

# FY2045 Quantum Mechanics I

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Week 2

# Measurement of a degenerate eigenvalue

## D: The measurement postulate

(i) The only possible result of a precise measurement of an observable  $F$  is **one of the eigenvalues**  $f_n$  of the corresponding linear operator  $\hat{F}$ .

(ii) Immediately after the measurement of the eigenvalue  $f_n$ , the system is in an eigenstate of  $\hat{F}$ , namely, the eigenstate  $\psi_n$  corresponding to the measured eigenvalue  $f_n$ .

## Non-degenerate case

$$\hat{F}\psi_n = f_n\psi_n$$

has only one solution  $\psi_n$  for eigenvalue  $f_n$ .

If a measurement of observable  $F$  gives  $f_n$ , the system is in state  $\psi_n$  immediately after the measurement.

# Measurement of a degenerate eigenvalue

## Degenerate case

$$\hat{F}\psi_{ni} = f_n\psi_{ni}, \quad i = 1, 2, \dots, g_n.$$

Complete set, expand general state as

$$\Psi = \sum_n \sum_{i=1}^{g_n} c_{ni} \psi_{ni},$$

resulting in probability of measuring  $f_n$

$$P_n = \sum_{i=1}^{g_n} |c_{ni}|^2.$$

Define function with eigenvalue  $f_n$ ,

$$\Psi_n = \sum_{i=1}^{g_n} c_{ni} \psi_{ni}.$$

Immediately after a measurement of eigenvalue  $f_n$ , the system is in the normalized state

$$\frac{\Psi_n}{\|\Psi_n\|},$$

with  $\|\Psi_n\|$  the norm of  $\Psi_n$ .

# Example — 3D isotropic harmonic oscillator

## 1D case



$$\hat{H} = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + \frac{1}{2} m \omega^2 x^2,$$

$$E_n = \hbar \omega \left( n + \frac{1}{2} \right), \quad n = 0, 1, 2 \dots$$

$$\psi_n = \left( \frac{m\omega}{\hbar\pi} \right)^{\frac{1}{4}} \frac{e^{-m\omega x^2/2\hbar}}{\sqrt{2^n n!}} H_n \left( x \sqrt{\frac{m\omega}{\hbar}} \right),$$

## 3D case

$$\hat{H} = -\frac{\hbar^2}{2m} \nabla^2 + \frac{1}{2} m \omega^2 (x^2 + y^2 + z^2),$$

$$\psi_{n_x n_y n_z} = \psi_{n_x}(x) \psi_{n_y}(y) \psi_{n_z}(z),$$

$$E_{n_x n_y n_z} = \hbar \omega \left( n_x + n_y + n_z + \frac{3}{2} \right)$$

$$= \hbar \omega \left( N + \frac{3}{2} \right) \equiv E_N.$$

# Eigenfunctions of continuous variables

## Momentum eigenfunctions

$$\hat{p}\psi_p(x) = p\psi_p(x) \quad \Rightarrow \quad \psi_p(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{ipx/\hbar}.$$

## Position eigenfunctions

$$\hat{x}\psi_y(x) = y\psi_y(x) \quad \Rightarrow \quad \psi_y(x) = \delta(x - y).$$

## Normalization

For continuous case,

$$\int d\tau \, \Psi_f^*, \Psi_{f'} = \delta(f - f'),$$

compared to

$$\int d\tau \, \Psi_n^*, \Psi_{n'} = \delta_{nn'},$$

in discrete case.

# Physical interpretation of the continuous case

## Discrete case

The probability that a measurement of  $F$  gives the result  $f_n$ , when the system is in the state  $\Psi$ , is

$$|c_n|^2 = \left| \int d\tau \, \Psi_n^* \Psi \right|^2,$$

where  $\Psi_n$  is the eigenstate corresponding to  $f_n$ .

## Continuous case

The probability that a measurement of  $F$  gives a result in the interval  $(f, f + df)$  when the system is in the state  $\Psi$ , is

$$|c(f)|^2 df = \left| \int d\tau \, \Psi_f^* \Psi \right|^2 df,$$

where  $\Psi_f$  is the eigenstate corresponding to the value  $f$ .

# Momentum-space representation

	Position-space formulation	Momentum-space formulation
Wavefunction	$\Psi(x, y, z, t)$	$\Phi(p_x, p_y, p_z, t)$
Operator $\hat{x}_i$	$x_i$	$-\frac{\hbar}{i} \frac{\partial}{\partial p_i}$
Operator $\hat{p}_i$	$\frac{\hbar}{i} \frac{\partial}{\partial x_i}$	$p_i$
Wave equation	$i\hbar \frac{\partial \Psi}{\partial t} = \hat{H}(\hat{x}_i, \hat{p}_i)\Psi$	$i\hbar \frac{\partial \Phi}{\partial t} = \hat{H}(\hat{x}_i, \hat{p}_i)\Phi$