

HAKAN GIRGIN

☎ +41 76 506 9890 | ✉ hakangirgin21@gmail.com | hgirgin.github.io
📍 Salzhausstrass 10B, 2503 Biel, Switzerland

PROFILE

I am currently affiliated to Swiss Cobotics Competence Center (S3C) in Biel as technical project manager. I received my Ph.D. degree in robotics at Ecole Polytechnique Fédérale de Lausanne (EPFL) and Idiap Research Institute supervised by Dr. Sylvain Calinon. My research focuses on optimization and active iterative refinement of feedback and feedforward control policies for acquiring robust and anticipatory robot skills from demonstration.

EDUCATION

Ph.D. Robotics Ecole Polytechnique Fédérale de Lausanne (EPFL)	2018 – 2023 Lausanne, Switzerland
Bachelor of Science Mechanical Engineering Bogazici University, Entrance rank: 0.13%, GPA: 3.90/4.0	2012 – 2017 Istanbul, Turkey
Exchange semester Mechanical Engineering Ecole Centrale Paris	2014 – 2015 Paris, France
Francophone Highschool Lycée de Galatasaray, Entrance rank: 0.06% GPA: 85.84/100	2007 – 2012 Istanbul, Turkey

WORK EXPERIENCE

Technical Project Manager Swiss Cobotics Competence Center (S3C)	2023 – Biel, Switzerland
<ul style="list-style-type: none">Responsible for adaptation of collaborative base cells (CBCs) for industrial manufacturing applicationsProviding webinars, testing, training and consultancy services to researchers, integrators and industrial end-users of cobots.	
Ph.D. Research Assistant Idiap Research Institute, Robot Learning and Interaction Group	2018 – 2023 Martigny, Switzerland
<ul style="list-style-type: none">Ph.D. research supervised by Dr. Sylvain CalinonWorked on EU-Horizon2020 project CoLLaboratE	
Teaching Assistant Robotics Course, AI-Master Programme, Unidistance	2020-2022 Martigny, Switzerland
<ul style="list-style-type: none">Preparation of exercises in Jupyter notebooks with ROS and in html formats	
Bachelor Research Assistant Bogazici University Cognitive Robotics and Learning Systems Lab (CoLoRs)	2017 – 2018 Istanbul, Turkey
<ul style="list-style-type: none">Assistance to Dr. Emre Ugur in forming CoLoRs labWorked on EU-Horizon 2020 project, IMAGINE	
Product Definition Engineering Intern General Electric Aviation	2015 – 2016 Istanbul, Turkey
System Engineering Intern ALTINAY Aerospace & Advanced Technologies	2016 Istanbul, Turkey

SKILLS

Languages: Turkish (Native), English (Proficient), French (Proficient), Japanese (B1), Italian (A1), German (A1)

Programming: Python, Jupyter, MATLAB, Tensorflow, PyTorch

Software: ROS, PyBullet, KDL

PUBLICATIONS

Demonstration-guided Optimal Control for Long-term Non-prehensile Planar Manipulation

T. Xue, H. Girgin, T. Lembono, S. Calinon, In Proc. IEEE Intl Conf. on Robotics and Automation ICRA 2023

Reactive Anticipatory Robot Skills with Memory

H. Girgin, J. Jankowski, S. Calinon, International Symposium on Robotics Research ISRR 2022

Optimization of robot configurations for motion planning in industrial riveting

H. Girgin, T. Lembono, R. Cirligeanu, S. Calinon, In Proc. IEEE Intl Conf. on Advanced Robotics ICAR 2021

Active Learning of Bayesian Probabilistic Movement Primitives

T. Kulak, H. Girgin, J.-M. Odobez, S. Calinon, IEEE Robotics and Automation Letters RAL 2021

Probabilistic Adaptive Control for Robust Behavior Imitation

J. Jankowski, H. Girgin, S. Calinon, IEEE Robotics and Automation Letters RAL 2021

Active Improvement of Control Policies with Bayesian Gaussian Mixture Model

H. Girgin, E. Pignat, N. Jaquier, S. Calinon, IEEE Intl. Conf. on Intelligent Robots and Systems IROS 2020

Generative Adversarial Training of Product of Policies for Robust and Adaptive Movement Primitives

E. Pignat, H. Girgin, S. Calinon, In Proc. Conference on Robot Learning CoRL 2020

Compliant Parametric Dynamic Movement Primitives

E. Ugur, H. Girgin, Robotica, 38(3), pp. 457-474 Robotica 2020

Associative Skill Memory Models

H. Girgin, E. Ugur, IEEE Intl. Conf. on Intelligent Robots and Systems IROS 2018