

COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

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Lecture 20

Spectral Graph Partitioning

- Focus on separating graphs with small but relatively balanced cuts.
- Connection to second smallest eigenvector of graph Laplacian.
- Today: Provable guarantees for stochastic block model.

- To partition a graph, find the eigenvector of the Laplacian with the second smallest eigenvalue. Partition nodes based on whether corresponding value in eigenvector is positive/negative.

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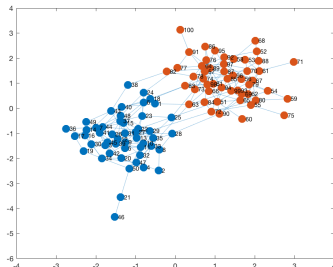
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- We argued this “should” partition graph along a small cut that separates the graph into large pieces.
- Haven’t given formal guarantees; it’s difficult for general input graphs. But can consider randoms “natural” graphs. . .

STOCHASTIC BLOCK MODEL

Stochastic Block Model (Planted Partition Model): Let $G_n(p, q)$ be a distribution over graphs on n nodes, split randomly into two groups B and C , each with $n/2$ nodes.

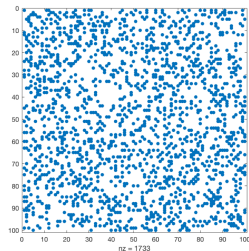
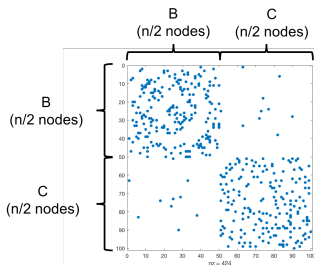
- Any two nodes in the **same group** are connected with probability p (including self-loops).
- Any two nodes in **different groups** are connected with prob. $q < p$.
- Connections are independent.



LINEAR ALGEBRAIC VIEW

Let G be a stochastic block model graph drawn from $G_n(p, q)$.

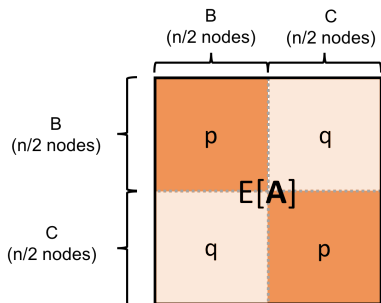
- Let $\mathbf{A} \in \mathbb{R}^{n \times n}$ be the adjacency matrix of G , ordered in terms of group ID.



$G_n(p, q)$: stochastic block model distribution. B, C : groups with $n/2$ nodes each. Connections are independent with probability p between nodes in the same group, and probability q between nodes not in the same group.

EXPECTED ADJACENCY SPECTRUM

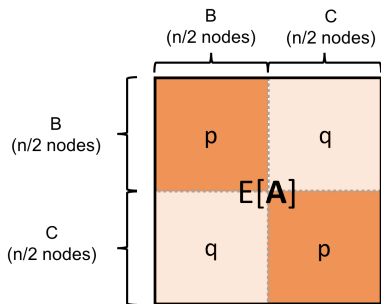
Letting G be a stochastic block model graph drawn from $G_n(p, q)$ and $\mathbf{A} \in \mathbb{R}^{n \times n}$ be its adjacency matrix. $(\mathbb{E}[\mathbf{A}])_{i,j} = p$ for i, j in same group, $(\mathbb{E}[\mathbf{A}])_{i,j} = q$ otherwise.



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What is $\text{rank}(\mathbb{E}[\mathbf{A}])$?

What are the eigenvectors and eigenvalues of $\mathbb{E}[\mathbf{A}]$?

