

# **Cpp Nuances**

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## Converting char to std::string

Suppose we have a char variable, and we need to "convert" it to a string. To do this we use the string class constructor, which has two parameters, the size of the string to create, and the character to use as the fill.

### 1.1 Constructor signature

```
0 string(size_t n, char x)
```

### 1.2 Example

```
0 char c = 'a';  
1 string s(1,c);
```

## std::string::npos

**Concept 1:** In C++, `std::string::npos` is a static member constant value with the greatest possible value for an element of type `size_t`. This value, when used as the length in string operations, typically represents "until the end of the string." It is often used in string manipulation functions to specify that the operation should proceed from the starting position to the end of the string, or until no more characters are found.

□

### 2.1 Example

```
0 string infix = buffer.substr(index + 2, string::npos);
```

`std::string::npos` is defined as the maximum value representable by the type `size_t`. This value is typically used to signify an error condition or a not-found condition when working with strings and other sequence types. However, when used as a length argument in methods like `std::string::substr`, it effectively becomes a directive to process characters until the end of the string. This is because any attempt to access beyond the end of the string would exceed the string's length, and the methods are designed to stop processing at that point.

## Narrowing

Narrowing happens when:

- A value of a larger or more precise type is converted to a smaller or less precise type (e.g., double to int, int to char).
- A floating-point value is converted to an integer type.
- An integer value is converted to a smaller integer type (e.g., int to short) and does not fit within the destination type's range.

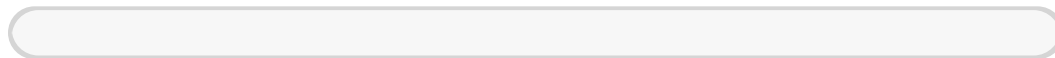
## Aggregate types

Aggregate types in C++ are simple data structures that hold collections of values and have minimal additional behavior. They are essentially "plain old data" structures that are easy to initialize and manipulate. The term "aggregate" is formally defined by the C++ standard.

A class, struct, or union is considered an aggregate if it satisfies all of the following conditions:

1. No User-Defined Constructors: It must not have any explicitly declared constructors (including default, copy, or move constructors).
2. No Private or Protected Non-Static Data Members: All non-static data members must be public.
3. No Virtual Functions: It must not have any virtual functions.
4. No Base Classes: It must not inherit from another class or struct.
5. No Virtual Base Classes: It must not use virtual inheritance.

For example



### 4.1 Aggregate initialization

Aggregate initialization in C++ refers to a special form of initialization for aggregate types using an initializer list enclosed in {} braces. This allows you to directly specify values for the members of an aggregate type in the order they are declared.

Each member of the aggregate is initialized with the corresponding value provided in the initializer list. The order of values in the initializer list must match the declaration order of members in the aggregate.

If fewer values are provided in the initializer list than there are members in the aggregate, the remaining members are value-initialized (e.g., zero-initialized for fundamental types).

If the type is not an aggregate (e.g., has a user-defined constructor, private members, or virtual functions), aggregate initialization cannot be used.

```
0  struct S {  
1      int x,y;  
2  };  
3  
4  S s = {1,2};
```

Consider the next example,

```

0  struct S {
1      int x,y;
2
3      S(int x, int y) : x(x), y(y) {}
4  };
5
6  S s = {1,2}; // Works fine

```

Since the class *S* has a user-defined constructor, it is no longer an aggregate type.

Aggregate initialization is not applicable here. Instead, C++ checks for constructors that match the initializer list {1, 2}.

Since it found one, the compiler interprets it as calling the constructor *S*(int x, int y) with the arguments 1 and 2.

In modern C++ (C++11 and later), brace-enclosed initialization is often used for uniform initialization.

If a constructor is available that matches the initializer list, it is called.

## 4.2 Narrowing is not allowed in aggregate-initialization from an initializer list

The error "narrowing is not allowed in aggregate-initialization from an initializer list" occurs in C++ when you try to initialize an aggregate type (e.g., structs, arrays, or classes with no user-defined constructors) using values in an initializer list, but the values undergo an implicit narrowing conversion that could lose information or precision.

```

0  struct A {
1      int x;
2      float y;
3  };
4
5  A a = {1, 3.14}; // OK, no narrowing
6  A b = {1, 3.14f}; // OK, no narrowing (3.14f is a float literal)
7
8  A c = {1, 3.14}; // ERROR: narrowing from `double` to `float`

```

## 4.3 implicit conversion using a single-argument constructor

A constructor that takes one argument can be used for implicit conversion of that argument type to the class type.

```

0  struct s {
1      int x;
2      s(int value) : x(value) {} // Single-argument constructor
3  };
4  s s1 = 1;

```

The integer 1 is implicitly converted to an object of type s using the s(int value) constructor.

By default, a single-argument constructor allows implicit conversions. If you want to prevent implicit conversions and require explicit construction, you can use the explicit keyword

```

0  struct s {
1      int x;
2      explicit s(int value) : x(value) {}
3  };
4
5  int main() {
6      s s1 = 1; // ERROR: Explicit constructor prevents implicit
    ↪ conversion
7      s s2(1); // OK: Direct initialization
8  }

```



## Floating point literals

Floating point literals in c++ will be of type double. For example,

```
o cout << typeid(4.09).name(); // d
```

Append *f* to the literal to make it a float

```
o cout << typeid(4.09f).name(); // d
```

## Size of structs and classes

Consider the code

```
0  struct s { }  
1  cout << sizeof(s) << endl; // 1  
2  
3  s s1;  
4  cout << sizeof(s1) << endl; // 1
```

Notice that empty structs do not have a size of zero. Empty structs have a size of one byte.

A size of zero for a struct would mean that it occupies no memory. If multiple instances of such a struct are created, they would have no unique memory location to occupy. As a result, the compiler would assign the same memory address to all instances, which would violate fundamental rules of object-oriented programming in C++.

Furthermore, giving fields to the struct or class increases the size of that struct or class by size of the type.

```
0  struct s { int x; }  
1  cout << sizeof(s); // 4
```

Notice that the size is **not** 5. Creating functions and creating variables in those functions does not add to the size

```
0  struct s {  
1      void f() {  
2          int x;  
3      }  
4  }  
5  cout << sizeof(s); // 1
```

Creating structs inside structs and even adding fields to the inner structs does not increase the size

```
0  struct s {  
1      struct k { int x; };  
2  };  
3  
4  cout << sizeof(s); // 1  
5  cout << sizeof(s:k); // 4
```

Lastly, constructors and destructors do not increase the size.

It seems only fields increase the size.

## 6.1 Padding

Consider the following struct

```
0  struct s {  
1      char c; // 1 byte  
2      int x; // 4 bytes  
3  };  
4  cout << sizeof(s) << endl; // 8
```

Notice that we do not get a size of 5. In C++, padding is introduced by the compiler to ensure proper memory alignment of data members. This improves performance on most hardware architectures. The first member, char *c*, occupies 1 byte. The next member, int *x*, requires 4 bytes and should be aligned to a 4-byte boundary (on most systems). To achieve this alignment, 3 bytes of padding are added after *c* before *x* starts.

# When is trailing return type useful

## 7.1 Decltype on template parameters

Suppose we had two template types  $T, U$ , and a function that accepts  $Ta, Ub$ . Suppose we wanted the return type to be the type of  $T + U$ , we could of course just write

```
0  template<typename T, typename U>
1  decltype(T{} + U{}) f(T a, U b) {
2      return a + b;
3  }
```

Or, we could utilize a trailing return

```
0  template<typename T, typename U>
1  auto f(T a, U b) -> decltype(a+b) {
2      return a + b;
3  }
```

## 7.2 Nested structs

Consider the code

```
0  struct A {
1      struct B {};
2
3      B f() const;
4  };
5
6  A::B A::f() const { }
```

Instead of having to use the scope resolution operator, we could use a trailing return type.

```
0  auto A::f() const -> B {
1
2  }
```

By using a trailing return type, we are essentially inside the scope of  $A$  by the time we specify the return type.

## Most vexing parse

The most vexing parse is a phenomenon in C++ where a line of code that looks like a variable declaration is instead interpreted by the compiler as a function declaration. This often happens because of C++'s ambiguous grammar for declarations.

```
0  std::string s(); // Treated as a function declaration
```

This will not be treated as a default constructed string by the C++ compiler, but instead as a function declaration. To fix this issue, we instead use brace initialization

```
0  std::string s{} // A default string variable
```

## Notes about copy constructors

The copy constructor in C++ typically takes a const reference (const T&) to ensure correctness and efficiency. If the copy constructor took its parameter by value, this would require making a copy of other before calling the constructor itself. But that copy itself would require calling the copy constructor, leading to infinite recursion until a stack overflow.

If the copy constructor took a non-const reference, this would not allow copying from const objects.

Since a copy operation should not modify the original object, using const ensures the copy constructor can be called for const objects.

Recall that functions (and methods) that take a const reference insure that the function can be called on both const objects and non-const objects. Functions that take non-const references can only accept non-const objects.

As a quick side note, since we are on the topic of const correctness, recall that constant member functions cannot call non-const member functions.

### 9.1 Copy constructors in inheritance

Consider the code

```
0  struct A {
1      A() { cout << "default" << endl; }
2      A(const A& other) { cout << "other" << endl; }
3  };
4
5  struct B : A {
6      B() { cout << "default" << endl; }
7      B(const B& other) { cout << "other" << endl; }
8  };
9  B b;
10 B b2(b);
11 // Default
12 // Default
13 // Default
14 // Other
```

So why isn't B b2(b) calling A's copy constructor?

When you write the copy constructor for class B without an initializer list for the base class A, the base class part of B is default-constructed by default

Since there is no initializer list here, A is constructed using its default constructor (which prints "default") rather than its copy constructor. To have A's copy constructor called when copying a B object, you need to explicitly initialize the A subobject using A(other) in B's copy constructor, like so:

```
o B(const B& other) : A(other) { cout << "other" << endl; }
```

This change ensures that when you copy a B object, the A part is also copied (using A's copy constructor), and the output would reflect that.

As it turns out, an implicitly-defined copy constructor would have called the copy constructor of its bases "The implicitly-defined copy/move constructor for a non-union class X performs a memberwise copy/move of its bases and members"). But when you provide a user-defined copy constructor, this is something you have to do explicitly

## Exceptions during a call to new

When using raw pointers, an exception occurring after a new allocation leads to a resource leak if the allocated memory is not properly managed. This happens because new dynamically allocates memory on the heap, but if an exception interrupts execution before delete is called, the allocated memory remains unreachable and never freed.

To prevent this, use smart pointers (`std::unique_ptr` or `std::shared_ptr`), which automatically manage memory and clean up even if an exception occurs.

However, it is true that using `std::unique_ptr` and `std::shared_ptr` does not guarantee that there will be no resource leaks if they are not used properly. Specifically, passing new directly to their constructors can still lead to resource leaks in certain cases. This is why `std::make_unique` and `std::make_shared` are preferred

`make_shared` performs a single allocation that stores both the object and the control block together. If an exception occurs, no memory leak happens because allocation and ownership setup happen in one step.

Same is true for `make_unique`

### 10.1 Exceptions during constructors

If a call to new results in an exception, the object is never allocated. When you use new, the operator first tries to allocate memory by calling `operator new(size)`, which is similar to `malloc`.

If memory allocation is successful, the constructor of the object is called.

If there isn't enough memory, `operator new` will throw a `std::bad_alloc` exception (unless you use `nothrow new`, which returns `nullptr`)

If memory allocation succeeds but the constructor of the object throws an exception, the allocated memory is automatically freed, so there is no memory leak. If an exception is thrown in the constructor after memory has been allocated but before construction is complete, the C++ runtime ensures that the allocated memory is automatically freed. This is done by:

- Catching the exception inside the new operator.
- Calling `operator delete(ptr)` to deallocate the memory.



## Notes about polymorphism

Consider the code

```
0  struct base {
1      virtual void print() const {
2          cout << "Base" << endl;
3      }
4
5      virtual ~base() {
6          cout << "Cleaned up base" << endl;
7      }
8  };
9  struct derived : base {
10     void print() const override {
11         cout << "Derived" << endl;
12     }
13
14     ~derived() {
15         cout << "Cleaned up derived" << endl;
16     }
17 };
18
19 void f(const base* o) {
20     o->print();
21 }
22
23 void f(const base& o) {
24     o.print();
25 }
26
27 derived d1;
28 base& b1 = d1;
29
30 f(b1);
31
32 base* d = new derived();
33 f(d);
34
35 delete d;
```

We get the output

```
0  Derived
1  Cleaned up derived
2  Cleaned up base
```

The reason both destructor messages ("Cleaned up derived" and "Cleaned up base") are printed when you call `delete d`; is due to polymorphic destruction.

The base class has a virtual destructor (virtual `~base()`). This ensures that when an object is deleted through a pointer to base, the destructor of the derived class will also be invoked before the base destructor.

`d` is deleted, and because base has a virtual destructor, the destructor call correctly cascades down the inheritance chain:

- First, `~derived()` runs and prints "Cleaned up derived".
- Then, `~base()` runs and prints "Cleaned up base".

If the destructor in base wasn't virtual, deleting a derived object through a `base*` pointer would cause undefined behavior (likely only `~base()` would be called, leading to memory leaks).

If base has fields (member variables), whether directly inherited by derived or not, the base destructor must be called to clean up those fields properly when a derived object is deleted.

## 11.1 Polymorphism with arrays and slicing

### 11.1.1 Object Slicing

Object slicing occurs when an object of a derived class is assigned to a variable of a base class type, causing the derived part of the object to be "sliced off", leaving only the base class portion.

Slicing occurs when

- A derived object is assigned to a base class object (not a pointer or reference).
- A derived object is stored in a container of base class objects (e.g., an array of base objects).

```
0  struct base {
1      int x{1};
2
3  };
4  struct derived : base {
5      int y{5};
6  };
7
8  base b = derived{};
9  // Error, no member named y in base
10 cout << b.x << endl << b.y;
```

### 11.1.2 Polymorphism with arrays

Consider the following code

```
0  struct base {
1      virtual void print() const {
2          cout << "Base" << endl;
3      }
4
5      virtual ~base() {
6          cout << "Cleaned up base" << endl;
7      }
8  };
9
10 struct derived : base {
11     void print() const override {
12         cout << "Derived" << endl;
13     }
14
15     ~derived() {
16         cout << "Cleaned up derived" << endl;
17     }
18 };
19
20 void f(const base& o) {
21     o.print();
22 }
23
24 auto main(int argc, const char* argv[]) -> int {
25     base* barr = new derived[5];
26
27     delete[] barr;
28
29     return EXIT_SUCCESS;
30 }
```

barr is declared as base\*, but the memory actually holds derived objects. When delete[] barr; is called, C++ treats barr as an array of base objects, not derived objects. This breaks proper destructor calls, leading to undefined behavior.

Even though base has a virtual ~base(), the problem is not about virtual dispatch. Instead, it's about how C++ tracks array allocations.

The array of derived objects was allocated using new derived[5], but delete[] barr; doesn't have enough information to correctly call derived destructors.

