Logic and Computer Design Fundamentals

Chapter 2 – Combinational Logic Circuits

Part 2 – Circuit Optimization

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Overview

- Part 1 Gate Circuits and Boolean Equations
 - Binary Logic and Gates
 - Boolean Algebra
 - Standard Forms
- Part 2 Circuit Optimization
 - Two-Level Optimization
 - Map Manipulation
 - Multi-Level Circuit Optimization
- Part 3 Additional Gates and Circuits
 - Other Gate Types
 - Exclusive-OR Operator and Gates
- Part 4 HDLs overview
 - Logic Synthesis
 - HDL Representations—Verilog

Circuit Optimization

- Goal: To obtain the simplest implementation for a given function
- Optimization is a more formal approach to simplification that is performed using a specific procedure or algorithm
- Optimization requires a cost criterion to measure the simplicity of a circuit
- Distinct cost criteria we will use:
 - Literal cost (L)
 - Gate input cost (G)
 - Gate input cost with NOTs (GN)

Literal Cost

- Literal a variable or its complement
- Literal cost the number of literal appearances in a Boolean expression corresponding to the logic circuit diagram
- Examples:

•
$$\mathbf{F} = \mathbf{B}\mathbf{D} + \mathbf{A}\mathbf{\overline{B}}\mathbf{C} + \mathbf{A}\mathbf{\overline{C}}\mathbf{\overline{D}}$$

$$L = 8$$

•
$$\mathbf{F} = \mathbf{B}\mathbf{D} + \mathbf{A}\mathbf{\overline{B}}\mathbf{C} + \mathbf{A}\mathbf{\overline{B}}\mathbf{\overline{D}} + \mathbf{A}\mathbf{B}\mathbf{\overline{C}}$$

$$L =$$

•
$$\mathbf{F} = (\mathbf{A} + \mathbf{B})(\mathbf{A} + \mathbf{D})(\mathbf{B} + \mathbf{C} + \mathbf{\overline{D}})(\mathbf{\overline{B}} + \mathbf{\overline{C}} + \mathbf{D}) \mathbf{L} =$$

• Which solution is best?

Literal Cost

Example (equivalent boolean expressions):

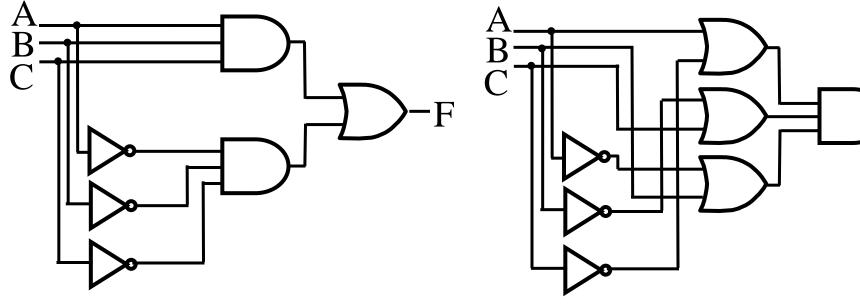
•
$$\mathbf{F} = \mathbf{ABC} + \overline{\mathbf{A}}\overline{\mathbf{B}}\overline{\mathbf{C}}$$

$$L = 6$$

•
$$\mathbf{F} = (\mathbf{A} + \overline{\mathbf{C}})(\overline{\mathbf{B}} + \mathbf{C})(\overline{\mathbf{A}} + \mathbf{B})$$
 $\mathbf{L} = \mathbf{6}$

$$L = 6$$

Which solution is best?



Gate Input Cost

- Example 1: \overline{B} \overline{C} \overline{B} \overline{C} $\overline{C$
- L (literal count) counts the AND inputs and the single literal OR input.
- G (gate input count) adds the remaining OR gate inputs
- GN(gate input count with NOTs) adds the inverter inputs

Gate Input Cost (continued)

Example 2:

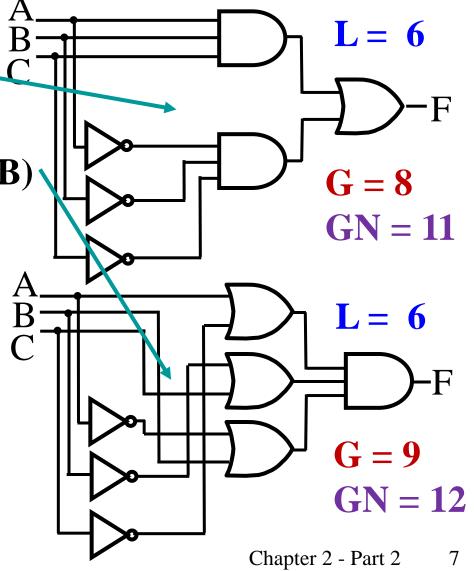
 $F = A B C + \overline{A} \overline{B} \overline{C}$

$$L = 6 G = 8 GN = 11$$

• $\mathbf{F} = (\mathbf{A} + \overline{\mathbf{C}})(\overline{\mathbf{B}} + \mathbf{C})(\overline{\mathbf{A}} + \mathbf{B})$

$$L = 6 G = 9 GN = 12$$

- Same function and same literal cost
- But first circuit has <u>better</u> gate input count and <u>better</u> gate input count with NOTs
- Select it!



Gate Input Cost (continued)

- Gate input costs the number of inputs to the gates in the implementation corresponding exactly to the given equation or equations. (G inverters not counted, GN inverters counted)
- For SOP and POS equations, it can be found from the equation(s) by finding the sum of:
 - all literal appearances
 - the number of terms excluding single literal terms (G) and
 - optionally, the number of distinct complemented single literals (GN).
- Example:

•
$$\mathbf{F} = \mathbf{B}\mathbf{D} + \mathbf{A}\overline{\mathbf{B}}\mathbf{C} + \mathbf{A}\overline{\mathbf{C}}\overline{\mathbf{D}}$$

$$G = 11, GN = 14$$

•
$$\mathbf{F} = \mathbf{B}\mathbf{D} + \mathbf{A}\overline{\mathbf{B}}\mathbf{C} + \mathbf{A}\overline{\mathbf{B}}\overline{\mathbf{D}} + \mathbf{A}\mathbf{B}\overline{\mathbf{C}}$$

$$G = 15, GN = 18$$

•
$$\mathbf{F} = (\mathbf{A} + \overline{\mathbf{B}})(\mathbf{A} + \mathbf{D})(\mathbf{B} + \mathbf{C} + \overline{\mathbf{D}})(\overline{\mathbf{B}} + \overline{\mathbf{C}} + \mathbf{D}) \mathbf{G} = 14, \mathbf{GN} = 17$$

• Which solution is best?

Gate Input Count

Example 1

$$\mathbf{F} = \overline{\mathbf{A}} \, \overline{\mathbf{C}} \, \overline{\mathbf{D}} + \overline{\mathbf{A}} \, \mathbf{B} \, \overline{\mathbf{C}} + \mathbf{A} \mathbf{B} \mathbf{C} + \mathbf{A} \mathbf{C} \, \overline{\mathbf{D}} \qquad \mathbf{G} = \mathbf{16}$$

Example 2

$$\mathbf{F} = \overline{\mathbf{A}} (\overline{\mathbf{C}} \overline{\mathbf{D}} + \mathbf{B} \overline{\mathbf{C}}) + \mathbf{A} (\mathbf{B} \mathbf{C} + \mathbf{C} \overline{\mathbf{D}}) \quad \mathbf{G} = \mathbf{18}$$

Example 3

$$\mathbf{F} = \overline{\mathbf{A}} \ \overline{\mathbf{C}} (\mathbf{B} + \overline{\mathbf{D}}) + \mathbf{AC} (\mathbf{B} + \overline{\mathbf{D}})$$
 $\mathbf{G} = 12$

Example 4

$$\mathbf{F} = (\overline{\mathbf{A}}\,\overline{\mathbf{C}} + \mathbf{A}\mathbf{C})\,(\mathbf{B} + \overline{\mathbf{D}})$$

$$\mathbf{G} = ?$$

Boolean Function Optimization

- Minimizing the gate input (or literal) cost of a (a set of) Boolean equation(s) reduces circuit cost.
- Boolean Algebra and graphical techniques are tools to minimize cost criteria values.
- Some important questions:
 - When do we stop trying to reduce the cost?
 - Do we know when we have a minimum cost?
- Treat optimum or near-optimum cost functions for two-level (SOP and POS) circuits first.
- Introduce a graphical technique using Karnaugh maps (K-maps, for short)

Big Picture of Boolean Function Optimization

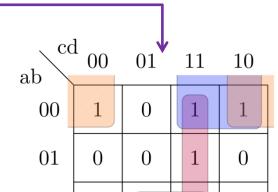
Boolean function

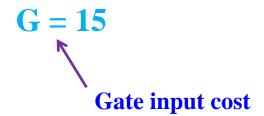


algebraic transformation

$$\sum$$
m(0,2,3,7,8,9, 10,11,13,15)

fill the K-map





Boolean function

Standard form (SOP/POS)

K-map

$$\overline{B}\overline{D} + CD + AD$$

$$G = 9$$



11

10

0

minimization theorem 0

Observations

When a boolean function is expressed as a sum of minterms (or a product of maxterms), optimization can be done using minimization theorem:

$$X \cdot Y + \overline{X} \cdot Y = Y$$
 or $(X+Y)(\overline{X}+Y) = Y$

X	Y	F	m _i
0	0	1	XY
0	1	0	Χ̈Υ
1	0	1	$X\overline{Y}$
1	1	0	XY

$$F(X,Y) = m_0 + m_2$$

$$= \overline{XY} + X\overline{Y} = \overline{Y}$$
or
$$F(X,Y) = M_1 \cdot M_3$$

$$= (X + \overline{Y}) \cdot (\overline{X} + \overline{Y})$$

K-Map and Truth Tables

- The K-Map is just a different form of the truth table.
- Example Two variable function:
 - We choose m_0, m_1, m_2 and m_3 from the set $\{0,1\}$ to implement a particular function, G(x,y).

