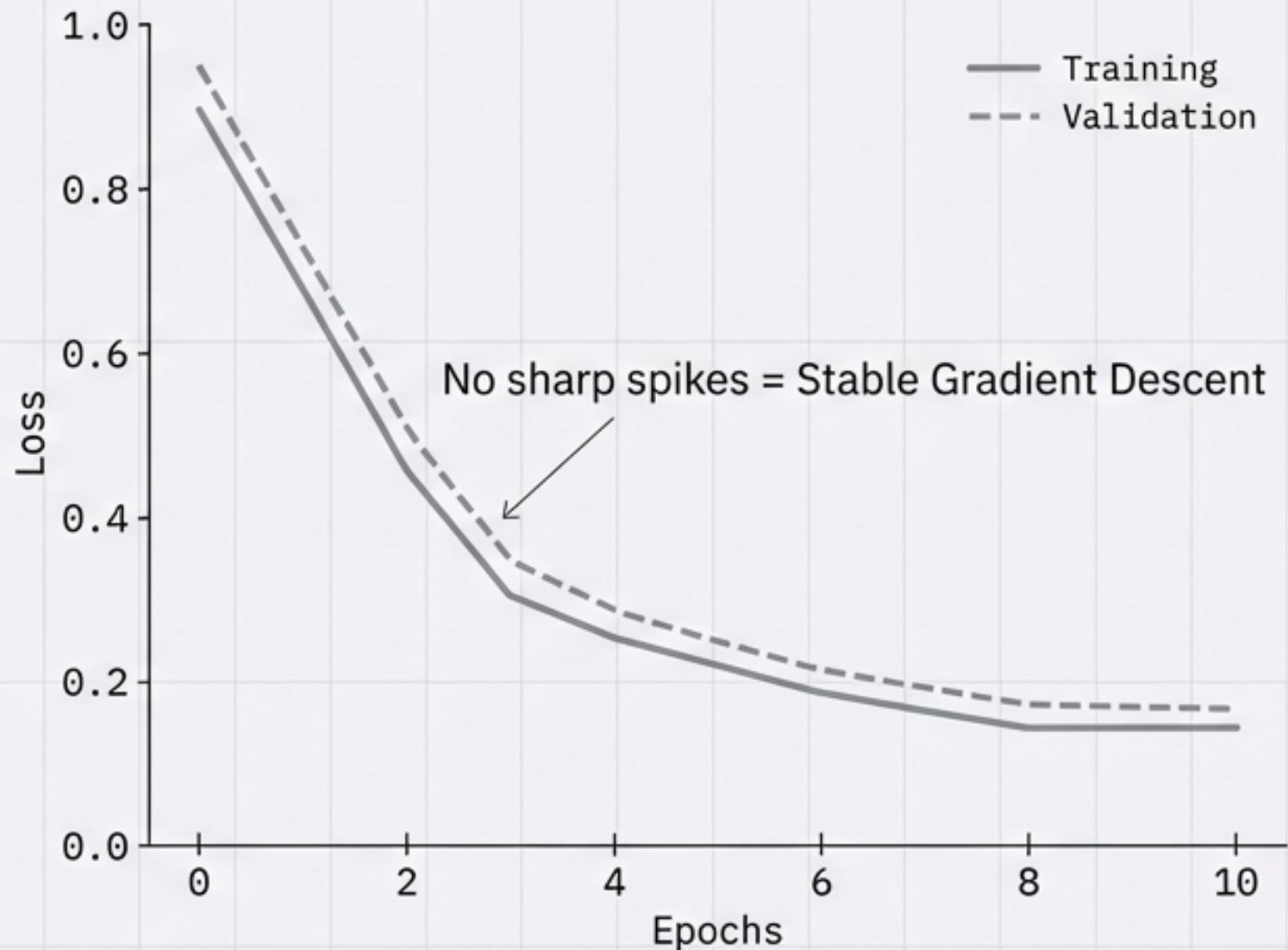
Despite the downsampled training set (10,000 images), the model achieved high accuracy, effectively validating the transfer learning hypothesis. The jump from 75% to 92% demonstrates the efficacy of the fine-tuning phase.

# Smooth Optimization Indicates Robust Generalization

Model Accuracy



Model Loss



Convergence stabilizes around Epoch 8. The parallel nature of Train/Val lines proves the model generalizes well to unseen data.