When delete[] barr; is called, C++ sees a base\* pointer and assumes it points to an array of base objects.

Instead we either,

```
0  derived* darr = new derived[n]
```

```

0  vector<unique_ptr<base>> v(5);
1  for (auto& item : v) {
2      item = make_unique<derived>();
3  }
4
5  // Or the standard approach
6  vector<base*> v2(5);
7  for (auto& item : v2) {
8      item = new derived();
9  }
10
11 for (auto& item : v2) {
12     delete item;
13 }

```

## 11.2 Runtime polymorphism, dynamic dispatch, dynamic binding, and the vtable

Runtime polymorphism in C++ is achieved through function overriding and is implemented using virtual functions in an inheritance hierarchy. It allows a derived class to provide a specific implementation of a function that is already defined in its base class.

### 11.2.1 Dynamic dispatch and dynamic binding

Dynamic dispatch is a mechanism where the function to be executed is determined at runtime, rather than at compile-time. This is a key feature of runtime polymorphism and is enabled by virtual functions in C++.

When a virtual function is declared in a base class and overridden in a derived class, C++ does not resolve function calls at compile-time.

Instead, when a function is called using a base class pointer/reference, C++ performs a runtime lookup to determine which function to execute.

This lookup is performed using the VTable (Virtual Table) and VPtr (Virtual Pointer) mechanism.

As a side note, the following will not work

```

0  struct foo {
1      constexpr virtual int print() const {
2          return 12;
3      }
4
5      virtual ~foo() {}
6  };
7
8  struct bar : foo {
9      constexpr int print() const override {
10         return 0;
11     }
12 };
13
14 foo* f = new bar{};
15 constexpr int x = f.print();

```

The issue is that since the print functions are determined and called at runtime, it cannot be a compile time constant expression. We get the error "The value of *f* is not usable in a constant expression"

Dynamic binding (also called late binding) is the underlying mechanism that allows dynamic dispatch to work. It refers to the process of determining which function implementation should be executed at runtime, rather than at compile time.

Binding refers to associating a function call with a function definition. Dynamic binding means this association happens at runtime, based on the actual type of the object.

Dynamic binding ensures that when a function is called on a base class pointer/reference, the correct overridden function from the derived class is invoked at runtime. Dynamic dispatch is the result of dynamic binding

### 11.2.2 The Vtable

C++ implements runtime polymorphism using a VTable (Virtual Table) and a VPtr (VPtr)

A VTable is a table of function pointers maintained per class. It stores pointers to the virtual functions defined in a class. Each class with virtual functions has a single VTable.

Each object of a class that has virtual functions contains a hidden pointer, called VPtr (Virtual Pointer). VPtr points to the VTable of that particular class.

During runtime, when a virtual function is called via a base class pointer, the VPtr is used to look up the correct function implementation in the VTable.

When the program starts, the compiler creates a VTable for every class that has virtual functions. Every object of such a class gets a hidden VPtr, which points to the corresponding VTable.

When a virtual function is called using a base class pointer, the call is resolved dynamically by checking the VTable.

The VTable (Virtual Table) is created at compile time, but the VPtr (Virtual Pointer) is assigned and used at runtime.

The VTable itself is constructed at compile time, meaning the compiler generates and lays out the function pointers in the table before the program runs.

The VPtr is assigned at runtime, when an object of the class is created.

Because having virtual functions in our struct / class requires this VPtr to be created, having virtual functions therefore will increase the size of the struct and the objects created by the size of a pointer (8 bytes on 64-bit systems or 4 bytes on 32-bit systems).

each class in the inheritance hierarchy that has at least one virtual function has its own vtable.

- A base class with virtual functions has a vtable that stores pointers to its virtual functions.
- A derived class that overrides any virtual functions gets its own vtable, which replaces the base class's function pointers with the derived class's implementations.
- The vtable is associated with a class, not individual objects.
- Each object of a class with virtual functions has a vptr (virtual table pointer) that points to the vtable of its actual type.

Consider the code

```
0  struct foo {
1      virtual void print() const {
2          cout << "Foo" << endl;
3      }
4
5      virtual ~foo() {}
6  };
7
8  struct bar : foo {
9      void print() const override {
10         cout << "Bar" << endl;
11     }
12 };
```

Since foo has virtual functions (print and the destructor), it will have a vtable.

Index	Function Pointer
0	foo::print()
1	foo::~foo() (destructor)

Every instance of foo has a vptr (virtual table pointer) pointing to this table.

Since bar overrides print(), but still inherits the virtual destructor from foo, its vtable will have the overridden version of print().

Index	Function Pointer
0	bar::print()
1	foo::~foo() (inherited destructor)

Each instance of `bar` will have its `vp`tr pointing to `vtable` for `bar`.

```
0  int main() {
1      foo* obj = new bar();
2      obj->print(); // Calls bar::print() because vp
```

↪ bar's vtable

```
3      delete obj; // Calls foo::~foo() due to virtual destructor
4  }
```

### 11.3 Can you call pure virtual methods

You cannot instantiate abstract classes. Thus, you cannot call pure virtual methods

### 11.4 Do the signatures need to exactly match on overridden functions

Yes, the function signature must exactly match the base class function (including return type, parameters, and `const` qualifiers). If the signature differs in any way, the function in the derived class will be considered a new, independent function rather than an override.

### 11.5 What happens if you forget the keyword `virtual` on base class methods

Consider

```
0  struct s{
1      void print() const & {cout << "Base" << endl;}
2  };
3
4  struct k : s{
5      virtual void print() const & override {cout << "Derived" <<
6      ↪ endl;}
7  };
```

We get a compiler error *print marked override but does not override any member functions*

### 11.6 Do you need the keyword `virtual` on overridden methods?

In the derived class, you do not need to explicitly write `virtual` again when overriding, though you can include it for clarity.

## 11.7 What happens if you forget the override

forgetting to put the `override` keyword when overriding a base class member function has the following consequences

The code will still compile, but if the function signature does not exactly match the base class function, you might accidentally create a new function in the derived class instead of overriding the base function.

If the function signature is incorrect (e.g., different return type, wrong parameters, or missing `const` qualifier), the base class function is hidden instead of being overridden. This means

- Calls to the function through a base class pointer/reference will not invoke the derived class function as intended.
- Instead, the base class implementation will be called, leading to unexpected behavior.
- If the function in the derived class has a different parameter list, the base class function can only be accessed using `Base::functionName(...)`.

The `override` keyword forces the compiler to check whether the function actually overrides a virtual function from the base class. Without it, if the base class function signature changes, the derived class function may silently stop overriding it, leading to subtle runtime errors.

```
0  struct A {  
1      virtual void print() const {cout << "A"; }  
2  };  
3  
4  struct B : A {  
5      virtual void print() {cout << "B";}   
6  };  
7  
8  A* b = new B;  
9  b->print(); // A  
10  
11 delete b;
```

We forgot the `override` keyword, which would be fine as long as the function signatures still matched exactly, but notice that we also forgot to mark B's `print` `const`. Thus, B's `print` method does not override A's, and it is an independent function. Therefore, B's VTable remains

Index	fn
0	A::print()

I.e. it does not get overridden. If we marked B's `print` with `override`, it would give a compiler error since the signatures don't match

## 11.8 Overrides with default args

Consider the code



```

0  struct A {
1      virtual void print(int x=5) const {cout << "A" << x; }
2  };
3
4  struct B : A {
5      virtual void print(int x=10) const override {cout << "B" <<
    ↪ x;}
6  };
7
8  A* b = new B;
9  b->print(); // B5
10
11 delete b;

```

So B's print gets called, but we get the default arg from A?

Since print() is virtual, dynamic dispatch occurs. The runtime determines that B::print() should be executed, not A::print().

However, default arguments are resolved at compile time, based on the static type of the pointer.

The call b->print(); is interpreted at compile time as

```

0  b->print(5); // Because `b` is an `A*`, it uses A's default
    ↪ argument

```

## 11.9 Private and public with polymorphism

Recall that for a struct *S*

```

0  struct S {
1      private:
2          void print() {}
3  };
4
5  S s;
6  s.print() // Error: Print is private

```

We cannot call private methods through an object. However, consider the code

```

0  struct base {
1      virtual void print() const {cout << "Base" << endl;}
2  };
3
4  struct derived : base{
5      private:
6          void print() const override {cout << "Derived" << endl;}
7  };
8  base* b = new derived{};
9  b->print(); // "Derived"

```

So why does this work? Why are we able to call this private method?

In C++, access control (private, protected, public) is enforced at compile time and is based on the class from which the call is made. However, when using dynamic dispatch (i.e., calling a virtual function through a base class pointer), the actual function that gets invoked is determined at runtime via the vtable mechanism, which is independent of access control.

### 11.10 Virtual methods are implicitly inline

In C++, virtual methods are implicitly considered inline by the compiler, but this doesn't mean they are always inlined at runtime.

The inline keyword in C++ does not necessarily mean "replace the function call with its body" (though that is one possible effect). Instead, it has two key meanings:

- **Allows multiple definitions across translation units:**
  - Normally, a function or method definition must appear in only one .cpp file (ODR - One Definition Rule).
  - An inline function can be defined in multiple translation units as long as all definitions are identical.
- **Hints for compiler optimization:** The compiler may replace calls to an inline function with its body (but this is not guaranteed).

Virtual Methods Are Typically Defined in Header Files

- Virtual methods must be known at compile-time to construct the vtable (virtual table) correctly.
- Because virtual methods are often declared in a class definition (inside a header file), they must be allowed in multiple translation units.
- Making them implicitly inline prevents ODR violations when the class is included in multiple .cpp files.

The primary reason for marking functions inline to avoid ODR (One Definition Rule) violations applies to functions defined in header files that are included in multiple translation units.

Normally, if you define a function in a header file, and that header is included in multiple .cpp files, you would get multiple definitions of the same function when linking.

Marking the function inline tells the compiler that all definitions of the function in different translation units are identical and should be treated as a single definition.

If a function is defined only in a .cpp file, it will not be included in multiple translation units, so inline is unnecessary.

### 11.11 Base class pointer if the base class is abstract

Consider the code

```
0  struct A {  
1      virtual void print() const = 0;  
2      ~A() = default;  
3  };  
4  struct B : A { };  
5  A* b = new B{};
```

print is declared as a pure virtual function. This means that any concrete (non-abstract) subclass of A must provide an override for print(). However, struct B does not implement print(), so B remains abstract, and you cannot instantiate an object of an abstract class.

Thus, the fix is to simply override print in B

```
0  struct A {  
1      virtual void print() const = 0;  
2      ~A() = default;  
3  };  
4  
5  struct B : A {  
6      void print() const override;  
7  };  
8  A* b = new B{}; // OK
```

### 11.12 Does the destructor need to be pure in an abstract class?

it's not necessary to make the destructor pure just because the class is abstract. Here's why:

- The class A is abstract due to the pure virtual function print(). You don't need a pure virtual destructor to make a class abstract; a single pure virtual function is enough.
- The destructor in an abstract class should be virtual to ensure proper cleanup of derived objects. Marking the destructor as virtual (even if defaulted) is sufficient. A pure virtual destructor requires an out-of-class definition, which can be unnecessary overhead if you already have other pure virtual functions enforcing abstraction.
- In many cases, a defaulted virtual destructor (i.e., ~A() = default;) is the simplest and most effective choice, allowing for correct object destruction without extra boilerplate.

## The existence of structs and classes

Does a Struct Exist in Memory Before an Object is Created? Yes and No. It depends on what part of the struct you're referring to:

- **Struct Definition (Type Information) – Exists at Compile Time:** The struct itself is just a blueprint (like a class). It does not occupy memory on its own.

Only when you create an object of the struct does memory get allocated for its members.

- **VTable (for Virtual Functions) – Exists in Memory, Even Without Objects:** If the struct contains virtual functions, the compiler generates a VTable at compile time. The VTable itself is stored in static memory (not per object). Even if no object is created, the struct's VTable exists somewhere in memory.
- **Object Instances – Exist in Memory When Created:** When you instantiate an object of the struct, memory is allocated for that object's data members. If the struct has virtual functions, each object has a hidden VPtr (Virtual Pointer), which increases its size.

If *A* is a struct, why does `sizeof(A)` have a size even if no object is created? When you define a struct in C++, the compiler determines the size of its layout at compile time. This means that even if you don't create an object of the struct, `sizeof(A)` can still return a valid size.

The compiler does not assign fixed memory addresses to struct members. Instead, it determines the memory layout (size, alignment, and padding) at compile time. Actual memory addresses are assigned at runtime when an object is created.

## Note about heap allocated memory in vectors

If your `std::vector` contains raw pointers (e.g., `std::vector<int*>`), the vector will only destroy the pointers themselves but not the dynamically allocated memory they point to. This will cause a memory leak if you don't manually delete each allocated object before the vector goes out of scope.

To avoid leaks, manually delete the elements before clearing the vector

## Function that takes a const reference can accept rvalues

In C++, a function that takes a const reference can accept rvalues because const references extend the lifetime of temporary (rvalue) objects.

```
0  template <typename T>
1  void f(const T& x) {}
```

A const T& (a reference to a const object of type T) can bind to both lvalues and rvalues, because:

1. Lvalues are naturally bindable to references.
2. Rvalues (temporaries) can bind to const T& because:
  - The const qualifier guarantees that the temporary will not be modified.
  - C++ extends the lifetime of the temporary to match the lifetime of the reference.

```
0  const int& ref = 100; // OK: binds to temporary, lifetime
    ↳ extended
1  std::cout << ref << std::endl; // Prints 100
2
3  int& ref = 100; // ERROR: Cannot bind non-const lvalue reference
    ↳ to an rvalue
```

- If an lvalue is passed → T deduces to int&, making T&& collapse to int&.
- If an rvalue is passed → T deduces to int, making T&& remain int&&.

## Notes about c++ casts

First, recall

- `static_cast` is used for safe and well-defined type conversions that are checked at compile-time.
- `dynamic_cast` is used only with polymorphic types (i.e., classes with at least one virtual function). It performs runtime type checking and is mainly used for safe downcasting.
- `const_cast` is used to add or remove `const` or `volatile` qualifiers from a variable. It is the only cast that can remove `const`, allowing modifications to otherwise constant data.
- `reinterpret_cast` is the most dangerous cast—it converts between completely unrelated types. It does not perform type checking and is used for low-level pointer manipulation.

### 15.1 `Static_cast`

**When to Use `static_cast`:**

- Converting between numeric types (e.g., `int` to `double`).
- Converting between pointers of related classes (e.g., upcasting in inheritance).
- Converting between explicitly defined conversion operators.

**What It CANNOT Do:**

- It does not check for validity at runtime.
- It cannot cast between unrelated types (use `reinterpret_cast` for that).
- It cannot remove `const` or `volatile` qualifiers (use `const_cast` for that).

### 15.2 `Dynamic_cast`

Dynamic casting in C++ is a feature provided by the language to safely convert pointers or references of base class types to pointers or references of derived class types at runtime. This is particularly useful in scenarios involving polymorphism, where you have a base class pointer or reference pointing to an object of a derived class, and you need to access derived class-specific members or methods.