Truth Table

K-Map

$$G(x,y)$$
 $y = 0$ $y = 1$
 $x = 0$ m_0 m_1
 $x = 1$ m_2 m_3

Karnaugh Maps (K-map)

- A K-map is a collection of squares
 - Each square represents a minterm or maxterm
 - The Boolean results are transferred from a truth table onto a two-dimensional grid
 - Adjacent squares differ in the value of one variable (each square is ordered in Gray Code)
 - Alternative algebraic expressions for the same function are derived by recognizing patterns of squares
- The K-map can be viewed as
 - A reorganized version of the truth table
 - A clever way to rewrite truth tables to make it easier to figure out the logic.
 - A topologically-warped Venn diagram as used to visualize sets in algebra of sets

Some Uses of K-Maps

- Provide a means for:
 - Finding optimum or near optimum
 - SOP and POS standard forms, and
 - two-level AND/OR and OR/AND circuit implementations

for functions with 2 to 5 variables

- Visualizing concepts related to manipulating Boolean expressions, and
- Demonstrating concepts used by computeraided design programs to simplify large circuits

Steps to Minimize Expressions using K-map

- Step 1: Identify minterms or maxterms
- Step 2: Fill the K-map with minterms or maxterms
 - For SOM, put 1's in squares respective to the minterms
 - For POM, put 0's in squares respective to the maxterms
- Step 3: Form the rectangular groups containing maximum number of terms in power of two
- Step 4: Obtain the simplified expression for groups
 - For SOM, find the product terms and sum them up
 - For POM, find the sum terms and take product of them

Two Variable Maps

Example:

$$\mathbf{F}(\mathbf{x},\mathbf{y}) = \mathbf{m}_2 + \mathbf{m}_3$$
$$= \mathbf{x}\mathbf{\overline{y}} + \mathbf{x}\mathbf{y}$$

$\mathbf{F}(\mathbf{x},\mathbf{y})$	y = 0	y = 1
$\mathbf{x} = 0$	0	0
x = 1	1	1

For function F(x,y), the two adjacent cells containing 1's can be combined using the Minimization Theorem:

$$\mathbf{F}(\mathbf{x}, \mathbf{y}) = \mathbf{x} \, \mathbf{\overline{y}} + \mathbf{x} \, \mathbf{y} = \mathbf{x}$$

Two Variable Maps

Example:

$$G(\mathbf{x},\mathbf{y}) = \mathbf{m}_1 + \mathbf{m}_2 + \mathbf{m}_3$$
$$= \overline{\mathbf{x}}\mathbf{y} + \mathbf{x}\overline{\mathbf{y}} + \mathbf{x}\mathbf{y}$$

G(x,y)	y = 0	y = 1
$\mathbf{x} = 0$	0	1
x = 1	1	1

repeated term

 For G(x,y), two pairs of adjacent cells containing 1's can be combined using the Minimization Theorem:

$$G(x,y) = (\bar{x}y + xy) + (\bar{xy} + xy) = x + y$$

Duplicate xy

A three-variable K-map:

nap: 	yz=00	yz=01	yz=11	yz=10
x=0	\mathbf{m}_{0}	\mathbf{m}_1	m_3	\mathbf{m}_2
x=1	$\mathbf{m_4}$	m_5	\mathbf{m}_7	\mathbf{m}_{6}

Where each minterm corresponds to the product

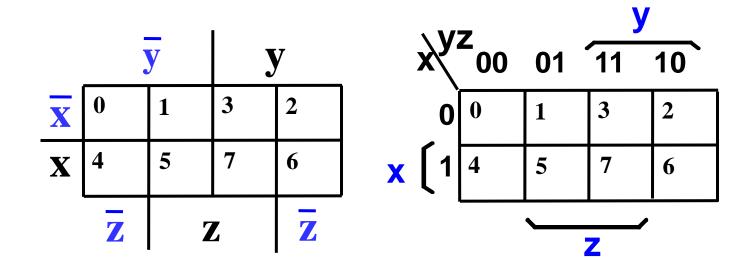
terms:

	yz=00	yz=01	yz=11	yz=10
x=0	$\overline{x}\overline{y}\overline{z}$	$\overline{x}\overline{y}z$	$-\mathbf{x}\mathbf{y}\mathbf{z}$	$\bar{x}y\bar{z}$
x=1	$x\overline{y}\overline{z}$	$x\overline{y}z$	хуz	x y z

 Note that if the binary value for an <u>index</u> differs in one bit position, the minterms are adjacent on the K-Map

Alternative Map Labeling

- Each K-map square can be addressed using a unique Gray code-labeling.
- Alternate labelings are useful:



Example Functions

By convention, we represent the minterms of F by a "1" in the map and leave the minterms of \overline{F} blank

• Example: $F(x, y, z) = \Sigma_m(2,3,4,5)$

			3	y
	0	1	³ 1	² 1
X	⁴ 1	⁵ 1	7	6
,		Z .		

Example:

$$G(a, b, c) = \Sigma_m(3,4,6,7)$$

Learn the locations of the 8 indices based on the variable order shown (x, most significant and z, least significant) on the map boundaries

			J	y
	0	1	³ 1	2
X	41	5	⁷ 1	⁶ 1
		Z		

Combining Squares

- By combining squares, we reduce number of literals in a product term, reducing the literal cost, thereby reducing the other two cost criteria.
- On a 3-variable K-Map:
 - One square represents a minterm with three variables
 - Two adjacent squares represent a product term with two variables
 - Four "adjacent" terms represent a product term with one variable
 - Eight "adjacent" terms is the function of all ones (no variables) = 1.

Example: Combining Squares

Example: Let $F = \Sigma m(2,3,6,7)$ \bar{y} y \bar{x} 0 1 31 21 \bar{z} \bar{z} \bar{z} \bar{z} \bar{z}

Applying the Minimization Theorem three times:

$$F(x,y,z) = \overline{x}y\overline{z} + \overline{x}yz + xy\overline{z} + xyz$$

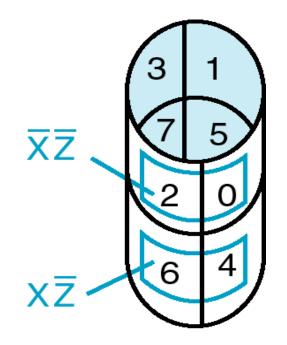
$$= \overline{x}y + xy$$

$$= v$$

Thus the four terms that form a 2×2 square correspond to the term "y".

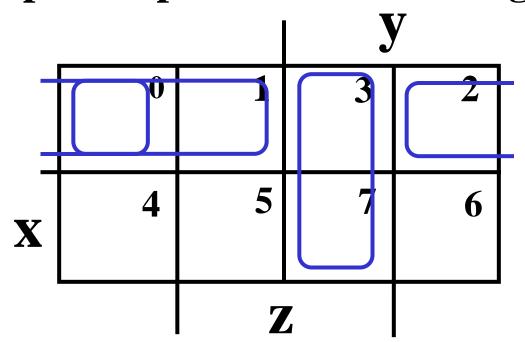
- Reduced literal product terms for SOP standard forms correspond to <u>rectangles</u> on K-maps containing cell counts that are powers of 2.
- Rectangles of 2 cells represent 2 adjacent minterms; Rectangles of 4 cells represent 4 minterms that form a "pairwise adjacent" ring.
- Rectangles can contain non-adjacent cells as illustrated by the "pairwise adjacent" ring above.

- Topological warps of 3-variable K-maps that show all adjacencies:
 - Cylinder



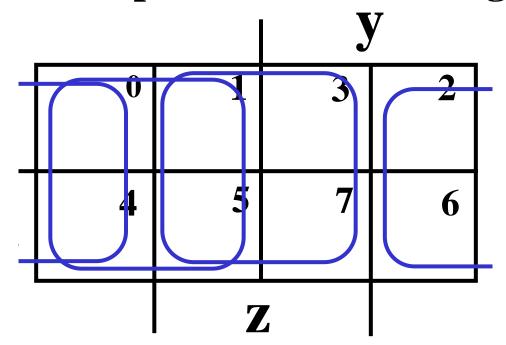
	y		3	y
X	⁰ 1	1	3	² 1
X	⁴ 1	5	7	⁶ 1
·	Z	Z		Z

Example Shapes of 2-cell Rectangles:



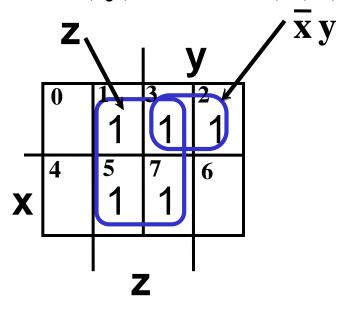
 Read off the product terms for the rectangles shown

Example Shapes of 4-cell Rectangles:



 Read off the product terms for the rectangles shown

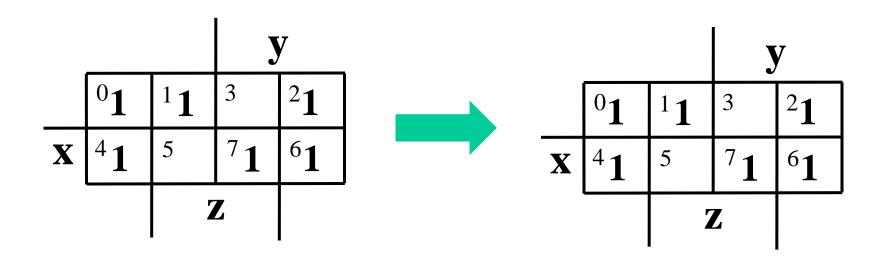
- K-Maps can be used to simplify Boolean functions by systematic methods. Terms are selected to cover the "1s" in the map.
- Example: Simplify $F(x, y, z) = \Sigma_m(1,2,3,5,7)$



$$F(x, y, z) = z + \overline{x} y$$

Three Variable Map Simplification

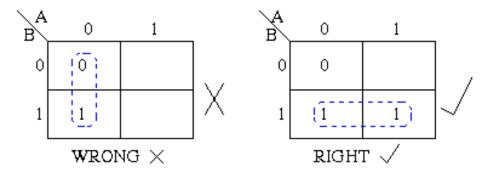
• Use a K-map to find an optimum SOP equation for $F(X, Y, Z) = \Sigma_m(0,1,2,4,6,7)$



