问题2

分别计算两种情况的最大输出功率及相应的最优阻尼系数

```
In [1]: # TODO import
        import re
        import os
        import sys
        import hmz
        import pathlib
        import mitosheet
        import numpy as np
        import pandas as pd
        import matlab.engine
        import scipy
        from scipy.integrate import odeint
        from scipy.optimize import minimize
        import time
        from time import time, sleep
        import copy
        import random
        import sympy
        from sympy import limit
        from sympy import diff
        from sympy import integrals
        import sklearn
        import graphviz
        from sklearn import tree
        from sklearn.model_selection import cross_val_score
        from sklearn.model selection import train test split
        from sklearn.metrics import r2_score
        from sklearn.metrics import mean_squared_error as MSE
        from sklearn.metrics import mean_absolute_error as MAE
        from sklearn.metrics import classification_report, roc_auc_score
        import sko
```

```
from sko.GA import GA
import numba
from numba import jit
import plotly
import plotly.express as px
import plotly.graph objects as go
import plotly.figure factory as ff
plotly.offline.init notebook mode()
import cufflinks as cf
cf.set config file(
    offline=True,
   world readable=True,
    theme='pearl', # cf.getThemes()
import matplotlib.pyplot as plt
plt.rcParams['font.sans-serif'] = ['SimHei'] # KaiTi
plt.rcParams['axes.unicode minus'] = False
from IPython.core.interactiveshell import InteractiveShell
InteractiveShell.ast node interactivity = 'all'
# InteractiveShell.ast_node_interactivity = 'last'
import cv2 as cv
# import torch
# import torchvision
# import torch.nn as nn
# import torch.nn.functional as F
# import torch.utils.data as Data
# from torch.utils.data import DataLoader
# from torch.utils.data.dataset import Dataset
import pylatex
import latexify
import warnings
warnings.filterwarnings("ignore")
```

```
# from colorama.Fore import RED, RESET
from colorama import Fore
import logging
fmt = '%(asctime)s - %(levelname)8s - %(message)s'
formatter = logging.Formatter(fmt)
handler control = logging.StreamHandler() # stdout to console
handler control.setLevel('INFO') # 设置 INFO 级别
handler control.setFormatter(formatter)
logger = logging.getLogger()
# logger.setLevel('INFO')
logger.addHandler(handler control)
def timeit(text):
    def func deco(func):
       """ 用来计时的装饰器函数 """
        def func wrapper(*args, **kwargs):
           from time import time
           t0 = time()
             Logging.info(text + "开始计时")
           print(Fore.RED, text + "开始计时: ", Fore.RESET)
           res = func(*args, **kwargs)
           t1 = time()
             logging.info(text + "用时: " + str(t1 - t0) + "s")
           print(Fore.RED, text + "结束计时, 用时: ", str(t1 - t0), "s", Fore.RESET)
           return res
        return func wrapper
   return func_deco
```

```
In [3]: # TODO DIR
ROOTDIR = pathlib.Path(os.path.abspath('.'))
IMG_HTML = ROOTDIR / 'img-html'
IMG_SVG = ROOTDIR / 'img-svg'
DATA_RAW = ROOTDIR / 'data-raw'
DATA_COOKED = ROOTDIR / 'data-processed'
```

```
In [4]: # TODO 附件4参数

浮子质量 = 4866 # kg

浮子底半径 = 1 # m

浮子圆柱部分高度 = 3 # m

浮子圆锥部分高度 = 0.8 # m

振子质量 = 2433 # kg

振子半径 = 0.5 # m

振子高度 = 0.5 # m

海水的密度 = 1025 # kg/m^3

重力加速度 = 9.8 # m/s^2
```

```
弹簧刚度 = 80000 # N/m
弹簧原长 = 0.5 # m
扭转弹簧刚度 = 250000 # N·m
静水恢复力矩系数 = 8890.7 # N·m
```

In [5]: # TODO 附件3参数 class question1234: """设置具体问题几的参数""" def init (self, question): global 入射波浪频率 global 垂荡附加质量 global 纵摇附加转动惯量 global 垂荡兴波阻尼系数 global 纵摇兴波阻尼系数 global 垂荡激励力振幅 global 纵摇激励力矩振幅 global 波浪频率 global 波浪周期 if question == 1: # 问题1: 参数 # 纵摇附加转动惯量 = 6779.315 # kg·m^2 # 纵摇兴波阻尼系数 = 151.4388 # N·m·s # 纵摇激励力矩振幅 = 1230 # N·m 纵摇附加转动惯量 = None # 问题1未使用,为避免使用/误用,初始化为 None 纵摇兴波阻尼系数 = None # 问题1未使用,为避免使用/误用,初始化为 None 纵摇激励力矩振幅 = None # 问题1未使用,为避免使用/误用,初始化为 None 入射波浪频率 = 1.4005 # s^{-1} 垂荡附加质量 = 1335.535 # kg 垂荡兴波阻尼系数 = 656.3616 # N·s/m 垂荡激励力振幅 = 6250 # N 波浪频率 = 入射波浪频率 波浪周期 = 1 / 波浪频率 elif question == 2: # 问题2: 参数 # 纵摇附加转动惯量 = 7131.29 # 纵摇兴波阻尼系数 = 2992.724 # 纵摇激励力矩振幅 = 2560 纵摇附加转动惯量 = None # 问题2未使用,为避免使用/误用,初始化为 None 纵摇兴波阻尼系数 = None # 问题2未使用,为避免使用/误用,初始化为 None 纵摇激励力矩振幅 = None # 问题2未使用,为避免使用/误用,初始化为 None 入射波浪频率 = 2.2143 垂荡附加质量 = 1165.992 垂荡兴波阻尼系数 = 167.8395