Dynamic casting is used with pointers or references in class hierarchies that involve polymorphism (i.e., classes with at least one virtual function).

```
◦ dynamic_cast<new_type>(expression)
```

Dynamic casting performs a runtime check to ensure the cast is valid. If the cast is not possible, it returns `nullptr` for pointers or throws a `std::bad_cast` exception for references.

Dynamic casting relies on Run-Time Type Information (RTTI), which must be enabled in your compiler.

### 15.2.1 When to Use Dynamic Casting

- When you need to safely downcast in a polymorphic hierarchy.
- When you are unsure of the actual type of the object at runtime and need to check it.

Dynamic casting incurs a runtime overhead due to the type checking. It only works with polymorphic types (classes with at least one virtual function).

Overuse of dynamic casting can indicate a design flaw; prefer virtual functions and polymorphism where possible.

### 15.2.2 RTTI

RTTI stands for Run-Time Type Information. It is a feature in C++ that provides mechanisms to determine the type of an object at runtime. RTTI is particularly useful in scenarios involving polymorphism, where you need to identify the actual type of an object pointed to by a base class pointer or reference.

RTTI relies on metadata stored by the compiler for polymorphic types (classes with at least one virtual function). This metadata includes:

- A vtable (virtual table) for each polymorphic class, which contains pointers to its virtual functions.
- A `type_info` object for each class, which stores information about the class's type.

When you use `typeid` or `dynamic_cast`, the compiler generates code to access this metadata at runtime to determine the object's type.

## 15.3 `const_cast`

`const_cast` is only used to remove `const` or `volatile` qualifiers from a variable. It cannot be used to add `const`.

```
0  #include <iostream>
1
2  void modify(int* ptr) {
3      *ptr = 42;
4  }
5
6  int main() {
7      const int x = 10;
8
9      // Removing const
10     int* ptr = const_cast<int*>(&x);
11
12     modify(ptr); // Undefined behavior if `x` was originally a
    ↪ `const` object
13
14     std::cout << "x: " << x << std::endl; // This may not
    ↪ reflect the change due to UB
15 }
```



This is unsafe if `x` was originally declared as `const int x = 10;`, because modifying `x` leads to undefined behavior. However, if `x` was originally non-const and then cast to const, modifying it later using `const_cast` is safe.

If you want to add const, you should use

- Implicit conversion
- `static_cast`
- Declaring a const reference or pointer to a non-const object

```
0  int a = 5;
1  const int* ptr = &a; // Adding const implicitly
2  const int& ref = a;  // Adding const implicitly
```

`const_cast` is useful in a few specific cases where you need to work around const qualifiers safely.

### 15.3.1 Modifying a non-const object that was passed as const

If a function receives a const parameter but you know that the actual object is non-const, you can safely cast away const and modify it.

### 15.3.2 Removing const to use overloaded functions

Sometimes you have an overloaded function where one version accepts const and another modifies the object. `const_cast` allows selecting the modifying version when needed.

```
0  #include <iostream>
1
2  class Example {
3      public:
4      void print() {
5          std::cout << "Non-const print" << std::endl;
6      }
7
8      void print() const {
9          std::cout << "Const print" << std::endl;
10     }
11 };
12
13 void forceModify(const Example& obj) {
14     const_cast<Example&>(obj).print(); // Calls non-const
    ↪ version
15 }
16
17 int main() {
18     Example e;
19     forceModify(e); // Calls non-const print()
20 }
```

**Note:** Const cast is a runtime operation and does not perform any checks

## 15.4 reinterpret\_cast

reinterpret\_cast is a type of casting operator in C++ that is used to convert one pointer type to another, even if the types are entirely unrelated. It performs a low-level reinterpretation of the underlying binary representation of the data.

**Note:** reinterpret\_cast is a runtime operation and does not perform any checks

## 15.5 Why are c casts unsafe?

C-style casting is unsafe and ambiguous because:

- It can perform multiple types of conversions at once, including:
  - static\_cast
  - reinterpret\_cast
  - const\_cast
  - Even dynamic\_cast (if a class has virtual functions)
- It lacks compile-time safety—you might unintentionally use an invalid cast.
- It is hard to search and debug since (Type) doesn't indicate what kind of conversion is being performed.

# The compiler and functions

The compiler handles functions through several stages, from parsing the source code to generating machine code. Here's an overview of how the compiler deals with functions

1. **Parsing and Syntax Analysis:** The compiler reads the source code and identifies function declarations and definitions.

It checks the syntax of the function, such as the return type, function name, parameter list, and body.

2. **Semantic Analysis:** The compiler checks the meaning of the function, such as
  - Whether the function is declared before use (or has a prototype).
  - Whether the function parameters and return type match the function calls.
  - Whether the function body adheres to type rules (e.g., no invalid operations on types).
3. **Function Overloading Resolution:** If multiple functions with the same name exist (function overloading), the compiler determines which function to call based on the arguments provided.
4. **Code Generation:** The compiler generates intermediate or machine code for the function body.

It allocates memory for local variables and parameters.

It generates instructions for the function's logic, such as arithmetic operations, loops, and conditionals.

5. **Function Calls:** When a function is called, the compiler generates code to:
  - Push the arguments onto the stack (or pass them via registers, depending on the calling convention).
  - Transfer control to the function's code.
  - Save the return address so the program knows where to continue after the function finishes.
6. **Inlining (Optional):** If a function is marked with the inline keyword or the compiler determines it is beneficial, the compiler may replace the function call with the actual function body to avoid the overhead of a function call.
7. **Linkage:** If a function is declared in one translation unit (source file) and defined in another, the compiler ensures the function is properly linked.

The compiler generates symbols for functions, which the linker resolves during the linking phase.

8. **Optimization:** The compiler may optimize functions to improve performance, such as:
  - Removing unused code (dead code elimination).
  - Unrolling loops.
  - Inlining small functions.
  - Optimizing tail-recursive functions.

When a function is called, the compiler (and the runtime environment) manages memory for local variables in a specific way

Local variables in a function are typically stored in the stack, a region of memory that is managed automatically by the compiler and runtime environment.

When a function is called, the compiler allocates memory on the stack for all of its local variables.

This memory is only valid for the duration of the function call. Once the function returns, the memory is deallocated (freed).

Each function call creates a stack frame (also called an activation record), which contains:

- The function's local variables.
- The return address (where the program should continue after the function finishes).
- The function's parameters (if any).

The stack grows downward in memory, and each new function call adds a new stack frame on top of the previous one.

When a function returns, its stack frame is deallocated, and the memory becomes available for reuse.

If the same function is called again, a new stack frame is created, and the local variables are allocated in the same memory region (which may have been overwritten by other function calls in the meantime).

Local variables have automatic storage duration, meaning they are created when the function is called and destroyed when the function returns.

This means that the values of local variables are not preserved between function calls.

`constexpr` variables are treated differently because they are compile-time constants.

The compiler evaluates `constexpr` variables at compile time and replaces their uses with their computed values.

No memory is allocated for `constexpr` variables at runtime—they are essentially "baked into" the code.

If a local variable is declared `static`, it has static storage duration, meaning it is allocated memory once and persists across function calls.

Static local variables are not stored on the stack but in a separate region of memory (typically the data segment).

## 16.1 Important: compile time constant variables and memory (constant propagation/constant folding)

When the compiler encounters a compile-time constant (e.g., a `constexpr` variable), it evaluates the constant expression at compile time and replaces all uses of the variable with the computed value. This means:

- **No Memory Allocation for the Variable:** Since the value of the compile-time constant is known at compile time, the compiler does not allocate memory for the variable at runtime.

Instead, the variable is treated like a literal value (e.g., 10, 3.14, etc.), and its value is "baked into" the generated code wherever it is used.

- **Replacement of Uses:** The compiler replaces every occurrence of the compile-time constant variable with its computed value. This process is called constant propagation or constant folding.

## Brace initialization vs Parenthesized Initialization

Brace initialization (also called uniform initialization or list initialization) was introduced in C++11 and has stricter rules compared to parenthesized initialization. Specifically, consider a uniform initialization of the form `type{expr}`

- **Prohibits narrowing conversions:** Brace initialization does not allow implicit narrowing conversions. If `expr` cannot be converted to `Type` without losing information (e.g., converting a double to an int), the compiler will emit an error.
- **Prevents most vexing parse:** Brace initialization avoids ambiguity with function declarations, which can occur with parenthesized initialization.
- **Calls constructors explicitly:** If `Type` has a constructor that takes an `std::initializer_list`, brace initialization will prefer that constructor.

If an `std::initializer_list` constructor exists, it will be chosen over other constructors, even if another constructor is a better match.

```
0  struct s {  
1      s(int x) {cout << "1" << endl;}  
2      s(initializer_list<int> x) {cout << "2" << endl;}  
3  };  
4  s s1{2}; // 2  
5  s s2(2); // 1
```

Parenthesized initialization (also called direct initialization) is more permissive and allows narrowing conversions. It behaves like a function call, where the compiler attempts to convert `expr` to `Type` using implicit conversions, even if narrowing occurs.

Note that parenthesized initialization does call constructors

Since c++20, direct initialization will work for aggregate types

*struct lattice {int x, y;}; lattice p(10, 20); // OK since c++20*

## Are chars unsigned?

In C++, the char type is neither inherently signed nor unsigned. It's implementation-defined behavior.

- char, signed char, and unsigned char are distinct types.
- The default behavior of char depends on the compiler. Some compilers treat char as signed char, while others treat it as unsigned char.
- To ensure consistent behavior, use signed char or unsigned char explicitly.

## Size of types

- **bool**: 1 Byte
- **char**: 1 Byte
- **short**: 2 Bytes
- **int**: 4 Bytes
- **long**: 4 or 8 bytes
- **long long**: 8 bytes
- **float**: 4 bytes
- **double**: 8 bytes
- **long double**: 16 bytes
- **string**: 32 bytes
- **Pointers**: 8 bytes

Note that the size of primitive types are usually implementation defined, and adding signed or unsigned does not change the size.

Also, references are the size of the type they refer to.



## Trivially copyable

A trivially copyable type in C++ is a type that can be copied efficiently using `memcpy` or similar low-level operations without breaking its correctness. This means it does not require custom copy/move constructors or destructors.

A class or struct is trivially copyable if:

- Can be copied with `memcpy` without breaking program semantics.
- Has no user-defined copy/move constructors, assignment operators, or destructors.
- Only contains trivially copyable members.
- Does not have virtual functions or virtual base classes.

## POD types (Plain old data)

POD (Plain Old Data) refers to a type in C++ that is simple, compatible with C structures, and has well-defined memory layouts. A POD type behaves like a C-style struct and lacks modern C++ features such as constructors, destructors, virtual functions, and non-trivial member functions.

A type is considered POD if:

- It is a trivial type (trivial constructor, destructor, copy/move operations).
- It is a standard-layout type (data layout matches C structs).

### 21.1 Trivial type

A type is trivial if:

- It has a trivial default constructor (compiler-generated, does nothing).
- It has a trivial copy/move constructor and assignment (member-wise copying).
- It has a trivial destructor (compiler-generated, does nothing).

### 21.2 Standard layout

A type is standard-layout if:

- It has no virtual functions or virtual base classes.
- It has only standard-layout base classes.
- All non-static data members have the same access control (public vs private matters).
- It does not inherit from multiple base classes with different access specifiers.

For a C++ structure (struct or class) to match a C struct's layout, it must

- Store its members in the same order as declared.
- Not have hidden padding or unexpected compiler transformations.
- Not have virtual functions or virtual base classes.
- Not use complex features like multiple inheritance.
- Use only standard-layout types for its members.

If a type is both trivial and standard-layout, it is POD.

## Notes about initialization

### 22.1 How many names does brace initialization have?

#### 22.1.1 Uniform Initialization (General Term)

Introduced in C++11, `{}` initialization is often referred to as uniform initialization because it provides a consistent syntax for initializing objects of any type.

Note that uniform initialization is an informal term

#### 22.1.2 List Initialization

List initialization is the official term in the C++ standard for using `{}` to initialize objects.

#### 22.1.3 Aggregate Initialization

When `{}` is used to initialize aggregates (structs, arrays, or classes with public members and no user-defined constructors), it's called aggregate initialization.

```
0  struct Point {
1      int x, y;
2  };
3  Point p = {1, 2}; // Aggregate initialization
```

#### 22.1.4 Value Initialization

If `{}` is used without any elements, it results in value initialization.

```
0  struct point {
1      int x{},y{}; // Default value initialized
2  };
```

Note that we can also do

```
0  struct point {
1      int x,y
2  };
3  point p{}; // Construct p and default value initialize x,y
```

### 22.1.5 Direct List Initialization

When `{}` is used with a constructor that takes a list, it is called direct list initialization.

```
0 std::vector<int> v{1, 2, 3}; // Direct list initialization
```

### 22.1.6 Copy List Initialization

When `{}` is used on the right-hand side of an assignment or in variable initialization without explicit construction, it's called copy list initialization.

```
0 std::vector<int> v = {1, 2, 3}; // Copy list initialization
```

### 22.1.7 Narrowing Prevention Initialization

`{}` initialization prevents narrowing conversions, meaning it does not allow implicit type conversions that lose information.

```
0 int x = 3.5; // Allowed (implicit conversion)
1 int y{3.5}; // Error (narrowing conversion)
```

### 22.1.8 Default Member Initialization

`{}` can be used to initialize class members with default values.

```
0 struct Example {
1     int a = {}; // Value-initialized to 0
2 };
```

### 22.1.9 Copy list initialization and direct list initialization in aggregate types

We note that for an aggregate type, copy list initialization and direct list initialization behave the same

```
0 struct point {
1     int x,y
2 };
3 point p1 = {1,2};
4 point p1{1,2};
```

For aggregates, both `=` (copy list initialization) and `{}` (direct list initialization) behave identically because C++ applies aggregate initialization in both cases.

However, if point had a user-defined constructor, then they could behave differently.

If we defined a constructor that takes an `initializer_list`, both the above objects would call that constructor

```
0  struct point {
1      int x{},y{}; // Default value initialized
2
3      point(std::initializer_list<int> l) {
4          cout << "called init list " << endl;
5      }
6  };
7
8  point p1 = {1,2}; // called init list
9  point p2{1,2}; // called init list
```

Note that if we define a virtual method, our type becomes polymorphic and is no longer aggregate. Therefore, we cannot use either initialization above. Note however that c++ will still implicitly give us the default constructors, so the following will still work

```
0  struct point {
1      int x,y;
2
3      virtual void f();
4  };
5  point p1{1,2} // Error
6  point p2 = {1,2} // Error
7  point p3{};
```

In this case, we need to explicitly define our constructor

```
0  struct point {
1      int x,y;
2
3      point(int x, int y) : x(x), y(y) {}
4
5      virtual void f();
6  };
7  point p1{1,2}
8  point p2 = {1,2}
9  point p3{};
```

## 22.2 Other forms of initialization and their names

### 22.2.1 Direct Initialization

Uses the parenthesis () syntax

```
0  int x(10);    // Direct initialization
1  std::string s("hello");
```

Note that aggregate initialization logic will not work with this syntax

```
0  struct point{
1      int x,y
2  };
3  point p(1,2) // Error! Must define the constructor.
```

### 22.2.2 Copy Initialization

Uses assignment =

```
0  int x = 10;
```

Creates a temporary object and copies/moves it to initialize the variable. May involve implicit conversions. Calls copy constructor if the type has one.

