### CH08-320201

# Algorithms and Data Structures ADS

Lecture 25

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# Linear Programming<sup>1</sup>

- ► Important tool for optimal allocation of scarce resources, among a number of competing activities.
- ▶ Powerful and general problem-solving method.
- Applications:
  - Computer science: Compiler register allocation, data mining.
  - ► Electrical engineering: VLSI design, optimal clocking.
  - ► Economics: Equilibrium theory, two-person zero-sum games.
  - ▶ Environment: Water quality management.
  - ▶ Logistics: Supply-chain management, Berlin airlift.
  - Manufacturing: Production line balancing, cutting stock.
  - ► Telecommunication: Network design, Internet routing.

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<sup>&</sup>lt;sup>1</sup>Source of slides: Kevin Wayne: Algorithms and Data Structures, Spring 2004, Princeton University

## Brewery Problem: A Toy LP Example

Small brewery produces ale and beer.

- Production limited by scarce resources: corn, hops, malt.
- Recipes for ale and beer require different proportions of resources.

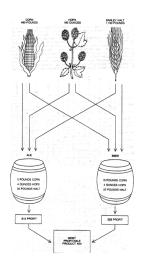
Beverage	Corn (pounds)	Hops (ounces)	Malt (pounds)	Profit (\$)
Ale	5	4	35	13
Beer	15	4	20	23
Quantity	480	160	1190	

How can brewer maximize profits?

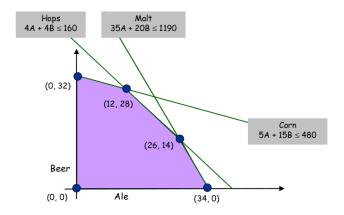
- ▶ Devote all resources to ale: 34 barrels of ale → \$442.
- ▶ Devote all resources to beer: 32 barrels of beer  $\rightarrow$  \$736.
- ▶ 7.5 barrels of ale, 29.5 barrels of beer  $\rightarrow$  \$776.
- ▶ 12 barrels of ale, 28 barrels of beer  $\rightarrow$  \$800.

## **Brewery Problem**

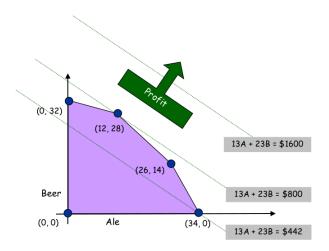




# Brewery Problem: Feasible Region

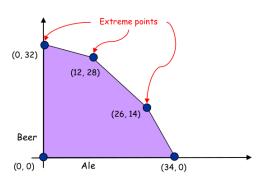


# Brewery Problem: Objective Function



## Brewery Problem: Geometry

Observation: Regardless of objective function coefficients, an optimal solution occurs at an extreme point.



## Linear Programming: Standard Form

#### Standard form:

- ▶ Input: real numbers  $c_j$ ,  $b_i$ ,  $a_{ij}$ .
- $\triangleright$  Output: real numbers  $x_i$ .
- ▶ n = # nonnegative variables, m = # constraints.
- Maximize linear objective function subject to linear inequalities.

(P) 
$$\max \sum_{j=1}^{n} c_j x_j$$
  
s.t.  $\sum_{j=1}^{n} a_{ij} x_j = b_i \quad 1 \le i \le m$   
 $x_j \ge 0 \quad 1 \le j \le n$ 

(P) 
$$\max c^T x$$
  
s.t.  $Ax = b$   
 $x \ge 0$ 

Linear: No  $x^2$ , xy, arccos(x), etc.

Programming: Planning (term predates computer programming).

## Brewery Problem: Converting to Standard Form

#### Original input:

#### Standard form:

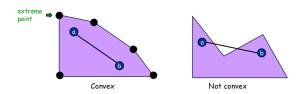
- Add slack variable for each inequality.
- Now a 5-dimensional problem.

## Geometry (1)

#### Geometry:

- Inequalities : halfplanes (2D), hyperplanes.
- Bounded feasible region: convex polygon (2D), (convex) polytope.