垂荡激励力振幅 = 4890

```
波浪频率 = 入射波浪频率
         波浪周期 = 1 / 波浪频率
      elif question == 3:
         # 问题3: 参数
         入射波浪频率 = 1.7152
         垂荡附加质量 = 1028.876
         纵摇附加转动惯量 = 7001.914
         垂荡兴波阻尼系数 = 683.4558
         纵摇兴波阻尼系数 = 654.3383
         垂荡激励力振幅 = 3640
         纵摇激励力矩振幅 = 1690
         波浪频率 = 入射波浪频率
         波浪周期 = 1 / 波浪频率
      elif question == 4:
         # 问题4: 参数
         入射波浪频率 = 1.9806
         垂荡附加质量 = 1091.099
         纵摇附加转动惯量 = 7142.493
         垂荡兴波阻尼系数 = 528.5018
         纵摇兴波阻尼系数 = 1655.909
         垂荡激励力振幅 = 1760
         纵摇激励力矩振幅 = 2140
         波浪频率 = 入射波浪频率
         波浪周期 = 1 / 波浪频率
      return None
class trange:
   """设置时间区间和间隔的参数"""
   def __init__(self, left, right, step):
      global t_left
      global t_right
      global t_step
      t_left = left
      t_right = right
      t_step = step
      return None
_{\rm } = question1234(2)
_ = trange(0, 200, 0.2)
```

In [6]: # TODO 跟变量有关的参数函数(这个后面有用,但是用处不大)

def S浮子底面积_func(r=浮子底半径):

```
return np.pi * r**2
S浮子底面积 = S浮子底面积 func()
def V排_func(h, pprint=True):
   :param h: 圆柱壳体的入水深度
   :param pprint: 是否打印状态
   :return: V排 (m^3)
   if h >= 0:
      print("圆锥壳体完全浸没")
      V排 = (1/3 * S浮子底面积 * 浮子圆锥部分高度) + (S浮子底面积 * h)
   else:
      print("圆锥壳体漂浮")
      depth = 浮子圆锥部分高度 + h
      r = 浮子底半径 * depth / 浮子圆锥部分高度
      V排 = 1/3 * S浮子底面积 func(r) * depth
   return V排
# print("浮子入水体积: ", V排_func(3))
# print("浮子入水体积: ", V排_func(2.4147))
# print("浮子入水体积: ", V排_func(0))
# print("浮子入水体积: ", V排_func(-0.001))
# print("浮子入水体积: ", V排_func(-0.8))
def F静水恢复力_func(h, pprint=False):
   """ 类似(就是)浮力 方向向上
   :param h: 圆柱壳体的入水深度
   :param pprint: 是否打印状态
   :return: F静水恢复力 (N)
   F静水恢复力 = 海水的密度 * 重力加速度 * V排_func(h, pprint)
   return F静水恢复力
# F静水恢复力 func(2.4147)
def F兴波阻尼力_func(v, k=垂荡兴波阻尼系数):
   """ 方向同速度方向
   :param v: 速度
   :return:
   F兴波阻尼力 = k * v
   return F兴波阻尼力
def F波浪激励力_func(t, omega=入射波浪频率, f=垂荡激励力振幅):
   """ 方向向上
   :param t: 时间
   :return: F波浪激励力 (N)
```

```
F波浪激励力 = f * np.cos(omega * t)
   return F波浪激励力
# F波浪激励力 func(0)
def F附加惯性力 func(m=垂荡附加质量, g=重力加速度):
   """ 方向向下 """
   F附加惯性力 = m * g
   return F附加惯性力
F附加惯性力 = F附加惯性力 func()
def F重力 func(m=浮子质量+振子质量, g=重力加速度):
   """ 方向向下 """
   F重力 = m * g
   return F重力
F重力 = F重力 func()
def c直线阻尼器的阻尼系数_func1():
   c直线阻尼器的阻尼系数 = 10000 # N·s/m
   return c直线阻尼器的阻尼系数
def c直线阻尼器的阻尼系数_func2(v浮子, v振子, k=10000, a=0.5):
   c直线阻尼器的阻尼系数 = k * abs(v \% \% \% \% \% )**a # N·s/m
   return c直线阻尼器的阻尼系数
```

平均输出功率公式

$$P = rac{1}{t_2 - t_1} \int_{t_1}^{t_2} F_G \Delta v dt = rac{1}{t_2 - t_1} \int_{t_1}^{t_2} c \Delta v^2 dt$$