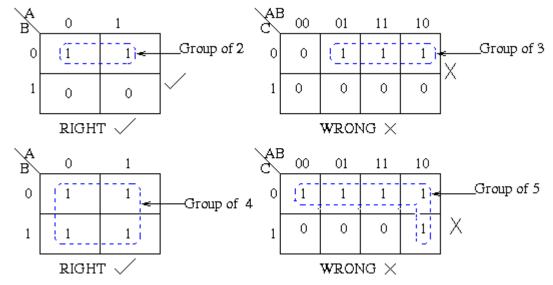
$$F(X, Y, Z) = \overline{Z} + \overline{X} \overline{Y} + XY$$

Pitfalls of Combining Squares (1/2)

No zeros allowed.

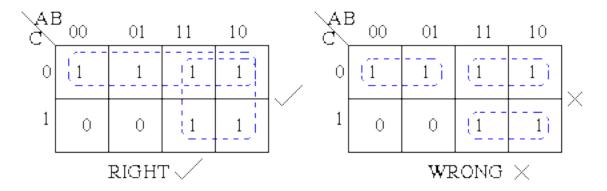


Only 2ⁿ number of squares in each group.

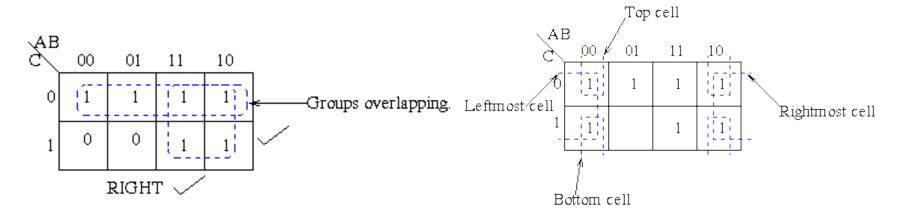


Pitfalls of Combining Squares (2/2)

Groups should be as large as possible.



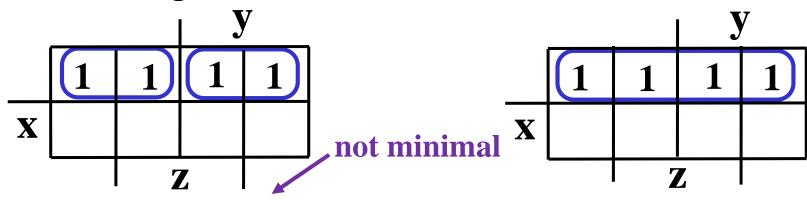
Groups may overlap.
 Wrap around allowed.



refer to: http://www.ee.surrey.ac.uk/Projects/Labview/minimisation/karrules.html

Questions about Combining Squares

- Why are only 2ⁿ number of squares considered in each group?
 - reducing 1 literal, needs 2 cells with X and \overline{X} ,
 - reducing 2 literals, needs 4 cells with \overline{XY} , \overline{XY} , \overline{XY} and \overline{XY} ,
 - therefore, reducing n literals, needs 2ⁿ cells.
- Why should each group be as large as possible?
 - reducing the number of variables to a minimum

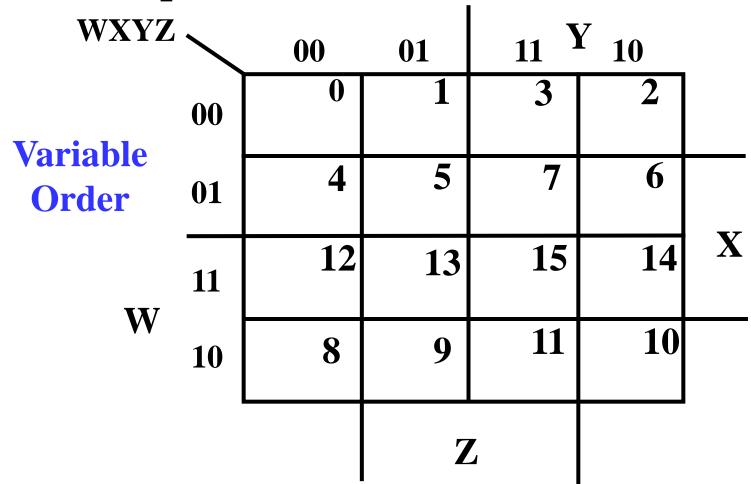


$$\mathbf{F}(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) = \overline{\mathbf{X}}\overline{\mathbf{Y}} + \overline{\mathbf{X}}\mathbf{Y} = \overline{\mathbf{X}}$$

$$\mathbf{F}(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) = \mathbf{X}$$

Four Variable Maps

Map and location of minterms:

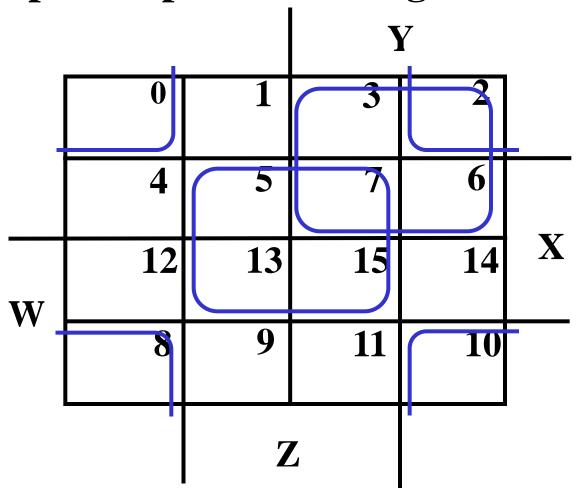


Four Variable Terms

- Four variable maps can have rectangles corresponding to:
 - A single 1 = 4 variables, (Minterm)
 - Two 1s = 3 variables,
 - Four 1s = 2 variables,
 - Eight 1s = 1 variable,
 - Sixteen 1s = zero variables (Constant "1")

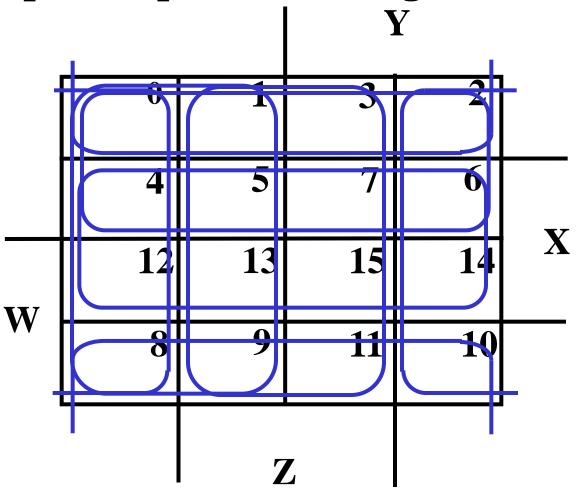
Four Variable Maps

Example Shapes of Rectangles:



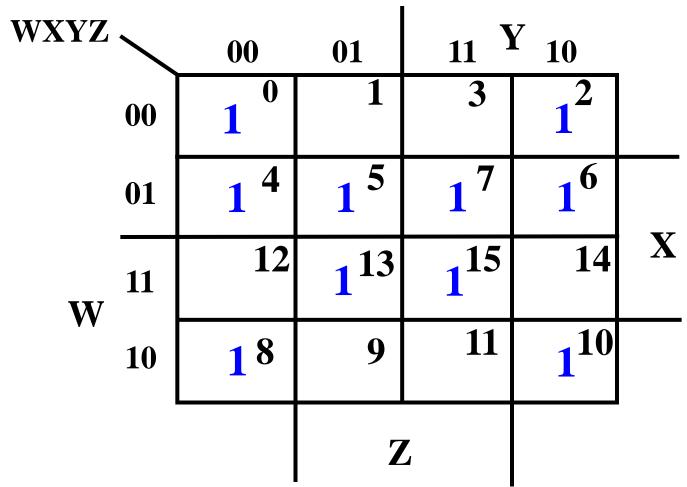
Four Variable Maps

Example Shapes of Rectangles:



Four Variable Map Simplification

 $^{\bullet}F(W, X, Y, Z) = \Sigma_{m}(0, 2, 4, 5, 6, 7, 8, 10, 13, 15)$



Four Variable Map Simplification

• $F(W, X, Y, Z) = \Sigma_m(3,4,5,7,9,13,14,15)$

WXYZ _	00	01	11	Y 10	
00	0	1	13	2	
01	1 4	15	1 7	6	
11	12	113	115	114	X
W 10	8	19	11	10	
•		7	Z		•

Five Variable Maps

25 Minterms, consists of 32 squares

		Gray Code order						
XYZ								
vw	000	001	011	010	110	111	101	100
00	0	1	3	2	6	7	5	4
01	8	9	11	10	14	15	13	12
11	24	25	27	26	30	31	29	28
10	16	17	19	18	22	23	21	20

5 variable K' Map: https://www.bilibili.com/video/BV1Nq4y1k71R? spm_id_from= 333.337.search-card.all.click

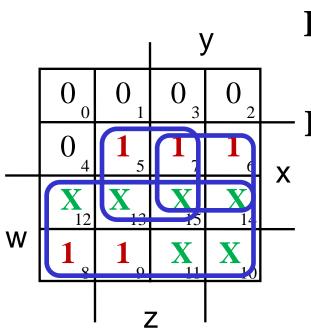
Don't Cares in K-Maps

- Sometimes a function table or map contains entries for which it is known:
 - The input values for the minterm will never occur, or
 - The output value for the minterm is not used
- In these cases, the output value need not be defined.
- The output value is defined as a "don't care" that may take on either a 0 or 1 value in resulting solutions.
- By placing "don't cares" (an "x" entry) in the function table or map, the cost of the logic circuit may be lowered.
- Example: A logic function having the binary codes for the BCD digits as its inputs. Only the codes for 0 through 9 are used. The six codes, 1010 through 1111 will never occur, so the output values for these codes are "don't cares."