### 22.2.3 Default Initialization

No explicit initializer

```
0  int x;        // Default initialization (uninitialized in local
    ↪ scope)
1  std::string s; // Calls default constructor (empty string)
```

## 22.3 Excess elements in scalar initialization

Consider the code

```
0  int x{1,2,3}
```

Results in a compilation error "excess elements in scalar initialization"

Further consider

```
0  template<typename ... Args>
1  struct foo {
2      int var;
3
4      foo(Args... args) : var(args...) {}
5  };
6  X x(1); // fine
7  X y(1,2,3); // Excess elements in scalar initialization
```

## Notes about constructors and destructors

### 23.1 Value initialized vs default initialized

Consider the code

```
0  struct s1 {  
1      string s{};  
2      int x{};  
3  };  
4  
5  struct s2 {  
6      string s;  
7      int x;  
8  };
```

Whats the difference? In s1, the members are explicitly initialized with {}

```
0  struct s1 {  
1      std::string s{}; // Initializes to an empty string  
2      int x{};        // Initializes to 0  
3  };
```

This ensures that when an instance of s1 is created, s will be initialized to an empty string (""), and x will be initialized to 0.

In s2, the members are not explicitly initialized:

```
0  struct s2 {  
1      std::string s; // Default constructor of std::string  
    ↪ initializes it to ""  
2      int x;        // Uninitialized, contains garbage value if  
    ↪ not explicitly set  
3  };
```

s is fine because std::string has a default constructor that initializes it to "".

x, however, remains uninitialized when a default-constructed object of s2 is created, leading to an indeterminate value.

### 23.2 What exactly is =default

the = default specifier is used to explicitly declare that a special member function should be automatically generated by the compiler with its default behavior.



```

0  struct s {
1      char c;
2      int x;
3
4      s() = default;
5  };

```

This declares a default constructor (`s()`) explicitly, but it tells the compiler to generate it using the default implementation.

By default, the compiler-generated constructor does not initialize member variables. So, this:

```

0  s() = default;

```

is equivalent to:

```

0  s() {} // Default constructor, does nothing

```

which means the members (`char c; int x;`) remain uninitialized when an object of `s` is created

### 23.2.1 Non-POD fields

=default construct (default constructor) calls default constructors of non-POD (plain-old-data) members.

```

0  struct S {
1      std::string str; // std::string has a default constructor
2      int x;
3
4      S() = default; // Compiler generates: S() {} (but calls
    ↪ std::string's constructor)
5  };

```

The `std::string` member is properly initialized (since `std::string` has a default constructor). The `int x` is uninitialized.

### 23.2.2 With copy constructors

```

0  struct S {
1      std::string str;
2      int x;
3
4      S() = default;
5      S(const S&) = default; // Compiler generates: S(const S&
    ↪ other) : str(other.str), x(other.x) {}
6  };

```

Generates a copy constructor that copies each member individually using their copy constructors.

### 23.2.3 Copy Assignment

Generates an assignment operator that copies each member individually.

```
0  struct S {  
1      std::string str;  
2      int x;  
3  
4      S& operator=(const S&) = default;  
5  };
```

Equivalent to

```
0  S& operator=(const S& other) {  
1      str = other.str; // Calls std::string's assignment operator  
2      x = other.x;     // Simply copies x  
3      return *this;  
4  }
```

### 23.2.4 Move constructor

Generates a move constructor that moves each member individually.

```
0  struct S {  
1      std::string str;  
2      int x;  
3  
4      S(S&&) = default; // Compiler generates: S(S&& other) :  
    ↪ str(std::move(other.str)), x(other.x) {}  
5  };
```

This allows efficient moving:

```
0  S obj1;  
1  S obj2 = std::move(obj1); // Moves `str`, but leaves `x` as a  
    ↪ copy
```

the move constructor does not "move" the int x. Instead, it simply copies x from the source. This is because int is a trivially copyable type, and moving it is no different from copying.

### 23.2.5 Move Assignment

Generates a move assignment operator that moves each member individually.

```
0 struct S {  
1     std::string str;  
2     int x;  
3  
4     S& operator=(S&&) = default;  
5 };
```

Equivalent to:

```
0 S& operator=(S&& other) {  
1     str = std::move(other.str); // Moves the string instead of  
    ↪ copying  
2     x = other.x; // Simply copies x (since int doesn't benefit  
    ↪ from move)  
3     return *this;  
4 }
```

### 23.2.6 Destructor

Generates a destructor that:

- Does nothing for fundamental types.
- Calls the destructors of member objects.

```
0 struct S {  
1     std::string str;  
2     int x;  
3  
4     ~S() = default; // Compiler generates: ~S() {} (but calls  
    ↪ std::string's destructor)  
5 };
```

### 23.2.7 Do you need to write them?

In C++, the compiler will automatically generate default implementations for special member functions only if they are needed and not explicitly declared.

However, if you declare any of them (without defining them), the compiler will not automatically generate them. This is where `= default` comes in—it explicitly tells the compiler to generate the default implementation.

### 23.3 =delete

=delete does the opposite of =default... It deletes the default implementation

### 23.4 Rule of five

In C++, the Rule of Five states that if you define or explicitly delete any of the following five special member functions, you should likely define or delete all five

- Destructor
- copy constructor
- copy assignment operator
- move constructor
- move assignment operator

```
0  struct s {  
1      string str{};  
2  
3      s(const s& other) {  
4          cout << "Copy constructor called" << endl;  
5          str = other.str;  
6      }  
7  };  
8  s s1;
```

In this case, we get an error. When you explicitly define a copy constructor in C++, the compiler does not automatically generate the default constructor for you. This is due to the Rule of Five

The C++ standard states that if you declare any of the above special member functions, the compiler will not generate a default constructor for you:

Once you define any of these functions, the compiler assumes you want full control over object creation and copying, so it does not provide the default constructor.

### 23.5 A confused compiler

Consider the code

```

0  struct point {
1      int x{};
2
3      point (int x) : x(x) {}
4
5      point(int&& other) {
6          cout << "called second" << endl;
7          x = other;
8      }
9  };
10 point p = 20; // Error

```

We get "error: conversion from 'int' to 'point' is ambiguous".

happens because there are multiple constructors that can accept an int, and the compiler doesn't know which one to pick.

- point(int) is a direct match for int.
- point(int&&) can accept an int as an rvalue reference.

The compiler does not know which one to pick, so it gives an error.

If we mark the first constructor explicit, we then prevent implicit conversion from int to point, and the second constructor will be the one called.

```

0  struct point {
1      int x{};
2
3      explicit point (int x) : x(x) {}
4
5      point(int&& other) {
6          cout << "called second" << endl;
7          x = other;
8      }
9  };
10 point p = 20;

```

## 23.6 Which constructor will be called

Suppose we have

```

0  struct point {
1      int x{};
2
3      point(const int& other) {
4          cout << "called first" << endl;
5          x = other;
6      }
7
8      point(int&& other) {
9          cout << "called second" << endl;
10         x = other;
11     }
12 };
13 point p = 20;

```

Which constructor gets called? The second constructor (`point(int&& other)`) is called in this case because the literal 20 is an rvalue.

We have two suitable constructors, and the compiler must determine which constructor to call.

The compiler deems the second as a better match than the first, because 20 is a pure rvalue. Note that if we removed the second constructor, the first would work. A constructor that takes a const reference can bind to both rvalues and lvalues.

## 23.7 Constructors are implicitly inline constexpr

constructors are implicitly constexpr under certain conditions. This means they can be evaluated at compile time if all their operations are constexpr. The main reason for this behavior is to make objects usable in constant expressions without requiring explicit constexpr annotations.

## 23.8 Destructors are implicitly noexcept

In C++, destructors are implicitly declared as noexcept unless a potentially throwing operation is explicitly present in the destructor's definition. This behavior exists to improve performance, exception safety, and compatibility with standard library features.

When a function is marked as noexcept, the compiler can generate more efficient code:

If destructors could throw by default, objects in RAII (Resource Acquisition Is Initialization) and smart pointers (`std::unique_ptr`, `std::shared_ptr`) would lead to undefined behavior or terminate the program when a destructor is called during stack unwinding.

```

0  struct B {
1      ~B() { throw std::runtime_error("Error!"); } // Dangerous!
2  };
3
4  void func() {
5      try {
6          B b;
7          throw std::runtime_error("Oops");
8      } catch (...) {
9          // Stack unwinding will terminate the program if ~B()
   ↪  throws
10     }
11 }

```

To prevent such issues, destructors are noexcept by default, meaning they do not propagate exceptions. If an exception occurs in a noexcept destructor, `std::terminate()` is called.

## 23.9 When is an object "Fully constructed"

In C++, an object is considered fully constructed when its constructor has finished executing successfully. Specifically:

- **For a non-inherited class (without base classes):** The object is fully constructed after its constructor runs to completion.
- **For a class with base classes:** The object is fully constructed after all base class subobjects and non-static data members have been successfully initialized.
- **For a class with member variables:** Each member is constructed in the order they are declared in the class definition, before the body of the constructor executes. If a member's constructor throws an exception, the object is not fully constructed.
- **For a derived class:** A derived class object is fully constructed only after
  - The base class constructor(s) finish execution.
  - All member variables of the derived class are constructed.
  - The body of the derived class constructor executes successfully.

### 23.10 When is an object not fully constructed

If a base class constructor throws, the derived class never completes construction.

If a member variable's constructor throws, the object never becomes fully constructed.

If a constructor exits via an exception, the destructor never runs, because the object was never fully formed.

Consider the code

```
0  struct B {
1      B() { throw std::runtime_error("Error"); }
2      ~B() { cout << "Destructor called" << endl; }
3  };
4
5  try {
6      B b;
7  } catch (...) {
8
9  }
```

Here we get no output, the constructor never finished, which means the object was not fully constructed, which means the destructor will not get called.

Further consider

```
0  struct B {
1      B() {}
2      B(int n) : B() { throw std::runtime_error("Error"); }
3      ~B() { cout << "Destructor called" << endl; }
4  };
5
6  try {
7      B b;
8  } catch (...) {
9
10 }
```

In this example, we do get "destructor called". The destructor is called because the default constructor B() successfully constructs an object, even though the other constructor (B(int)) throws an exception.

## 23.11 Converting constructors (cast constructors)

A converting constructor is a constructor that allows you to create an object of a class from a value of another type, often implicitly. For example, if a class B has a constructor that takes an A as a parameter (and it's not marked explicit), then an object of type A can be automatically converted to a B when needed

```
0  struct A {
1      A() { std::cout << "a"; }
2  };
3
4  struct B {
5      B() { std::cout << "b"; }
6      B(const A&) { std::cout << "B"; }
7  };
8  B b = A{};
```



Consider the example

```
0  struct A {
1      int value;
2      A(int value) : value(value) {}
3      operator int() { // Notice no return type
4          return value;
5      }
6  };
7  A a(5);
8  int x = int(a) // OK, since we defined operator int()
9  int x = a; // Allow enables implicit conversions since operator
   ↪ int() is not marked explicit
```

This is an example of a conversion constructor. These operator overloads do not have return types in their signature. a conversion operator like `operator int()` doesn't explicitly state a return type because its return type is implicit—it's defined by the type you're converting to, the function automatically returns an `int`.

The C++ language grammar specifies that conversion operators are declared without a return type; the type following the operator keyword is the type to which the class is converted

## 23.12 operator void() overload

Consider the code

```
0  struct S {
1      operator void() {
2          std::cout << "F";
3      }
4  };
5  (void)s;
6  static_cast<void>(s);
7  s.operator void();
```

The only one that actually calls our overload is the third (manual call). According to the C++ standard, conversion functions will never be used to convert an object to `void`. So the conversion function is only called once, when we manually call it on the line `s.operator void()`

## Dividing by zero

Consider the code

```
0  int a = 5, b = 0;  
1  int c = a/b;
```

Here we get *terminated by signal SIGFPE (Floating point exception)*

## Notes about inheritance

### 25.1 Constructor chain

In C++ inheritance, the constructor chain (or constructor delegation) refers to the sequence in which constructors of base and derived classes are called when an object of the derived class is created.

When an object of a derived class is created, the constructor of the base class runs before the constructor of the derived class.

If the base class has multiple levels, constructors are called in top-to-bottom order (from base to most derived).

If the base class does not have a user-defined constructor, the compiler provides a default constructor that is automatically invoked.

If the base class has a parameterized constructor, you must explicitly call it in the initializer list of the derived class.

### 25.2 Destructor chain

When a class has a virtual destructor, the vtable includes a pointer to the most derived destructor. However, destructors are special because they are split into two parts in the vtable:

- **Complete Object Destructor:** Calls all destructors in the chain (Child → Dad → Grandfather).
- **Base Object Destructor:** Only relevant when the object is part of another object (not directly deleted).

When Child overrides Dad (which overrides Grandfather), the vtable for Child includes a pointer to the most derived destructor (`~Child`), but that destructor is responsible for calling the entire chain.

If Grandfather's destructor is not virtual, the vtable will not be consulted during `delete obj`. Instead, the compiler resolves `delete obj` at compile-time and calls `Grandfather::~~Grandfather()` directly, ignoring the destructors of Dad and Child.

Destructors execute in reverse order of constructors (i.e., derived class destructor runs first, then base class destructor).

### 25.3 So who needs a virtual destructor?

Consider the situation

```

0  struct grandfather {
1      virtual ~grandfather() = default;
2  };
3
4
5  struct dad : grandfather {
6  };
7
8  struct child : dad {
9  };

```

When a destructor is declared virtual in a base class (grandfather), all derived classes (dad and child) automatically have virtual destructors, even if they don't explicitly declare them

Since dad and child inherit from grandfather, they do not need to explicitly mark their destructors as virtual—they already are.

```

0  struct grandfather {
1      virtual ~grandfather() { std::cout << "grandfather
   ↳ destroyed\n"; }
2  };
3
4  struct mom : public virtual grandfather {
5      ~mom() { std::cout << "mom destroyed\n"; } // Implicitly
   ↳ virtual
6  };
7
8  struct dad : public virtual grandfather {
9      ~dad() { std::cout << "dad destroyed\n"; } // Implicitly
   ↳ virtual
10 };
11
12 struct child : public mom, public dad {
13     ~child() { std::cout << "child destroyed\n"; } // Implicitly
   ↳ virtual
14 };
15 grandfather* g = new child();
16 delete g;
17 /*
18 child destroyed
19 dad destroyed
20 mom destroyed
21 grandfather destroyed
22 */

```

## 25.4 Default access modifier

Consider the code

```
0  class A {};  
1  class B : A {};
```

The default access modifier is private for class inheritance, and public for structs.