准备

```
In [7]: # TODO parameters and func
m1 = 浮子质量
m2 = 振子质量
m1 = 浮子质量 + 垂荡附加质量
m2 = 振子质量 + 垂荡附加质量
k = 弹簧刚度
c直线阻尼器的阻尼系数 = c直线阻尼器的阻尼系数_func1()
c = c直线阻尼器的阻尼系数
f = 垂荡激励力振幅
omega = 入射波浪频率
k1 = -垂荡兴波阻尼系数
```

```
k2 = -海水的密度 * 重力加速度 * S浮子底面积
def differential equations 1(ys, t, c=c, k=k, k1=k1, k2=k2):
   """ 第1小问的方程求解函数 """
   y1 = ys[2-1]
   y3 = ys[4-1]
   y4 = c * (ys[2-1] - ys[4-1]) + k * (ys[1-1] - ys[3-1])
   y2 = f * np.cos(omega * t) + k1 * ys[2-1] + k2 * ys[1-1] - y4
   y2 = y2 / m1
   y4 = y4 / m2
   return [y1, y2, y3, y4]
def differential equations 2(ys, t, xishu, mici, k=k, k1=k1, k2=k2):
   """ 第2小问的方程求解函数 """
   y1 = ys[2-1]
   y3 = ys[4-1]
   c = c直线阻尼器的阻尼系数_func2(ys[2-1], ys[4-1], k=xishu, a=mici)
   y4 = c * (ys[2-1] - ys[4-1]) + k * (ys[1-1] - ys[3-1])
   y2 = f * np.cos(omega * t) + k1 * ys[2-1] + k2 * ys[1-1] - y4
   y2 = y2 / m1
   y4 = y4 / m2
   return np.array([y1, y2, y3, y4])
def get_power(task,
             pprint=False,
            t left=0,
             t_right=100,
            t_step=None,
             stable_time_begin=60,
            stable_time_end=100,
            c=c, k=k, k1=k1, k2=k2,
            xishu=10000, mici=0.5,
            y0=[0 \text{ for in } range(4)]):
   """ 获得平均输出功率(该函数与其他函数独立)
   :param task: 第几小问
   :param t left: 设置为 0, 固定值
   :param t_right: 设置为 100, 固定值
   :param t step: 设置为 0.2, 非固定值, 可以改
       时间间隔, 时间间隔越小结果越准确
   0.00
   t_left = 0
   t_right = 100
```

```
t step = 0.2 if t step is None else t step
t = np.linspace(t left, t right, num=int(t right / t step) + 1)
if task == 1:
    result1 = odeint(differential_equations_1, y0, t, args=(c, ))
elif task == 2:
    result1 = odeint(differential equations 2, y0, t, args=(xishu, mici, ))
delta = abs(result1[:, 1] - result1[:, 3]) # 相对速度
if task == 1:
    c = c
elif task == 2:
    c = xishu * delta**mici
F zuli = c * delta
power i = F zuli * delta
power i = power i[1:] * t step # 矩形
power i = (power i[1:] + power i[:-1]) * t step / 2 # 梯形
idx_begin = int(stable_time_begin / t_step)
idx_end = int(stable_time_end / t_step)
stable time length = stable time end - stable time begin
power = power_i[idx_begin:idx_end]
P = power.sum() / stable_time_length
if pprint:
    print("平均输出功率: ", P)
return P
```

(1) c 常量

c=10000

```
In [8]: # TODO 第1小问求解类
class solver_task1:
    """ 第 1 小问求解 """
    def __init__(self):
        self.task = 1
        self.pprint = False
        self.epoch = None
        self.c_range = None
        self.ps = None
        self.jit = True

# TODO 遗传
def _GA_func(self, c):
```

```
return -get power(task=self.task, pprint=self.pprint, c=c)
@timeit(text="遗传")
def run GA(self):
    """ 遗传 GA """
    1b, ub = 0, 1e5
    ga = GA(
       func=self. GA func,
       n dim=1,
        size pop=50,
       max iter=200,
       prob mut=0.001,
       lb=[lb],
       ub=[ub],
       constraint_eq=tuple(),
        constraint ueq=tuple(),
       precision=1e-07,
       early stop=True,
    xbest, ybest = ga.run()
    print("直线阻尼器的阻尼系数: ", xbest, "最大输出功率", -ybest)
    return float(xbest), -float(ybest)
# TODO 规划
def Program func(self, c):
    return -get_power(task=self.task, pprint=self.pprint, c=c)
@timeit(text="规划")
def run Program(self, x0=35000):
    """ 规划 Program """
    1b, ub = 0, 1e5
    opt = minimize(
       self._Program_func,
       x0=x0,
       bounds=((lb, ub), ),
       method='trust-constr', # SLSQP trust-constr
         options={'xtol': 1e-30, 'gtol': 1e-30, 'disp': True},
    xbest = opt.x
   ybest = -self._Program_func(xbest)
    print("直线阻尼器的阻尼系数: ", xbest, "最大输出功率", ybest)
    return float(xbest), float(ybest)
# TODO 变步长
def _LMS_func(self, c):
    return get_power(task=self.task, pprint=self.pprint, c=c)
def _find_LMS_best(self, c_range, ps):
    self.c_range = c_range
```

```
self.ps = ps
    return c range[np.argmax(ps)], np.max(ps)
@timeit(text="变步长")
def run LMS(self, lb, ub, num, alpha=0):
    func = self. run LMS jit if self.jit else self. run LMS nojit
    return func(lb, ub, num, alpha)
def LMS main(self, lb, ub, num, alpha):
    """ 变步长 LMS """
    num len = len(str(num))
    fm = "%" + str(num len) + "d/%" + str(num_len) + "d"
    if self.epoch is not None: # 用户的分割
        batch size = num // self.epoch
        if batch size == 0: # 用户非法分割
            self.epoch = None
    if self.epoch is None: # 自动处理非法分割
        batch size = num // 100 # 分割 100 份
        self.epoch = 100
        batch_size = num // 10 if batch_size == 0 else batch_size # 分割 10 份
        self.epoch = 10
        batch size = num // 1 if batch size == 0 else batch size # 分割 1 份
        self.epoch = 1
    \# ps = [0 \text{ for } in \text{ range}(num + 1)] # list
    ps = np.zeros(num + 1) # np.ndarray
    t0 = time()
    lb = lb * (1 - alpha)
    ub = ub * (1 + alpha)
    print(f"变步长范围: [", lb, ',', ub, "]: ")
    c_range = np.linspace(lb, ub, num + 1)
    for i, c in enumerate(c_range):
        p = self._LMS_func(c)
        ps[i] = p # list / np.ndarray
        # info
       if i % batch_size == 0:
           t1 = time()
           _stars = '[' + '*' * (i // batch_size) + '.' * ((num - i) // batch_size) + ']'
            print(fm % (i, num), _stars, round(t1 - t0, 2), "s/iter")
            t0 = time()
    xbest, ybest = self._find_LMS_best(c_range, ps)
    return xbest, ybest
def _run_LMS_nojit(self, lb, ub, num, alpha):
    return self._LMS_main(lb, ub, num, alpha)
@jit
def _run_LMS_jit(self, lb, ub, num, alpha):
```

```
return self. LMS main(lb, ub, num, alpha)
# TODO 绘图
def plot result(self, show=True, save=False):
   # TODO 阻尼系数和平均输出功率的关系
   x = self.c range
   y = self.ps
   trace = go.Scatter(x=x, y=y)
   fig = go.Figure(data=trace)
   fig.update layout(
       width=1000,
       height=600,
       xaxis=dict(title='$阻尼系数 (N·s/m)$'),
       yaxis=dict(title='$平均输出功率 (W)$'),
       title=dict(text='阻尼系数和平均输出功率的关系'),
   if save:
       fig.write_image(IMG_SVG / "问题2-阻尼系数和平均输出功率的关系.svg")
   if show:
       fig.show()
   return None
```