# Confusion Matrix Analysis: The Limits of Resolution

		Predicted Class									
		Airp...	Aut...	Cat	Deer	Dog	Frog	Horse	Ship	Truck	
Actual Class	Airplane	915	10	5	15	15	5	20	5	10	
	Automobile	10	920	5	5	15	5	15	5	5	
	Bird	40	35	890	15	15	15	20	5	35	
	Cat	15	10	7	885	45	50	15	20	35	
	Deer	10	5	5	15	905	50	15	10	40	
	Dog	10	15	15	20	20	895	5	5	10	
	Frog	10	25	5	10	5	15	910	7	15	
	Horse	10	5	15	10	15	15	15	925	15	
	Ship	10	5	7	10	5	5	5	900	20	
	Truck	15	10	5	15	20	15	20	20	915	

## The Texture Leak (Cat vs. Dog)

High confusion. At 32x32 pixels, fur textures and facial features are indistinguishable. The model relies on shape, which is similar for both quadrupeds.

## The Background Bias (Bird vs. Airplane)

Birds are often misclassified as Airplanes.  
**Reason:** Both classes frequently feature a dominant blue sky background, leading to context interference.

# Performance Divergence: Geometric vs. Organic



## Structured / Rigid

- Automobile: F1-Score **0.95**
- Ship: **High Precision**

Strong geometric features (metal edges, wheels, silhouettes) are preserved well even at low resolution.



## Organic / Natural

- Cat: F1-Score **0.80**
- Dog: F1-Score **0.79**

Texture nuances (fur, ears, tails) blur together at 32x32 pixels, causing lower precision.

Insight: The model effectively transfers 'vision' for rigid structures but struggles with organic nuance without higher resolution input.

# Strategic Project Evaluation (SWOT)

## STRENGTHS ↗

- High Accuracy (**92%**)
- Efficient Feature Extraction (ResNet50)
- Stable Convergence

## WEAKNESSES ↘

- Semantic Similarity struggles (Cat vs Dog)
- Sensitivity to background noise (Bird vs Plane)
- Computationally expensive relative to image size

## OPPORTUNITIES ↗

- Data Augmentation (Rotations/Flips)
- API Deployment
- Unfreezing more layers

## THREATS ↘

- Risk of Overfitting (needs regularization)
- Domain Shift on high-res real-world data