Convex: if a and b are feasible solutions, then so is (a + b)/2. Extreme point: feasible solution x that cannot be written as (a + b)/2 for any two distinct feasible solutions a and b.



## Geometry (2)

Extreme point property: If there exists an optimal solution to (P), then there exists one that is an extreme point.

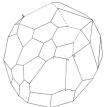
- Only need to consider finitely many possible solutions.

Challenge: Number of extreme points can be exponential.

- Consider *n*-dimensional hypercube.

Greedy: Local optima are global optima.

- Extreme point is optimal if no neighboring extreme point is better.



## Simplex Algorithm

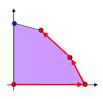
Simplex algorithm: (George Dantzig, 1947)

- ▶ Developed after WWII in response to logistical problems.
- ▶ Used for 1948 Berlin airlift.

#### Generic algorithm:

- Start at some extreme point.
- Pivot from one extreme point to a neighboring one. (never decrease objective function)
- Repeat until optimal.

How to implement? Linear algebra.

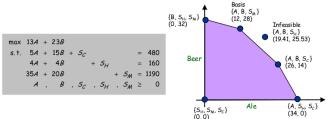


## Simplex Algorithm: Basis

Basis: Subset of m of the n variables.

Basic feasible solution (BFS): Set n-m nonbasic variables to 0, solve for remaining m variables.

- Solve m equations in m unknowns.
- If unique and feasible solution → BFS.
- BFS corresponds to extreme point.
- Simplex only considers BFS.



# Simplex Algorithm: Pivot 1 (1)

Basis = 
$$\{S_C, S_H, S_M\}$$
  
A = B = 0  
Z = 0  
 $S_C$  = 480  
 $S_H$  = 160  
 $S_M$  = 1190

Substitute:  $B = 1/15 (480 - 5A - S_c)$ 

Basis = {B,  $S_H$ ,  $S_M$ }  $A = S_c = 0$  Z = 736 B = 32  $S_H = 32$  $S_M = 550$ 

# Simplex Algorithm: Pivot 1 (2)

```
Basis = \{S_C, S_H, S_M\}

A = B = 0

Z = 0

S_C = 480

S_H = 160

S_M = 1190
```

#### Why pivot on column 2?

- ► Each unit increase in *B* increases objective value by \$23.
- Pivoting on column 1 also OK.

#### Why pivot on row 2?

- ▶ Preserves feasibility by ensuring  $RHS \ge 0$ .
- ▶ Minimum ratio rule: min{480/15, 160/4, 1190/20}.

## Simplex Algorithm: Pivot 2

Basis = {B, 
$$S_H$$
,  $S_M$ }  
 $A = S_C = 0$   
 $Z = 736$   
 $B = 32$   
 $S_H = 32$   
 $S_M = 550$ 

Substitute:  $A = 3/8 (32 + 4/15 S_c - S_H)$ 

Basis =  $\{A, B, S_{\mu}\}$ 

## Simplex Algorithm: Optimality

When to stop pivoting?

▶ If all coefficients in top row are non-positive.

Why is resulting solution optimal?

- Any feasible solution satisfies system of equations in tableaux.
  - in particular:  $Z = 800 S_C 2S_H$
- ▶ Thus, optimal objective value  $Z^* \le 800$  since  $S_C, S_H \ge 0$ .
- ► Current BFS has value 800 → optimal.

Basis = {A, B, 
$$S_M$$
}  
 $S_C = S_H = 0$   
 $Z = 800$   
 $B = 28$   
 $A = 12$   
 $S_M = 110$ 

## Simplex Algorithm: Issues

Remarkable property: In practice, simplex algorithm typically terminates in at most 2(m + n) pivots.

- ▶ No polynomial pivot rule known.
- ▶ Most pivot rules known to be exponential in worst-case.

Issues: Which neighboring extreme point?

Degeneracy: New basis, same extreme point.

"Stalling" is common in practice.

Cycling: Get stuck by cycling through different bases that all correspond to same extreme point.

- Does not occur in the wild.
- ▶ Bland's least index rule → finite # of pivots.