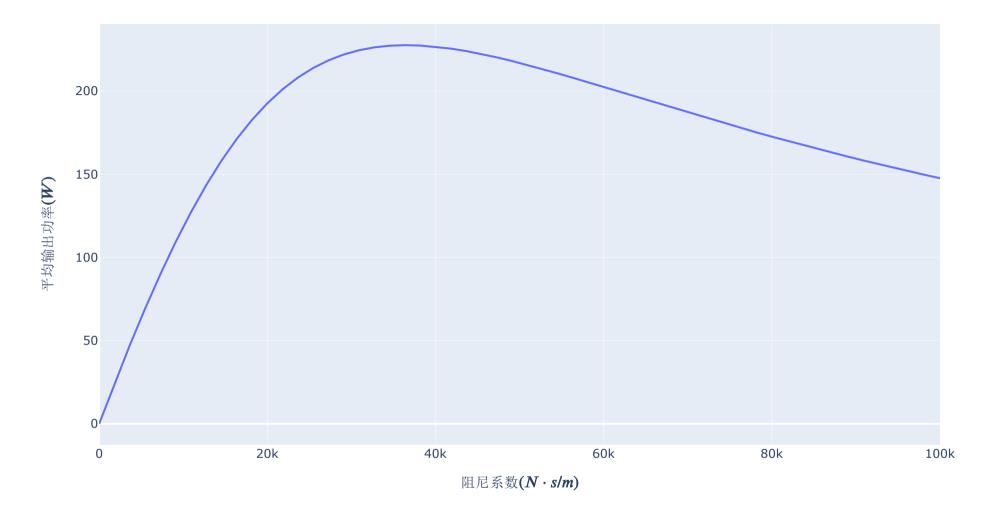
```
In [9]: # TODO 单独运行求解
solver1 = solver_task1()
solver1.pprint = False
solver1.epoch = 11
solver1.jit = True

# xbest, ybest = solver1.run_GA() # 遗传
# solver1.run_Program(x0=35000) # 规划
solver1.run_LMS(0, 100000, 55, alpha=0) # 变步长
solver1.plot_result(show=True, save=True) # 绘图
```

变步长开始计时:

Out[9]: (36363.63636363637, 227.61665763794673)

阻尼系数和平均输出功率的关系



```
In [11]: # TODO 联合运行求解
solver1 = solver_task1()
solver1.pprint = False
solver1.epoch = 24
solver1.jit = True

# TODO GA + LMS
t0 = time()
```

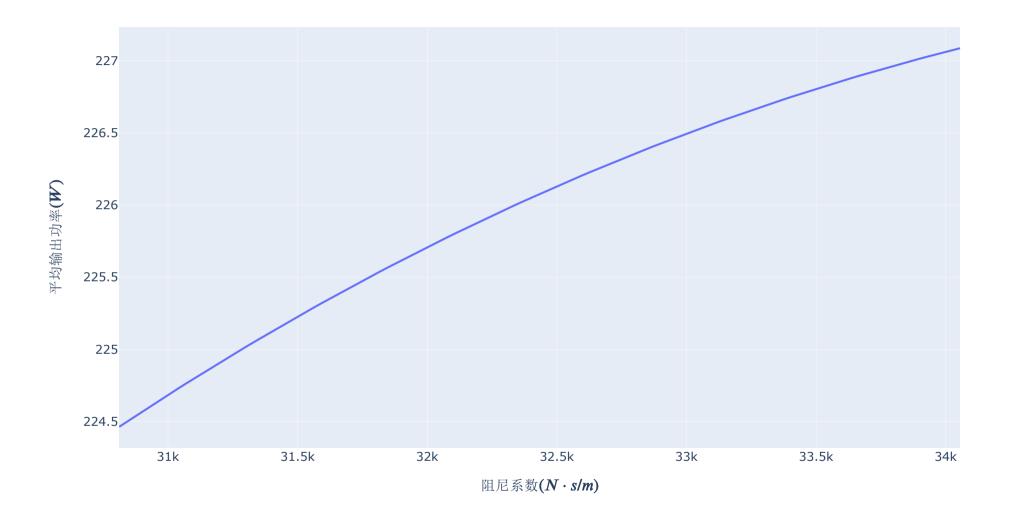
```
xbest, ybest = solver1.run GA() # 遗传
solver1.run LMS(xbest, xbest, 100, alpha=0.05) # 变步长
print("总用时: ", time() - t0)
solver1.plot result(show=True, save=False) #绘图
print('-' * 100)
# TODO Program + LMS
t0 = time()
xbest, ybest = solver1.run Program(x0=35000) # 规划
solver1.run LMS(xbest, xbest, 100, alpha=0.05) # 变步长
print("总用时: ", time() - t0)
solver1.plot result(show=True, save=False) #绘图
遗传开始计时:
直线阻尼器的阻尼系数: [32433.27713756] 最大输出功率 [226.07675711]
遗传结束计时,用时: 7.074131727218628 s
变步长开始计时:
变步长范围: [ 30811.613280685207 , 34054.940994441546 ]:
 0/100 [.....] 0.08 s/iter
 4/100 [*.....] 0.25 s/iter
 8/100 [**.....] 0.22 s/iter
12/100 [***.....] 0.25 s/iter
20/100 [*****..... 0.2 s/iter
24/100 [****** ..... 0.28 s/iter
28/100 [******* ..... 0.3 s/iter
32/100 [******* 0.25 s/iter
36/100 [******** ..... 0.29 s/iter
40/100 [********* 0.25 s/iter
44/100 [********** ..... 0.3 s/iter
48/100 [************ ..... 0.27 s/iter
52/100 [************** 0...] 0.24 s/iter
56/100 [*************** 0.24 s/iter
60/100 [*************** 0.3 s/iter
64/100 [********************* 0.29 s/iter
68/100 [*********************** 0.22 s/iter
72/100 [*********************** 0.23 s/iter
76/100 [************************ 0.26 s/iter
84/100 [**************************** ....] 0.3 s/iter
88/100 [******************************* ...] 0.38 s/iter
```