Some input values will never occur!

Example: BCD "5 or More"

• Function F=(w,x,y,z) is defined as "5 or more" over BCD inputs (e.g., F(0011)=0, F(1001)=1). With the don't cares used for the 6 non-BCD combinations:



$$\mathbf{F_1}(\mathbf{w}, \mathbf{x}, \mathbf{y}, \mathbf{z}) = \overline{\mathbf{w}} \times \mathbf{z} + \overline{\mathbf{w}} \times \mathbf{y} + \mathbf{w} \overline{\mathbf{x}} \overline{\mathbf{y}}$$
(without don't cares) $\mathbf{G} = 12$

$$F_2(w,x,y,z) = w + x z + x y$$
(with don't cares) $G = 7$

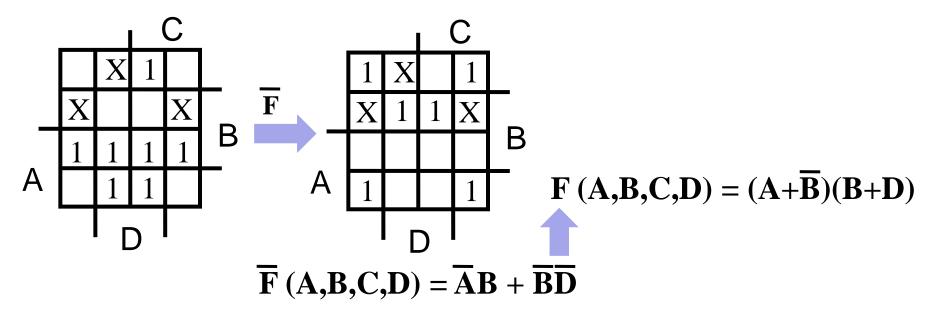
- F_2 is much lower in cost than F_1 where the "don't cares" were treated as "0s".
- For this particular function, cost G for the POS solution for $F_2(w,x,y,z)$ is not changed by using the don't cares.

Product of Sums Example

• Find the optimum **POS** solution:

$$F(A, B, C, D) = \sum_{m} (3,9,11,12,13,14,15) + \sum_{m} don't cares$$

• Hint: Use $\overline{\mathbf{F}}$ and complement it to get the result.



Encoding Schema and Optimization

Using binary and one-hot encodings to represent three elements (e.g., three primary colors):

Binary encoding

2-bit binary	X	Y	F 1	F2
ncoding	0	0	1	0
	0	1	0	1
	1	0	0	1
	1	1	V	V

$$\mathbf{F1}(\mathbf{X},\mathbf{Y}) = \mathbf{XY}$$

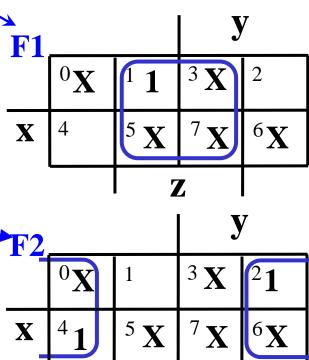
$$\mathbf{F2}(\mathbf{X},\mathbf{Y}) = \mathbf{X} + \mathbf{Y} \qquad \mathbf{F2}(\mathbf{X},\mathbf{Y},\mathbf{Z}) = \overline{\mathbf{Z}}$$

3-bit	One-hot encoding
one-hot	One-not encouring

X	Y	Z	F1	F2
0	0	1	1	0
0	1	0	0	1
1	0	0	0	1
X	X	X	X	X

$$\mathbf{F1} \ (\mathbf{X}, \mathbf{Y}, \mathbf{Z}) = \mathbf{Z}$$

$$F2 (X,Y,Z) = \overline{Z}$$



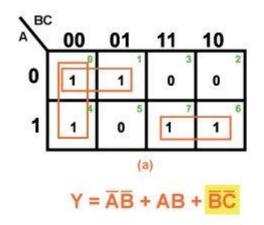
We can do one-hot design by inspection.

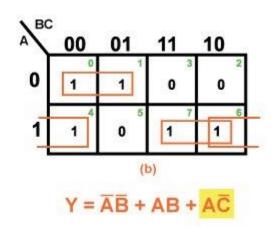
Advantages of K-Maps

- The K-map simplification technique is simpler and less error-prone.
- It prevents the need to remember each and every Boolean algebraic theorem.
- It involves fewer steps than the algebraic minimization technique to arrive at a simplified expression.
- K-map simplification technique always results in minimum expression if carried out properly.

Disadvantages of K-Maps

- As the number of variables in the logical expression increases, the K-map simplification process becomes complicated.
- The minimum logical expression may not be unique depending on the choices made while forming the groups.





K-map with a non-unique solution

Optimization Algorithm

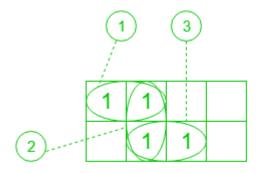
- Minimizing boolean functions by hand using the classical K-map is a laborious, tedious and error prone process.
- It isn't suited for more than six input variables and practical only for up to 5 variables, while product term sharing for multiple output functions is even harder to carry out.
- Moreover, this method doesn't lead itself to be automated in the form of a computer program.
- Demonstration: Truth Table Solver from: https://truthtablesolve.sourceforge.net

Example of Boolean Minimization

- Truth Table Solver is a program that solves the truth table and output all the possible minimized boolean expressions.
- It uses Quine-McCluskey algorithm (the method of prime implicants) for boolean minimization.
- Quine-McCluskey Solver: http://www.quinemccluskey.com

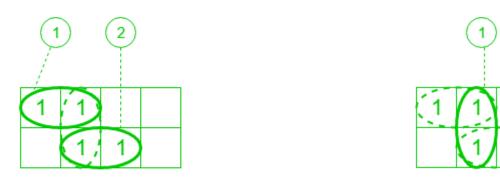
Systematic Simplification

- Implicant is a product in SOP or a sum in POS. For example: F = AB + ABC + BC. Implicants are AB, ABC and BC.
- In K-map, the implicant is a group containing 2ⁿ squares.
- There are two types of implicants: Prime Implicant and Essential Prime Implicant.
- A *Prime Implicant* is a product term obtained by combining the maximum possible number of adjacent squares in the map with 2ⁿ number of squares.



Systematic Simplification (1/2)

An *Essential Prime Implicant* is a prime implicant that covers one or more minterms that no combination of other prime implicants are able to include.

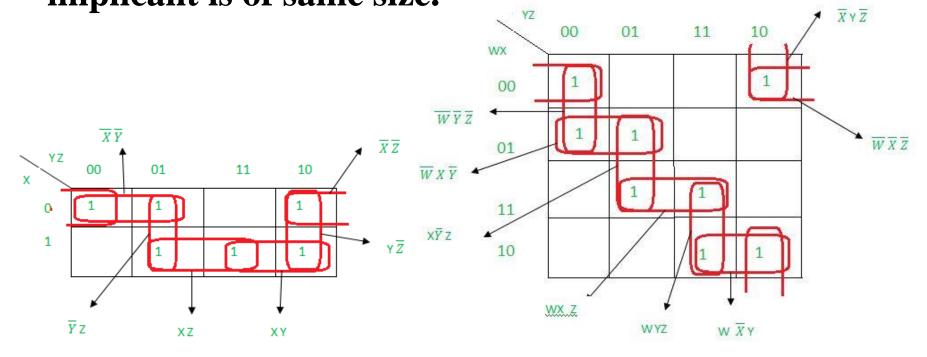


No. of Essential Prime Implicants = 2 No. of Redundant Prime Implicants = 1

A set of prime implicants "covers all minterms" if, for each minterm of the function, at least one prime implicant in the set of prime implicants includes the minterm.

Systematic Simplification (2/2)

However a cyclic Boolean function doesn't have Essential Prime Implicant. Every minterm is covered by at least two prime implicants and every prime implicant is of same size.

