

Data structures

Array

- container, fixed index, can do random Access,

- memory allocated
- o static : fixed → 已定 size

dynamic

- ~~插入~~ complexity *

o insert

o delete

o lookup

= algorithm

$O(n)$, $O(n \log n)$...

- \mathbb{P} : random Access $O(1)$

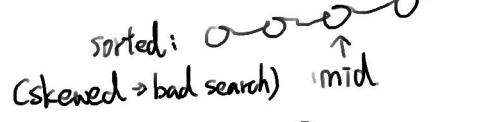
Random Access: $O(1)$

sequential search: $O(n)$

⇒ after sorting: $O(\log n)$

ex: binary search (rule)

BST:

sorted: 
(skewed → bad search) ↑ mid



balanced
(good search)

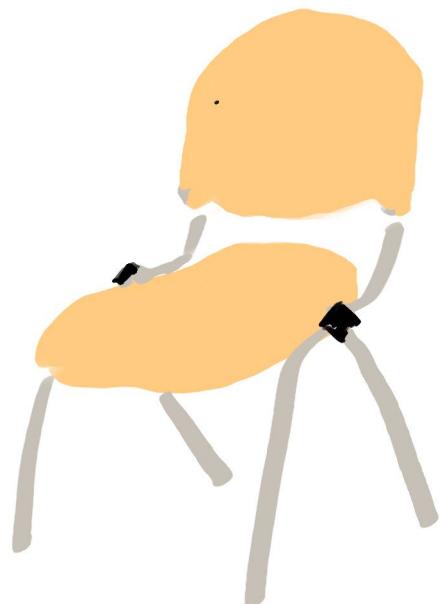
efficient (adj.)

- \mathbb{P} : 空間利用率 (在不確定資料量的情況下) 低

⇒ hash table (use array) ⇒ if function design badly,
there may be lot of
space don't be used.

linked list

- Node & pointer
- traverse to find data = $O(n)$
Random Access : not exist.
- sequential search : $O(n)$



Stack / Queue

FIFO :

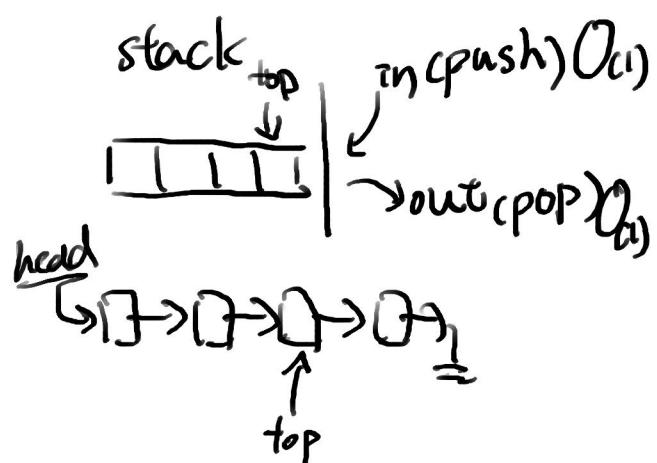
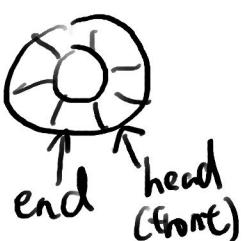
↳ FIFO : function call.

implement:

Array

linked list

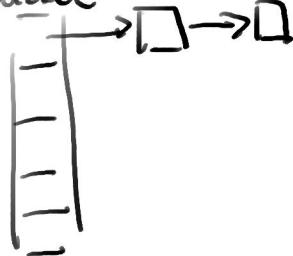
Queue



hash

Array + linked list

bucket



→ travers bad (in linked list)

- collision

- Open Addressing



no \rightarrow (can use random Access)

- linear probing

↳ primary clustering
(某個地方特別擁擠)

- quadratic probing

↳ secondary clustering

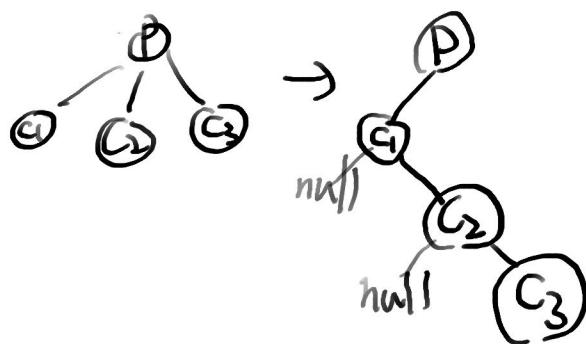
- Double hashing

↳ less clustering

Tree

general \rightarrow binary tree
1 degree ≤ 2

* left child, right sibling



① binary tree \rightarrow BST

↳ complete binary tree

↳ Heap $O(n)$ ↳ ^{max}_{min}

↳ priority queue

traversal: $O(\log n)$

Graph

$G(V, E)$

Adjacent. (\in)