## Comprehensive Compendium:

Calculus II

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# 1 Calc II

### 1.1 Chapter 1 Key Equations

• Mean Value Theorem For Integrals: If f(x) is continuous over an interval [a,b], then there is at least one point  $c \in [a,b]$  such that

$$f(c) = \frac{1}{b-a} \int f(x) \ dx.$$

• Integrals resulting in inverse trig functions

1.

$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \sin^{-1} \frac{x}{|a|} + C.$$

2.

$$\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \tan^{-1} \frac{x}{a} + C.$$

3.

$$\int \frac{dx}{x\sqrt{x^2 - a^2}} = \frac{1}{|a|} \sec^{-1} \frac{|x|}{a} + C.$$

#### 1.2 Chapter 2 Key Terms / Ideas

- Finding limits of integration for region between two functions: Usually, we want our limits of integration to be the points where the functions intersect
- A "complex region" between curves usually refers to an area that is not easily described by a single, continuous function over the interval of interest.
- compound regions are regions bounded by the graphs of functions that cross one another
- Cross-section: The intersection of a plane and a solid object.
- a **cylinder** is a three-dimensional shape that has two parallel, congruent bases connected by a curved surface. The bases are usually circles, but they can be other shapes as well
- The line segment connecting the centers of the two bases is called the "axis" of the cylinder.
- Slicing method: A method of calculating the volume of a solid that involves cutting the solid into pieces, estimating the volume of each piece, then adding these estimates to arrive at an estimate of the total volume; as the number of slices goes to infinity, this estimate becomes an integral that gives the exact value of the volume.
  - 1. Examine the solid and determine the shape of a cross-section of the solid. It is often helpful to draw a picture if one is not provided.
  - 2. Determine a formula for the area of the cross-section.
  - 3. Integrate the area formula over the appropriate interval to get the volume.
- Solid of revolution: A solid generated by revolving a region in a plane around a line in that plane.
- Disk method: A special case of the slicing method used with solids of revolution when the slices are disks.
- A Washer (Annuli) is a disk with holes in the center.
- Washer method: A special case of the slicing method used with solids of revolution when the slices are washers.
- Method of cylindrical shells: A method of calculating the volume of a solid of revolution by dividing the solid into nested cylindrical shells; this method is different from the methods of disks or washers in that we integrate with respect to the opposite variable.
- **Arc length:** The arc length of a curve can be thought of as the distance a person would travel along the path of the curve.
- Surface area: The surface area of a solid is the total area of the outer layer of the object; for objects such as cubes or bricks, the surface area of the object is the sum of the areas of all of its faces.

#### Chapter 2 Key Equations

Area between two curves, integrating on the x-axis

$$A = \int_{a}^{b} \left[ f(x) - g(x) \right] dx \tag{1}$$

Where  $f(x) \ge g(x)$ 

$$A = \int_a^b \left[ g(x) - f(x) \right] dx.$$

for  $g(x) \geqslant f(x)$ 

• Area between two curves, integrating on the y-axis

$$A = \int_{c}^{d} \left[ u(y) - v(y) \right] dy \tag{2}$$

Areas of compound regions

$$\int_a^b |f(x) - g(x)| \ dx.$$

• Area of complex regions

$$\int_a^b f(x) \ dx + \int_b^c g(x) \ dx.$$

· Slicing Method

$$V(s) = \sum_{i=1}^{n} A(x_i^*) \Delta x = \int_a^b A(x) dx.$$

• Disk Method along the x-axis

$$V = \int_a^b \pi [f(x)]^2 dx \tag{3}$$

• Disk Method along the y-axis

$$V = \int_{c}^{d} \pi [g(y)]^{2} dy \tag{4}$$

• Washer Method along the x-axis

$$V = \int_{a}^{b} \pi [(f(x))^{2} - (g(x))^{2}] dx$$
 (5)

• Washer Method along the y-axis

$$V = \int_{0}^{d} \pi [(u(y))^{2} - (v(y))^{2}] dy$$
 (6)

• Radius if revolved around other line (Washer Method)

$$If: x = -k$$

$$Then: r = Function + k.$$

Then: 
$$r = Function + k$$
.

$$If: x = k$$

Then: 
$$r = k - Function$$
.