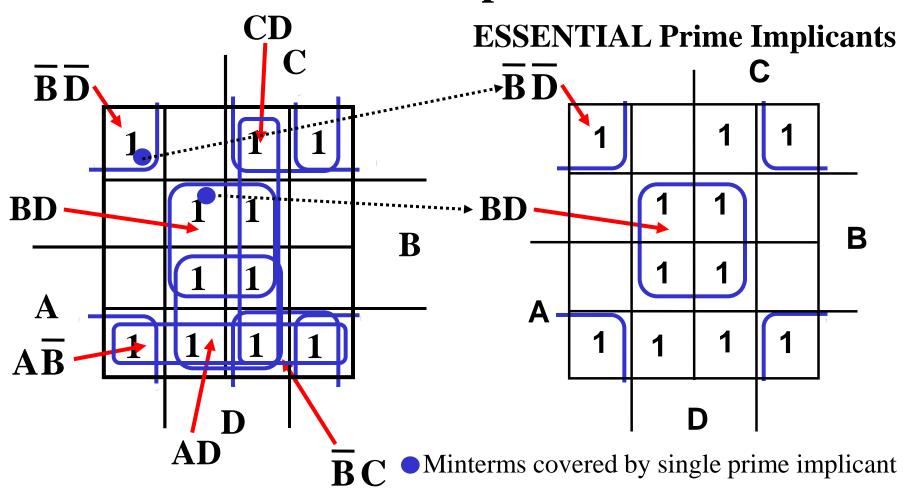


3 variables cyclic function

4 variables cyclic function

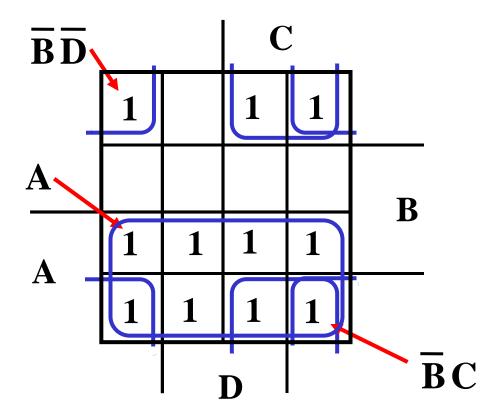
Example of Prime Implicants

Find ALL Prime Implicants



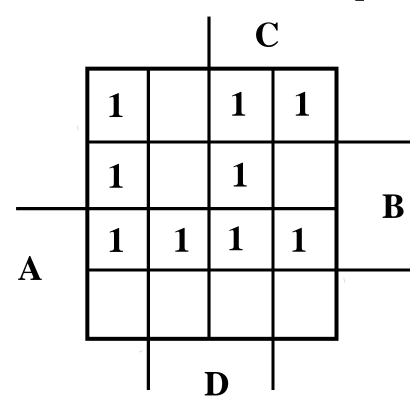
Prime Implicant Practice

• Find all prime implicants for: $F(A, B, C, D) = \Sigma_m(0,2,3,8,9,10,11,12,13,14,15)$



Another Example

- Find all prime implicants for: $G(A, B, C, D) = \Sigma_m(0,2,3,4,7,12,13,14,15)$
 - Hint: There are seven prime implicants!



Quine-McCluskey Algorithm

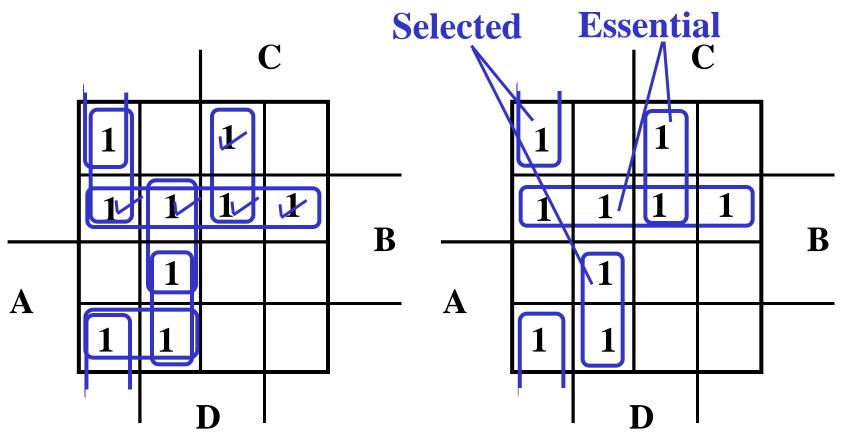
- Find <u>all</u> prime implicants.
- Include <u>all</u> essential prime implicants in the solution
- Select a minimum cost set of non-essential prime implicants to cover all minterms not yet covered:
 - Obtaining an optimum solution: See Reading Supplement - More on Optimization
 - Obtaining a good simplified solution: Use the Selection Rule
- Appendix C: Quine–McCluskey Solver

Prime Implicant Selection Rule

 Minimize the overlap among prime implicants as much as possible. In particular, in the final solution, make sure that each prime implicant selected includes at least one minterm not included in any other prime implicant selected.

Selection Rule Example

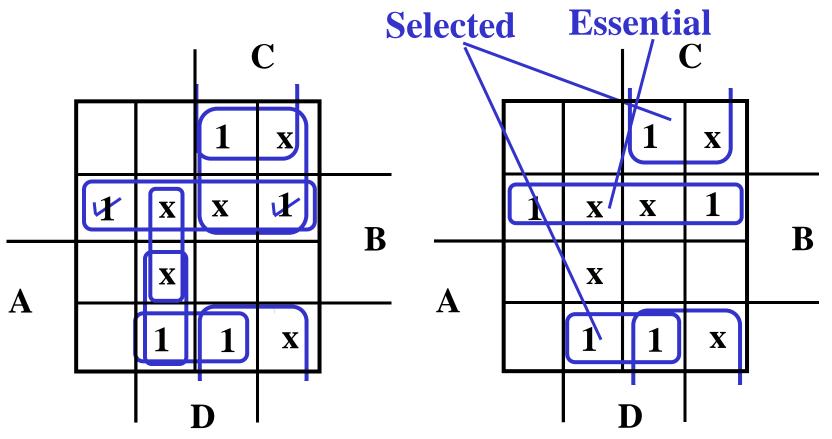
Simplify F(A, B, C, D) given on the K-map.



Minterms covered by essential prime implicants

Selection Rule Example with Don't Cares

Simplify F(A, B, C, D) given on the K-map.



Minterms covered by essential prime implicants

Multiple-Level Optimization

- Multiple-level circuits circuits that are not two-level (with or without input and/or output inverters)
- Multiple-level circuits can have reduced gate input cost compared to two-level (SOP and POS) circuits
- Multiple-level optimization is performed by applying transformations to circuits represented by equations while evaluating cost

Transformation Examples

- $F(A, B, C, D) = \sum_{m} (0, 4, 5, 10, 14, 15)$
- Algebraic Factoring

$$\mathbf{F} = \overline{\mathbf{A}} \, \overline{\mathbf{C}} \, \overline{\mathbf{D}} + \overline{\mathbf{A}} \, \mathbf{B} \, \overline{\mathbf{C}} + \mathbf{A} \mathbf{B} \mathbf{C} + \mathbf{A} \mathbf{C} \, \overline{\mathbf{D}} \qquad \mathbf{G} = \mathbf{16}$$

• Factoring:

$$F = \overline{A} (\overline{C} \overline{D} + B\overline{C}) + A (BC + C\overline{D}) G = 18$$

Factoring again:

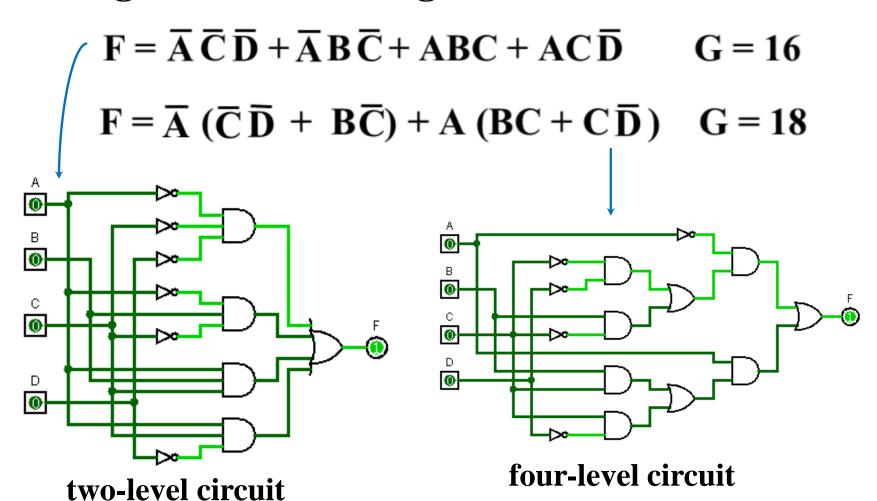
$$\mathbf{F} = \overline{\mathbf{A}} \ \overline{\mathbf{C}} (\mathbf{B} + \overline{\mathbf{D}}) + \mathbf{AC} (\mathbf{B} + \overline{\mathbf{D}})$$
 $\mathbf{G} = 12$

• Factoring again:

$$\mathbf{F} = (\overline{\mathbf{A}} \, \overline{\mathbf{C}} + \mathbf{AC}) \, (\mathbf{B} + \overline{\mathbf{D}}) \qquad \qquad \mathbf{G} = \mathbf{10}$$

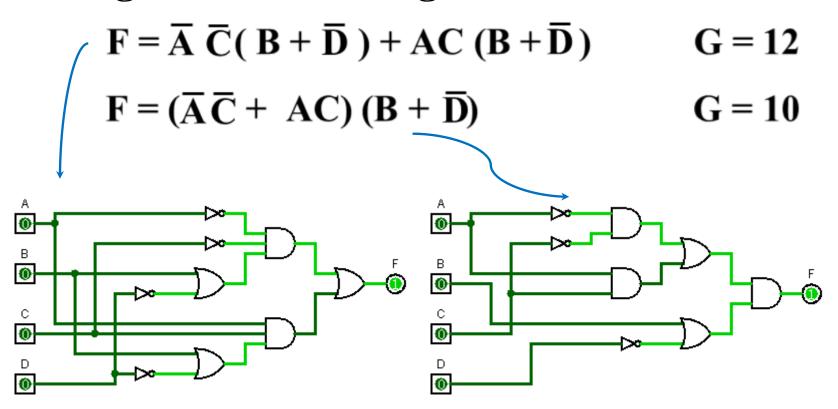
Transformation Examples

Algebraic Factoring



Transformation Examples

Algebraic Factoring



three-level circuit

three-level circuit

Overview

- Part 1 Gate Circuits and Boolean Equations
 - Binary Logic and Gates
 - Boolean Algebra
 - Standard Forms
- Part 2 Circuit Optimization
 - Two-Level Optimization
 - Map Manipulation
 - Practical Optimization
 - Multi-Level Circuit Optimization
- Part 3 Additional Gates and Circuits
 - Other Gate Types
 - Exclusive-OR Operator and Gates
 - High-Impedance Outputs

Other Gate Types

Why?

