Chapter 6: Substantivalism – Newton versus Leibniz

- (R1) All motion is the relative motion of bodies, and consequently, spacetime does not have structures that support absolute quantities of motion.
- (R2) Spatiotemporal relations among bodies and events are direct; i.e. they are not derived from relations among a substratum of space-time points that underlie events.

Stage setting

"...the best judgment emerging from the evidence marshalled in chapters 4 and 5 is that (R1) is in fact false in both the classical and relativistic settings." (p 111)

Chapter 3 supposedly shows (R1) and "determinism is possible" implies (R2)

"...if we want to allow for the possibility that particle motions are deterministic and if we want to make a substantivalist interpretation of the space-time manifold (not R2), it follows that the structure of space-time must be at least as rich as that of neo-Newtonian spacetime (not R1)." (p 55)

Definition: A theory is *deterministic* (in the sense of David Lewis) if for any nomologically possible worlds W and W', if W and W' agree on an initial segment, then W = W'.

Earman will argue that not-R2 and R1 imply not-determinism.

Fact: Let M be a classical spacetime with less structure than Galilean spacetime. There is a symmetry $\varphi: M \to M$ that is the identity for $t \leq 0$, but not the identity for t > 0. (HH agrees.) Thus, R1 implies the existence of such a symmetry.

"... we can thus produce two dynamically possible models where the world lines of the particles coincide for all $t \le 0$ but diverge for t > 0, a violation of determinism."

HH: It is not clear how not-R2 is supposed to function in this argument.

Earman produces a second argument. R1 was taken to mean "less structure than Galilean spacetime". But even if we allow Galilean spacetime, we still might get failure of determinism.

Let R1' = not full Newtonian spacetime. Hence R1 implies R1' but not vice versa.

Now Earman argues that not-R2 and R1' implies not-determinism. The key fact now is that there is a Galilean transformation that is the identity at t = 0 but not the identity elsewhere.

Leibniz's argument(s)

Leibniz argues for (R2), in particular that absolute space is an idle wheel.

Principle of Sufficient Reason: (1) God would have a good reason to create one world instead of another. (2) Nothing happens without a cause.

Principle of the Identity of Indiscernibles: If $a \neq b$, then there is some property that a has and that b lacks, or vice versa.

Leibniz's shift argument: If space is a substance, all matter can be moved n meters to the east of its current location, and the result is a new possible world. (see p 118)

The existence of these possible worlds $\{W_r : r \in \mathbb{R}\}$ is a problem both for PSR (which should God create?), and for PIdIn (the substantivalist declares them non-equal when they agree on all properties).

Earman: For Leibniz's invocation of PIdIn to work, it would need to be supplemented by an implausible verificationist assumption. For example: if two things agree on observable properties, then they agree. ("verifiability version of PIdIn" p 120)