92/100 [**************************.] 0.34 s/iter 96/100 [******************************.] 0.32 s/iter

Out[11]: (34054.940994441546, 227.08648987690094)

总用时: 14.200635194778442

阻尼系数和平均输出功率的关系

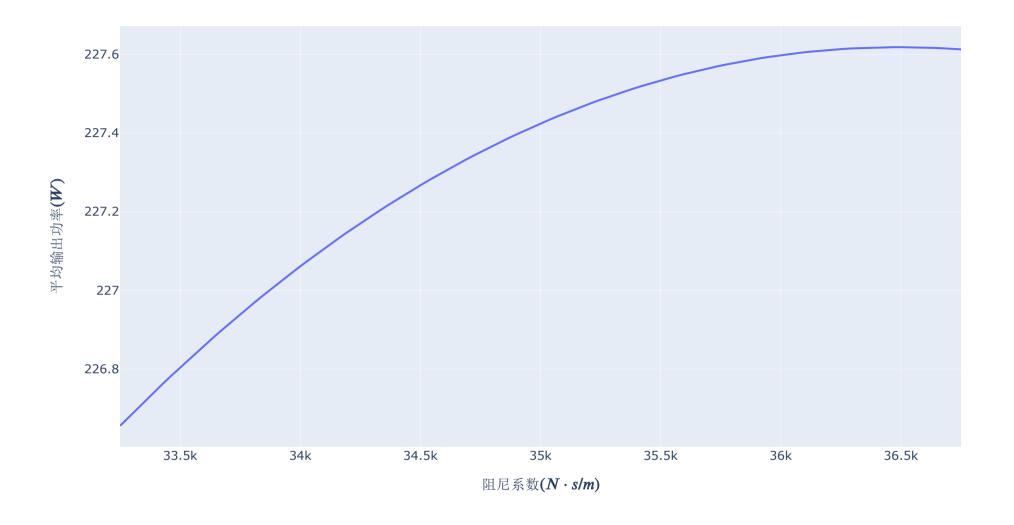


规划开始计时: 直线阻尼器的阻尼系数: [34999.975705] 最大输出功率 227.42405210598844 规划结束计时,用时: 13.769381999969482 s 变步长开始计时: 变步长范围: [33249.97691975324 , 36749.97449025358]: 0/100 [.....] 0.06 s/iter 4/100 [*.....] 0.27 s/iter 8/100 [**.....] 0.35 s/iter 12/100 [***..... 0.38 s/iter 16/100 [****..... 0.33 s/iter 20/100 [***** 0.35 s/iter 24/100 [****** 0.32 s/iter 28/100 [******* 0.3 s/iter 32/100 [******* 0.3 s/iter 36/100 [******** 0.3 s/iter 40/100 [********* 0.4 s/iter 44/100 [*********** 0.41 s/iter 48/100 [*************** 0.3 s/iter 52/100 [************** 0.35 s/iter 56/100 [************** 0.29 s/iter 60/100 [*********************** 0.38 s/iter 64/100 [********************* 0.38 s/iter 68/100 [*********************** 0.44 s/iter 72/100 [************************ 0.36 s/iter 76/100 [************************ 0.39 s/iter 80/100 [****************************** 0.43 s/iter 84/100 [***************************** 0.35 s/iter 88/100 [******************************** ...] 0.41 s/iter 92/100 [************************..] 0.36 s/iter 96/100 [******************.] 0.37 s/iter 100/100 [********************* 0.35 s/iter 变步长结束计时,用时: 8.927614450454712 s

Out[11]: (36504.974660318556, 227.6179770710277)