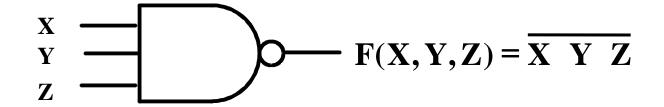
- Implementation feasibility and low cost
- Power in implementing Boolean functions
- Convenient conceptual representation

Gate classifications

- Primitive gate a gate that can be described using a single primitive operation type (AND or OR) plus an optional inversion(s).
- Complex gate a gate that requires more than one primitive operation type for its description
- Primitive gates will be covered first

NAND Gate

- The basic NAND gate has the following symbol, illustrated for three inputs:
 - AND-Invert (NAND)



NAND represents <u>NOT AND</u>, i. e., the AND function with a NOT applied. The symbol shown is an AND-Invert. The small circle ("bubble") represents the invert function.

NAND Gates (continued)

Applying DeMorgan's Law gives Invert-OR (NAND)

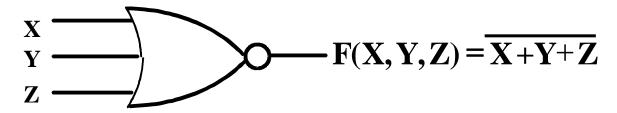
- This NAND symbol is called Invert-OR, since inputs are inverted and then ORed together.
- AND-Invert and Invert-OR both represent the NAND gate. Having both makes visualization of circuit function easier.
- A NAND gate with one input degenerates to an inverter.

NAND Gates (continued)

- The NAND gate is the natural implementation for CMOS technology in terms of chip area and speed.
- Universal gate a gate type that can implement any Boolean function.
- The NAND gate is a universal gate as shown in Figure 2-4 of the text.
- NAND usually does not have an operation symbol defined since
 - the NAND operation is not associative, and
 - we have difficulty dealing with non-associative mathematics!

NOR Gate

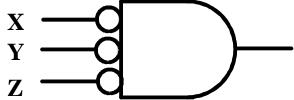
- The basic NOR gate has the following symbol, illustrated for three inputs:
 - OR-Invert (NOR)



NOR represents NOT - OR, i. e., the OR function with a NOT applied. The symbol shown is an OR-Invert. The small circle ("bubble") represents the invert function.

NOR Gate (continued)

 Applying DeMorgan's Law gives Invert-AND (NOR)



- This NOR symbol is called Invert-AND, since inputs are inverted and then ANDed together.
- OR-Invert and Invert-AND both represent the NOR gate. Having both makes visualization of circuit function easier.
- A NOR gate with one input degenerates to an inverter.

NOR Gate (continued)

- The NOR gate is a natural implementation for some technologies other than CMOS in terms of chip area and speed.
- The NOR gate is a universal gate
- NOR usually does not have a defined operation symbol since
 - the NOR operation is not associative, and
 - we have difficulty dealing with non-associative mathematics!

Other Gate Types

Name

 Other gate types aim to lower the cost and transmit time in circuit.

	snape symbol	equation	table
Exclusive-OR (XOR)	$X \longrightarrow F$	$F = X\overline{Y} + \overline{X}Y$ $= X \oplus Y$	X Y F 0 0 0 0 1 1 1 0 1 1 1 0
Exclusive–NOR (XNOR)	X Y F	$F = XY + \overline{X}\overline{Y}$ $= \overline{X \oplus Y}$	X Y F 0 0 1 0 1 0 1 0 0 1 1 1
AND-OR-INVERT (AOI)	W X Y Z F	$F = \overline{WX + YZ}$	
OR-AND -INVERT (OAI)	W T	$F = (\overline{W + X})(Y + \overline{Z})$	
AND-OR (AO)	W X Y Z	F = WX + YZ	
OR-AND (OA)	W X Y Z	F = (W + X)(Y + Z)	

Algebraic

equation

Truth

table

Distinctive

shape symbol

Exclusive OR/Exclusive NOR

- The *eXclusive OR (XOR)* function is an important Boolean function used extensively in logic circuits.
- The XOR function may be:
 - implemented directly as an electronic circuit (truly a gate) or
 - implemented by interconnecting other gate types (used as a convenient representation)
- The *eXclusive NOR* function is the complement of the XOR function
- XOR and XNOR gates are both complex gates.

Truth Tables for XOR/XNOR

Operator Rules: XOR

 $|\mathbf{y} = \mathbf{0}|\mathbf{y} = \mathbf{1}|$

0

 $\mathbf{x} = \mathbf{0}$

 $\mathbf{x} = \mathbf{1}$

	X	Y	X⊕Y
	0	0	0
_	0	1	1
	1	0	1

XNOR

X	Y	$\overline{(X \oplus Y)}$	
		or X≡Y	
0	0	1	
0	1	0	
1	0	0	
1	1	1	

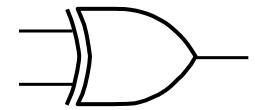
- The XOR function means: X OR Y, but NOT BOTH
- Why is the XNOR function also known as the equivalence function, denoted by the operator ≡?

Exclusive OR/ Exclusive NOR

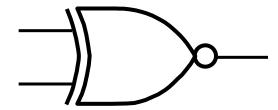
- Definitions
 - The XOR function is: $X \oplus Y = X \overline{Y} + \overline{X} Y$
 - The eXclusive NOR (XNOR) function, otherwise known as *equivalence* is: $\overline{X} \oplus \overline{Y} = XY + \overline{X} \overline{Y}$
- Uses for the XOR and XNORs gate include:
 - Adders/subtractors/multipliers
 - Counters/incrementers/decrementers
 - Parity generators/checkers
- Strictly speaking, XOR and XNOR gates do not exist for more than two inputs. Instead, they are replaced by odd and even functions.

Symbols For XOR and XNOR

XOR symbol:



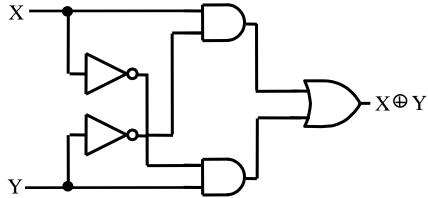
XNOR symbol:



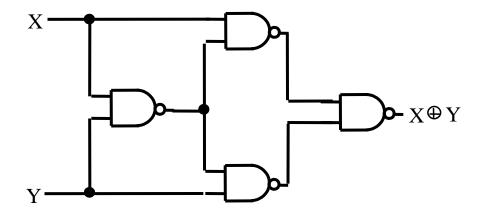
Shaped symbols exist only for two inputs

XOR Implementations

■ The simple SOP implementation uses the following structure: x—————



A NAND only implementation is:



XOR/XNOR (Continued)

The XOR identities:

$$X \oplus 0 = X$$
 $X \oplus \underline{1} = \overline{X}$
 $X \oplus X = 0$ $X \oplus \overline{X} = 1$
 $X \oplus Y = Y \oplus X$
 $(X \oplus Y) \oplus Z = X \oplus (Y \oplus Z) = X \oplus Y \oplus Z$

XOR and XNOR are associative operations.

Find the Element that Appears Once

- An array is consisting of integer numbers. Each number except one appears twice. The remaining number appears only once. How to find a number which occurs only once?
- Example: Suppose that an array contains values
 1, 4, 2, 1, 3, 4, 2. Find 3 that appears only once.

```
Function Singular(int a[], int Count)

value = 0

for i = 0, Count-1

value = value \(\phi\) a[i]

return value
```

- using 4 XOR identities
- **✓** commutative law
- ✓ associative law
- $\checkmark X \oplus X = 0$
- $\checkmark X \oplus 0 = X$

XOR/XNOR (Continued)

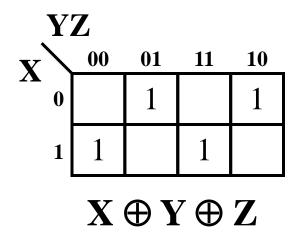
The XOR function can be extended to 3 or more variables. For more than 2 variables, it is called an *odd function* or *modulo 2 sum* (*Mod 2 sum*), not an XOR:

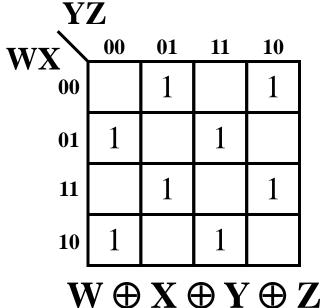
$$X \oplus Y \oplus Z = \overline{X} \overline{Y} Z + \overline{X} Y \overline{Z} + X \overline{Y} \overline{Z} + X Y Z$$

 The complement of the odd function is the even function.

Odd and Even Functions

The odd and even functions on a K-map form "checkerboard" patterns.