### 25.5 Can a class inherit from a struct, or a struct inherit from a class?

Yes, perfectly acceptable. Recall though the default access specifiers for class vs struct inheritance

## Booleans under the hood: Adding two booleans

In C++, `bool` is typically represented under the hood as an integral type, often stored as a single byte (char-sized) in memory. However, when used in expressions, `bool` values implicitly promote to `int`.

In C++, `bool` is effectively an integer type but only holds 0 (false) or 1 (true).

When used in an arithmetic expression, a `bool` value is promoted to an `int`.

This is part of the integral promotion rules in C++.

```
0  bool b1 = 1, b2 = 1;  
1  cout << typeid(b1 + b2).name();
```

## Type Promotion

Type promotion in C++ refers to the implicit conversion of smaller or lower-ranked types to larger or higher-ranked types in expressions. This ensures consistent operations without data loss.

- **Boolean Promotion:** `bool` converts to `int` (`false`  $\rightarrow$  0, `true`  $\rightarrow$  1) when used in arithmetic or bitwise operations.
- **Integral Promotion:** Types smaller than `int` (`char`, `short`, `bool`) promote to `int` if `int` can represent all values; otherwise, they promote to unsigned `int`.

If operands have different types, the one with the lower rank is converted to the higher-ranked type.

### 27.1 Ranking

Standard conversion sequences are categorized in one of three ranks. The ranks are listed in order from best to worst:

- **Exact match:** This rank includes the following conversions:
  - Identity conversions
  - Lvalue-to-rvalue conversions
  - Array-to-pointer conversions
  - Qualification conversions
- **Promotion:** This rank includes integral and floating point promotions.
- **Conversion:** This rank includes the following conversions:
  - Integral and floating-point conversions
  - Floating-integral conversions
  - Pointer conversions
  - Pointer-to-member conversions
  - Boolean conversions

Consider

```
0 void f(double x) { }  
1 void f(unsigned x) { }  
2 f(1.0); // Error, call to f is ambiguous
```

This situation is ambiguous because the integer literal `1.0` can be converted to either `int` or unsigned `int`, and both conversions have the same rank in the standard conversion sequence (Floating-integral conversions)

Further, consider

```

0 void f(int x) { cout << "1"; }
1 void f(unsigned x) { cout << "2"; }
2 f((short)5); // 1

```

Although both conversions have rank *promotion*, the compiler chooses the first

The compiler looks for the best function match among the available overloads

- short → int is an integral promotion.
- short → unsigned int is also a promotion, but only considered if int is not available.

Since integral promotions have higher precedence than standard conversions, f(int) is chosen because it's a direct promotion, whereas f(unsigned) is a conversion if int is available.

Consider

```

0 void f(char x) { cout << "1"; }
1 void f(short x) { cout << "2"; }
2 f((bool)5); // Error: call to f is ambiguous

```

The function call f((bool)5); is ambiguous because both void f(char) and void f(short) are equally valid candidates based on integral promotions, and neither is strictly better than the other

This situation falls under conversion rank because bool is promoted to int first, and then int must be converted to either char or short, both of which have equal ranking in standard conversions.

promotions are a subset of standard conversions that always take precedence over regular conversions in overload resolution. A promotion only occurs when converting a smaller type to a larger type of the same category (integral or floating-point), without changing its fundamental nature.

Integral promotions occur when a smaller integer type is promoted to at least int or unsigned int. These promotions are preferred over standard conversions and are commonly used in arithmetic expressions, function calls, and overload resolution.



## Notes about static

### 28.1 Static variables inside member functions

Static variables inside member functions behave the same as static variables in regular functions

### 28.2 Using instances to call static methods

We note that we can use instances to call static methods using the dot notation

```
0  struct s{
1      int x = 20;
2      static void f() {
3          cout << "static method" << endl;
4      }
5  };
6  s::f();
7
8  s S;
9  S.f();
```

### 28.3 Can you make pure virtual methods static?

No, you cannot

### 28.4 Inline Static methods?

Consider the code

```
0  struct s{
1      static void print() {} // Implicitly inline... Means
2      static inline void print() {} // Exact same
3  };
```

However, defining static methods outside the class does not make it implicitly inline

```
0  struct s {
1      static void print();
2  };
3  void s::print() {} // Not inline
```

The inline keyword suggests that the function can be defined inside the header file (or within the struct/class definition) without violating the one-definition rule (ODR).

It is a hint to the compiler that function calls may be replaced with the actual function body to reduce function call overhead (though modern compilers decide this automatically).

More importantly, in this case, inline ensures that if the function is defined in a header file and included in multiple translation units, it does not cause multiple definition errors.

We can of course still explicitly make the second version inline..

```
0  struct s {
1      static void print();
2  };
3  inline void s::print() {} // Not inline
```

## 28.5 Static and extern (linkage)

Global variables without the use of the keyword static have external linkage. In other translation units that are compiled with the file that has the global variable, we use the keyword **extern** to access it

```
0  // File1.cpp
1  int x = 20;
2
3  // File2.cpp
4  extern int x; // Refers to x from file1.cpp
```

Declaring a global variable as static restricts its visibility to the current translation unit

If we declare a global variable static in one unit, we can get a separate copy in a different unit by declaring the same variable (with the same signature) and also using the keyword static

```
0  // File1.cpp
1  static int x = 20;
2
3  // File2.cpp
4  static int x = 20; // File2 gets its own copy of x
```

### 28.5.1 Using extern to declare a variable with the same name as a static variable from another translation unit

If you use extern to declare a variable with the same name as a static variable from another translation unit, the linker will not find the definition of that variable, leading to a linker error (undefined reference). This is because static variables have internal linkage, meaning they are restricted to their translation unit and cannot be accessed from another file.

```

0 // File1.cpp
1 static int x = 20;
2
3 // File2.cpp
4 extern int x; // Linker error

```

### 28.5.2 Forgetting to use extern

If you forget to put `extern` when declaring a global variable in another translation unit, the compiler will treat it as a new, separate definition rather than referring to an existing one. This can lead to multiple definition errors at the linking stage

```

0 // File1.cpp
1 int x = 20;
2
3 // File2.cpp
4 int x; // Liner error: Multiple definition

```

### 28.5.3 Forgetting to use keyword static

```

0 // File1.cpp
1 static int x = 20;
2
3 // File2.cpp
4 int x = 20;

```

No errors for two units, file2 will simply make its own version of `x` with external linkage. If you add a third unit and forget to put `static` on that `x` as well, we would then get multiple definition errors.

### 28.5.4 Constinit with extern

`constinit` is only required in the definition (where the variable is actually allocated memory).

When using `extern` to refer to that variable in another translation unit, `constinit` is not necessary because `extern` simply tells the compiler that the variable is defined elsewhere.

```

0 // File1.cpp
1 constinit int x = 50;
2
3 // File2.cpp
4 extern int x;

```

## Trying to move const objects

Consider the code

```
0  struct s {  
1      string str{};  
2  
3      s() = default;  
4  
5      s(const string& other) {  
6          cout << "Copy constructor called" << endl;  
7          str = other;  
8      }  
9  
10     s(string&& other) {  
11         cout << "Move constructor called " << endl;  
12     }  
13 }  
14 };  
15 const string str = "Hello";  
16 s s1(std::move(str));
```

Something interesting happens, we get *"Copy constructor called"*. A constant object cannot be moved because moving modifies the source object.

The move constructor requires an argument of type `std::string&&` (a temporary, non-const string).

However, `std::move(str)` produces a const `std::string&&` (rvalue reference to const), which cannot be passed to the move constructor because the move constructor expects a non-const rvalue reference (`string&&`).

```
0  s(const string& other) {    // (1) Copy constructor  
1      cout << "Copy constructor called" << endl;  
2      str = other;  
3  }  
4  
5  s(string&& other) {         // (2) Move constructor  
6      cout << "Move constructor called" << endl;  
7  }
```

Since `std::move(str)` produces const `std::string&&`, it cannot bind to (2) `s(string&&)`, because the move constructor does not accept const.

Instead, `s(const string&)` (the copy constructor) is selected, because it can accept a const `std::string&`.

This is one reason why we have const in the copy constructor, if the copy constructors argument was not const, we would get an error trying to move the const object.

## Smart pointers in conjunction with raw ptrs

### 30.1 Shared\_ptr with raw ptrs

Consider the code

```
0  int x = 50;  
1  std::shared_ptr<int> ptr = std::make_shared<int>(50);
```

What happens if we do

```
0  int* ptr2 = &(*ptr);
```

Will it increase the reference count? No it does not

```
0  cout << ptr.use_count() << endl; // 1
```

### 30.2 Unique\_ptr with raw ptrs

What if we do

```
0  std::unique_ptr<int> ptr = std::make_unique<int>(50);  
1  int* ptr2 = &(*ptr);
```

Does this even work? Yes, this works perfectly fine. `*ptr` dereferences the `std::unique_ptr<int>`, retrieving the integer it owns. `&(*ptr)` takes the address of that integer, effectively obtaining a raw pointer to the managed object.

If `ptr2` is used only within the scope where `ptr` exists and is valid, it's generally fine

If `ptr` is reset or goes out of scope, `ptr2` becomes a dangling pointer, leading to undefined behavior

## Calling delete on a nullptr

Calling delete on a nullptr is perfectly safe and has no effect.

The delete operator first checks whether the pointer is nullptr. If the pointer is nullptr, delete does nothing and returns immediately.

This behavior ensures that you don't have to explicitly check for nullptr before calling delete.

## Notes about short circuits

Short-circuiting in C++ refers to the behavior of logical operators ( `&` and `||` ) where the second operand is not evaluated if the result of the entire expression can be determined from the first operand alone.

### 32.1 With ands

Consider the following code

```
0  bool foo() {
1      cout << "Foo" << endl;
2      return false;
3  }
4
5  bool bar() {
6      cout << "bar" << endl;
7      return true;
8  }
9
10 if (foo() && bar()) // "Foo"
```

The bar function never gets called because when the foo function returns, the if statement "short-circuits" and exits. If we want to prevent short circuiting, we use a bitwise and (`&`)

```
0  if (foo() & bar()) // Foo\n bar
```

### 32.2 With ors

Similarly,

```
0  bool foo() {
1      cout << "Foo" << endl;
2      return true;
3  }
4
5  bool bar() {
6      cout << "bar" << endl;
7      return true;
8  }
9
10 if (foo() || bar()) // Foo
```

We again just get "Foo". When the foo function returns true, the if statement is automatically true and again we get a short circuit, which leads to bar never getting called. If we want to prevent short circuiting with ors, we use bitwise or (`||`)

```
o  if (foo() | bar()) // Foo\n bar
```



## Notes about types

- bool
- char (unsigned and signed)
- short (unsigned and signed)
- int (unsigned and signed)
- long (unsigned and signed)
- long long (unsigned and signed)

## Notes about inline functions

Recall that an inline function in C++ is a function that is expanded in place where it is called, rather than executing a traditional function call. This is a compiler directive that can reduce function call overhead and potentially improve performance.

When a function is declared as inline, the compiler replaces the function call with the actual function definition (code) at compile time. This eliminates the overhead of a function call, such as:

- Pushing arguments onto the stack.
- Jumping to the function's memory location.
- Returning to the caller.

### Advantages:

- **Eliminates Function Call Overhead:** Since the function code is directly inserted at the call site, there is no function call overhead.
- **Faster Execution:** If the function is small, inlining can make the program faster.
- **Useful for Small, Repeated Functions:** It is particularly useful for small functions that are frequently called (e.g., getter functions in classes).

### Disadvantages:

- **Increased Binary Size (Code Bloat):** If a function is large and used in multiple places, its repeated expansion increases the binary size.
- **Decreased Cache Efficiency:** More inline code means a larger executable, which may lead to poor instruction cache performance.

Note that inlining is a suggestion, not a command. The compiler may ignore the inline keyword if the function is too complex.

## 34.1 Inline functions in the context of multiple translation units

In C++, a program can consist of multiple translation units, where each source file (.cpp) and its included headers form a separate unit compiled independently before linking. Using inline functions across multiple translation units can help avoid multiple definition errors.

When defining a function in a header file (.h), multiple source files (.cpp) including the header may result in multiple definitions of the function.

When compiled separately and linked together, the linker will complain about multiple definitions of `square(int)` because each translation unit includes its own separate copy.

The inline keyword tells the compiler that multiple identical definitions of the function are allowed across translation units, and they should be merged.

Normally, functions with external linkage (`int square(int)`) violate the One Definition Rule (ODR) when included in multiple translation units.

Marking the function inline allows the linker to consolidate multiple instances into one.

### **34.2 Class/Struct methods are implicitly inline**

Since it is common to define classes or structs in header files, the c++ compiler makes all methods inline to avoid violation of the one definition rule (ODR)

## Notes about object creation

Consider the code

```
0  struct A{
1      A() { cout << 'a'}
2      ~A() { cout << 'A'}
3  };
4
5  struct B {
6      B() {cout << 'b'}
7      ~B() {cout << 'B'}
8      A a;
9  };
10
11 int main() {B b;} // abBA
```

Member variables are initialized before the constructor is called. The destructor is called before member variables are destroyed.

### 35.1 Default initialize const object (const default constructible)?

Consider

```
0  struct A {
1      A() = default;
2      int i;
3  } ;
4  const A a;
```

We actually get an error here: Default initialization of an object of const type 'const A' without a user provided default constructor

A class type T is const-default-constructible if default-initialization of T would invoke a user-provided constructor of T (not inherited from a base class)

In C++, a const object must have all of its data members fully initialized at construction time

In the code above, the default constructor is defaulted, which means it does nothing more than “default-initialize” each member. For a built-in type like int, default initialization leaves it with an indeterminate value. When you try to create a const object of type A

the member i would remain uninitialized, which is not allowed because a const object must be initialized completely. To make A const default constructible, you need to provide an initializer for i

```
0 // Make const default constructable
1 struct A {
2     A() { i=0; }
3     int i;
4 };
```

We can also simply do the following

```
0 struct A {
1     A() = default;
2     int i{};
3 };
```

Note that types like strings are default initialized with a determinant value, the empty string, so the following will not cause an error

```
0 struct A {
1     A() = default;
2     string s;
3 };
```

## What is a "function signature"

a function signature refers to the combination of components that uniquely identify a function within a given scope. However, different contexts use "function signature" to mean slightly different things.

When the compiler determines whether two functions are overloaded (i.e., different functions in the same scope), it considers:

- Function name
- Parameter types (including order and const qualifiers on parameters)

### 36.1 Function Signature (Overriding Perspective)

When dealing with function overriding in a derived class, the function signature must exactly match the base class function's:

- return types
- Function name
- Parameter types (including order and const/reference qualifiers)
- const qualifier (for member functions)
- Volatile qualifier (volatile if present)
- Ref-qualifier (& or &&)

While return types are not part of the function signature in the overloading perspective, they are in the overriding perspective

```
0  struct s {  
1      virtual void print() const {}  
2  };  
3  struct k : s {  
4      int print() const override {} // Error: Return type must  
   ↪ match the overridden function  
5  }
```

### 36.2 What is NOT Part of a Function Signature?

The following do not contribute to a function's signature:

- **Return type:** Functions cannot be overloaded solely by differing return types.
- **Default arguments:** Default arguments are resolved at compile time, so they are not part of the function signature.