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EXPECTED ADJACENCY SPECTRUM

$$\begin{array}{c}
 \begin{array}{cc}
 \text{B} & \text{C} \\
 (n/2 \text{ nodes}) & (n/2 \text{ nodes})
 \end{array} \\
 \begin{array}{|c|c|}
 \hline
 \begin{array}{c} p \\ q \end{array} & \begin{array}{c} q \\ p \end{array} \\
 \hline
 \end{array}
 \end{array}
 \begin{array}{c}
 \text{E[A]} \\
 =
 \end{array}
 \begin{array}{c}
 \mathbf{V} \\
 \begin{array}{|c|}
 \hline
 \begin{array}{c} 1 \ 1 \\ 1 \ 1 \\ 1 \ 1 \\ 1 \ 1 \\ 1 \ -1 \\ 1 \ -1 \\ 1 \ -1 \\ 1 \ -1 \end{array} \\
 \hline
 \end{array}
 \end{array}
 \begin{array}{c}
 \mathbf{\Lambda} \\
 \begin{array}{|c|}
 \hline
 \begin{array}{c} \frac{n(p+q)}{2} \\ \frac{n(p-q)}{2} \end{array} \\
 \hline
 \end{array}
 \end{array}
 \begin{array}{c}
 \mathbf{V}^T \\
 \begin{array}{|c|}
 \hline
 \begin{array}{cccccccc} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \end{array} \\
 \hline
 \end{array}
 \end{array}
 \end{array}$$

If we compute \vec{v}_2 then we recover the communities B and C !

EXPECTED ADJACENCY SPECTRUM

The diagram illustrates the expected adjacency matrix $\mathbb{E}[\mathbf{A}]$ and its spectral decomposition $\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$.

Expected Adjacency Matrix $\mathbb{E}[\mathbf{A}]$: A 2×2 block matrix with two communities, B and C, each containing $n/2$ nodes.

B ($n/2$ nodes)		C ($n/2$ nodes)	
p	q	q	p
q	p	p	q

Spectral Decomposition $\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$:

Matrix \mathbf{V} :

1	1
1	1
1	1
1	1
1	-1
1	-1
1	-1
1	-1

Matrix $\mathbf{\Lambda}$:

$\frac{n(p+q)}{2}$
$\frac{n(p-q)}{2}$

Matrix \mathbf{V}^T :

1	1	1	1	1	1	1	1
1	1	1	1	-1	-1	-1	-1

If we compute \vec{v}_2 then we recover the communities B and C !

- Can show that for $G \sim G_n(p, q)$, \mathbf{A} is “close” to $\mathbb{E}[\mathbf{A}]$ in some appropriate sense (matrix concentration inequality).

EXPECTED ADJACENCY SPECTRUM

The diagram illustrates the expected adjacency matrix $E[\mathbf{A}]$ and its spectral decomposition $\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$.

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Matrix \mathbf{V} :

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If we compute \vec{v}_2 then we recover the communities B and C !

- Can show that for $G \sim G_n(p, q)$, \mathbf{A} is “close” to $\mathbb{E}[\mathbf{A}]$ in some appropriate sense (matrix concentration inequality).
- Second eigenvector of A is close to $[1, 1, 1, \dots, -1, -1, -1]$ and gives a good estimate of the communities.

EXPECTED ADJACENCY SPECTRUM

The diagram illustrates the spectral decomposition of the expected adjacency matrix $E[A]$. On the left, $E[A]$ is a block matrix with two communities, B and C, each containing $n/2$ nodes. Community B has an internal edge probability p (orange) and a probability q (light orange) of connecting to community C. Community C has a probability q (light orange) of connecting to community B and an internal edge probability p (orange). This matrix is equal to the product of three matrices: V , Λ , and V^T .

V is a matrix of eigenvectors, shown as a 10x2 grid of values: $\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \\ 1 & 1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix}$.

Λ is a diagonal matrix of eigenvalues, shown as a 2x2 grid of values: $\begin{bmatrix} \frac{n(p+q)}{2} & 0 \\ 0 & \frac{n(p-q)}{2} \end{bmatrix}$.

V^T is the transpose of V , shown as a 2x10 grid of values: $\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 & -1 & -1 \end{bmatrix}$.

If we compute \vec{v}_2 then we recover the communities B and C !

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When rows/columns aren't sorted by ID, second eigenvector is e.g., $[1, -1, 1, -1, \dots, 1, 1, -1]$ and entries give community ids.

Letting G be a stochastic block model graph drawn from $G_n(p, q)$, $\mathbf{A} \in \mathbb{R}^{n \times n}$ be its adjacency matrix and \mathbf{L} be its Laplacian, what are the eigenvectors and eigenvalues of $\mathbb{E}[\mathbf{L}]$?

Upshot: The second smallest eigenvector of $\mathbb{E}[\mathbf{L}]$ is $\chi_{B,C}$ – the indicator vector for the cut between the communities.

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- If the matrices \mathbf{A} and \mathbf{L} were exactly equal to their expectation, partitioning using this eigenvector (i.e., spectral clustering) would exactly recover the two communities B and C .