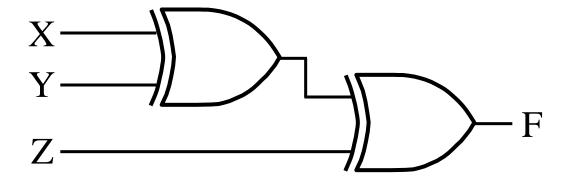


Odd and Even Functions (continued)

- The 1s of an odd function correspond to minterms having an index with an odd number of 1s.
- The 1s of an even function correspond to minterms having an index with an even number of 1s.
- Implementation of odd and even functions for greater than four variables as a two-level circuit is difficult, so we use "trees" made up of:
 - 2-input XOR or XNORs
 - 3- or 4-input odd or even functions

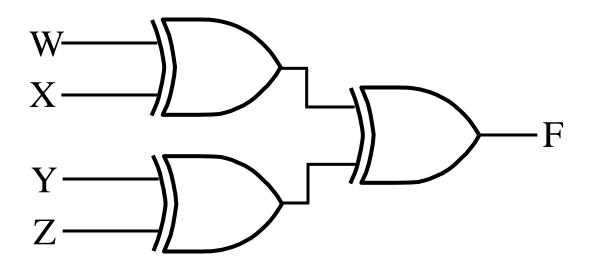
Example: Odd Function Implementation

- Design a 3-input odd function $F = X \oplus Y \oplus Z$ with 2-input XOR gates
- Factoring, $F = (X \oplus Y) \oplus Z$
- The circuit:

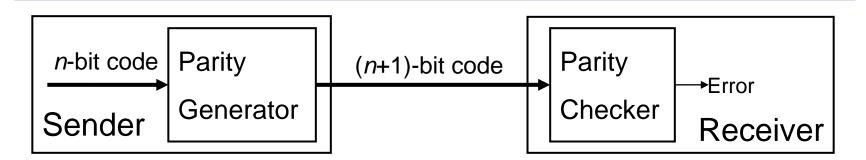


Example: Odd Function Implementation

- Design a 4-input odd function $F = W \oplus X \oplus Y \oplus Z$ with 2-input XOR gates
- Factoring, $F = (W \oplus X) \oplus (Y \oplus Z)$
- The circuit:



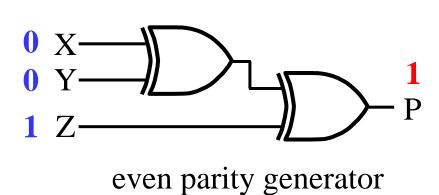
Parity Generator & Checkers

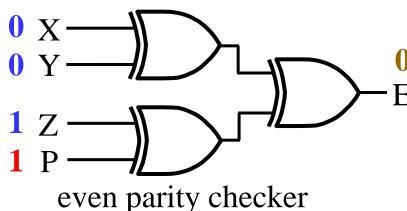


- Even Parity bit: count of 1s in (n+1)-bit code is even
 - So use an odd function to generate the even parity bit
- To check for even parity
 - Use an odd function to check the (n+1)-bit code
- Odd Parity bit: count of 1s in (n+1)-bit code is odd
 - So use an even function to generate the odd parity bit
- To check for odd parity
 - Use an even function to check the (n+1)-bit code

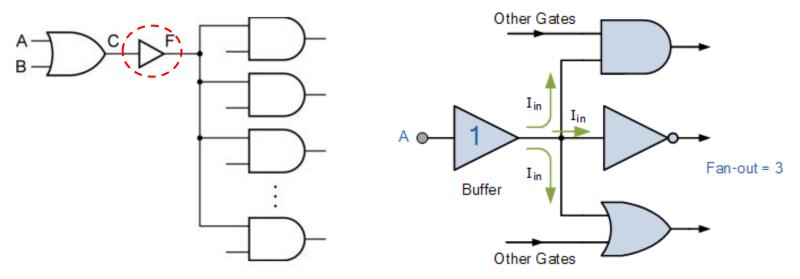
Parity Generator & Checkers

- Design an even parity generator and checker for 3-bit codes
- Solution: Use 3-bit odd function to generate even parity bit
- Use 4-bit odd function to check for errors in even parity codes
- Operation: (X,Y,Z) = (0,0,1) gives (X,Y,Z,P) = (0,0,1,1) and E = 0
- If Y changes from 0 to 1 between generator and checker, then E = 1 indicates an error

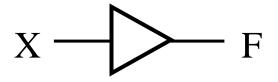




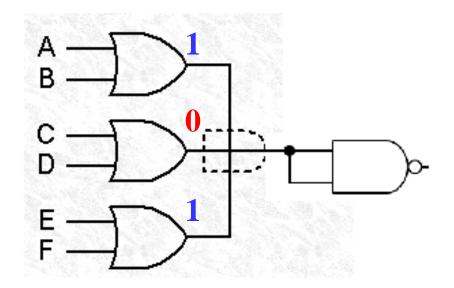
Buffer



- A buffer is an electronic amplifier used to improve circuit voltage levels and increase the speed of circuit operation.
- The buffer is a gate with the function F = X



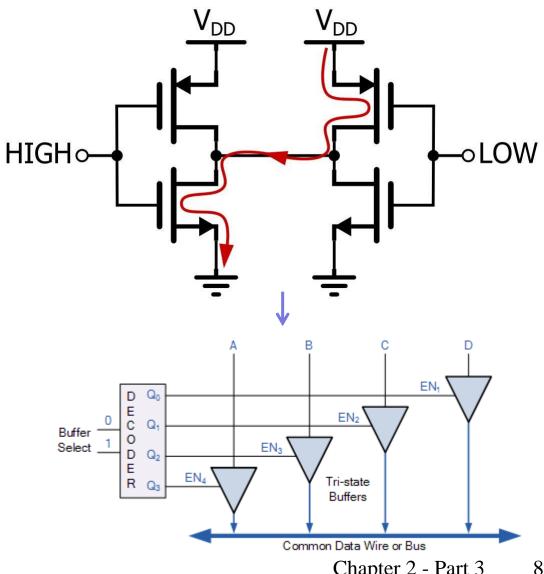
Wired Output



- Can we connect the output of multiple gates together?
- Logic gates introduced thus far ...
 - Have 1 and 0 output values
 - Cannot have their outputs connected together

Wired Output (continued)

In the case of two inverters wired together, if one is logic high and the other is logic low, the current will flow freely from VDD to ground!



The 3-State Buffer

- Three-state logic adds a third logic value:
 - Hi-Impedance output: Hi-Z

- open Q = Z

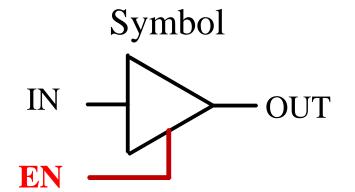
 A Closed Q = A

 Enable = "0"

 Enable = "1"
- What is Hi-Impedance output?
 - The output appears to be disconnected from the input
 - Behaves as an open circuit between gate input & output
- Hi-Z state makes a gate output behave differently:
 - Three output values: 1, 0, and Hi-Z
 - Hi-impedance gates can connect their outputs together

The 3-State Buffer

- IN = data input
- EN = Enable control input
- OUT = data output
- If EN = 0, then OUT = Hi-Z
 - Regardless of the value on IN
 - Output disconnected from input
- If EN = 1, then OUT =IN
 - Output follows the input value
- Variations:
 - EN can be inverted
 - OUT can be inverted
 - By addition of bubbles to signals

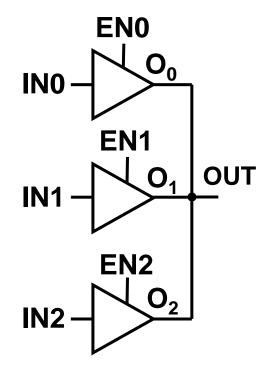


Truth Table

EN	IN	OUT
0	X	Hi-Z
1	0	0
1	1	1

The 3-State Buffer: Resolving Output Value

- The output of 3-state buffers can be wired together
- At most one 3-state buffer can be enabled. Resolved output is equal to the output of the enabled 3-state buffer
- If multiple 3-state buffers are enabled at the same time then conflicting outputs will burn the circuit

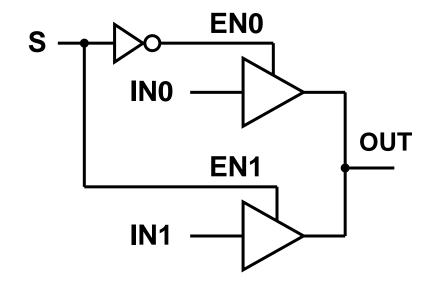


Resolution Table			
\mathbf{O}_0	\mathbf{O}_1	$\mathbf{O_2}$	OUT
0 or 1	Hi-Z	Hi-Z	O 0
Hi-Z	0 or 1	Hi-Z	01
Hi-Z	Hi-Z	0 or 1	O2
Hi-Z	Hi-Z	Hi-Z	Hi-Z
0 or 1	0 or 1	0 or 1	Burn

Data Selection Circuit

- Performing data selection with 3-state buffers:
 - If S = 0 then OUT = IN0 else OUT = IN1

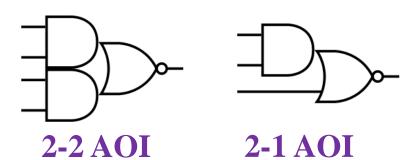
S	EN0	EN1	IN0	IN1	OUT
0	1	0	0	X	0
0	1	0	1	X	1
1	0	1	X	0	0
1	0	1	X	1	1



- The outputs of the 3-state buffers are wired together
- Since $EN0 = \overline{S}$ and EN1 = S, one of the two buffer outputs is always Hi-Z

More Complex Gates

- The remaining complex gates are SOP or POS structures with and without an output inverter.
- The names are derived using:
 - A AND
 - O OR
 - I Inverter



• Numbers of inputs on first-level "gates" or directly to second-level "gates"

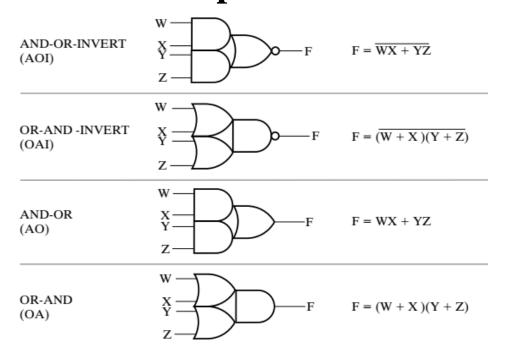
More Complex Gates (continued)