总用时: 22.699984073638916

阻尼系数和平均输出功率的关系



(2) c 非常量

$$c = 10000 |V|^{0.5} = 10000 |V_1 - V_2|^{0.5} = 10000 |\dot{X_1} - \dot{X_2}|^{0.5}$$

```
def init (self):
    self.task = 2
   self.pprint = False
   self.epoch = 100
    self.xishu s = None
   self.mici s = None
   self.pss = None
    self.jit = True
# TODO 遗传
@staticmethod
def GA func(xishu, mici):
    return -get power(task=2, pprint=False, xishu=xishu, mici=mici)
@timeit("遗传")
def run GA(self):
    """ 遗传 GA """
    1b, ub = 0, 1e5
    ga = GA(
       func=self._GA_func,
       n_{dim=2}
        size pop=50,
       max_iter=200,
       prob_mut=0.001,
       lb=[lb, 0],
       ub=[ub, 1],
       constraint_eq=tuple(),
        constraint_ueq=tuple(),
        precision=1e-07,
        early_stop=True,
   xbest, ybest = ga.run()
    print("[比例系数,幂指数]: ",xbest,"最大输出功率",-ybest)
    return xbest, -ybest
# TODO 规划
def _Program_func(self, x):
   return -get_power(task=self.task, pprint=self.pprint, xishu=x[0], mici=x[1])
@timeit("规划")
def run_Program(self, x0=[80000, 0.4]):
    """ 规划 Program """
    opt = minimize(
        self._Program_func,
       x0=x0
       bounds=((0, 100000), (0, 1)),
       method='SLSQP', # SLSQP trust-constr
```

```
options={'xtol': 1e-5, 'gtol': 1e-5, 'disp': True}
    xbest = opt.x
    ybest = -self. Program func(xbest)
    print("[比例系数,幂指数]: ",xbest,"最大输出功率",ybest)
    return xbest, vbest
# TODO 变步长
def LMS func(self, xishu, mici):
    return get power(task=self.task, pprint=self.pprint, xishu=xishu, mici=mici)
def find LMS best(self, xishu s, mici s, pss):
    self.xishu s = xishu s # np.ndarray
    self.mici s = mici s # np.ndarray
    self.pss = pss # np.ndarray
   index = np.unravel index(self.pss.argmax(), self.pss.shape)
    return [self.xishu s[index[0]], self.mici s[index[1]]], self.pss[index]
@timeit("变步长")
def run_LMS(self, *args, **kwargs):
    if self.jit:
        return self. run LMS jit(*args, **kwargs)
    else:
        return self._run_LMS_nojit(*args, **kwargs)
    func = self. run LMS jit if self.jit else self. run LMS nojit
   return func(*args, **kwargs)
def LMS main(self,
             xishu lb=0, xishu ub=100000, xishu num=100, xishu alpha=0,
             mici_lb=0, mici_ub=1, mici_num=10, mici_alpha=0):
    """ 变步长 LMS """
    t0 = time()
    batch_size = xishu_num // self.epoch
    num len = len(str(xishu num))
   fm = "%" + str(num len) + "d/%" + str(num len) + "d"
    if self.epoch is not None: # 用户的分割
        batch size = xishu num // self.epoch
       if batch size == 0: # 用户非法分割
           self.epoch = None
    if self.epoch is None: # 自动处理非法分割
        batch size = xishu num // 100 # 分割 100 份
        self.epoch = 100
       batch_size = xishu_num // 10 if batch_size == 0 else batch size # 分割 10 份
        self.epoch = 10
        batch_size = xishu_num // 1 if batch_size == 0 else batch_size # 分割 1 份
        self.epoch = 1
```

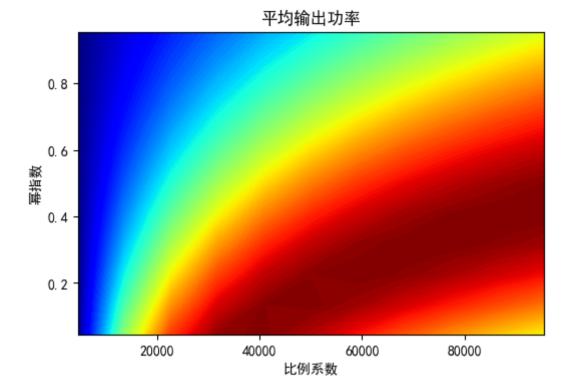
```
pss = np.zeros([xishu num+1, mici num+1])
    xishu lb = xishu lb * (1 - xishu alpha)
    xishu ub = xishu ub * (1 + xishu alpha)
    mici lb = mici lb * (1 - mici alpha)
    mici ub = mici ub * (1 + mici alpha)
    xishu s = np.linspace(xishu lb, xishu ub, xishu num+1)
    mici s = np.linspace(mici_lb, mici_ub, mici_num+1)
    for i, xishu in enumerate(xishu s):
        for j, mici in enumerate(mici s):
            pss[i, j] = self. LMS func(xishu=xishu, mici=mici)
       if i % batch size == 0:
           t1 = time()
            stars = '[' + '*' * (i // batch size) + '.' * ((xishu num - i) // batch size) + ']'
            print(fm % (i, xishu num), stars, round(t1 - t0, 2), "s/iter")
            t0 = time()
    xbest, ybest = self._find_LMS_best(xishu_s, mici_s, pss)
    print("[比例系数, 幂指数]: ", xbest, "最大输出功率", ybest)
   return xbest, ybest
def _run_LMS_nojit(self, *args, **kwargs):
    return self. LMS main(*args, **kwargs)
@jit
def run LMS jit(self, *args, **kwargs):
    return self. LMS main(*args, **kwargs)
# TODO 绘图
def plt contourf(self, show=True, save=False):
    mi, mx = self.pss.min(), self.pss.max()
    lb1, ub1, lb2, ub2 = self.xishu_s.min(), self.xishu_s.max(), self.mici_s.min(), self.mici_s.max()
    print(mi, mx, lb1, ub1, lb2, ub2)
    plt.figure(dpi=100)
    plt.contourf(self.pss.T, np.arange(mi, mx+1, (mx - mi) / 100), origin='lower', extent=[lb1, ub1, lb2, ub2], cmap=plt.cm.jet)
    plt.xlabel('比例系数')
    plt.ylabel('幂指数')
    plt.title("平均输出功率")
        plt.savefig(IMG SVG / '问题2-二维等高线图.svg')
    if show:
        plt.show()
    return True
def plotly Contour(self, show=True, save=False):
```