How do we show that a matrix is close to its expectation? Matrix concentration inequalities.

- Analogous to scalar concentration inequalities like Markovs, Chebyshevs, Bernsteins.
- Random matrix theory is a very recent and cutting edge subfield of mathematics that is being actively applied in computer science, statistics, and ML.

Matrix Concentration Inequality: If $p \geq O\left(\frac{\log^4 n}{n}\right)$, then with high probability

$$\|\mathbf{A} - \mathbb{E}[\mathbf{A}]\|_2 \leq O(\sqrt{pn}).$$

where $\|\cdot\|_2$ is the matrix **spectral** norm (operator norm).

For any $\mathbf{X} \in \mathbb{R}^{n \times d}$, $\|\mathbf{X}\|_2 = \max_{z \in \mathbb{R}^d: \|z\|_2=1} \|\mathbf{X}z\|_2$.

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For the stochastic block model application, we want to show that the second eigenvectors of \mathbf{A} and $\mathbb{E}[\mathbf{A}]$ are close. How does this relate to their difference in spectral norm?

Davis-Kahan Eigenvector Perturbation Theorem: Suppose $\mathbf{A}, \bar{\mathbf{A}} \in \mathbb{R}^{d \times d}$ are symmetric with $\|\mathbf{A} - \bar{\mathbf{A}}\|_2 \leq \epsilon$ and eigenvectors v_1, v_2, \dots, v_d and $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_d$. Letting $\theta(v_i, \bar{v}_i)$ denote the angle between v_i and \bar{v}_i , for all i :

$$\sin[\theta(v_i, \bar{v}_i)] \leq \frac{\epsilon}{\min_{j \neq i} |\lambda_i - \lambda_j|}$$

where $\lambda_1, \dots, \lambda_d$ are the eigenvalues of $\bar{\mathbf{A}}$.

The errors get large if there's eigenvalues with similar magnitudes.

Claim 1 (Matrix Concentration): For $p \geq O\left(\frac{\log^4 n}{n}\right)$,

$$\|\mathbf{A} - \mathbb{E}[\mathbf{A}]\|_2 \leq O(\sqrt{pn}).$$

Claim 2 (Davis-Kahan): For $p \geq O\left(\frac{\log^4 n}{n}\right)$,

$$\sin \theta(v_2, \bar{v}_2) \leq \frac{O(\sqrt{pn})}{\min_{j \neq i} |\lambda_i - \lambda_j|}$$

\mathbf{A} adjacency matrix of random stochastic block model graph. p : connection probability within clusters. $q < p$: connection probability between clusters. n : number of nodes. v_2, \bar{v}_2 : second eigenvectors of \mathbf{A} and $\mathbb{E}[\mathbf{A}]$ respectively.

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APPLICATION TO STOCHASTIC BLOCK MODEL

So Far: $\sin \theta(v_2, \bar{v}_2) \leq O\left(\frac{\sqrt{p}}{(p-q)\sqrt{n}}\right)$. What does this give us?

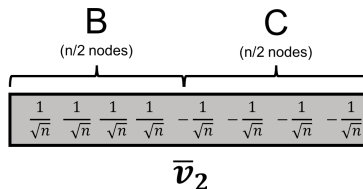
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- \bar{v}_2 is $\frac{1}{\sqrt{n}}\chi_{B,C}$: the community indicator vector.

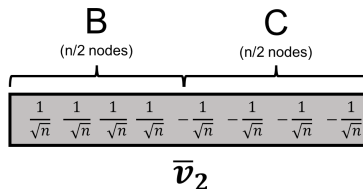


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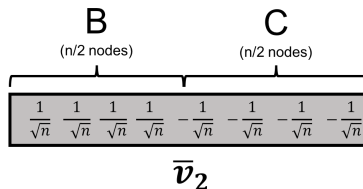
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- Every i where $v_2(i)$, $\bar{v}_2(i)$ **differ in sign** contributes $\geq \frac{1}{n}$ to $\|v_2 - \bar{v}_2\|_2^2$.
- So they differ in sign in at most $O\left(\frac{p}{(p-q)^2}\right)$ positions.

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Upshot: If G is a stochastic block model graph with adjacency matrix \mathbf{A} , if we compute its second large eigenvector v_2 and assign nodes to communities according to the sign pattern of this vector, we will correctly assign all but $O\left(\frac{P}{(\rho-q)^2}\right)$ nodes.