Example: 2-2 AOI consists of two 2-input ANDS driving an OR function which is inverted.

$$F = WX + YZ$$

 Example: 2-2-1 AO has two 2-input ANDS driving an OR with one additional OR input.

$$F = WX + YZ + V$$



Assignments

Reading:

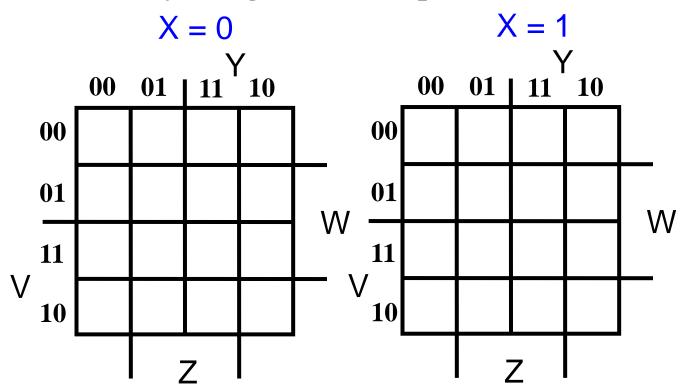
2.4-2.6

Problem assignment:

2-15c; 2-17b; 2-19a; 2-22a; 2-25b

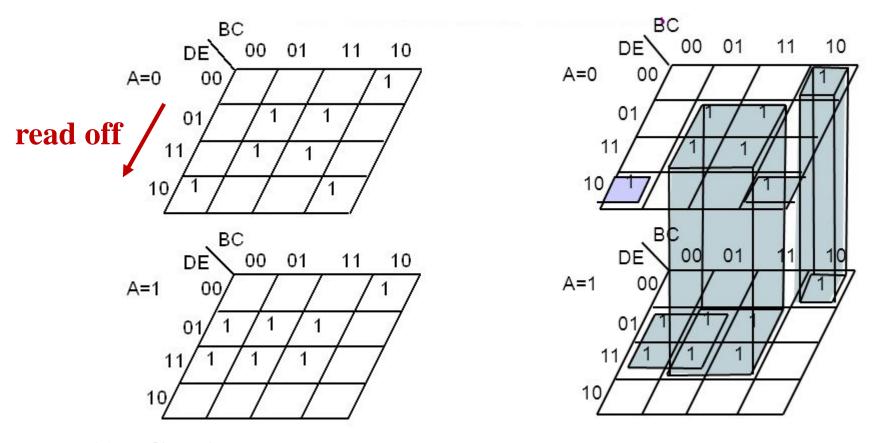
Appendix A: Five Variable Maps

• For five variable problems, we use two adjacent K-maps. It becomes harder to visualize adjacent minterms for selecting PIs. You can extend the problem to six variables by using four K-Maps.



Five Variable Maps

The overlay mode of the Karnaugh map

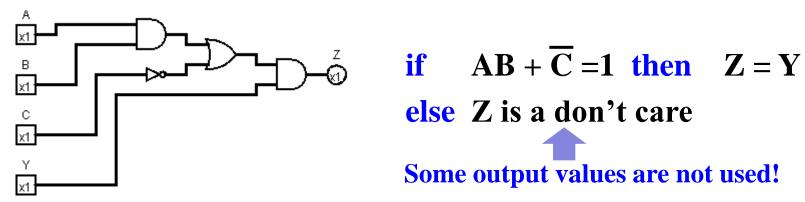


 $\mathbf{F(ABCDE)} = \sum_{m} (2, 5, 7, 8, 10, 13, 15, 17, 19, 21, 23, 24, 29, 31)$

$$F(ABCDE) = CE + A\overline{B}E + B\overline{C}\overline{D}\overline{E} + \overline{A}\overline{C}D\overline{E}$$

Appendix B: Don't Cares in K-Maps

Example 2: A circuit that represents a very common situation that has two distinct sets of input variables and a single output Z:

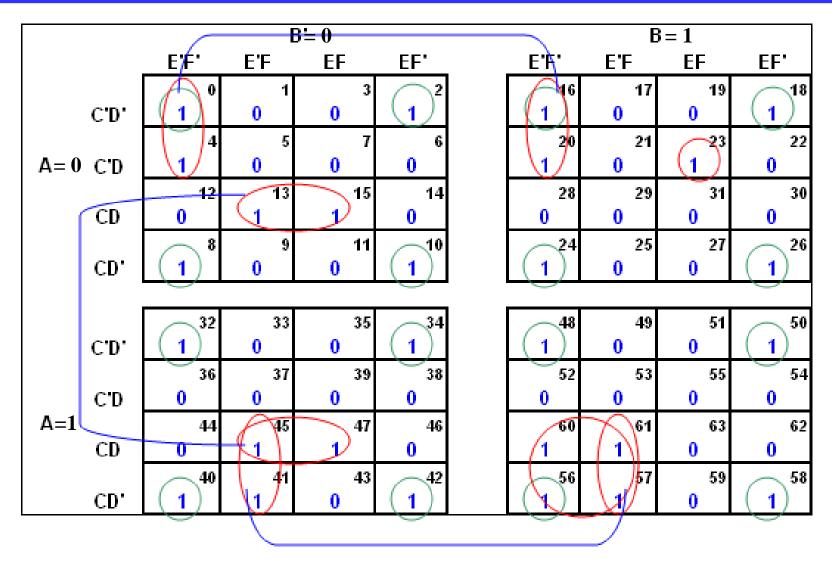


- A, B, and C which take on all possible combinations, and
- Y which takes on values 0 or 1.

The circuit that receives the input Y observes it only for combinations of A, B, and C such A = 1 and B = 1 or C = 0, otherwise ignoring it.

- Thus, Z is specified only for those combinations, and for all other combinations of A, B, and C, Z is a don't care.
- Any minterm with value "x" need not be covered by a prime implicant.

Appendix C: Six Variable Maps



Appendix D: Quine-McCluskey Solver

- Quine-McCluskey Solver http://www.quinemccluskey.com/
- Input
- Comparasion
- Prime Implicants
- Coverage Table
- **Essential Prime Implicants**

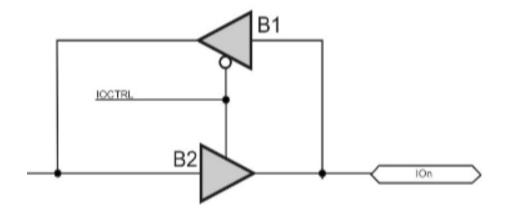
Resolving 3-State Values on a Connection

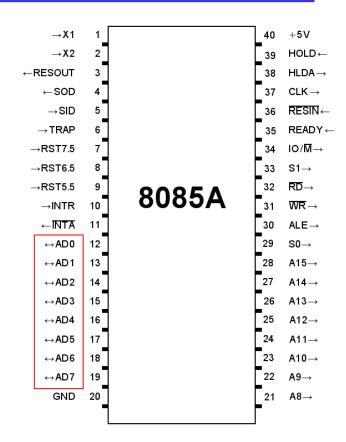
- Connection of two 3-state buffer outputs, B1 and B0, to a wire, OUT
- Assumption: Buffer data inputs can take any combination of values (0/1)
- Resulting Rule: At least one buffer output value must be Hi-Z.
- How many valid buffer output combinations exist?
- What is the rule for *n* 3-state buffers connected to wire, OUT?
 - n-1 buffer outputs must be Hi-Z
- How many valid buffer output combinations exist?

Resolution Table			
B 1	B 0	OUT	
0	Hi-Z	0	
1	Hi-Z	1	
Hi-Z	0	0	
Hi-Z	1	1	
Hi-Z	Hi-Z	Hi-Z	

Appendix E: Bidirectional

- Bidirectional means the data incoming and outgoing data flows over the same channel.
- 3-state buffers are always used to create bidirectional.



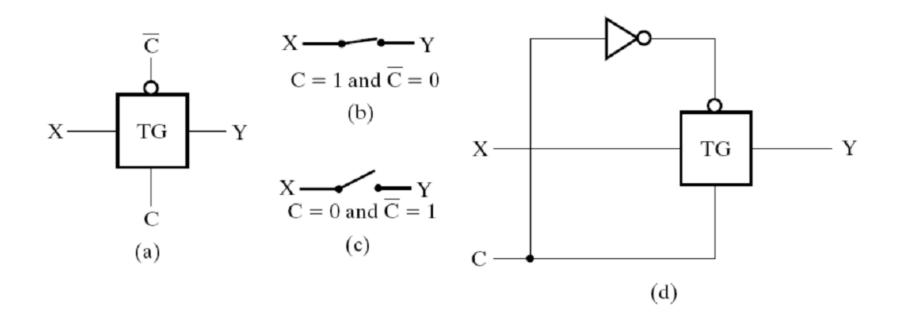


Pin 12-19

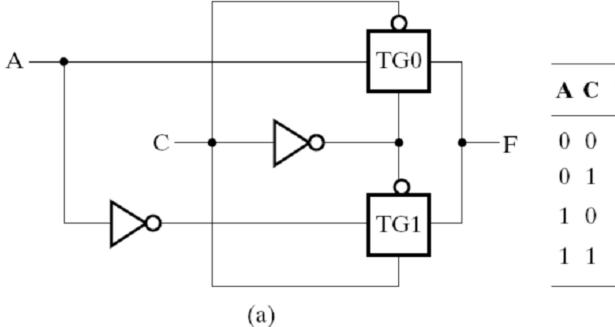
- multiplexed addr/data bus
- bidirectional

Appendix F: Transmission gate

A transmission gate is similar to a relay that can conduct in both directions or block by a control signal with almost any voltage potential.



XOR Function with transmission gate



A	C	TG1	TG0	F
0	0	No path	Path	0
0	1	Path	No path	1
1	0	No path	Path	1
1	1	Path	No path	0
(b)				