**Note:** Even if parameter types are aliased, they resolve to the same type and do not create a different signature.

### **36.3 noexcept?**

The `noexcept` specifier is part of the function signature for function overloading but not for overriding.

## Maximal munch principle

Consider the code

```
0  int a=5, b=2;  
1  cout << a+++++b; // ERROR
```

Why is this an error? Why is it not simply  $a++ + ++b = 8$ ? The Maximal Munch Principle is a rule used in lexical analysis (tokenization) to determine how to group characters into tokens. It states: *Always consume the longest possible sequence of characters that form a valid token.*

When scanning input text, the lexer tries to form the longest valid token at each step before moving on. This avoids ambiguity in tokenization. So after parsing  $a++$ , it is not allowed to just parse  $+$ , it has to parse  $++$ . The sequence is thus parsed as:

```
0  a ++ ++ + b
```

which is ill-formed since post-increment requires a modifiable lvalue but the first post-increment will produce a prvalue



## What happens if a noexcept function throws an exception?

If a function is declared noexcept but still throws an exception, the program immediately terminates by calling `std::terminate()`. This behavior exists to enforce the contract that noexcept functions are not supposed to throw.

noexcept functions promise not to throw. The compiler and standard library rely on this assumption. If a noexcept function throws, continuing execution would violate the contract and lead to undefined behavior. Instead of allowing UB, C++ forces a hard fail by calling `std::terminate()`.

If a noexcept function must perform an operation that might throw, you need to catch exceptions inside the function and handle them before returning.

## Exception propagation

When an exception propagates, it means that the exception is not handled in the current function and is instead passed up the call stack until it reaches a function that can handle it (i.e., a function with a try-catch block). If no function catches the exception, the program terminates.

When an exception is thrown using `throw`, control is immediately transferred to the nearest matching catch block in the call stack.

```
0  void foo() {  
1      throw std::runtime_error("Error in foo");  
2  }  
3  
4  void bar() {  
5      foo(); // No try-catch here, so the exception propagates  
6  }  
7  
8  int main() {  
9      try {  
10         bar(); // Calls bar(), which calls foo()  
11     } catch (const std::runtime_error& e) {  
12         std::cout << "Caught exception: " << e.what() << '\n';  
13     }  
14 }
```

## The catch all exception handler (...)

In C++, `catch (...)` is a catch-all exception handler, meaning it catches any exception, regardless of its type. It is useful when you want to handle or log exceptions without knowing their exact type.

```
0  try {  
1      someFunction();  
2  } catch (...) {  
3      std::cerr << "An unknown exception occurred!\n";  
4  }
```

## A typedef cannot be a template

We must use a *using* directive instead

## Return value optimization

Consider the code

```
0  struct E
1  {
2      E() { std::cout << "1"; }
3      E(const E&) { std::cout << "2"; }
4      ~E() { std::cout << "3"; }
5  };
6
7  E f()
8  {
9      return E();
10 }
11
12 int main()
13 {
14     f(); // 13 (no copy constructor called)
15 }
```

The copy constructor isn't called because of a compiler optimization known as copy elision (specifically, Return Value Optimization or RVO). In this case, the temporary `E()` object is constructed directly in the location where the return value of the function `f()` resides, so no copy (or move) constructor call is needed. This optimization is allowed (and in some cases mandated in C++17 and later) by the C++ standard.

## Using function templates in multiple files

Consider the following program, which doesn't work correctly:

```
0  // main.cpp:
1  #include <iostream>
2
3  template <typename T>
4  T addOne(T x); // function template forward declaration
5
6  int main() {
7      std::cout << addOne(1) << '\n';
8      std::cout << addOne(2.3) << '\n';
9
10     return 0;
11 }
12
13 // add.cpp
14 template <typename T>
15 T addOne(T x) // function template definition
16 {
17     return x + 1;
18 }
```

If `addOne` were a non-template function, this program would work fine: In `main.cpp`, the compiler would be satisfied with the forward declaration of `addOne`, and the linker would connect the call to `addOne()` in `main.cpp` to the function definition in `add.cpp`.

But because `addOne` is a template, this program doesn't work, and we get a linker error:

In `main.cpp`, we call `addOne<int>` and `addOne<double>`. However, since the compiler can't see the definition for function template `addOne`, it can't instantiate those functions inside `main.cpp`. It does see the forward declaration for `addOne` though, and will assume those functions exist elsewhere and will be linked in later.

When the compiler goes to compile `add.cpp`, it will see the definition for function template `addOne`. However, there are no uses of this template in `add.cpp`, so the compiler will not instantiate anything. The end result is that the linker is unable to connect the calls to `addOne<int>` and `addOne<double>` in `main.cpp` to the actual functions, because those functions were never instantiated.

If `add.cpp` had instantiated those functions, the program would have compiled and linked just fine. But such solutions are fragile and should be avoided:

The most conventional way to address this issue is to put all your template code in a header (.h) file instead of a source (.cpp) file

```

0  // add.h
1  #ifndef ADD_H
2  #define ADD_H
3
4  template <typename T>
5  T addOne(T x) // function template definition
6  {
7      return x + 1;
8  }
9
10 #endif
11 // main.cpp
12 #include "add.h" // import the function template definition
13 #include <iostream>
14
15 int main()
16 {
17     std::cout << addOne(1) << '\n';
18     std::cout << addOne(2.3) << '\n';
19
20     return 0;
21 }

```

That way, any files that need access to the template can include the relevant header, and the template definition will be copied by the preprocessor into the source file. The compiler will then be able to instantiate any functions that are needed.

You may be wondering why this doesn't cause a violation of the one-definition rule (ODR). The ODR says that types, templates, inline functions, and inline variables are allowed to have identical definitions in different files. So there is no problem if the template definition is copied into multiple files (as long as each definition is identical).

But what about the instantiated functions themselves? If a function is instantiated in multiple files, how does that not cause a violation of the ODR? The answer is that functions implicitly instantiated from templates are implicitly inline. And as you know, inline functions can be defined in multiple files, so long as the definition is identical in each.

## Review of access modifiers in inheritance

- **Public:** Public members of the base class remain public in the derived class.

Protected members remain protected.

Private members are not accessible directly by the derived class (though they are still part of the object).

- **Protected:** Both public and protected members of the base class become protected in the derived class.

Private members remain inaccessible.

- **Private:** Both public and protected members of the base class become private in the derived class.

Private members remain inaccessible.

Recall what it means to be protected

- **Within the class:** The protected member is accessible just like a private member.
- **Outside the class hierarchy:** The protected member is not accessible from code that is not part of the class or its descendants.
- **In derived classes:** The protected member is accessible to any class that inherits from the base class.



## Notes about the conditional operator

Consider the code

```
0  struct A {  
1      A() { std::cout << "a"; }  
2  
3      void foo() { std::cout << "1"; }  
4  };  
5  
6  struct B {  
7      B() { std::cout << "b"; }  
8      B(const A&) { std::cout << "B"; }  
9  
10     void foo() { std::cout << "2"; }  
11 };  
12  
13 auto L(auto flag) {  
14     return flag ? A{} : B{};  
15 }  
16 L(true).foo();  
17 L(false).foo();
```

We get the output `aB2b2`. The conditional operator in `L` has two branches that return different types: one returns an `A` and the other a `B`. However, the conditional operator requires both branches to have a common type. Since `B` has a converting constructor `B(const A&)`, the `A` in the true branch is converted to a `B`.

Thus, `L` always returns a `B` object. When the function is called with the argument `flag` set to `true`, a temporary `A` is constructed, converted to `B`, then `B.foo()` is called. When the function is called with `flag` set to `false`, `B` is constructed and `B.foo()` is called. Thus, the output is `aB2b2`

So what happens if we remove the converting constructor in `B`?

```
0  auto L(auto flag) {  
1      return flag ? A{} : B{};  
2  }  
3  L(true);
```

We get an error: incompatible operand types

## Notes about CTAD (Class template argument deduction)

CTAD does not consider user-defined conversions (Conversions provided by conversion constructors or conversion operators defined by a user) during deduction

Consider the code

```
0  template <typename T>
1  void call_with(std::function<void(T)> f, T val) {
2      f(val);
3  }
4  auto print = [] (int x) { std::cout << x; };
5  call_with(print, 42)
```

the lambda `print` has a unique, unnamed type—not `std::function<void(int)>`. Even though it can be converted to `std::function<void(int)>` (since it has a matching `operator()`), that conversion is a user-defined conversion, and such conversions are not considered during template argument deduction.

One way to resolve this would be

```
0  call_with<int>(print, 42);
```

When you write `call_with<int>(print, 42);`, you're explicitly specifying that `T` is `int`.

At this point, the compiler already knows that it needs a `std::function<void(int)>` for the first parameter. Now, when you pass the lambda `print`, the compiler sees that `print` is convertible to `std::function<void(int)>` via a user-defined conversion (using the converting constructor of `std::function`). Since the template argument is already fixed as `int`, the conversion is allowed during the normal overload resolution and conversion process.

In summary, explicitly specifying `T` bypasses the template argument deduction phase. Therefore, the compiler doesn't have to deduce `T` by matching the lambda to `std::function<void(T)>` (which would fail because user-defined conversions aren't considered during deduction). Instead, it only needs to check that the lambda can be converted to the already specified type `std::function<void(int)>`, and that conversion works as expected.

### 46.1 const vs non-const template parameters

Consider the code

```

0  template <typename T>
1  void foo(T& x)
2  {
3      std::cout << std::is_same_v<const int, T>;
4  }
5
6  template <typename T>
7  void bar(const T& x)
8  {
9      std::cout << std::is_same_v<const int, T>;
10 }
11 const int i{};
12 int j{};
13
14 foo(i);
15 foo(j);
16 bar(i);
17 bar(j);

```

We get 1000.

In a function like:

```

0  template <typename T>
1  void foo(T& x)
2  {
3      // ...
4  }

```

the type T is deduced to match the argument exactly.

- If you pass a const int, T becomes const int.
- If you pass an int, T becomes int.

In a function like

```

0  template <typename T>
1  void bar(const T& x)
2  {
3      // ...
4  }

```

the const in the parameter (const T&) applies to the entire parameter but is not used in deducing T. This means:

- Whether you pass a const int or an int, T is deduced as int.

During template argument deduction, the compiler examines the argument type and tries to determine what T must be. With a parameter of type const T&, the compiler looks at the underlying type of the argument without taking the const in the parameter into account.

## Strong types

A strong type is a type that enforces strict type safety by not allowing implicit conversions to or from its underlying type. This means that even if a strong type wraps a primitive type (like an `int` or `double`), it won't automatically convert to that primitive type or another type without an explicit conversion. This helps prevent accidental mixing of types that represent different concepts.

```
0  struct Meter {  
1      explicit Meter(int v) : value(v) {} // Explicit constructor  
2      int value;  
3  };  
4  Meter m(10); // Ok  
5  Meter k=5; // Int cannot be implicitly converted to Meter, must  
    ↪ be explicit  
6  Meter r=static_cast<Meter>(5); // Ok
```

C++11 introduced enum classes, which are also an example of strong types. Unlike traditional enums, enum classes do not implicitly convert to integers:

```
0  enum E {x,y,z};  
1  E e = x; // Works fine  
2  int x = e; // Works fine
```

```
0  enum class E {x,y,z};  
1  E e = E::x; // Works fine  
2  int x = e; // No implicit conversion, must be explicit  
3  int y = static_cast<int>(e);
```

### 47.1 Why Use Strong Types?

- **Type Safety:** They prevent mixing up logically different values (like meters vs. seconds) that might have the same underlying type.
- **Code Clarity:** They make the programmer's intent explicit, reducing the chance of bugs.
- **Maintenance:** They help document the domain model of your application, making the code easier to understand and maintain.

### 47.2 Strong typing in regards to readability

Consider the following example

```

0  struct Car {
1      Car(int horsepower, int nDoors, bool isAutomatic, bool
   ↪ isElectric) : horsepower(horsepower), nDoors(nDoors),
   ↪ isAutomatic(isAutomatic), isElectric(isElectric) {}
2      int horsepower, nDoors;
3      bool isAutomatic, isElectric;
4  };
5  Car c1(400,4,true, false);

```

So what's the problem? If the class definition were far away, we would need to take the time to look at it to figure out what the argument list in the instantiation means. Instead, we can enforce strong typing.

A strong type in this context is a type that carries extra information, a specific meaning through its name

Regarding the example above, we could instead enforce strong typing

```

0  struct HorsePower {
1      int horsepower{};
2      HorsePower(int horsepower) : horsepower(horsepower) {}
3  };
4
5  struct Car {
6      Car(HorsePower horsepower) : horsepower(horsepower) {}
7      HorsePower horsepower;
8  };
9  Car c1(HorsePower(400));

```

## Argument dependent name lookup (ADL/Koenig lookup)

Consider the code

```
0 namespace x {  
1     class C {};  
2     void f(const C& i) {  
3         std::cout << "1";  
4     }  
5 }  
6  
7 namespace y {  
8     void f(const x::C& i) {  
9         std::cout << "2";  
10    }  
11 }  
12 int main() {  
13     f(x::C());  
14 }
```

This outputs 1

Since the functions `f` are declared inside namespaces, and the call `f(x::C())` is unqualified (not preceded by `x::` or `y::`), this would normally not compile.

However, due to argument-dependent name lookup a.k.a. "Koenig lookup", the behavior is well-defined.

With argument-dependent name lookup, the namespaces of the arguments to a function is added to the set of namespaces to be searched for that function. Since we're passing an `x::C` to `f`, the namespace `x` is also searched, and the function `x::f` is found

If instead we have

```
0 int main() {  
1     y::f(x::C());  
2 }
```

We would get 2 as output.

Next, consider

```

0  template<typename T>
1  void adl(T)
2  {
3      std::cout << "T";
4  }
5
6  struct S{};
7
8  template<typename T>
9  void call_adl(T t)
10 {
11     adl(S());
12     adl(t);
13 }
14 void adl(S)
15 {
16     std::cout << "S";
17 }
18
19 call_adl(S());

```

We get output TS.

- **First Call (adl(S()) inside call<sub>adl</sub>)** : This call is non-dependent (its argument is of a fixed type, *S*, that does not depend on any template parameter). This call is resolved when the template is defined. At that point, only the template version of *adl* is visible (the non-template *adl(S)* is defined later). Thus, the call resolves to the template function, which prints "T". **Second Call (adl(t) inside call<sub>adl</sub>)** : This call is dependent (its argument *t* is of type *T*, which is a template parameter). This call is resolved when the template is instantiated. At that point, both the template and non-template versions of *adl* are visible. The call resolves to the non-template function *adl(S)* because it is a better match (an exact match for type *S*) compared to the template version. This function prints "S".