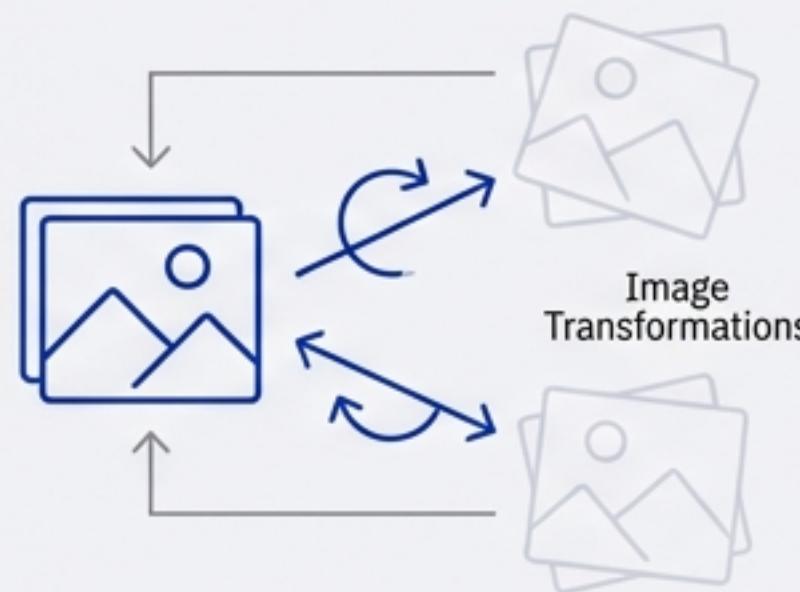
# Optimization Roadmap: The Path to 99%



## Action: Data Augmentation

### Problem: Orientation Bias

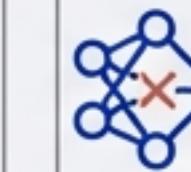
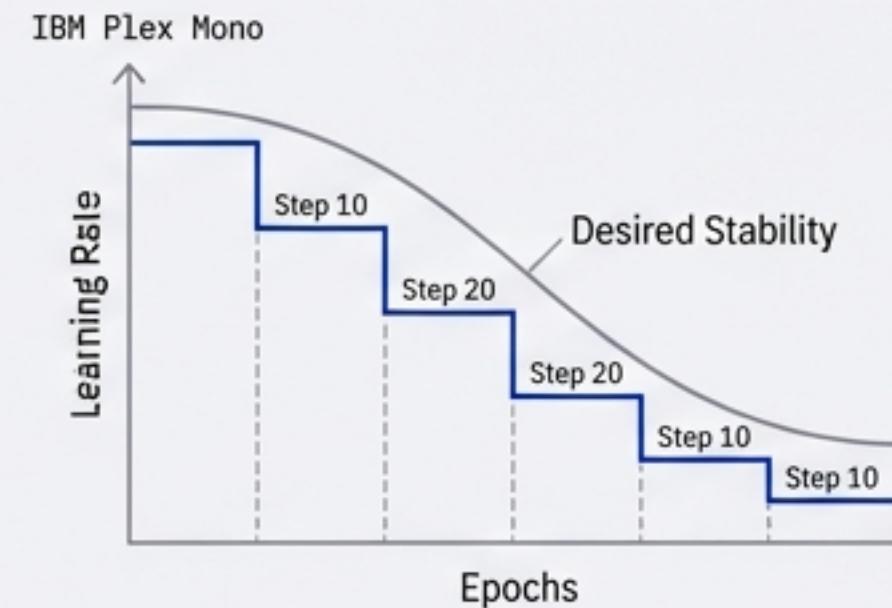
Introduce random rotations and horizontal flips to force the model to learn invariant features.



## Action: Scheduler Implementation

### Problem: Fine-tuning Instability

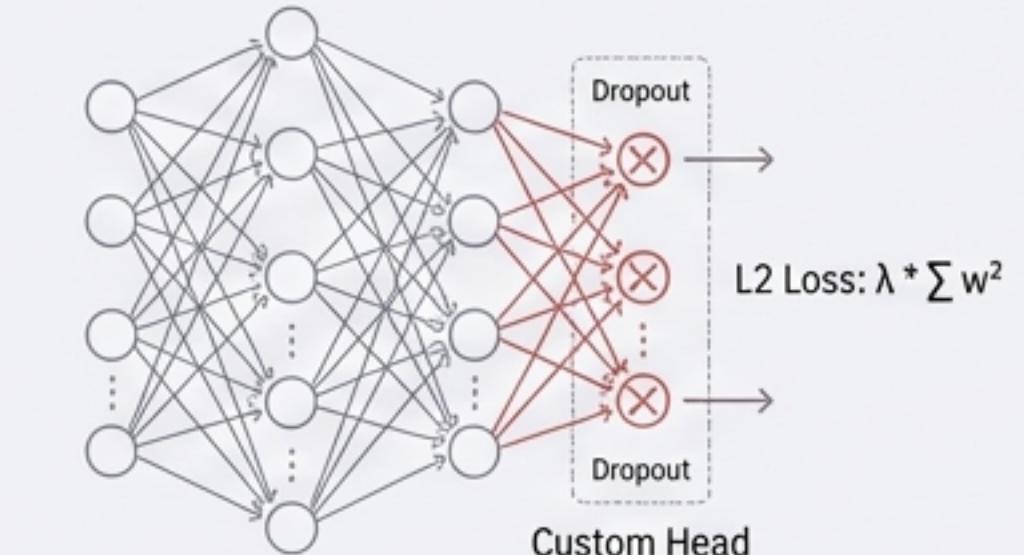
Implement automated learning rate decay to smooth the descent in later epochs.



## Action: Regularization

### Problem: Small Dataset Variance

Add Dropout layers or L2 regularization to the custom head to prevent overfitting on the 10k image set.



# Final Verdict: A Solid Baseline for Computer Vision

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ResNet50 has proven to be a formidable foundation, successfully bridging the gap between low-resolution inputs and high-performance classification.

**Critical Takeaway:** While the model mastered structural recognition (Vehicles), the ‘Cat vs. Dog’ confusion highlights that resolution constraints eventually hit a ‘semantic ceiling’ that requires data augmentation to break.

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**STATUS: READY FOR AUGMENTATION & DEPLOYMENT TESTING**

# Technical References & Stack

- Dataset:
  - CIFAR-10 (Canadian Institute for Advanced Research)
- Architecture:
  - ResNet50 (He et al., Microsoft Research)
  - Weights: ImageNet (Pre-training)
- Tools & Environment:
  - TensorFlow / Keras
  - Google Colab (GPU Runtime)