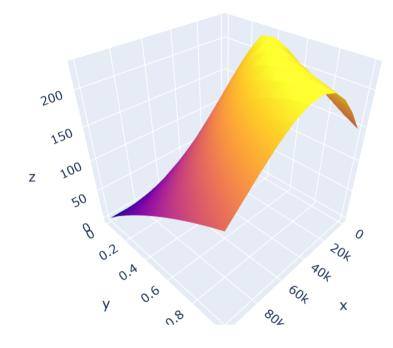
```
fig = go.Figure(data=go.Contour(
        z=self.pss,
         x=self.xishu s, v=self.mici s,
         fillcolor=True,
          colorscale='jet',
        autocolorscale=False,
        autocontour=False,
        colorscale=[[0.0, "rgb(165,0,38)"],
                    [1/9, "rgb(215,48,39)"],
                    [2/9, "rgb(244,109,67)"],
                    [3/9, "rgb(253,174,97)"],
                    [4/9, "rgb(254,224,144)"],
                    [6/9, "rgb(224,243,248)"],
                    [6/9, "rgb(171,217,233)"],
                    [8/9, "rgb(116,173,209)"],
                    [8/9, "rgb(69,117,180)"],
                    [1.0, "rgb(49,54,149)"]],
    ))
    if save:
        fig.write_image('temp.png')
    if show:
        fig.show()
    return True
def _plotly_Surface(self, show=True, save=False):
    fig = go.Figure(data=[go.Surface(
       x=self.xishu_s,
       y=self.mici_s,
        z=self.pss,
    )])
    if save:
        fig.write_image(IMG_SVG / '问题2-3D曲线图.svg')
    if show:
        fig.show()
    return True
def plot_result(self, *args, **kwargs):
    self._plt_contourf(*args, **kwargs)
    self._plotly_Surface(*args, **kwargs)
    return None
```

```
In [13]: solver2 = solver_task2()
    solver2.epoch = 100
    solver2.pprint = False
```

```
solver2.jit = False
         solver2.run GA() # 遗传
         solver2.run Program(x0=[42424, 0.5]) # 规划
         solver2.run LMS(xishu lb=0, xishu ub=100000, xishu num=10, xishu alpha=0,
                       mici lb=0, mici ub=1, mici num=10, mici alpha=0) # 变步长
         # solver2.run LMS(xishu lb=0, xishu ub=100000, xishu num=1000000, xishu alpha=0,
                         mici lb=0, mici ub=1, mici num=100, mici alpha=0) # 遍历: 运行时间很长.....
         solver2.plot result(show=True, save=False) #绘图
         遗传开始计时:
         [比例系数,幂指数]: [6.75209262e+04 2.57741169e-01] 最大输出功率 [227.60337422]
         遗传结束计时,用时: 11.672255277633667 s
Out[13]: (array([6.75209262e+04, 2.57741169e-01]), array([227.60337422]))
         规划开始计时:
         Optimization terminated successfully
                                             (Exit mode 0)
                    Current function value: -225.16902175018322
                   Iterations: 7
                    Function evaluations: 71
                    Gradient evaluations: 7
         [比例系数,幂指数]: [4.24237907e+04 8.42700465e-04] 最大输出功率 225.16902175018322
         规划结束计时,用时: 12.281152248382568 s
Out[13]: (array([4.24237907e+04, 8.42700465e-04]), 225.16902175018322)
         变步长开始计时:
         0/10 [.....] 1.75 s/iter
         1/10 [*.....] 1.97 s/iter
         2/10 [**.....] 1.93 s/iter
         3/10 [***.....] 1.93 s/iter
         4/10 [****.....] 2.04 s/iter
         5/10 [*****....] 2.1 s/iter
         6/10 [******....] 2.49 s/iter
         7/10 [******* ...] 2.17 s/iter
         8/10 [********..] 2.16 s/iter
         9/10 [********.] 2.75 s/iter
        10/10 [******** 2.33 s/iter
         [比例系数,幂指数]: [100000.0,0.4] 最大输出功率 227.64617885502085
         变步长结束计时,用时: 23.62815570831299 s
```

Out[13]: ([100000.0, 0.4], 227.64617885502085) 0.0 227.64617885502085 0.0 100000.0 0.0 1.0