• Method of Cylindrical Shells (x-axis)

$$V = \int_{a}^{b} 2\pi x f(x) dx \tag{7}$$

• Method of Cylindrical Shells (y-axis)

$$V = \int_{c}^{d} 2\pi y g(y) \, dy \tag{8}$$

• Region revolved around other line (method of cylindrical shells):

$$If: x = -k$$
 Then:  $V = \int_{-b}^{b} 2\pi (x+k)(f(x)) dx$ .

$$If: x = k$$

$$Then: V = \int_a^b 2\pi (k - x)(f(x)) dx.$$

• A Region of Revolution Bounded by the Graphs of Two Functions (method cylindrical shells)

$$V = \int_{a}^{b} 2\pi x [f(x) - g(x)] dx.$$

Arc Length of a Function of x

$$Arc Length = \int_{a}^{b} \sqrt{1 + [f'(x)]^2} dx$$
 (9)

· Arc Length of a Function of y

$$Arc Length = \int_{c}^{d} \sqrt{1 + [g'(y)]^2} \, dy$$
 (10)

• Surface Area of a Function of x

Surface Area = 
$$\int_{a}^{b} 2\pi f(x) \sqrt{1 + [f'(x)]^2} dx$$
 (11)

• Natural logarithm function

$$\ln x = \int_1^x \frac{1}{t} dt \ Z \tag{12}$$

• Exponential function

$$y = e^x, \quad \ln y = \ln(e^x) = x \ Z \tag{13}$$

• Logarithm Differentiation

$$f'(x) = f(x) \cdot \frac{d}{dx} \ln (f'(x)).$$

Note: Use properties of logs before you differentiate whats inside the logarithm

#### 1.4 Chapter 3 Key Terms

- integration by parts: a technique of integration that allows the exchange of one integral for another using the formula
- integration table: a table that lists integration formulas.
- **power reduction formula**: a rule that allows an integral of a power of a trigonometric function to be exchanged for an integral involving a lower power.
- trigonometric integral: an integral involving powers and products of trigonometric functions.
- **trigonometric substitution**: an integration technique that converts an algebraic integral containing expressions of the form  $\sqrt{a^2 x^2}$ ,  $\sqrt{a^2 + x^2}$ , or  $\sqrt{x^2 a^2}$  into a trigonometric integral.
- partial fraction decomposition: a technique used to break down a rational function into the sum of simple rational functions.
- **improper integral**: an integral over an infinite interval or an integral of a function containing an infinite discontinuity on the interval; an improper integral is defined in terms of a limit. The improper integral converges if this limit is a finite real number; otherwise, the improper integral diverges.

#### 1.5 Chapter 3 Key Equations

• Integration by parts formula

$$\int u \, dv = uv - \int v \, du.$$

Integration by parts for definite integral

$$\int_a^b u \, dv = uv \Big|_a^b - \int_a^b v \, du$$

- To integrate products involving  $\sin(ax)$ ,  $\sin(bx)$ ,  $\cos(ax)$ , and  $\cos(bx)$ , use the substitutions:
  - Sine Products

$$\sin(ax)\sin(bx) = \frac{1}{2}\cos((a-b)x) - \frac{1}{2}\cos((a+b)x)$$

- Sine and Cosine Products

$$\sin(ax)\cos(bx) = \frac{1}{2}\sin((a-b)x) + \frac{1}{2}\sin((a+b)x)$$

- Cosine Products

$$\cos(ax)\cos(bx) = \frac{1}{2}\cos((a-b)x) + \frac{1}{2}\cos((a+b)x)$$

- Power Reduction Formula (sine)

$$\int \sin^n x \ dx = -\frac{1}{n} \sin^{n-1} x \cos x + \frac{n-1}{n} \int \sin^{n-2} x \ dx$$
$$\int_0^{\frac{\pi}{2}} \sin^n x \ dx = \frac{n-1}{n} \int_0^{\frac{\pi}{2}} \sin^{n-2} x \ dx.$$

- Power Reduction Formula (cosine)

$$\int \cos^n x \ dx = \frac{1}{n} \cos^{n-1} x \sin x + \frac{n-1}{n} \int \cos^{n-2} x \ dx$$
$$\int_0^{\frac{\pi}{2}} \cos^n x \ dx = \frac{n-1}{n} \int_0^{\frac{\pi}{2}} \cos^{n-2} x \ dx.$$

- Power Reduction Formula (secant)

$$\int \sec^n x \, dx = \frac{1}{n-1} \sec^{n-1} x \sin x + \frac{n-2}{n-1} \int \sec^{n-2} x \, dx$$
$$\int \sec^n x \, dx = \frac{1}{n-1} \sec^{n-2} x \tan x + \frac{n-2}{n-1} \int \sec^{n-2} x \, dx$$

- Power Reduction Formula (tangent)

$$\int \tan^n x \, dx = \frac{1}{n-1} \tan^{n-1} x - \int \tan^{n-2} x \, dx$$

• Trigonometric Substitution

$$-\sqrt{a^2-x^2}$$
 use  $x=a\sin\theta$  with domain restriction  $\left[-\frac{\pi}{2},\frac{\pi}{2}\right]$ 

$$-\sqrt{a^2+x^2}$$
 use  $x=a\tan\theta$  with domain restriction  $\left(-\frac{\pi}{2},\frac{\pi}{2}\right)$ 

 $-\sqrt{x^2-a^2}$  use  $x=a\sec\theta$  with domain restriction  $\left[0,\frac{\pi}{2}\right)\cup\left[\pi,\frac{3\pi}{2}\right)$ 

- Steps for fraction decomposition
  - 1. Ensure deg(Q) < deg(P), if not, long divide
  - 2. Factor denominator
  - 3. Split up fraction into factors
  - 4. Multiply through to clear denominator
  - 5. Group terms and equalize
  - 6. Solve for constants
  - 7. Plug constants into split up fraction
  - 8. Compute integral
- Solving for constants Either:
  - Plug in values (often the roots)
  - Equalize
- Cases for partial fractions
  - Non repeated linear factors
  - Repeated linear factors
  - Nonfactorable quadratic factors
- Midpoint rule

$$M_n = \sum_{i=1}^n f(m_i) \ \Delta x.$$

• Absolute error

$$err = \left| \text{Actual} - \text{Estimated} \right|.$$

• Absolute error

$$err = \left| \frac{\text{Actual} - \text{Estimated}}{\text{Actual}} \right| \cdot 100\%.$$

• Error bound for midpoint rule

$$E_M \leqslant \frac{M(b-a)^3}{24n^2}$$

• Trapezoidal rule

$$T_n \frac{1}{2} \Delta x \left( f(x_0) + 2f(x_1) + 2f(x_2) + \dots + 2f(x_{n-1}) + f(x_n) \right)$$

• Error bound for trapezoidal rule

$$E_T \leqslant \frac{M(b-a)^3}{12n^2}$$

· Simpson's rule

$$S_n = \frac{\Delta x}{3} \left( f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + 4f(x_5) + \dots + 2f(x_{n-2}) + 4f(x_{n-1}) + f(x_n) \right)$$

• Error bound for Simpson's rule

$$E_S \leqslant \frac{M(b-a)^5}{180n^4}$$

- M in the error bound functions represents the maximum value of f''(x) in the interval
- Note: error bound function is upper bounds for the error
- Finding n with error bound functions
  - 1. Find f''(x)
  - 2. Find maximum values of f''(x) in the interval
  - 3. Plug into error bound function
  - 4. Set value  $\leq$  desired accuracy (ex: 0.01)
  - 5. Solve: Don't round down
  - 6. If we were to truncate, we would use the ceil function [n]