```
11 View Controller, Switt
                                                                                11 Turbo SQuid & dae format
   import UIKit
                                                                                perceptive => front
   import Scene Kit
                                                                                 convert dat to scritte
  import ARKit
class view Controller: UIV:en Controller, ARSCN View Delegate {
      var scene View: ARSCAView!
     var planer = [OverlayPlane]()
    override func siewbidLoad(){
        super. view D:dLoad()
        self. sceneview = ARSCNV; ew (frame & self. view. frame)
        self. sceneview, debug Options = TARS (NDe bug Options. Show Feature Points, ARS (NDebug Options, Show World Origin]
         self. view. addSubview (self. sceneview)
        scene View. delegate = self
         sceneliew, shows Statistics = true
         let missleScene = S(NScene (named: "art. schassets/missile-1, sch")
       Il let missleNode = missleScene? rootNode. child Node (with Name: "missle", recursively: true)
       11 missleNode? position = SCN Vector 3 (0, 0, -0.5)
        let missile = Missile (scene: missile Scene) Il missile is a node with sub nodes
         missile. name = "Missile" 115ive the node a name
        missile.position = SCN Vector 3(0, 0, -4)
        scene. root Node. add Child Node ( missile)
        scene View. scene = scene
        register Gesture Recognizers ()
    private func register Gesture Recognizers ()
         (et tap Gesture Recognizer = UITap Gesture Recognizer (target: selt, action: #selector (tapped))
self. scene View. add Gesture Recognizer (tap Gesture Recognizer)
     3
     @objl func tupped (recognizer: UI Gesture Recognizer) {
            guard let missileNode =
                  self. sceneview. scene. rootNode. child Node ( with Name: "Missile", recursively; true) else {
                 total Error ("Missile not found")
           guard let smoke Node = missile Node. child Node ( with Name: "smoke Node", recarsively: true) else {
                 futal zrior ("no smoke node found")
           smokeNode, removeAllPartle (e Systems()
            let fire = SCN Particle System ( named ! "fire. scnp", in Directory ! nil)
           smoke Node. add Particle System (tire!)
           missile Node. physics Body = SCN Physics Body (type: dynamic, shape: nil)
missile Node. physics Body?. is Affected By Gravity = talse
missile Node. physics Body?. damping = 0.0 // friction > default is
```

```
missileNode, physicsBody?. apply Force (SCN Vector3 (0, 100, 0), as Impulse: Hase)
        tother delegate functions
11 Missile . switt
    import Foundation
    import Scenekit
   Import ARKIT
   class Missile : SCNNode{
          private var scene: SCNScene!
          init (scene: SCNScene) {
              super. init()
              self. scene = scene
              setupl)
         private func setupl){
              guard let missile Node = self, siene, root Node, child Node (with Name: "missile Node", recursively: true),
let smoke Node = self, siene, root Node, child Node (with Name: "smoke Node", recursively: true)
                    fata (Error ("Node not found")
                                                                         new file Desearch partlal & Scenek! L Partide System File
               Let smoke = SCN Particle System (named: "smoke.scnp", in Directory: nil)
smokeNode, add farticle System (smoke!)
               self. add (hild Node lmissile Node)
               self. add Child Node (snoke Node)
        ?
                      init? (coder alecoder: NSCoder) {
               super. init (coder: a Decoder)
        3
```