Dependent calls within a template—like the call to *adl(t)*—are not fully resolved until the template is instantiated. In this case, instantiation happens when you call *call<sub>adl</sub>(S())*. At that point, the compiler performs a full lookup for *adl*.

- **Non-dependent call (adl(S()))**: Looked up at definition time.

**Dependent call (adl(t))**: Instantiated and looked up during the template instantiation phase when *call<sub>adl</sub>* is called with a specific type (here, *S*).

## C vs c++ external linkage

### 49.1 C++ external linkage

This is the default when we use the extern keyword

```
0 extern int x;
```

Which means

- **Name mangling:** The symbol for b might be mangled to include additional type and scope information.
- **C++ specific features:** This mangling supports function overloading and other C++ features.

Name mangling is the process by which C++ compilers encode extra information into the names of functions and variables. This extra information typically includes details like:

- **Function parameters:** To distinguish between overloaded functions.
- **Namespaces or class membership:** So that functions or variables in different scopes (like classes or namespaces) have unique names.
- **Other attributes:** Such as constness, etc.

when you define overloaded functions

```
0 int add(int a, int b);  
1 double add(double a, double b);
```

the compiler transforms (or "mangles") these names into unique symbols internally (e.g., something like `_Z3addii` for the first function and `_Z3adddd` for the second) so that the linker can differentiate between them. This process is essential for supporting C++ features that are not present in C, which does not allow function overloading and thus doesn't need name mangling.

### 49.2 C external linkage

We could also do

```
0 extern "C" int x;
```



Which tells the compiler that the variable `a` should use C linkage. This means

- **No name mangling:** The symbol for `a` will have the plain C name.

The compiler is instructed to leave the name unmangled. The symbol in the object file for `a` remains simply `a` and for `add` it remains exactly `add`.

This is crucial when linking C++ code with C code. C does not support name mangling (since it doesn't have function overloading), so the symbols need to match exactly between the C library and your C++ code.

- **C calling convention:** When used with functions (though here it's a variable), it would use the C calling convention.

The calling convention defines how functions receive parameters, return values, and how the call stack is managed. It covers aspects like:

- **Order of parameter passing:** Right-to-left vs. left-to-right.
  - **Who cleans up the stack:** The caller or the callee.
  - **Register usage:** Which registers are used for passing parameters.
- **Interoperability:** It can be linked with C code that expects a symbol named exactly `a`.

By using `extern "C"`, your C++ code can directly link to and use C libraries. This interoperability is essential when integrating legacy C code with newer C++ codebases or when using system libraries written in C.

Consider the following example

```
0  namespace A{
1      extern "C" int x;
2  };
3
4  namespace B{
5      extern "C" int x;
6  };
7
8  int A::x = 0;
9
10 int main(){
11     std::cout << B::x;
12     A::x=1;
13     std::cout << B::x;
14 }
```

Due to the `extern "C"` specifications, `A::x` and `B::x` actually refer to the same variable.

`x` is first initialized to 0, then `main()` starts, 0 is printed, `x` is incremented to 1, and finally 1 is printed.

## Who cleans up the call stack, the caller or the callee

It depends on the calling convention. With the most common `cdecl` calling convention used in many C++ environments, the caller is responsible for cleaning up the call stack after the function call. However, if a function uses a calling convention like `stdcall`, then the callee cleans up the stack before returning.

So, in standard C++ using `cdecl`, the caller cleans up the stack, but this can vary with different calling conventions.

## Notes about sizeof

### 51.1 non types in sizeof?

Consider

```
0  cout << sizeof(1); //4
1  cout << sizeof(1.0); // 8
2  short x = 5;
3  cout << sizeof(x); // 2
```

In C++, the sizeof operator is evaluated at compile time and it inspects the type of its operand rather than evaluating the operand itself. This means that it doesn't matter whether you pass an lvalue or an rvalue.

### 51.2 No side effects?

Consider the code

```
0  int x = 5;
1  cout << sizeof(++x) << endl;
2  cout << x; // 5
```

Why is  $x$  not changed? sizeof is computed during compilation. No code is executed to determine its value, which means even if the operand has side effects, those side effects will not occur.

### 51.3 What is the output?

Consider

```
0  int n = sizeof(0)["abcdefghij"];
1  std::cout << n; // 1
```

First, recall the sizeof is an operator, not a function.  $\text{sizeof}(0) = \text{sizeof } 0$ . Since the subscript operator has higher precedence over the sizeof operator, what we get is

```
0  sizeof 0["abcdefghi"]
```

Which is

```
0 sizeof(0["abcdefghi"])
```

Which is

```
0 sizeof(a) // Char is 1 byte
```

## 51.4 sizeof("")

```
0 int main() {  
1     cout << sizeof(""); // 1  
2 }
```

every string literal includes a terminating null character ("). So, the literal "" is not truly "empty" but is actually an array containing one character—the null terminator. Since sizeof computes the total number of bytes in the array and a char occupies one byte, sizeof("") evaluates to 1.

But,

```
0 void f(auto x) {  
1     cout << sizeof(x);  
2 }  
3 f(""); // 8
```

The array decays to a pointer to its first element. Therefore, x is deduced as a const char\*, and sizeof(x) returns the size of a pointer on your platform—which is typically 8 bytes on a 64-bit system

## Parenthesized declarators

Consider the following code

```
0  int main() {  
1      int(myint) = 10;  
2      // Equivalent to  
3      int myint = 10;  
4  }
```

This syntax is perfectly legal to create an `int` named `myint`, although some warnings will show up about redundant parenthesis. This syntax is just

```
0  int (myint) = 10;
```

Without the space after `int`. With this concept in mind, examine the following code

```
0  struct A {  
1      A() {cout << "1";}  
2      A(const A& other) { cout << "2"; }  
3  } object;  
4  
5  int main() {  
6      A(object);  
7  }
```

We get output: 11, the copy constructor is not called, because in main we are creating a new `A` object named `object`, which will shadow the global one

Note that if we had a constructor that took a value, the compiler will try to use that constructor

```
0  struct A {  
1      int x{};  
2      A(int x) : x(x) {}  
3  };  
4  A(object); // Error: No matching constructor
```

## Notes about classes and member variables

### 53.1 Const member variable assigned in constructor?

Consider

```
0 struct A{
1     const int x;
2     A(int x) : x(x) {}
3 };
```

This works just fine. Although in a function that is not a constructor, it will not.

```
0 void setX(int y) {
1     x = y; // Error x is const-qualified
2 }
```

In C++, const member variables must be initialized at the time of object creation rather than being assigned to later. The constructor's initializer list (the part after the colon in the constructor) is specifically designed for this purpose. When you write:

```
0 A(int x) : x(x) {
1     cout << "Constructed A object with x = " << x << endl;
2 }
```

you aren't performing an assignment inside the constructor body; instead, you're initializing the const member `x` directly with the value provided as an argument. This initialization is allowed even though `x` is const, because once it's set during construction, its value cannot be changed thereafter

**Note:** Trying to assign `x` inside the body of the constructor will fail

```
0 struct A {
1     const int x = 12;
2     A(int y) {
3         x = y; // Error: x is const-qualified
4         cout << "Constructed A object with x = " << x <<
5         endl;
6     }
7 };
```

**What is the type of a string literal?**

Of type `const char*`

## Notes about `const_cast`

### 55.0.1 Dangers of trying to modify string literals (`const char*`)

Consider the following code

```
0 char* a = const_cast<char*>("Hello");  
1 a[4] = '\\0';  
2 std::cout << a;
```

So we have this `const char*` string literal "Hello", and we store it in a `char*` by `const` casting the constness away. Then, we try to modify it.

Modifying the contents pointed to by `a` would result in undefined behavior because string literals are usually stored in read-only memory.

### 55.1 `const_cast` is UB example

Consider the code



## Notes about friend functions

### 56.1 Recall friend

In C++, the friend keyword is used within a class to grant non-member functions or other classes access to its private and protected members. This can be particularly useful when you want a function or another class to have access to the internals of your class without making those members public.

- **Friend Function:** A non-member function can be declared as a friend inside a class. This function, although not a member of the class, can access the class's private and protected members.
- **Friend Class:** You can declare an entire class as a friend. Every member of that friend class will have access to the private and protected members of the class that declares the friendship.
- **Encapsulation Consideration:** Using the friend keyword is a deliberate break of encapsulation. It should be used sparingly and only when necessary to allow closely related classes or functions to interact efficiently.
- **Not Inherited:** Friendship is not inherited. If Class A declares Class B as a friend, and Class C inherits from A, Class B is not automatically a friend of Class C.
- Friendship is not inherited
- Friendship isn't mutual i.e. if some class called Friend is a friend of some other class called NotAFriend then NotAFriend doesn't automatically become a friend of the Friend class
- The total number of friend classes and friend functions should be limited in a program as the overabundance of the same might lead to a depreciation of the concept of encapsulation of separate classes, which is an inherent and desirable quality of object-oriented programming
- A common use-case for friend classes and functions is unittesting. The test class becomes a friend of the class under test

#### 56.1.1 Friend functions

```

0  class A {
1      public:
2          A(int x) : x(x) {}
3      private:
4          int x{};
5      friend void print(const A& obj);
6  };
7
8  void print(const A& obj) {
9      cout << obj.x << endl;
10 }

```

### 56.1.2 Friend class

```

0  class B;
1
2  class A {
3      public:
4          A(int x) : x(x) {}
5      private:
6          int x{};
7      friend B;
8  };
9
10 class B {
11     public:
12     void print(const A& a) {
13         cout << a.x << endl;
14     }
15 };
16 A a(10);
17 B aObserver{};
18 aObserver.print(a);

```

Note that we can also remove the forward declare and just do `friend class B`

```

0  class A; // Forward declaration for A (needed for B)
1
2  class B {
3      public:
4          void print(const A& a); // Declare print here.
5  };
6
7  class A {
8      public:
9          A(int x) : x(x) {}
10     private:
11         int x{};
12     friend void B::print(const A& a); // Now the compiler
    ↪ knows B::print exists.
13 };
14
15 void B::print(const A& a) {
16     cout << a.x << endl;
17 }

```

## What is the value of argv[argc]?

Consider the code

```
0  int main(int argc, char** argv) {  
1      cout << boolalpha << (argv[argc] == nullptr);  
2  }
```

We get true... The standard states that the value of argv[argc] shall be 0.

## Notes about const

### 58.1 Returning const?

Consider the function

```
0  const int f() {  
1      const int x = 10;  
2      return x;  
3  }
```

When you call the function, you receive a temporary object of type `const int`. This means you can't directly modify the temporary (e.g., writing `f() = 30;` would be illegal).

If you assign the result of the function to a non-const variable, the `const` qualifier is not carried over. For example:

Since the function returns a copy, marking it as `const` doesn't protect any underlying data. It only prevents modifications on the temporary object itself before it's used to initialize another variable.

Imagine that you buy a house but you cannot modify it? While there can be special cases, in general, you want your house to be your castle. Similarly, you want your copy to really be your object and you want to be able to do with it just whatever as an owner of it.

It doesn't make sense and it's misleading to return by value a `const` object

Also, returning by value a `const` object will not allow the compiler to perform the RVO where the temporary is moved instead of copied, since a move would modify the temporary

Using `const` in the return type by value is generally discouraged because it can interfere with move semantics and does not provide additional safety benefits. It's more common and useful to use `const` when returning by reference, where you want to prevent the caller from modifying the original object

```
0  const int& f(const int& x) {  
1      return x;  
2  }  
3  int x = 20;  
4  int& y = f(x); // Error: cannot drop const qualifier
```

## 58.2 is\_const\_v

Consider the code

```
0  std::cout << std::is_const_v<const int *>
1              << std::is_const_v<const int [1]>
2              << std::is_const_v<const int **>
3              << std::is_const_v<const int (*)[1]>
4              << std::is_const_v<const int *[1]>
5              << std::is_const_v<const int [1][1]>;
```

We get 010001. The output is determined by how `std::is_const` checks for a top-level const qualification. In C++, a type's const qualification is considered "top-level" if it applies directly to the type rather than to something the type points to or contains

"An array type whose elements are cv-qualified is also considered to have the same cv-qualifications as its elements." Since the array's element type is `const`, the array type itself is also `const`

## 58.3 Top-level and low-level cv-qualifiers

In C++, cv-qualifiers (i.e. `const` and `volatile`) are applied at two distinct levels:

- **Top-level cv-qualifiers:** These qualify the object itself. For example, in the declaration

```
0  int* const ptr;
```

the `const` is a top-level qualifier—it makes the pointer itself constant, meaning you cannot change which address `ptr` holds. Top-level qualifiers are typically ignored in contexts such as copying objects or function parameter passing.

- **Low-level cv-qualifiers:** These qualify the type that the object points to or refers to. For example, in

```
0  const int* ptr;
```

the `const` qualifies the `int` pointed to by `ptr`. This is a low-level qualifier—it tells you that the integer value pointed to cannot be modified via this pointer, even though the pointer itself can be changed.

## Mixed type references

Consider the code

```
0  int a = '0';  
1  char const &b = a;  
2  std::cout << b;  
3  a++;  
4  std::cout << b;
```

We get output 00. In C++, binding a const reference of a different type (in this case, a char const to an int) does not bind the reference directly to the original variable. Instead, it creates a temporary object

Since a is an int and b is a char const &, C++ performs an implicit conversion from int to char by creating a temporary char object holding the value '0'. The const reference b is then bound to this temporary object, not directly to a. The lifetime of this temporary is extended to match that of b.

Even after incrementing a, the temporary object (which b refers to) remains unchanged. Therefore, printing b twice results in "00".

## The types of literals and builtin suffixes

- **Integer Literals:** The type of integral literals depend on the size of the literal. Small integral literals will be of type `int`, where as large values will be of type `long` or even `unsigned long`.
- **Floating-Point Literals:** A literal like `3.14` is of type `double` by default
- **Character literals:** A literal like `'a'` is of type `char`,
- **String Literals:** Are of type `const char[]` by default
- **Boolean literals:** (`true/false`) Of type `bool`, note that `1` and `0` are of type `int`
- **Nullptr literal:** of type `std::nullptr_t`

### 60.1 Suffixes

For integrals,

```
0  42 // no suffix: int if it fits
1  42u // unsigned
2  42U // unsigned
3  42l // long
4  42L // long
5  42ll // long long
6  42LL // long long
```

For floating point literals,

```
0  3.14 // No suffix: double
1  3.14f // float
2  3.14F // float
3  3.14l // long double
4  3.14L // long double
```

For chars,

```
0  'a' // No suffix: char
1  L'a' // wchar_t
2  u'a' // utf-16 (char16_t)
3  U'a' // utf-32 (char32_t)
```

For strings,



```
0  L>Hello" // Array of wchar_t
1  u8"hello" // UTF-8 encoded string (array of const char8_t)
2  u"hello" // UTF-16 (array of const char16_t)
3  U"hello" // UTF-32 (array of const char32_t)
```

## Notes about perfect forwarding

Consider the code with the unexpected results

```
0 void f(float &&) { std::cout << "f"; }
1 void f(int &&) { std::cout << "i"; }
2
3 template <typename... T>
4 void g(T&&... v)
5 {
6     (f(v), ...);
7 }
8 g(1.0f, 1); // if
9 g(1.0f, 1.2f); // ii
10 g(1,1); // ff
```

even though each parameter is declared as a forwarding (universal) reference ( $T\&\&$ ), when you refer to a named parameter (here, “v”), it is an lvalue. That means that even if you pass an rvalue (like 1.0f or 1), inside g the variables v are lvalues.