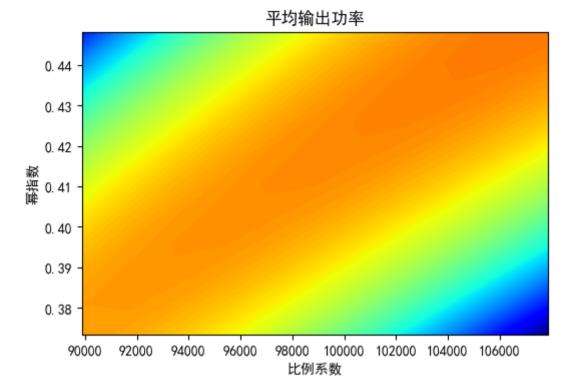


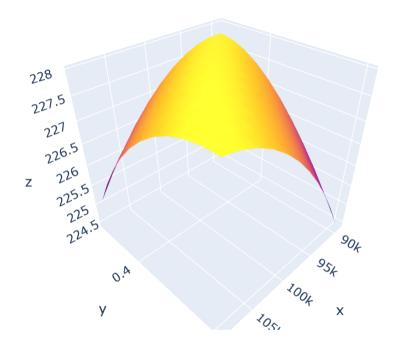
```
In [14]: # # TODO 手动检查数据
# get_power(task=2, pprint=False, xishu=3.71721006e+04, mici=7.90606784e-02)
# get_power(task=2, pprint=False, xishu=4.24228511e+04, mici=5.01296092e-17)
# get_power(task=2, pprint=False, xishu=100000, mici=0.4)

In []:

In [15]: # TODO 联合运行求解
solver2 = solver_task2()
# TODO GA + LMS
solver2.epoch = 10
```

```
solver2.pprint = False
         solver2.jit = False
         t0 = time()
         xbest, ybest = solver2.run GA() # 遗传
         # xbest = (80000, 1)
         solver2.run LMS(xishu lb=xbest[0], xishu ub=xbest[0], xishu num=10, xishu alpha=0.1,
                        mici lb=xbest[1], mici ub=xbest[1], mici num=10, mici alpha=0.1) # 变步长
         print("总用时: ", time() - t0)
         solver2.plot result(show=True, save=False) # 绘图
         print('-' * 100)
         # TODO Program + LMS
         solver2.epoch = 100
         solver2.pprint = False
         solver2.jit = False
         t0 = time()
         xbest, ybest = solver2.run Program(x0=[80000, 0.4]) # 规划
         solver2.run LMS(xishu lb=xbest[0], xishu ub=xbest[0], xishu num=10, xishu alpha=0.1,
                        mici lb=xbest[1], mici ub=xbest[1], mici num=10, mici alpha=0.1) # 变步长
         print("总用时: ", time() - t0)
         solver2.plot result(show=True, save=False) # 绘图
         遗传开始计时:
         [比例系数,幂指数]: [9.88658007e+04 4.10816217e-01] 最大输出功率 [227.84305425]
         遗传结束计时,用时: 10.767147541046143 s
         变步长开始计时:
         0/10 [.....] 2.34 s/iter
         1/10 [*.....] 2.49 s/iter
         2/10 [**.....] 2.54 s/iter
         3/10 [***.....] 2.56 s/iter
         4/10 [****.....] 2.47 s/iter
         5/10 [*****....] 2.78 s/iter
         6/10 [******....] 2.49 s/iter
         7/10 [*******...] 2.65 s/iter
         8/10 [*******..] 2.47 s/iter
         9/10 [********.] 2.57 s/iter
         10/10 [******** 2.41 s/iter
         [比例系数,幂指数]: [108752.3808184858, 0.4518978388248586] 最大输出功率 227.94186216235866
         变步长结束计时,用时: 27.748749017715454 s
Out[15]: ([108752.3808184858, 0.4518978388248586], 227.94186216235866)
         总用时: 38.5202112197876
         224.47140601527843 227.94186216235866 88979.22066967019 108752.3808184858 0.36973459540215703 0.4518978388248586
```



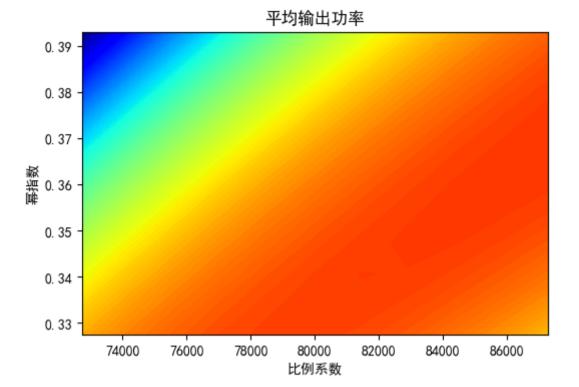


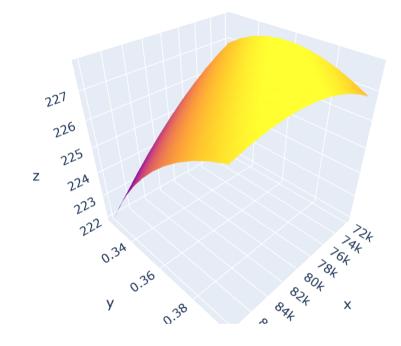
•

4

```
规划开始计时:
        Optimization terminated successfully (Exit mode 0)
                   Current function value: -227.24712185040116
                   Iterations: 10
                   Function evaluations: 117
                   Gradient evaluations: 10
        [比例系数,幂指数]: [8.00026845e+04 3.60299680e-01] 最大输出功率 227.24712185040116
         规划结束计时,用时: 24.791813850402832 s
         变步长开始计时:
         0/10 [.....] 2.4 s/iter
         1/10 [*.....] 2.38 s/iter
         2/10 [**.....] 2.08 s/iter
         3/10 [***.....] 2.29 s/iter
         4/10 [****.....] 2.31 s/iter
         5/10 [***** .....] 2.65 s/iter
         6/10 [****** ....] 2.36 s/iter
         7/10 [*******...] 2.31 s/iter
         8/10 [*******..] 2.39 s/iter
         9/10 [********.] 2.46 s/iter
        10/10 [******** 2.37 s/iter
        [比例系数,幂指数]: [88002.9529980827, 0.3675056738229399] 最大输出功率 227.7653029616472
         变步长结束计时,用时: 26.013054847717285 s
Out[15]: ([88002.9529980827, 0.3675056738229399], 227.7653029616472)
        总用时: 50.80678367614746
```

222.00697113533874 227.7653029616472 72002.41608934039 88002.9529980827 0.3242697121967117 0.3963296482404254





```
In [16]: # TODO 手动检查数据
get_power(task=2, pprint=False, xishu=59552.85847047485, mici=0.20415461684194905)
get_power(task=2, pprint=False, xishu=88002.9529980827, mici=0.3675056738229399)
```

Out[16]: 227.55871280599794
Out[16]: 227.7653029616472

In []: