```
0.00
Install from PvPI:
  pip install safety-gymnasium
. . . . . . . . . . . .
import safety gymnasium
# Create the safety-task environment
env = safety gymnasium.make("SafetyPointGoal1-v0", render mode="human")
# Reset the environment
obs. info = env.reset()
while True:
    # Sample a random action
    act = env.action space.sample()
    # Step the environment: costs are returned
    obs, reward, cost, terminated, truncated, info = env.step(act)
    if terminated or truncated:
        break
```