The functions *f* only accept rvalue arguments. Since the named parameters in g are lvalues, neither  $f(\text{float}\&\&)$  nor  $f(\text{int}\&\&)$  can bind directly. However, implicit conversion is available. For an lvalue of type float (coming from 1.0f):

- It cannot bind to  $f(\text{float}\&\&)$  (because it’s an lvalue).
- It can convert to an long, which then binds to  $f(\text{int}\&\&)$  and prints “i”.

Similarly, for an lvalue of type int (coming from 1):

- It cannot bind to  $f(\text{int}\&\&)$ .
- It converts to a float, binding to  $f(\text{float}\&\&)$  and printing “f”.

To preserve the original value category and get the expected overload, you should forward the arguments:

```
0 template <typename... T>
1 void g(T&&... v) {
2     (f(std::forward<decltype(v)>(v)), ...);
3 }
```

Since a named int (an lvalue) cannot bind directly to an rvalue reference like  $\text{int}\&\&$ , the  $f(\text{int}\&\&)$  overload is rejected. However, the compiler can perform an implicit conversion: it converts the int lvalue to a float, producing a prvalue (an rvalue) that can bind to  $f(\text{float}\&\&)$ . That’s why an int ends up calling  $f(\text{float}\&\&)$  (printing “f”).

Similarly, if you pass a float, it ends up converting to int for the other overload, because the float lvalue cannot bind to  $\text{float}\&\&$  directly, so it converts to an int prvalue to bind to  $f(\text{int}\&\&)$ .

## lazy instantiation in templates

Lazy instantiation means that the compiler defers generating the full definition of a template until it's actually needed.

When you write a template (like a class template), you're providing a blueprint. The compiler doesn't generate code for that blueprint until you use it with a specific type in a context that requires the complete definition. For example, merely declaring a pointer to a template instantiation doesn't force the compiler to instantiate its members.

This approach improves compile times by only generating code for the parts of the template that are actually used. It also allows you to write templates that can work with a broader range of types—even if some types would cause errors in unused parts of the template, they won't be instantiated unless needed.

Consider the code

```
0  template<typename T>
1  struct A {
2      static_assert(false);
3  };
4
5  A<int>* a; // does not cause static_assert to execute, since
    ↪ a is a pointer
```

## Notes about `initializer_list`

Consider the code

```
0  struct A {  
1      A () = default;  
2      A(const A& other) { cout << "Copied" << endl; }  
3  };  
4  void f(std::initializer_list<A> i) {}  
5  
6  A a;  
7  std::initializer_list<A> i{a};  
8  f(i);  
9  f(i);
```

So when we construct the initializer list `i`, we can imagine a temporary array of one `C` being created, where the element is copy-initialized. Since `c` is an lvalue, a copy is made (not for instance a move), and 1 is printed.

Then, `f` is called twice, taking the freshly created `initializer_list` by value. So a copy of the `initializer_list` is made for each call. Does that make a copy of the elements in the initializer list, as it would when taking for instance a vector or a list by value? No...

Copying an initializer list does not copy the underlying elements.

If you write an initializer list constructor for your class, never move the elements out of the initializer list. Even if you took it by value, you were not passed an exclusive copy of the elements, which might still be used by others.

## Notes about operator precedence

### 64.1 Logical operators

consider the code

```
0  int i=1,j=1,k=1;  
1  if (++i  ++j && ++ k);  
2  cout << i << j << k;
```

Here, we get 1211, only  $i$  is incremented.  $\&\&$  (logical-and-expression) has higher precedence than  $\|\|$  (logical-or-expression)

Logical precedence from lowest to highest

1. logical-or-expression:
2. logical-and-expression
3. logical-or-expression  $\|\|$  logical-and-expression

So  $(++I \|\| ++J \&\& ++K)$  will be equal to  $(++I \|\| (++J \&\& ++K))$ . Since  $++i$  is true, the short circuiting principle guarantees that the right side will be skipped.

## Alternative tokens

Alternative token representations are provided for some operators and punctuators. In all respects of the language, each alternative token behaves the same, respectively, as its primary token, except for its spelling. The set of alternative tokens is

Alternative	Primary	Alternative	Primary	Alternative	Primary
<%	{	and	&&	and_eq	&=
%>	}	bitor		or_eq	=
<:	[	or		xor_eq	^=
:>	]	xor	^	not	!
%:	#	compl	~	not_eq	!=
%::	##	bitand	&		

## Notes about C arrays

Consider the following

```
0  void f(int* arr) {
1      cout << sizeof(arr) << endl // 8: decays to int pointer
2  }
3
4  void f(int arr[]) {
5      cout << sizeof(arr) << endl // 8: decays to int pointer
6  }
7
8  void f(int (&arr)[10]) {
9      cout << sizeof(arr) << endl; // 40: the result is the
   ↪ size of the referenced type.
10     // arr is a reference to an array of 10 ints
11 }
12
13 int main() {
14     int arr[10];
15
16     cout << sizeof(arr) << endl; // 40 (bytes): ten four
   ↪ byte integers
17 }
```

## Notes about operator overloads

### 67.1 Manually calling operator overloads

We can manual call our operator overloads. Observe

```
0  struct S {  
1      int x{};  
2      S(int x) : x(x) {}  
3      bool operator<(const S& other) {  
4          return x < other.x;  
5      }  
6  };  
7  S s1(5);  
8  S s2(10);  
9  cout << s1.operator <(s2) << endl;
```



## Notes about pointers

## 68.1 The introduction of the nullptr

nullptr was introduced in C++11 to address several issues and improve type safety when dealing with null pointers. Prior to C++11, the standard way to represent a null pointer was to use the macro NULL, which is typically defined as 0 or ((void\*)0) in C++. However, this approach had several drawbacks:

### 68.1.1 Ambiguity in Overloaded Functions

In C++, NULL is typically defined as 0, which is an integer. This can lead to ambiguity when overloading functions that take both integer and pointer arguments. For example

```
0 void foo(int);  
1 void foo(char*);  
2  
3 foo(NULL); // Which foo is called? Ambiguous, as NULL is an  
   ↪ integer.
```

nullptr resolves this ambiguity because it has its own type, std::nullptr\_t, which is implicitly convertible to any pointer type but not to integral types. Thus:

```
0 foo(nullptr); // Unambiguously calls foo(char*)
```

### 68.1.2 Type safety

Using 0 or NULL for null pointers can lead to type safety issues because 0 is an integer literal, and it can be implicitly converted to other types, such as bool or int. This can result in unintended behavior or bugs.

nullptr is a keyword that explicitly represents a null pointer, and it cannot be implicitly converted to an integer. This makes the code more type-safe and less prone to errors.

### 68.1.3 The type of nullptr

nullptr is of type nullptr\_t

```
0 auto ptr = nullptr // has type nullptr_t
```

#### 68.1.4 nullptr vs void\*

nullptr is used to explicitly indicate that a pointer does not point to any valid memory location.

It has its own type, `std::nullptr_t`, which is implicitly convertible to any pointer type (e.g., `int*`, `char*`, etc.) but not to other types like integers.

`void*` is a generic pointer type that can point to any data type.

#### 68.1.5 Zero is a nullptr?

The literal 0 is special in C++—it's a null pointer constant. This means that when 0 is used in a pointer context, it is implicitly converted to a null pointer.

```
0 cout << (nullptr == 0); // True
```

### 68.2 What does an uninitialized pointer point to?

In C++, if you declare a pointer like `int* ptr;` without initializing it, the pointer's value is indeterminate. This means it doesn't point to a specific, valid memory location—it essentially contains a "garbage" value. Dereferencing such a pointer leads to undefined behavior. It's best practice to initialize pointers to at least `nullptr`. This way, you can safely check if the pointer is valid before using it.

An uninitialized pointer contains whatever "garbage" value happens to be in that memory location, so it might point to some

## Notes about gotos

### 69.1 Scope

Consider the code

```
0  class A {  
1      public:  
2      A() { std::cout << "a"; }  
3      ~A() { std::cout << "A"; }  
4  };  
5  int i = 1;  
6  
7  int main(int argc, const char *argv[]) {  
8      label:  
9      A a;  
10     if (i--)  
11         goto label;  
12     return EXIT_SUCCESS;  
13 }
```

We get output aAaA. In C++, the lifetime of an automatic (local) object is tied to the scope in which it's defined. Even though the label is textually within the same function block, when the program executes the `goto label;` statement, it leaves the scope of the current instance of `a`, triggering its destructor before jumping back to the label.

The `goto label;` statement causes the program to exit the region where that instance of `a` is alive. According to C++ rules, exiting the scope of an object (even via `goto`) must trigger its destructor.

## Notes about lambdas

### 70.1 Global variables

```
0  int a =5;
1
2  int main() {
3      cout << [](int x){return a + x;}(5); // 10
4  }
```

You may think that the global *a* needs to be captured. However, only local variables may be captured by a lambda. *a* is a global variable with static storage duration and may not be captured

## Notes about function types

### 71.1 Top-level cv-qualifiers

The constness of parameters are not part of the function type.

```
0  std::cout << std::is_same_v<  
1  void(int),  
2  void(const int)>>; // 1
```

The top-level cv-qualifier of the parameter is removed when considering the type of a function.

```
0  std::cout << std::is_same_v<  
1  void(int*),  
2  void(const int*)>>; // 0
```

The second parameter has low-level cv-qualification. Thus, there is no const to remove and they are different types.

## Notes about name resolution

```
0  int foo() {  
1      return 10;  
2  }  
3  
4  struct foobar {  
5      static int x;  
6      static int foo() {  
7          return 11;  
8      }  
9  };  
10 int foobar::x = foo();  
11  
12 int main() {cout << foobar::x; } // 11
```

First, notice that `foo` is not qualified by any name. So why is the `foo` in `foobar` chosen?

This behavior occurs because the out-of-class definition of a class member is treated as if it were within the class's scope.

The unqualified call to `foo()` is looked up in the context of `foobar` first—even though the definition is written outside the class body. As a result, it finds the static member function `foobar::foo()` (which returns 11) rather than the free function `::foo()` (which returns 10).

This lookup mechanism is sometimes described as unqualified name lookup in an out-of-class member definition, where the definition is treated as if it were in the class's scope. This “injection” of the class scope into the member definition is what causes the resolution to favor `foobar::foo()` over the global `foo()`.

## Notes about default parameters

In a function declaration, after a parameter with a default argument, all subsequent parameters must have a default argument supplied in this or a previous declaration from the same scope...unless the parameter was expanded from a parameter pack, and keep in mind that ellipsis(...) is not a parameter.

This means that that the `int calculateArea(int a=5, int b);` would not compile. On the other hand, `int g(int n = 0, ...)` would compile as ellipsis does not count as a parameter.

Default arguments are only allowed in the parameter lists of function declarations and lambda-expressions, (since C++14) and are not allowed in the declarations of pointers to functions, references to functions, or in typedef declarations.

One last thing to note is that you should always declare your defaults in the header, not in the cpp file.



## Notes about the this pointer

### 74.1 Can you delete the this pointer

Yes, but it will cause a program crash if any objects are created on the stack. If all objects are created on the heap, the program will run but have UB

```
0  struct A {  
1      A() {  
2          delete this;  
3      }  
4  
5      void f() {  
6          cout << "Hello" << endl;  
7          this->g();  
8      }  
9  
10     void g() {  
11         cout << "World" << endl;  
12     }  
13 };  
14 A* a = new A;  
15 a->f();
```

The constructor calls `delete this;` immediately when an object of type `A` is created. This deallocates the memory of the object before the constructor has fully finished its job and before you intend to use the object.

After the constructor finishes, you call `a->f();` in `main`. At this point, `a` is a pointer to an object that has already been destroyed. Accessing methods (or any members) on a deleted object is undefined behavior. Sometimes it might appear to work because the memory hasn't been overwritten yet, but there is no guarantee—this can lead to crashes or other erratic behavior in different environments or even with different compiler optimizations.

In many implementations, the memory isn't immediately reused or corrupted after a deletion, so the function calls on the "deleted" object might still find the expected code and data in place. However, this is entirely accidental and non-portable. Relying on such behavior is dangerous and considered a bug.

Once `delete this` is done, any member of the deleted object should not be accessed after deletion.

The best thing is to not do `delete this` at all because it is easy to accidentally access member variables after the deletion. Besides, the caller might not realize your object has self-destructed.

Also, delete this is a “code smell” indicating that your code might not have an asymmetric strategy for object ownership (who allocates and who deletes).

When still used, It is usually found in reference-counted classes that, when the ref-count is decremented to 0, the `DecrementRefCount()/Release()/whatever` member function calls `delete` this.

## Argument evaluation order: Indeterminately sequence

Consider the code

```
0 void f(int x, int y) {  
1     cout << x << y;  
2 }  
3 int i=0;  
4 f(++i, ++i);
```

First of all, the evaluation order of the two `++i` expressions is unspecified

The initialization of a parameter, including every associated value computation and side effect, is indeterminately sequenced with respect to that of any other parameter.

What does "indeterminately sequenced" mean? Evaluations *A* and *B* are indeterminately sequenced when either *A* is sequenced before *B* or *B* is sequenced before *A*, but it is unspecified which.

Let's say the implementation decides to go left to right. Then the first parameter *x* is initialized by the leftmost expression `++i`, which increments *i* and results in the updated *i* which is now 1. Next, the second parameter *y* is initialized by the rightmost expression `++i`, which increments *i* and results in the updated *i* which is now 2. Then, `print` prints 12.

Alternatively, the implementation could decide to go right to left, and `print` would print 21.

Interestingly, 22 is what GCC prints at the time of writing, and there's an open bug for that.

## Do static members increase the size of a class or object?

Static members are not part of the class object and as such, they are not included in the object's layout, they don't add up to the object's size.

## Note about enums

### 77.1 cv-qualifiers?

The type-specifier-seq of an enum-base shall name an integral type; any cv-qualification is ignored.

## Notes about templates

### 78.1 template templates

Consider the code

```
0  struct A {};  
1  struct B {};  
2  
3  template<typename T = A>  
4  struct X;  
5  
6  template<>  
7  struct X<A> {  
8      static void f() { std::cout << 1; }  
9  };  
10  
11  template<>  
12  struct X<B> {  
13      static void f() { std::cout << 2; }  
14  };  
15  
16  template<template<typename T = B> typename C>  
17  void g() {  
18      C<>::f();  
19  }
```

The syntax

```
0  template<template<typename T = B> class C>
```

means that the function template `g` is parameterized by a class template `C`. Here, `C` itself is a template that takes one type parameter `T` with a default type of `B`. This implies that `C` must be a template that can be instantiated with a single type argument, and if none is provided, it will use `B` by default.